

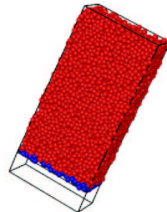
Rheology of Granular Flow

*Gary Grest, James Landry, Leo Silbert
and Steve Plimpton*

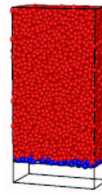
Sandia National Laboratories

Deniz Ertas and Thomas Halsey, ExxonMobil, NJ

Dov Levine, Technion, Haifa, Israel



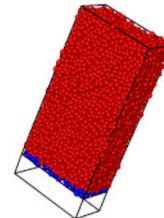
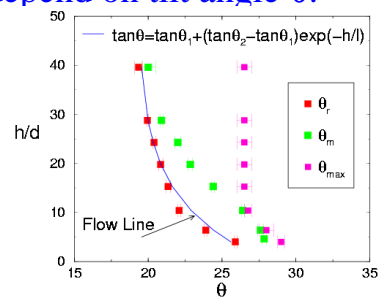
Chute flows



Packings

Flow down an inclined plane

- **Simplest dynamical system to relate stress and structure**
- **Three distinct regimes of flow depend on tilt angle θ :**
 - $\theta < \theta_r(h)$: *No motion*
 - $\theta_r < \theta < \theta_{max}(h)$: *Steady state flow*
 - $\theta > \theta_{max}(h)$: *Avalanching flow*
- **Steady state flow depends on material properties: μ and ϵ**
- **Dimensional analysis expect $\sigma \propto \gamma^2$**
- **For constant density this leads to $\langle v \rangle \propto h^{3/2}$**



Physical Interests in Granular Systems

Granular materials are ubiquitous in everyday life

Ceramics in a die

Sand on a beach

Grains

- **STATICS**

- Grains in a pile
- Silos
- Coffee-grounds
- Pills in a bottle

- **DYNAMICS**

- Rock debris flows
- Avalanches
- Coal on a conveyor belt
- Flow in a hopper

- *Storage, transport, and handling of granular materials is of immense industrial importance*

Current Issues in Granular Matter

- Theoretical understanding of the basic phenomena is needed:
 - Granular matter: macroscopic particles of different shape, size, and material properties
 - Friction and plastic deformation dissipate energy
 - Standard methods of statistical mechanics *not* applicable
 - Need constitutive equations for continuum calculations
- There are few *well-controlled* experiments to test theoretical models

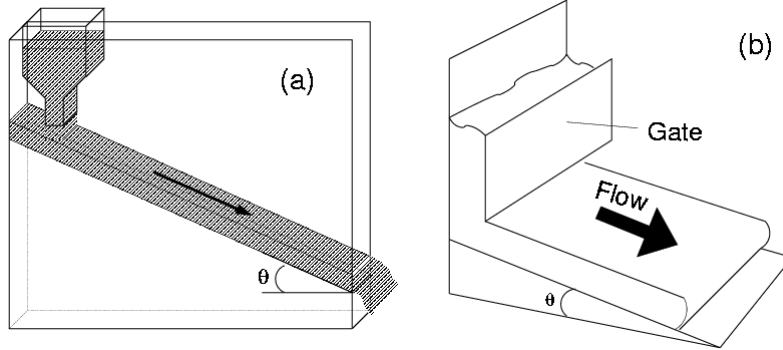
Granular Simulations - Recent Developments

- An efficient, highly parallel molecular dynamics code has been developed to simulate granular materials
 - Mono or polydispersed particulates
 - Arbitrary materials properties: hardness, coefficient of restitution, and friction coefficients
 - Arbitrary shaped container: smooth or rough wall
- Maximum number of particles in range 1-2 million
- Variety of analysis codes have been developed
- Results for gravity driven flow and geometry of frictional sphere packings will be focus of this presentation

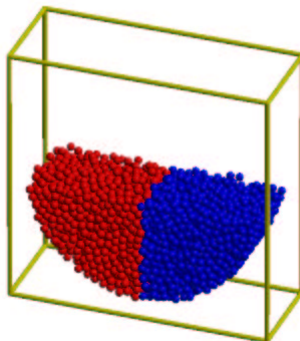
Simulation Technique

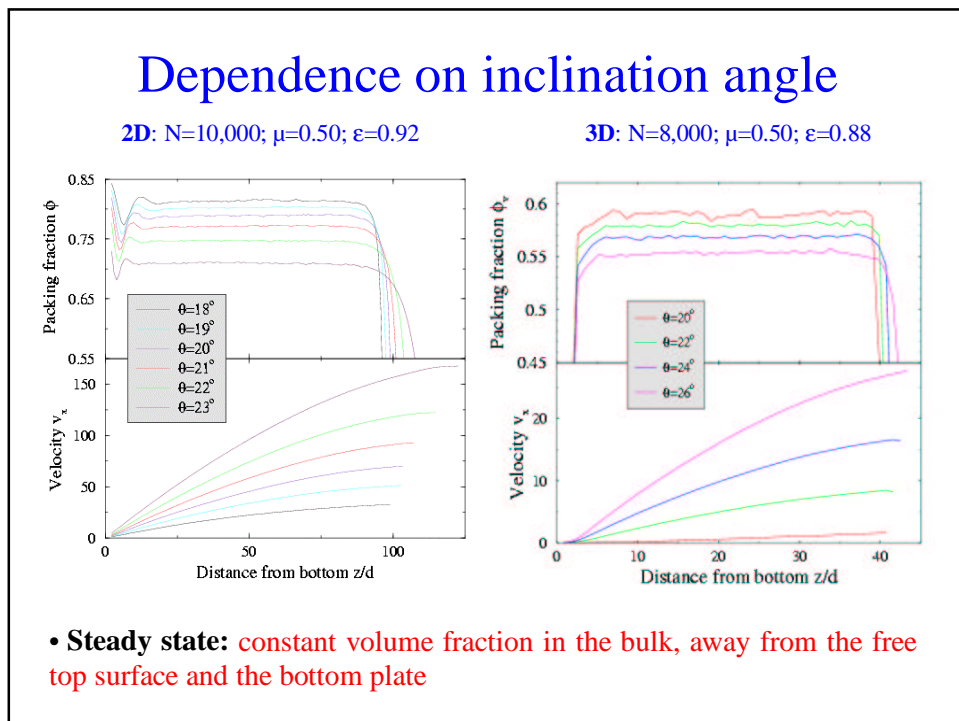
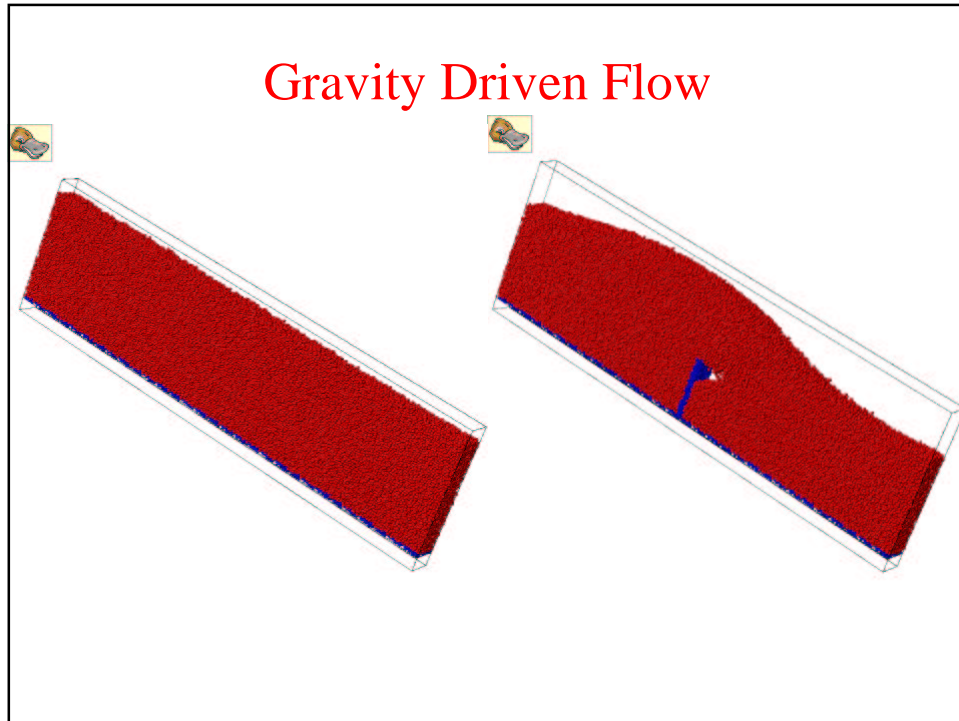
- Molecular Dynamics - Solve Newton's Equation
 - translational and rotational degrees of freedom
- Interaction forces depend on particle-particle overlap δ
 - μ - particle friction coefficient (Coulomb criterion)
 - ε - coefficient of restitution (determine inelasticity)
- Dry limit - purely repulsive forces which act only on contact $\mathbf{F} = \mathbf{F}_n + \mathbf{F}_t$
 - $\mathbf{F}_n = f(\delta/d) (k_n \delta \mathbf{n} + \gamma_n m_{\text{eff}} \mathbf{v}_n)$, $f(\delta/d) = 1$ or $(\delta/d)^{1/2}$
 - $\mathbf{F}_t = f(\delta/d) (-k_t \Delta \mathbf{s}_t - \gamma_t m_{\text{eff}} \mathbf{v}_t)$, $\Delta \mathbf{s}_t$ is integral over relative displacement of two particles in contact
 - Coulomb proportionality $|\mathbf{F}_t| \leq \mu |\mathbf{F}_n|$

Experimental Geometries

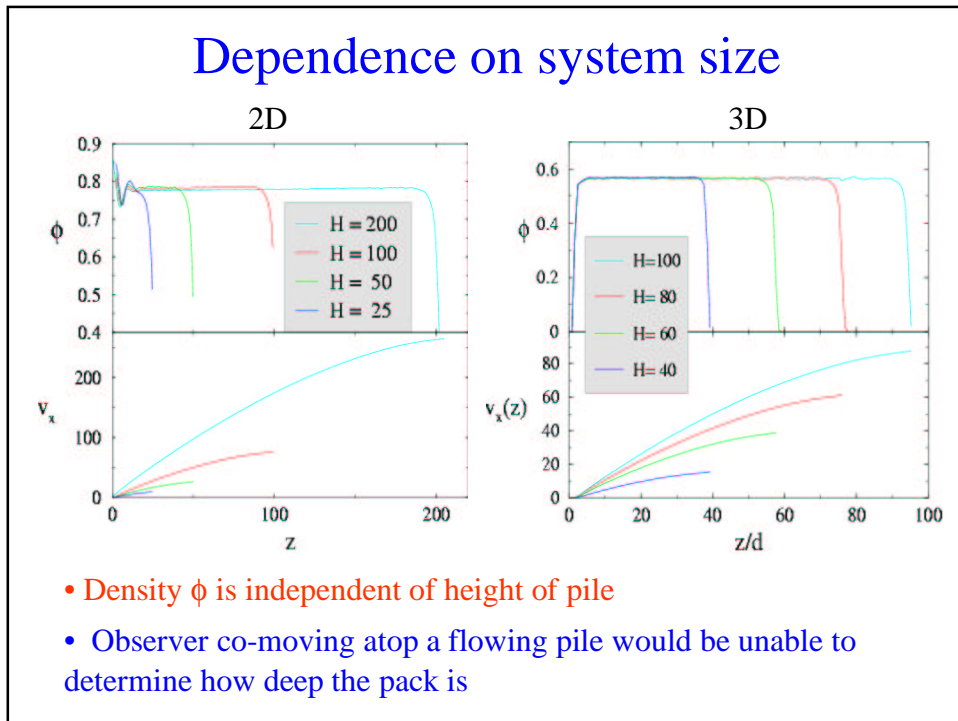


Rotating Drum





Dependence on system size



System size scaling

- Force balance:

$$\frac{\partial \sigma_{zz}}{\partial z} = \rho g \cos \theta \quad \frac{\partial \sigma_{xz}}{\partial z} = \rho g \sin \theta$$

- For a given tilt angle

$$\sigma_{xz}(z) = \sigma_{zz}(z) \tan \theta$$

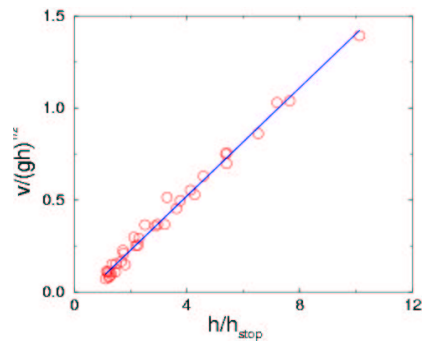
- Bagnold's momentum-collision analysis proposes that for constant density, $\left(\frac{dv_x(x)}{dz}\right)^2 \propto \sigma$

- Dependence of the velocity on the height of the pile

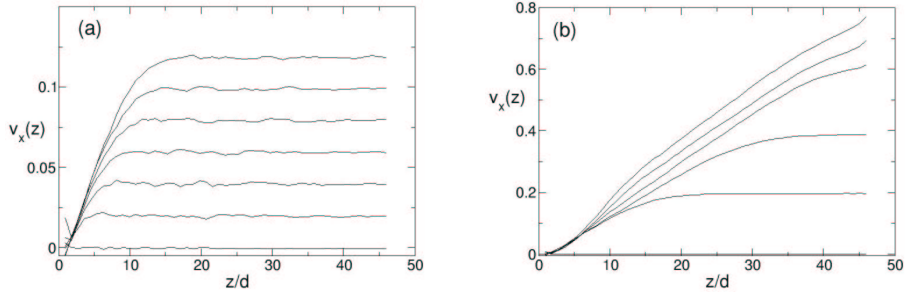
$$v_x(z) \propto [h^{3/2} - (h-z)^{3/2}]$$

- Velocity v scales with height h as

$$\langle v \rangle \sim h^{3/2}$$

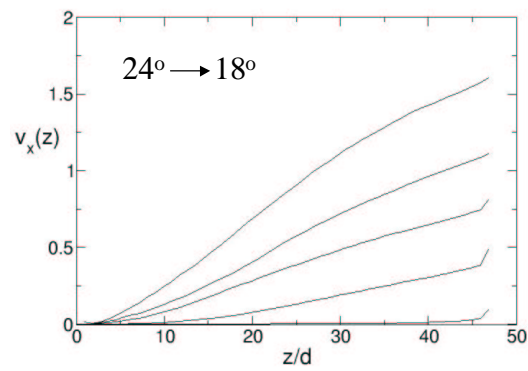


Initiation of Flow



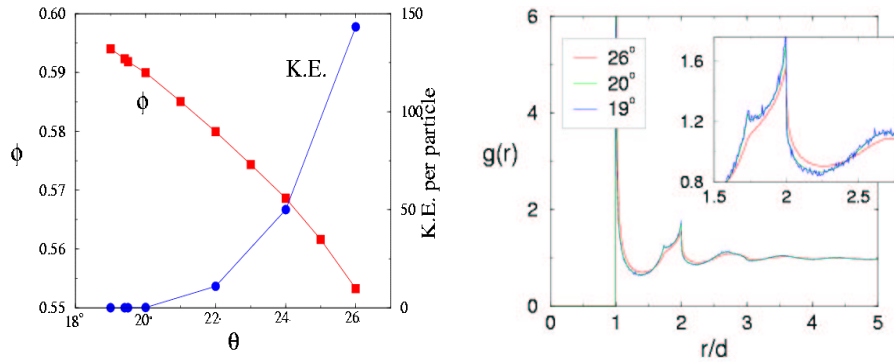
- Flow is initiated at base - top initially moves as plug
- Fluctuating region moves vertically

Cessation of Flow



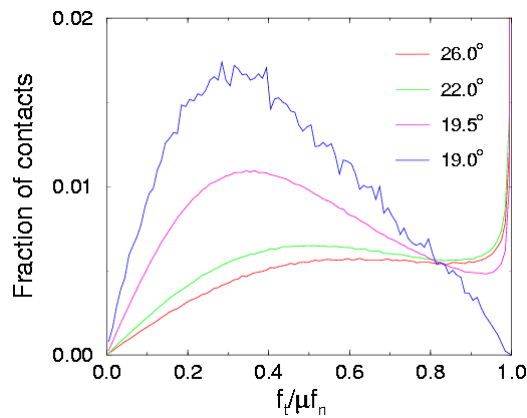
- Cessation of flow begins at base and moves vertically even though velocity fluctuations are greatest at bottom of pile

Jamming Transition



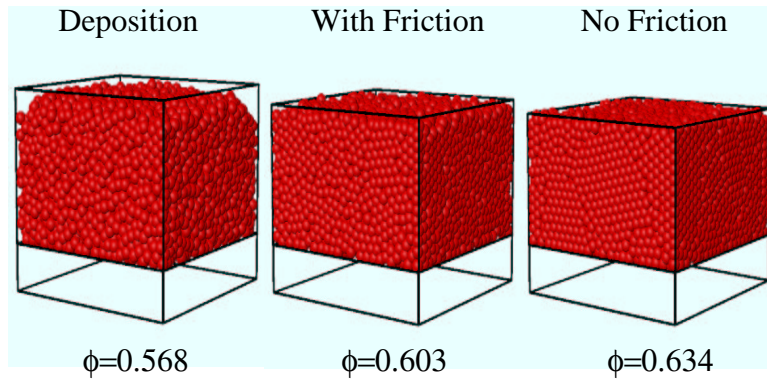
- System compacts and cools as θ is reduced
- Flow ceases at the angle of repose $\theta_r=19.4^\circ$
- Emerging amorphous phase is seen as a splitting of the second peak in $g(r)$

Plastic-Elastic Transition



- Force ratio: friction force / maximal force = $f_t/\mu f_n$
- Flowing states have a predominance of plastic contacts, i.e. contacts exactly at yield
- Once $\theta < \theta_r$ plastic contacts relax and convert to elastic ones

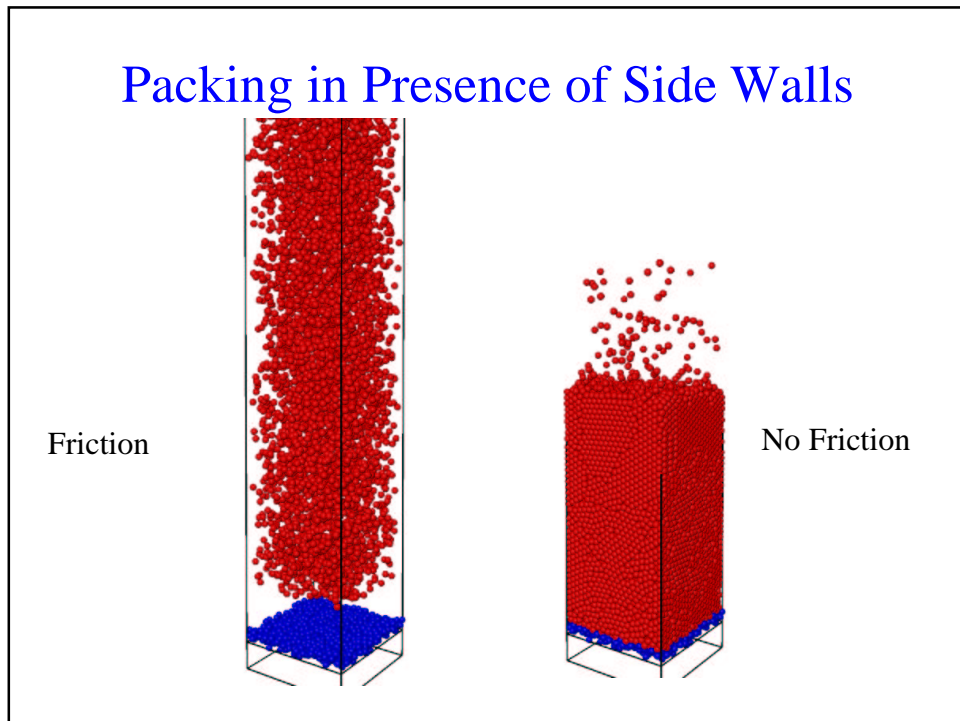
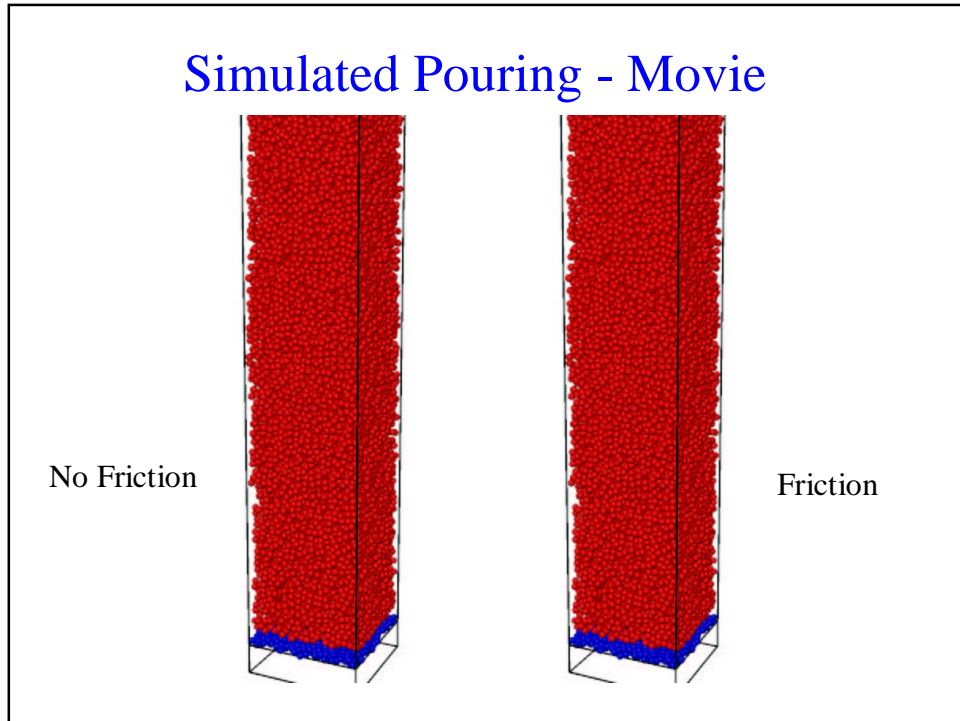
Effect of Friction on Packing



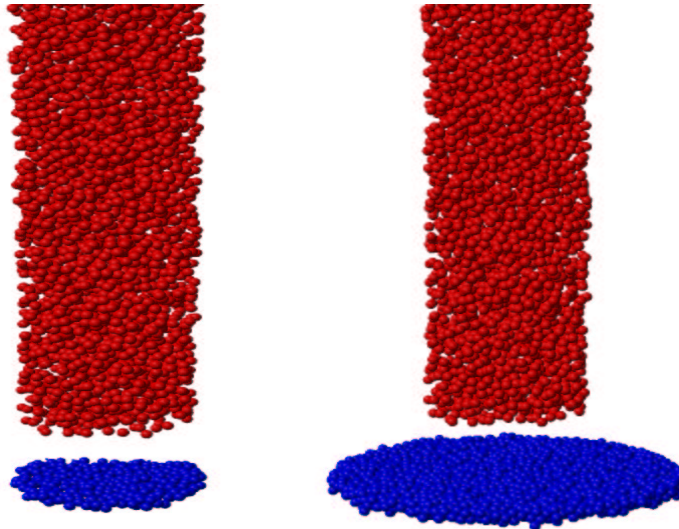
- Loose random packing generated by J Cesarano (Sandia)
- Reducing particle friction increases particle contact
 - leading to denser, more ordered structures

Granular Packing

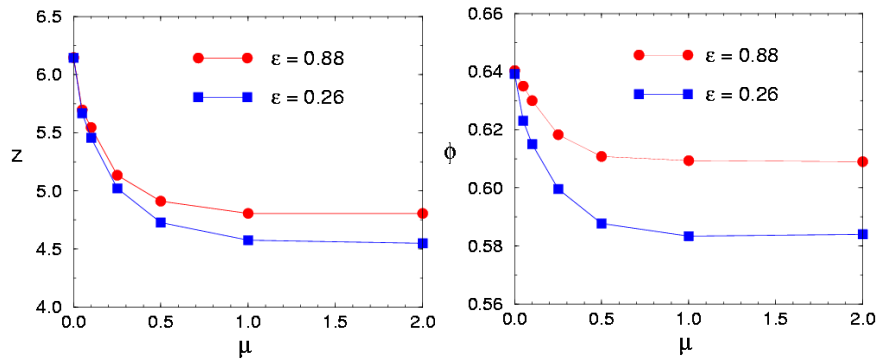
- Nature of granular packing depends strongly on its history
- Coordination number for a stable packing:
 - $z_n=6$ for frictionless spheres
 - $z_f=4$ for frictional spheres
 - packings with $z_n=6$ or $z_f=4$ are *isostatic*
- We studied the packing of granular materials which have settled under the influence of gravity - poured into a container
 - dependence on hardness k_n
 - coefficient of friction μ



Pouring in Presence of Walls



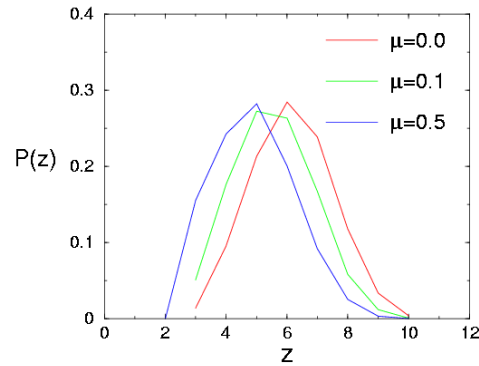
Effect of Friction on Packing



$k_n = 2 \times 10^5 \text{ mg/d}$

- Coordination z and density ϕ decrease smoothly as coefficient of friction μ increase
- Similar results obtained on cessation of flow on inclined plane

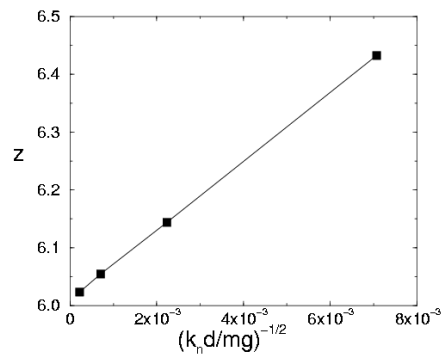
Distribution of Coordination Numbers



- Distribution shifts to lower values of z and μ increases

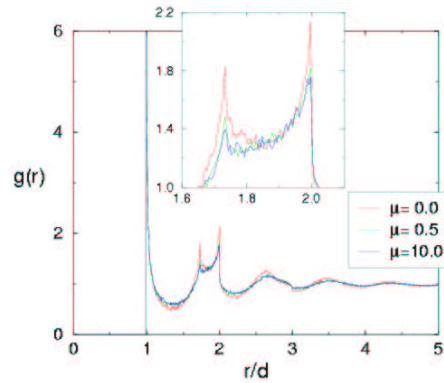
Packing of Frictionless Spheres

Effect of hardness on local coordination



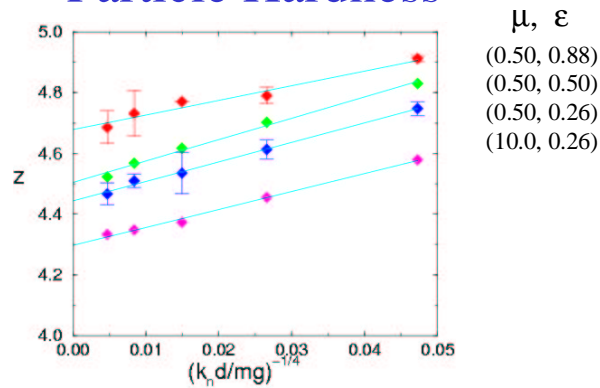
- $z=6$ in hard sphere limit
- Frictionless hard sphere packings are *isostatic*

Radial Distribution Function



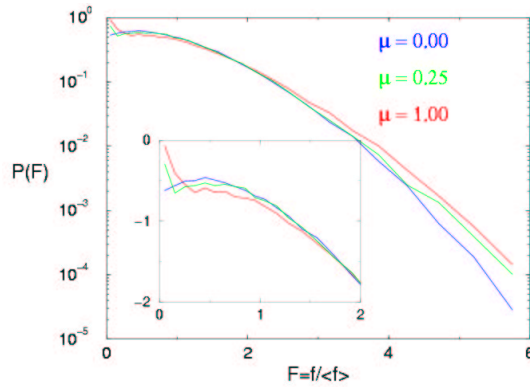
- Friction as small effect on overall pair correlations
- As μ increases, secondary peaks in $g(r)$ diminish

Frictional Spheres - Effect of Particle Hardness



- Hard sphere limit packings are hyperstatic, $z_f > 4$
- Further crossover at extreme stiffness cannot be ruled out
- Stiffest spheres experience strains $\delta/d < 10^{-8}$

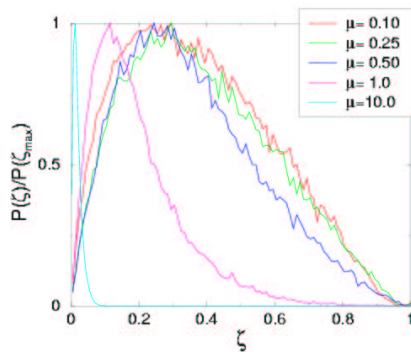
Force Distributions



- No Friction - $P(F)$ has a maximum at $f/\langle f \rangle \sim 0.5$
- Friction - peak occurs at small f and grows as μ increases
 - tail shifts to right as μ increases

Plastic Contacts

- Contacts for which $F_t = \mu F_n$ are plastic
 - Isostaticity condition would need to be modified if there are a finite fraction of plastic contacts



- All contacts in the static packings are below their frictional threshold

$$\zeta = F_t / \mu F_n$$

Summary

- Efficient molecular dynamics algorithm has been developed to study large systems for long times
- For gravity-driven flow, density is uniform and shear stress satisfies simple scaling result
- Jamming transition at the angle of repose has features in common with regular glass transitions
- Packing of frictionless spheres is *isostatic* but frictional spheres are not and strongly dependent on preparation
- Current/Future simulations will study:
 - Effect of side walls and complex geometries
 - Flow in silos and hoppers
 - Slurries