Bit Threads & Holographic Entanglement

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1 How should one think about the minimal surface?

In semiclassical gravity, surface areas are related to entropies

Bekenstein-Hawking '74:

For black hole,

$$S = \frac{1}{4G_{\rm N}} \operatorname{area}(\operatorname{horizon})$$

Why?

Possible answer:

Microstate bits "live" on horizon, 1 bit/4 Planck areas





Ryu-Takayanagi '06: For region in holographic field theory (classical Einstein gravity, static state)

$$S(A) = \frac{1}{4G_{\rm N}} \operatorname{area}(m(A))$$

 $\boldsymbol{m}(\boldsymbol{A}) = \mathsf{bulk}$ minimal surface homologous to \boldsymbol{A}

Bulk geometry packages entanglement entropies in a simple & beautiful way

Do microstate bits of A "live" on m(A)?

Unlike horizon, m(A) is not a special place; by choosing A, we can put m(A) almost anywhere Puzzles:

• Under continuous changes in boundary region, minimal surface can jump Example: Union of separated regions *A*, *B*



• Information-theoretic quantities are given by differences of areas of surfaces passing through different parts of bulk:

Conditional entropy:	H(A B) = S(AB) - S(B)
Mutual information:	I(A:B) = S(A) + S(B) - S(AB)
Conditional mutual information:	I(A:B C) = S(AB) + S(BC) - S(ABC) - S(C)

What do differences between areas of surfaces, passing through different parts of bulk, have to do with these measures of information?

• RT obeys strong subadditivity [Headrick-Takayanagi '07]

$$I(A:BC) \ge I(A:C)$$

What does proof (by cutting & gluing minimal surfaces) have to do with information-theoretic meaning of SSA (monotonicity of correlations)?

To try to answer these questions, I will present a new formulation of RT

- Does not refer to minimal surfaces (demoted to a calculational device)
- Suggests a new way to think about the holographic principle & about the connection between spacetime geometry and information

2 Reformulation of RT

Consider a Riemannian manifold with boundary

Flow: vector field v obeying $\nabla \cdot v = 0$, $|v| \le 1$ Think of flow as a set of oriented threads (flow lines) beginning & ending on boundary, transverse density $= |v| \le 1$

Let \boldsymbol{A} be a subset of boundary



Max flow-min cut theorem (originally on graphs; Riemannian version: [Federer '74, Strang '83, Nozawa '90]):

$$\max_v \int_A v = \min_{m \sim A} \operatorname{area}(m)$$

(Headrick-Hubeny '17 contains exposition of proof: Finding max flow is convex program, related by Lagrangian duality & convex relaxation to finding minimal surface



Also prove a min flow-max cut theorem for Lorentzian spacetimes, relating maximal-volume slices to minimal-flux flows, where a flow is a future-directed timelike vector field with norm ≥ 1)

Note that max flow is highly non-unique (except on m(A), where v = unit normal)



Threads can end on A^c or horizon

Each thread has cross section of 4 Planck areas & is identified with 1 (independent) bit of A

Automatically incorporates homology & global minimization conditions of RT



Threads are "floppy": lots of freedom to move them around in bulk & move where they attach to ${\cal A}$

Also lots of room near boundary to add extra threads that begin & end on A (don't contribute to S(A))

Role of minimal surface: bottleneck, where threads are maximally packed, hence counted by area

Holographic principle: entropy \propto area because bits are carried by one-dimensional objects

Bekenstein-Hawking:



3 Threads & information

Now we address conceptual puzzles with RT raised before

First: even when m(A) jumps, v(A) changes continuously with A

Next, consider two regions A, B

We can maximize flux through A or B, not in general both But we can always maximize through A and AB (nesting property) Call such a flow v(A, B)



Example 1: S(A) = S(B) = 2, $S(AB) = 3 \Rightarrow I(A:B) = 1$, H(A|B) = 1



Lesson 1:

- Threads that are stuck on A represent bits unique to A
- Threads that can be moved between A & B represent correlated pairs of bits

Example 2: S(A) = S(B) = 2, $S(AB) = 1 \Rightarrow I(A:B) = 3$, $H(A|B) = -1 \Rightarrow$ entanglement

One thread leaving A must go to B, and vice versa



Lesson 2:

• Threads that connect A & B (switching orientation) represent entangled pairs of qubits



Apply lessons to single region:

- freedom to move beginning points around reflects correlations within ${\cal A}$
- freedom to add threads that begin & end on ${\cal A}$ reflects entanglement within ${\cal A}$

Equations:

Conditional entropy:

$$H(A|B) = S(AB) - S(B)$$

$$= \int_{AB} v(AB) - \int_{B} v(B)$$

$$= \int_{AB} v(B, A) - \int_{B} v(B, A)$$

$$= \int_{A} v(B, A)$$

$$= \min \text{ flux on } A \text{ (maximizing on } AB)$$
ion:
$$I(A:B) = S(A) - H(A|B)$$

$$= \int v(A, B) - \int v(B, A)$$

Mutual information: I(A:B) = S(A) - H(A|B) $= \int_{A} v(A,B) - \int_{A} v(B,A)$ $= \max - \min \text{ flux on } A \text{ (maximizing on } AB)$

= flux movable between A and B (maximizing on AB)

Subadditivity is clear

Max flow can be defined even when flux is infinite: flow that cannot be augmented Regulator-free computation of mutual information:

$$I(A:B) = \int_A \left(v(A,B) - v(B,A) \right)$$

Define

$$v(A:B) = \frac{1}{2}(v(A,B) - v(B,A))$$

Flow from A to B through homology region r(AB) w/flux $\frac{1}{2}I(A:B)$ Implies

$$\frac{1}{2}I(A:B) \leq \text{cross section of } r(AB)$$



(Takayanagi-Umemoto '17, Nguyen et al. '17 use this to interpret cross section as entanglement of purification)

Conditional mutual information:

$$I(A:B|C) = H(A|C) - H(A|BC)$$

$$A \qquad C \qquad B \qquad = \int_{A} v(C,A,B) - \int_{A} v(C,B,A)$$

$$= \max - \min \text{ flux on } A \text{ (maximizing on } C \& ABC)$$

$$= \text{ flux movable between } A \& B \text{ (maximizing on } C \& ABC)$$

$$= (\text{flux movable between } A \& BC) - (\text{movable between } A \& C)$$

$$= I(A:BC) - I(A:C)$$

Strong subadditivity $I(A:B|C) \ge 0$ is clear

In each case, clear connection to information-theoretic meaning of quantity/property

4 Monogamy of mutual information

Work in progress with Shawn Cui, Patrick Hayden, Temple He, Bogdan Stoica, Michael Walter

Given a 3-party state ρ_{ABC} , define *tripartite information*:

$$-I_3(A:B:C) := S(AB) + S(BC) + S(AC) - S(A) - S(B) - S(C) - S(ABC)$$

= $I(A:BC) - I(A:B) - I(A:C)$

Cases:

$ ho_{ABC}$	$-I_3(A:B:C)$
pure	0
$ ho_A \otimes ho_{BC}$	0
marginal of higher-party GHZ, e.g. $ \psi angle_{ABCD}=(0000 angle+ 1111 angle)/\sqrt{2}$	< 0
marginal of 4-party perfect tensor (e.g. 4-qutrit code)	> 0

Hayden-Headrick-Maloney '11 used cutting-and-pasting of minimal surfaces to show that RT implies

 $-I_3(A:B:C) \ge 0$

"Monogamy of mutual information" (MMI)

Suggests that perfect-tensor entanglement dominates over GHZ-type entanglement in holographic states (also true in random stabilizer tensor networks [Nezami-Walter '16])

Can prove MMI using flows

Use *multi-commodity flows* to obtain a geometric decomposition of the bulk into parts representing different kinds of entanglement

First consider simplest case where AB is pure (no C):

Bulk is "bridge" connecting A and B, capacity = $S(A) = S(B) = \frac{1}{2}I(A:B)$





Bulk can be decomposed into

- A B bridge with capacity $\frac{1}{2}I(A:B)$
- B C bridge with capacity $\frac{1}{2}I(B:C)$
- A C bridge with capacity $\frac{1}{2}I(A:C)$

Now the general case: ABC is mixed; let D = rest of boundary, so ABCD is pure Decomposition of bulk into 7 pieces:

- A B bridge with capacity $\frac{1}{2}I(A:B)$
- A-C bridge with capacity $\frac{1}{2}I(A:C)$
- A D bridge with capacity $\frac{1}{2}I(A:D)$
- B C bridge with capacity $\frac{1}{2}I(B:C)$
- B D bridge with capacity $\frac{1}{2}I(B:D)$
- C D bridge with capacity $\frac{1}{2}I(C:D)$
- 4-way bridge with capacity on each leg $-\frac{1}{2}I_3(A:B:C)$

2-way bridges account for all pairwise MIs; 4-way bridge accounts for all of $-I_3(A:B:C)$

These are the extremal rays of 4-party holographic entropy cone

Question:

Does the state enjoy a similar (approximate) decomposition, into pairwise Bell pairs and 4-party perfect tensors?



5 No time left

5.1 Quantum corrections

Faulkner-Lewkowycz-Maldacena '13:

Quantum (order $G_{\rm N}^0)$ correction to RT is from entanglement of bulk fields

May be reproduced by allowing threads to jump from one point to another

(or tunnel through microscopic wormholes, à la ER = EPR [Maldacena-Susskind '13])

5.2 Covariant bit threads

Work in progress with Veronika Hubeny

A m(A)v(A)



Hubeny-Rangamani-Takayanagi ['07] covariant entanglement entropy formula:

 $S(A) = \operatorname{area}(m(A))$

m(A) = minimal extremal surface homologous to A

Generalization of max flow-min cut theorem to Lorentzian setting:

A *flow* is still a divergenceless vector field vAlso have "clock function" ϕ , with boundary condition

 $\phi = 0 \quad \text{on } J^-(\partial A) \,, \qquad \phi = 1 \quad \text{on } J^+(\partial A)$

Density of threads in rest frame of observer with 4-velocity u is $|v|_u := \sqrt{v^2 + (u \cdot v)^2}$ Density constraint: $|v|_u \le u^\mu \partial_\mu \phi$ for any timelike unit vector uObserver w/proper time τ sees density $\le d\phi/d\tau$

Theorem (assuming NEC, using results of Wall '12 & Headrick-Hubeny-Lawrence-Rangamani '14):

 $\max_{v} \int_{D(A)} v = \operatorname{area}(m(A)) \qquad \qquad D(A) = \text{boundary causal domain of } A$

Finding extremal surface area becomes convex optimization problem

HRT version 2.0:

$$S(A) = \max_{v} \int_{D(A)} v$$

c

To maximize flux, threads seek out $m({\cal A}),$ automatically confining themselves to entanglement wedge

Threads can lie on common Cauchy slice (equivalent to Wall's ['12] maximin by standard max flow-min cut) or spread out in time

