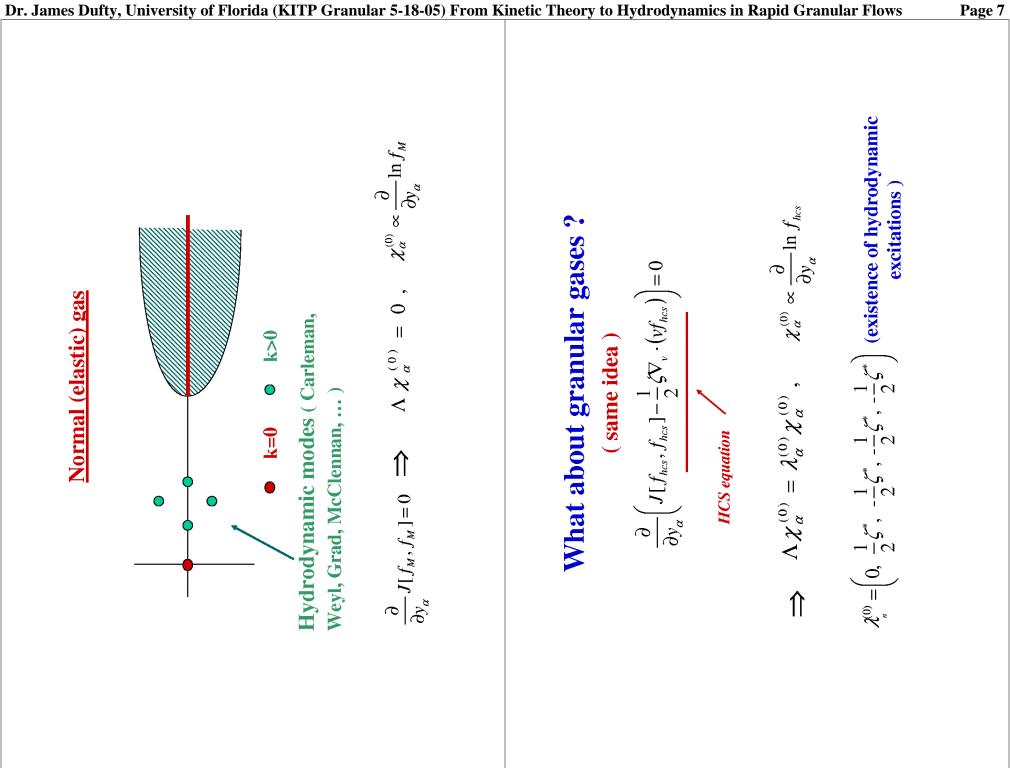
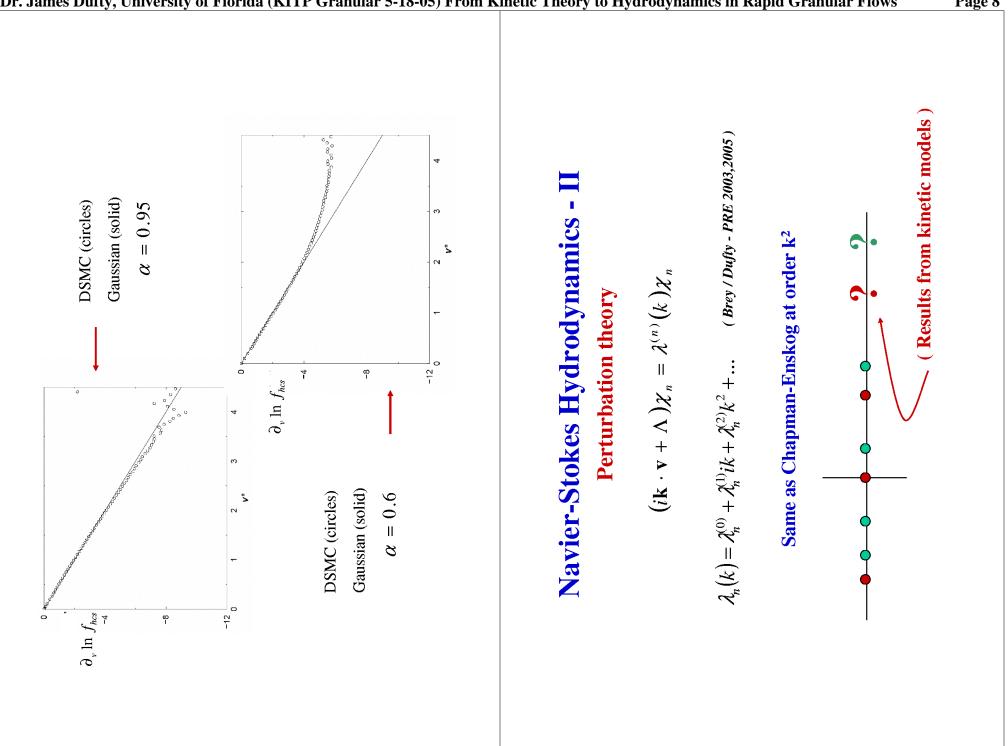
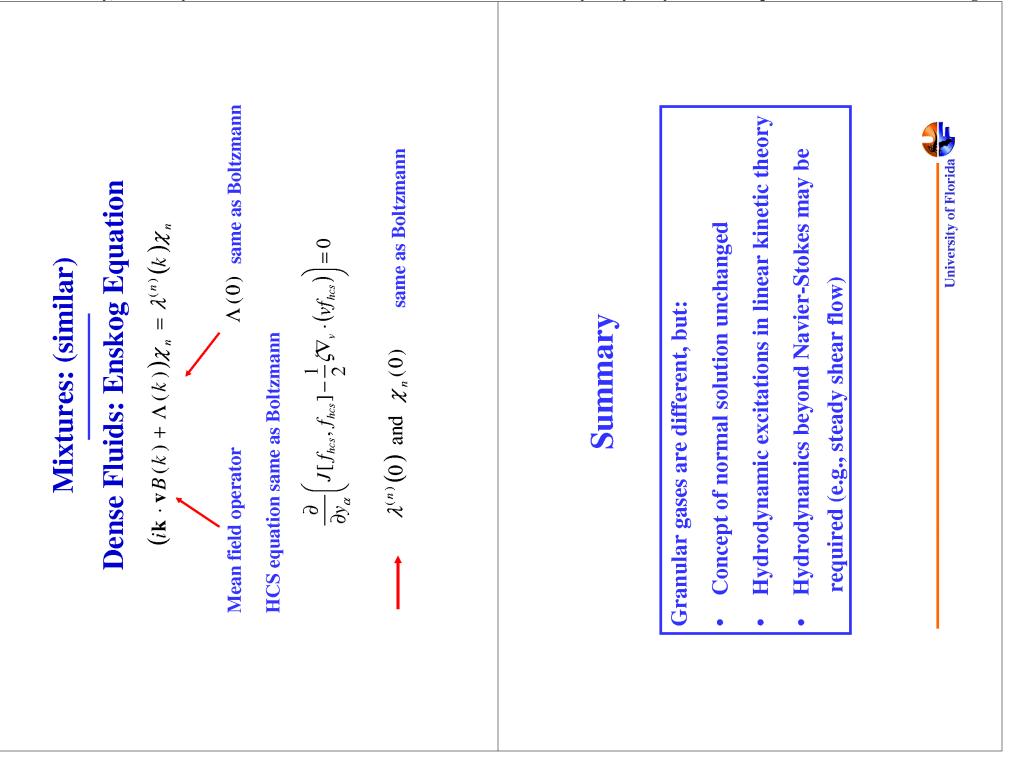


Key concept: rapid relaxation to normal form implies hydrodynamics; same as for normal gases. Navier-Stokes Hydrodynamics - I	Special case: states with <i>small</i> gradients $f = f^{(0)}(\mathbf{v}, \{y(\mathbf{r}, t)\}) \left[1 + X_{\beta}(\mathbf{v}, \{y(\mathbf{r}, t)\}) \nabla_{\beta_{\beta}}(\mathbf{r}, t) + \cdots \right]$ $P_{\beta}(\mathbf{r}, t f) \rightarrow -\eta(T, n, \alpha) \left(\partial_{i}u_{j} + \partial_{j}u_{i} - \frac{2}{3} \delta_{ij} \nabla \cdot \mathbf{u} \right)$ $\mathbf{q}(\mathbf{r}, t f) \rightarrow -\kappa(T, n, \alpha) \nabla T - \mu(T, n, \alpha) \nabla n$ Explicit form of solution: technical details (Chapman-Enskog)	Another perspective on hydrodynamics spectrum of excitations ("hydrodynamic modes")	

$$f(\mathbf{r}, \mathbf{v}, t = 0) = f_{nn}(v, 0)\mathbf{l} + \phi_n(\mathbf{v})\hat{\mathbf{S}}\gamma_n(r, 0)\mathbf{l}$$
$$f(\mathbf{r}, \mathbf{v}, t) = f_{nn}(v, t)\mathbf{l} + \phi_n(\mathbf{v}, t, t)\mathbf{l}$$
$$f(\mathbf{r}, \mathbf{v}, t) = f_{nn}(v, t, t)\mathbf{l} + \phi(\mathbf{r}, \mathbf{v}, t, t)\mathbf{l}$$
$$\mathbf{Linearized Boltzmann equation (dimensionless, Fourier transform)$$
$$(\partial_i + i\mathbf{k} \cdot \mathbf{v} + \Lambda)\phi = 0$$
$$\Delta \mathbf{x} = -J[f_{nn}^{in}, f_{nn}^{in}\mathbf{x}] - J[f_{nn}^{in}, f_{nn}^{in}\mathbf{x}] + \frac{1}{2}\hat{\mathbf{S}}^{in}\mathbf{v}_{i}(v, f_{nn}^{in}, \mathbf{x})$$
$$\mathbf{S}_{in}(\mathbf{r}, t) = \int d\mathbf{v}\psi_n(\mathbf{v}, t) - f_{nn}(\mathbf{v}, t))$$
$$(\hat{\mathbf{S}}_{in}(\mathbf{k}, s) = \int d\mathbf{v}\psi_n(\mathbf{k}, s)\phi_n^{in}\phi_n^{in}(\mathbf{k}, s)\phi_n^{in}(\mathbf{k}, s)\phi_n^{in}($$







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Informal Discussion – Kinetic Theory	(today, 1:30)	Some possible topics:	Validity and context of the Boltzmann equation	Validity and context of the Enskog equation	Representation of binary collisions	Representation of boundary conditions			