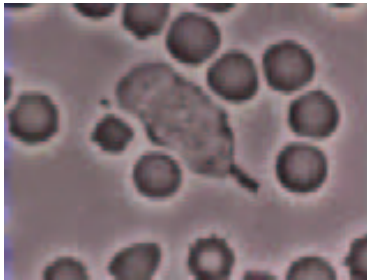




# Mechanical Properties of Filament/Motor Mixtures



David Rodgers '50s

**Tanniemola B Liverpool**  
**Blackett Laboratory, Imperial College, London**



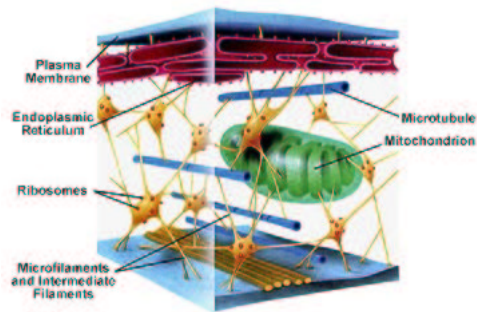
## Plan

- 1) Cell Movement and Mechanics
  - a) The Cell Cytoskeleton
  - b) Filaments and Molecular Motors
- 2) Semiflexible Polymers
- 3) Rheology of Semiflexible polymers
- 4) Motile Polymers
  - a) Active cross-links
  - b) Active forces
- 5) Conclusions and outlook



## Inside the Cell

- The Cell Cytoskeleton



Prentice Hall



## Cell Movement

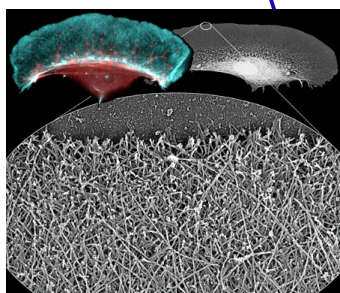
- Actin cytoskeleton - retrograde flow

QuickTime™ and a  
None decompressor  
are needed to see this picture.



## Cell Movement

- Cell Fragment (Keratocyte)



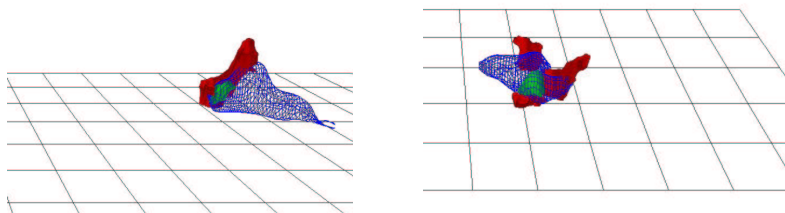
QuickTime™ and a  
None decompressor  
are needed to see this picture.

Svitkina et al, '99




## Cell Movement

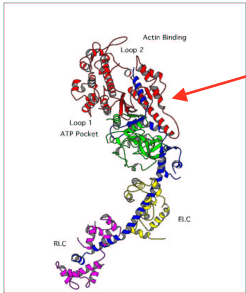
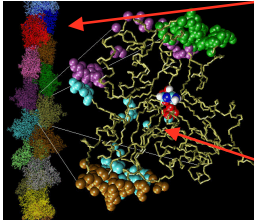
Dictostylium with/without Myosin 1B




Titus Lab (U Minnesota)

 **The Players**

- Myosin
- F-actin (polar)
- G-actin

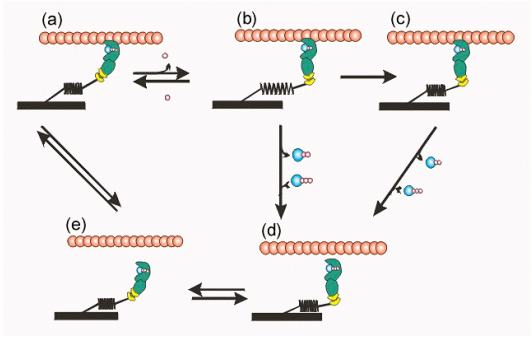



 **Acto-myosin molecular motor**

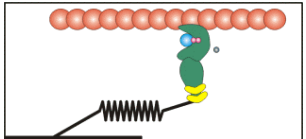
- F-actin and Myosin use Adenosine TriPhosphate (ATP) to turn chemical energy into mechanical work

Muscle !

Rigor



**Far from equilibrium**





## In vitro experiments

- Mechanical experiments on purified cytoskeletal filamentous proteins (F-actin) - **early '90s**  
Janmey, Sackmann, Schmidt ....
- Actin Filaments + different types of Myosin + ATP-  
**last couple of years**  
Sackmann, Käs, Amblard ....
- THEORY?



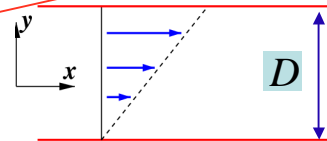
## Linear Rheology

- Apply **small** shear strain and measure shear stress

$$\sigma_{xy}(t) = \int_{-\infty}^t dt' G(t-t') \dot{\gamma}_{xy}(t')$$

- Shear Modulus

$$\dot{\gamma}_{xy} = V/D$$



- Frequency dependent modulus

$$G^*(\omega) = i\omega \int dt G(t) e^{i\omega t} = G(\omega) + iG''(\omega)$$

Storage modulus  
(elastic)

Loss modulus  
(viscous)



## Questions/Goals

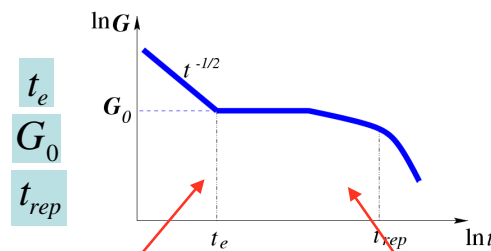
- What happens to the **viscoelasticity** of an F-actin solution due to the presence of Myosin II/ S1 Myosin and ATP?
- Develop a microscopic theory which can explain the **viscoelastic** response of F-actin solutions.
- Compare in vitro mixture of Actin/Myosin/ATP with just Actin
- (Lots of unjustified approximations and assumptions)



## Rheology of Polymers


- Entangled **flexible** polymer solutions are **viscoelastic**

Entanglement time  
 Plateau modulus  
 Reptation time



‘Theory’: Free chains move by ‘reptation’

Tube model: deGennes; Doi/Edwards

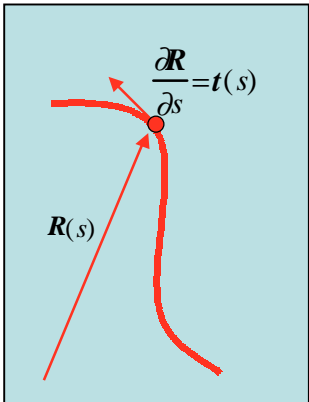



## Semiflexible Polymers

- Wormlike Chain (WLC)  
Bending Energy

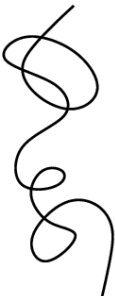
$$H_{wlc}[\mathbf{R}(s)] = \frac{A}{2} \int ds \left( \frac{\partial^2 \mathbf{R}}{\partial s^2} \right)^2$$

- Inextensible  $\left( \frac{\partial \mathbf{R}}{\partial s} \right)^2 = 1$
- Tangent correlation function  $\langle \mathbf{t}(s) \cdot \mathbf{t}(0) \rangle = \exp(-s/L_p)$
- Persistence length  $L_p = \frac{A}{k_B T}$



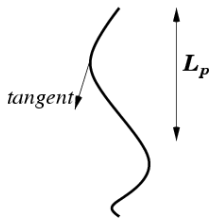


## Persistence Length




Coil

$L \gg L_p$




Semiflexible

$L \approx L_p$



Rod

$L \ll L_p$




## Semiflexible Polymer Dynamics

Viscous Friction   Shear   Bending Elasticity   ‘Tension’   Thermal Active

$$\zeta \cdot \frac{\partial}{\partial t} \mathbf{R}(s,t) - \zeta \cdot \mathbf{Y} \cdot \mathbf{R} = -A \frac{\partial^4 \mathbf{R}}{\partial s^4} + \frac{\partial}{\partial s} \left( \Lambda(s,t) \frac{\partial \mathbf{R}}{\partial s} \right) + f(s,t) + f_{act}(s,t)$$

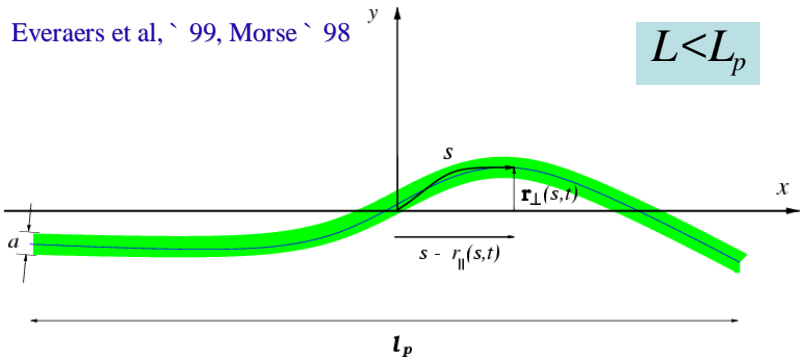
$$\left( \frac{\partial}{\partial s} \mathbf{R}(s,t) \right)^2 = 1 \Rightarrow \Lambda(s,t)$$

- Dynamics with constraints



## Anisotropic Dynamics

Everaers et al, '99, Morse '98



$L < L_p$

- Transverse motion (Bending)  $\mathbf{r}_\perp(s,t)$
- Longitudinal motion (Inextensibility)  $\mathbf{r}_\parallel(s,t)$





## Anisotropic Dynamics

Everaers et al, '99, Morse '98

$$\ell_{\perp}(t) \approx (t L_p k_B T / \zeta)^{1/4} \quad \text{Transverse relaxation length}$$

$$\ell_{\parallel}(t) \approx (t L_p^5 k_B T / \zeta)^{1/8} \quad \text{Longitudinal relaxation length (friction)}$$

$$\partial_t \mathbf{r}_{\perp}(s, t) = \frac{1}{\zeta_{\perp}} [-A \partial_s^4 \mathbf{r}_{\perp} + \partial_s (\Lambda(s, t) \partial_s \mathbf{r}_{\perp})] + \mathbf{f}_{\perp}(s, t)$$

$$\partial_t r_{\parallel}(s, t) = \frac{1}{\zeta_{\parallel}} [-A \partial_s^4 r_{\parallel} - \partial_s \Lambda] + f_{\parallel}(s, t)$$

$$\partial_s r_{\parallel} = \frac{1}{2} |\partial_s \mathbf{r}_{\perp}|^2 + \dots \quad \zeta_{\perp} = 2 \zeta_{\parallel} = 4 \pi \eta / \text{Log}(l/a)$$

TBL, Maggs, *Macrom.* **34**, 6064, 2001



## Self consistent dynamics

- Transverse fluctuations

$$\mathbf{r}_{\perp}(q, \omega) = \int ds d\mathbf{e}^{i\alpha s + i q s} \mathbf{r}_{\perp}(s, t) \approx \frac{\mathbf{f}_{\perp}(q, \omega) + \int_{k, \Omega} q k \Lambda(q - k, \omega - \Omega) \mathbf{r}_{\perp}(k, \Omega)}{i\omega + \alpha q^4}$$


- Inextensibility

$$iq(r_{\parallel}(q, \omega) - r_{\parallel}^{eq}(q, \omega)) = K(q, \omega) \Lambda(q, \omega)$$

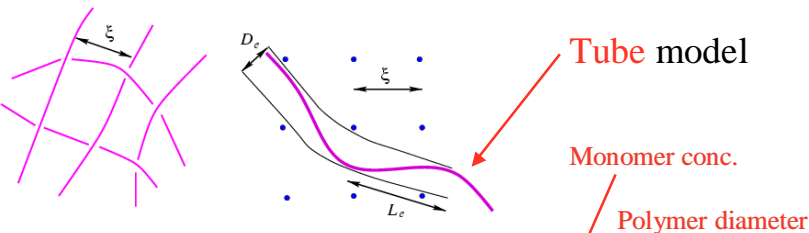
$$K(q, \omega) = 2^{-3/4} k_B T A^{-5/4} (i\omega \zeta_{\perp})^{-3/4} f(q^4 / \omega)$$

- Longitudinal fluctuations

$$r_{\parallel}(q, \omega) - r_{\parallel}^{eq}(q, \omega) = \frac{f_{\parallel}(q, \omega)}{i\omega + K(q, \omega) q^2}$$



## Tightly Entangled Polymers



- Mesh-size
- Entanglement length
- Tube diameter
- Monodisperse  $L$

$$\xi = 1 / \sqrt{\rho_a a} \ll L_p$$


$$L_e \approx L_p (\xi / L_p)^{4/5}$$

$$D_e \approx L_p (\xi / L_p)^{6/5}$$

Monomer conc.

Polymer diameter

Semenov/Odijk




## Stress Tensor

- Kramers-Kirkwood formula for stress in fluctuating ‘beads’

$$\sigma_{ij}(t) = -\frac{\rho}{L} \int_0^L ds \langle F_i(s,t) R_j(s,t) \rangle \approx \sum_{n=1}^4 \sigma_{ij}^n$$

$\sigma_{ij}^1(t) = u_i u_j \frac{\rho}{\ell} \int_0^\ell ds \langle \Lambda(s,t) \rangle$	Tension stress
$\sigma_{ij}^2(t) = A \frac{\rho}{\ell} \int_0^\ell ds \langle r_{\perp i}(s,t) \partial_s^4 r_{\perp j}(s,t) \rangle$	Curvature stress
$\sigma_{ij}^3(t) = u_i u_j \frac{\rho}{\ell} \int_0^\ell ds \langle \partial_s r_{\parallel i}(s,t) \Lambda(s,t) \rangle$	Longitudinal stress
$\sigma_{ij}^4(t) = k_B T \frac{\rho}{L} \left\langle u_i u_j - \frac{1}{3} \delta_{ij} \right\rangle$	Orientational stress



## Shear modulus

- Linear response

$$G^1(t) \approx \frac{\xi^{-2} k_B T L_p^2}{(t k_B T L_p / \zeta_{\perp})^{3/4}}$$

Tension

$$G^2(t) \approx \frac{\xi^{-2} k_B T}{(t k_B T L_p / \zeta_{\perp})^{1/4}}$$


Curvature

$$G^4(t) = k_B T \frac{3\rho}{5L} \exp(-6t k_B T / \zeta_u); L < L_p$$

Orientation

$$G^3(t) \approx \frac{\xi^{-2} k_B T}{(t k_B T (2L_p)^5 / \zeta_{\perp})^{1/8}}$$

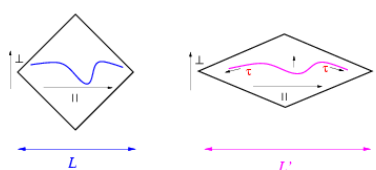
Longitudinal



## Contributions to Stress

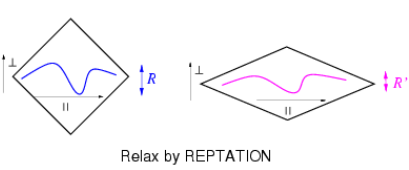
Passive Solutions - High Frequency

Tension (Inextensibility)



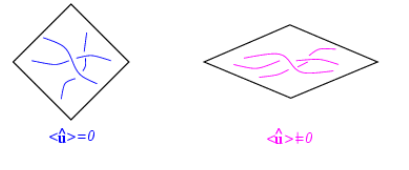
Passive Solutions - Low Frequency

Curvature (Bending)



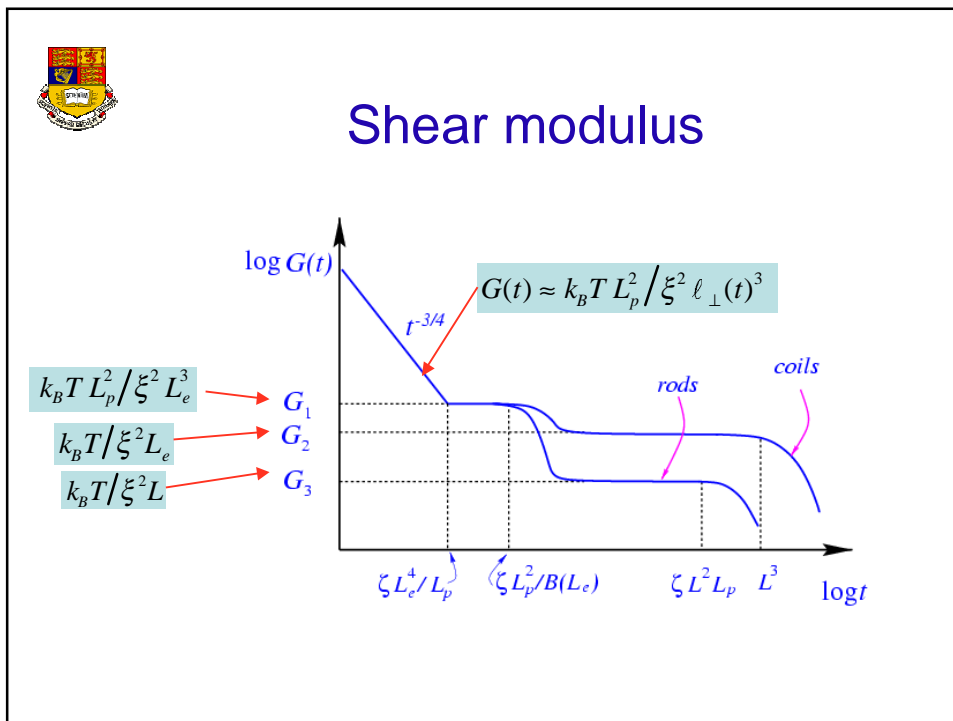
Relax by REPTATION

Orientation



$\langle \hat{u} \rangle = 0$

$\langle \hat{u} \rangle \neq 0$



**Motile Solution-Active X-links**

**ACTIVE** temporary cross-links

**LARGE** longitudinal fluctuations

$k_B T \Rightarrow k_B (T + T_{act})$

**DIRECTED** motion in 'tube'

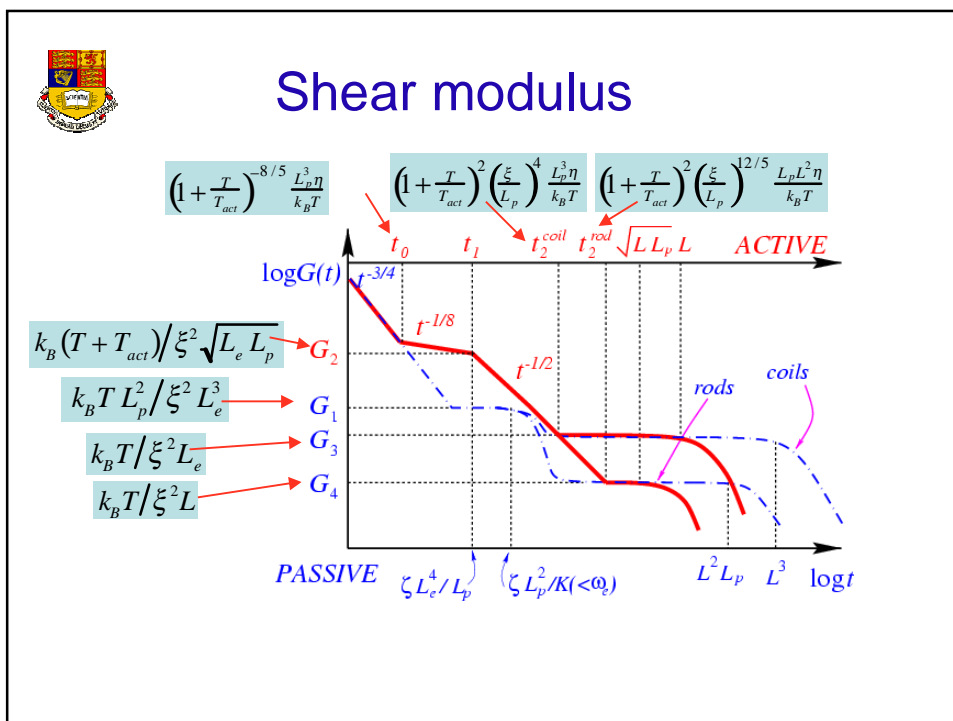
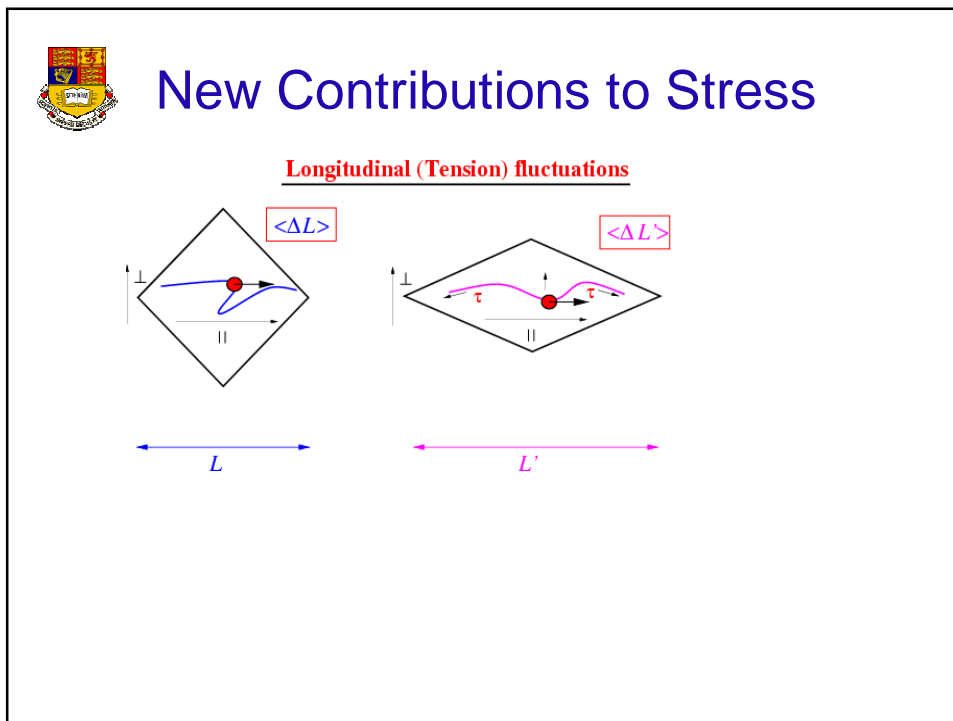
**polar filament!**


$v_m$

QuickTime™ and a Cinepak decompressor are needed to see this picture.

J. Käs' Lab

TBL, Maggs & Ajdari, PRL **86**, 4171, 2001






## Numbers

- Distance between aggregates  $\ell_m \approx 1/\rho_m \xi^2$
- Active temperature  $k_B T_{act} \approx f_0^2 t_s / \zeta \ell_m$
- Tube velocity  $v_m \approx f_0 / \zeta \ell_m$

Motor concentration
Motor cycle time  
Typical Motor force

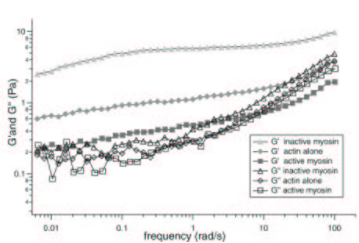
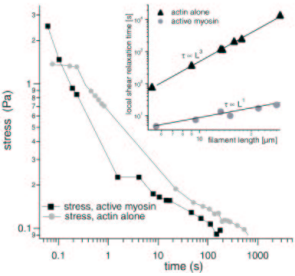
F-actin  $\rho_a = 100 \mu\text{g/ml}$ , Myosin  $\rho_m = 0.1 \mu\text{M}$

$T_{act} / T \approx 100 \Rightarrow t_{rep} (10^4 \text{ s} \Rightarrow 1 \text{ s})$




## Experiments on MII/Actin/ATP

- Longest relaxation time
- Plateau modulus

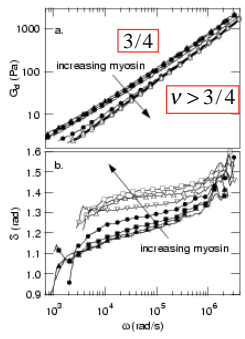



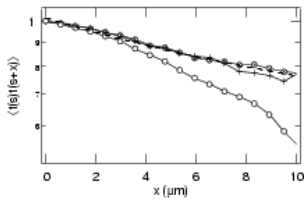
Josef Käs' Lab



## Experiments on S1/Actin/ATP


- Tangent correlations  
- **not WLC!**



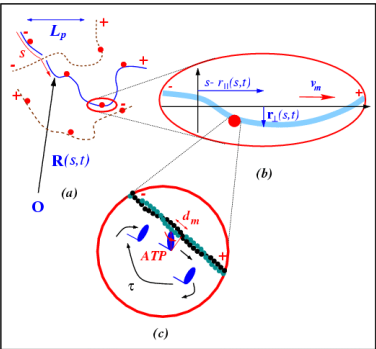


- High freq. shear modulus

Le Goff et al



## Motile Solution-Active Forces



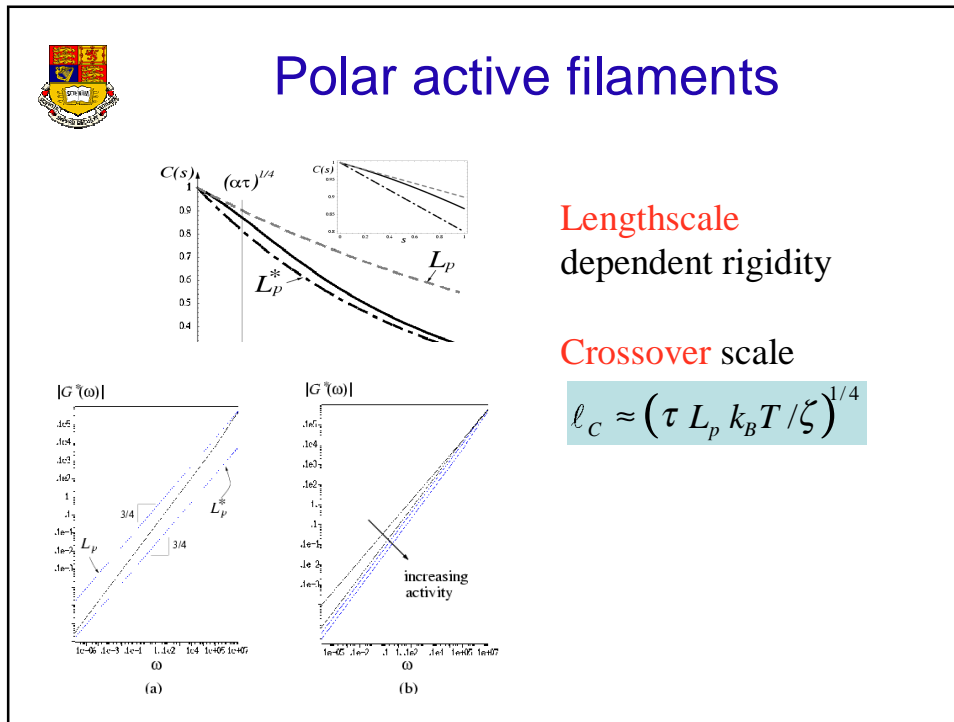
Myosin S1 fragments do not form clusters

**ACTIVE** forces due to myosin interacting with **single** filaments

Time-scale of activity

$\tau$

TBL (preprint) , 2001



- 
- Conclusions**
- F-actin solutions have a rich viscoelastic response over a large range of moduli and time-scales
  - The rheological properties are changed dramatically by myosin activity
    - Non-equilibrium motile solution is **harder** on short timescales and **softer** on longer timescales than the equivalent passive solution
    - Non-equilibrium active filaments have different static and dynamic fluctuations which affects high frequency response





## Acknowledgements

Anthony Maggs, Armand Ajdari  
(ESPCI, Paris)

David Humphrey, Josef Käs  
(UT Austin)

Loic le Goff, Eric Furst , François Amblard  
(Institut Curie, Paris)

The Royal Society