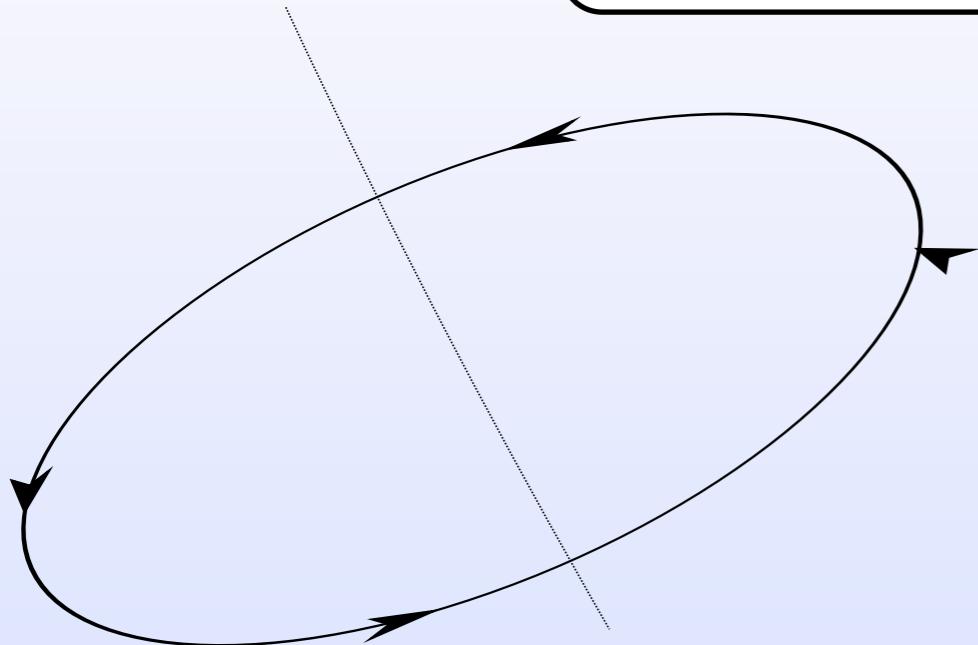


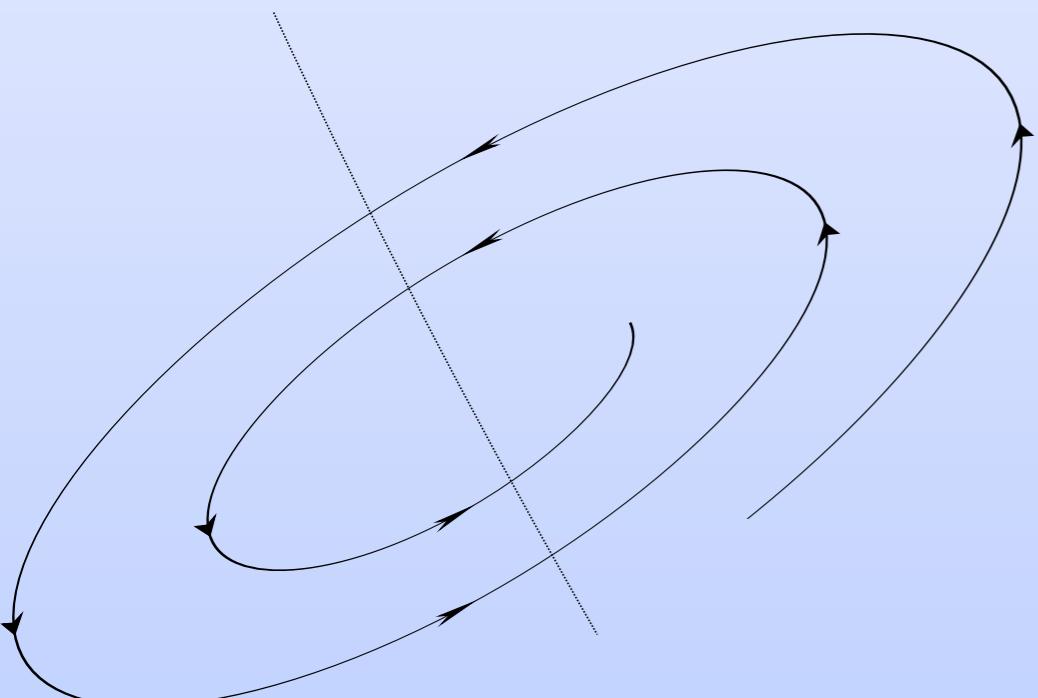
Global Simulations of Magnetised Accretion Disk Turbulence

Ross Parkin & Geoff Bicknell

Rule number one



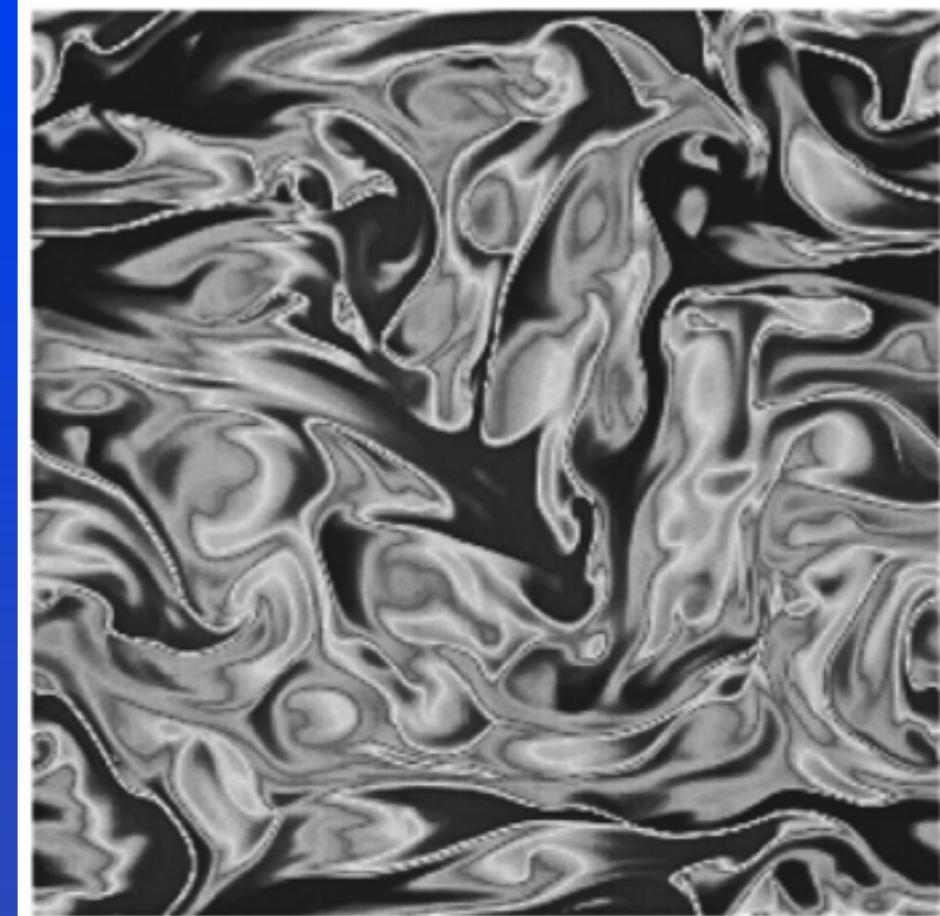
No angular momentum loss
= test particle orbits forever



Angular momentum loss
= test particle falls on to
central object

Magnetorotational turbulence

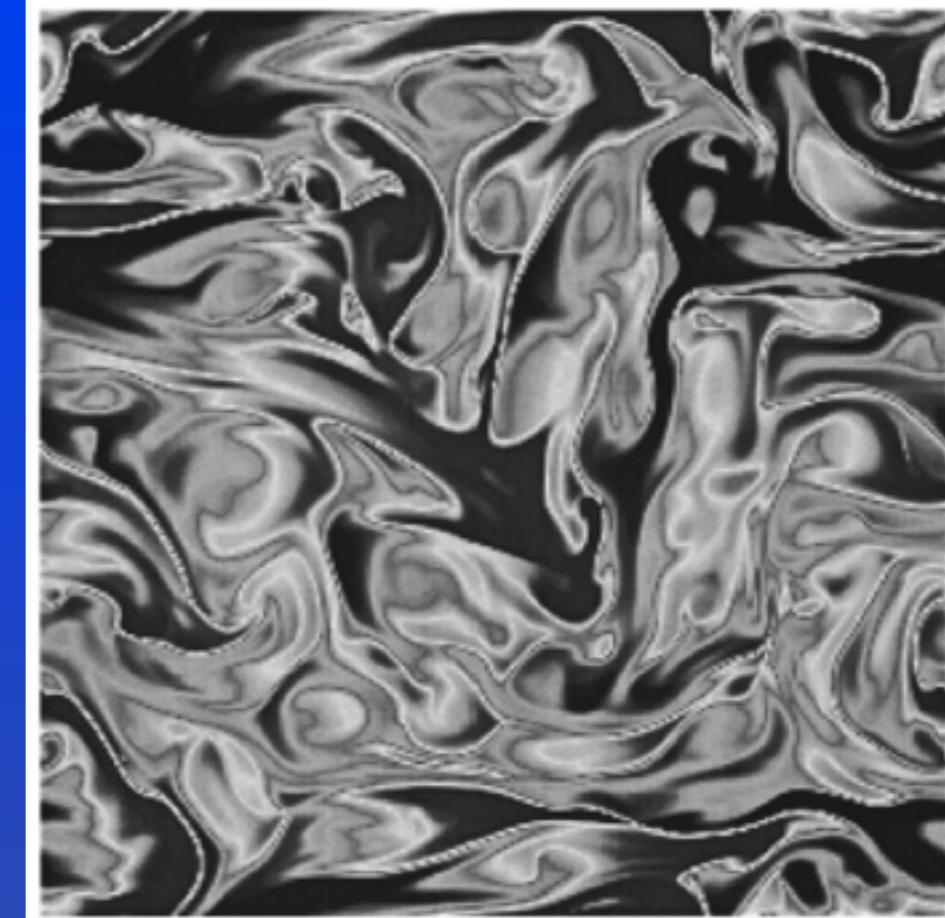
- Angular momentum transport can be facilitated by magnetorotational instability driven turbulence
- Sustained turbulence demonstrated in unstratified shearing boxes (Hawley+ 1995)
- However, stress decreases with increasing resolution in zero-net flux simulations (Fromang & Papaloizou 2007)



Balbus & Hawley (1998)

Magnetorotational turbulence

- Angular momentum transport can be facilitated by magnetorotational instability driven turbulence
- Sustained turbulence demonstrated in unstratified shearing boxes (Hawley+ 1995)
- However, stress decreases with increasing resolution in zero-net flux simulations (Fromang & Papaloizou 2007)



Balbus & Hawley (1998)

$$W_{R\phi} = \rho \delta v_R \delta v_\phi - B_R B_\phi$$



$$\alpha = \frac{W_{R\phi}}{P}$$

Model	Box size	Resolution	Run time (in orbits)	α_{Rey}	α_{Max}	α
FS64	$(H, 2\pi H, H)$	$(64, 200, 64)$	300	1.8×10^{-3}	4.2×10^{-3}	5.9×10^{-3}
STD64	$(H, \pi H, H)$	$(64, 100, 64)$	1000	9.4×10^{-4}	3.2×10^{-3}	4.1×10^{-3}
STD128	$(H, \pi H, H)$	$(128, 200, 128)$	250	5.0×10^{-4}	1.7×10^{-3}	2.2×10^{-3}
STD256	$(H, \pi H, H)$	$(256, 400, 256)$	105	2.4×10^{-4}	8.1×10^{-4}	1.1×10^{-3}

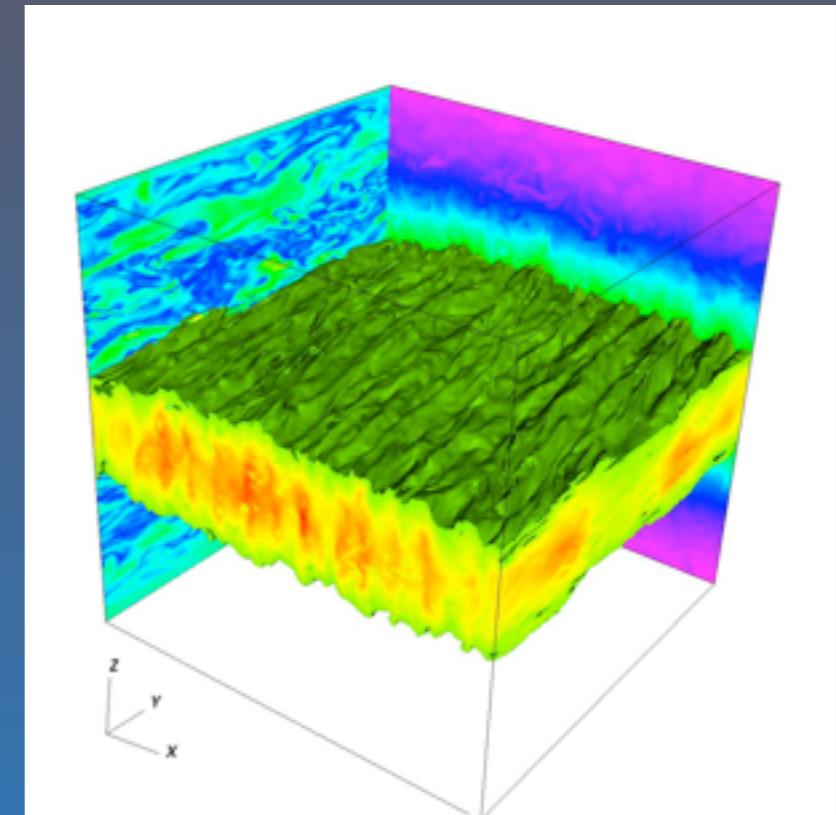


ANU

THE AUSTRALIAN NATIONAL UNIVERSITY

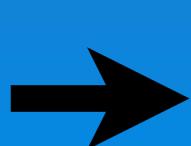
Stratified models show convergence

- Sustained turbulence demonstrated in stratified shearing boxes (e.g. Brandenburg+1995, Stone+1996, Davis+ 2010, Shi+2010, Simon +2011, Oishi & MacLow 2011)
- Results converge with increasing resolution when the vertical component of gravity is included (ie stratification).

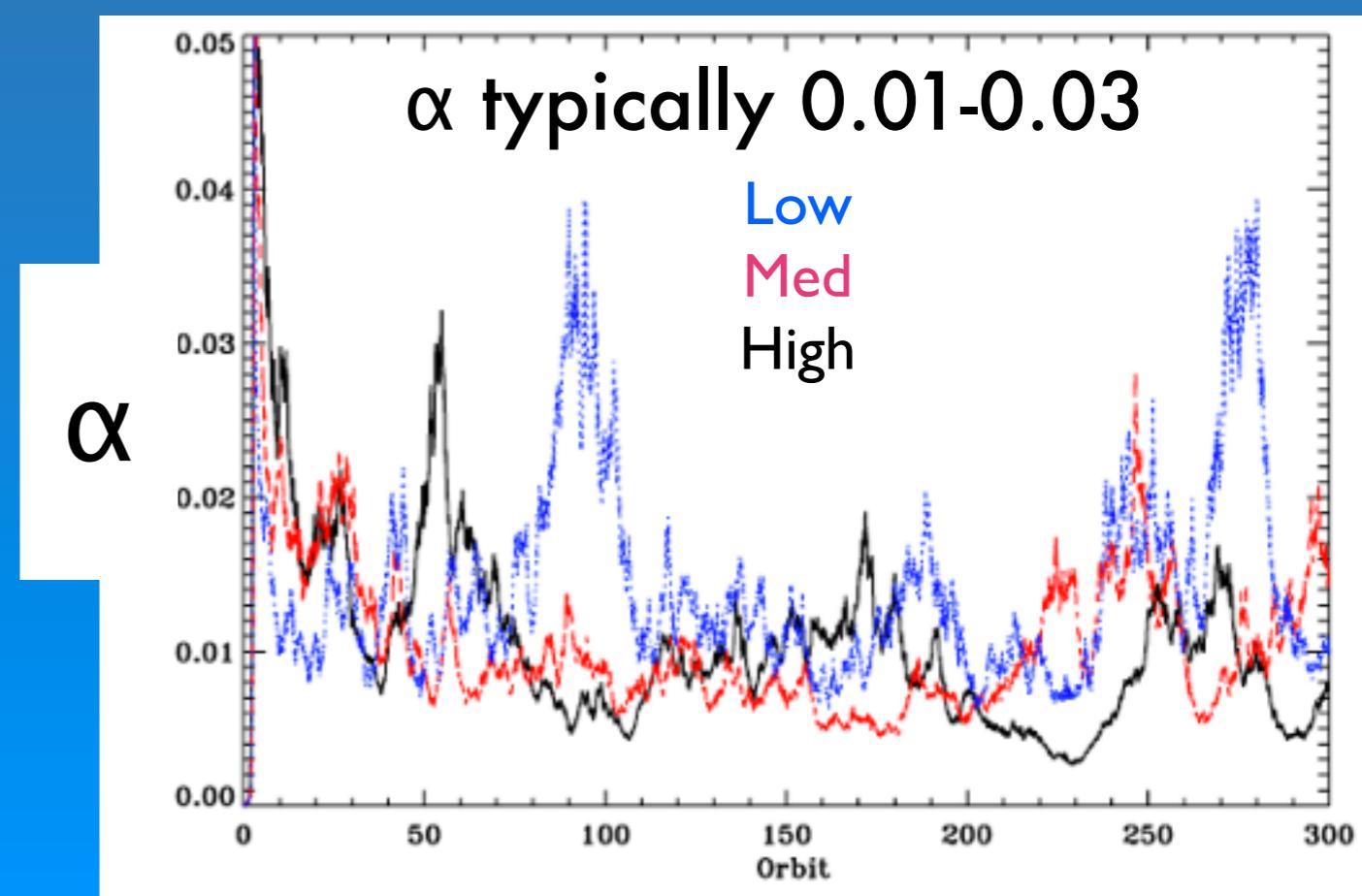


Davis+ (2010)

$$W_{R\phi} = \rho \delta v_R \delta v_\phi - B_R B_\phi$$



$$\alpha = \frac{W_{R\phi}}{P}$$



Main questions

Main questions

- Will global stratified disk models converge?

Main questions

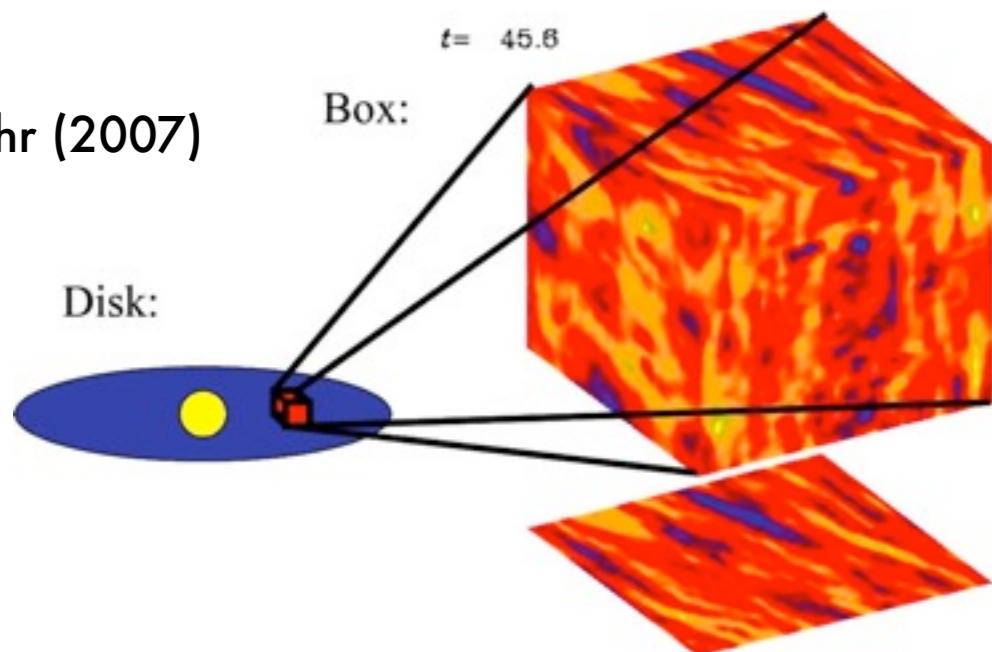
- Will global stratified disk models converge?
- If so, at what resolution, and with what value for the turbulent stresses (α)?

Main questions

- Will global stratified disk models converge?
- If so, at what resolution, and with what value for the turbulent stresses (α)?
- How do global models and shearing-boxes differ in terms of magnetic energy production and large scale field development?

Shearing-box

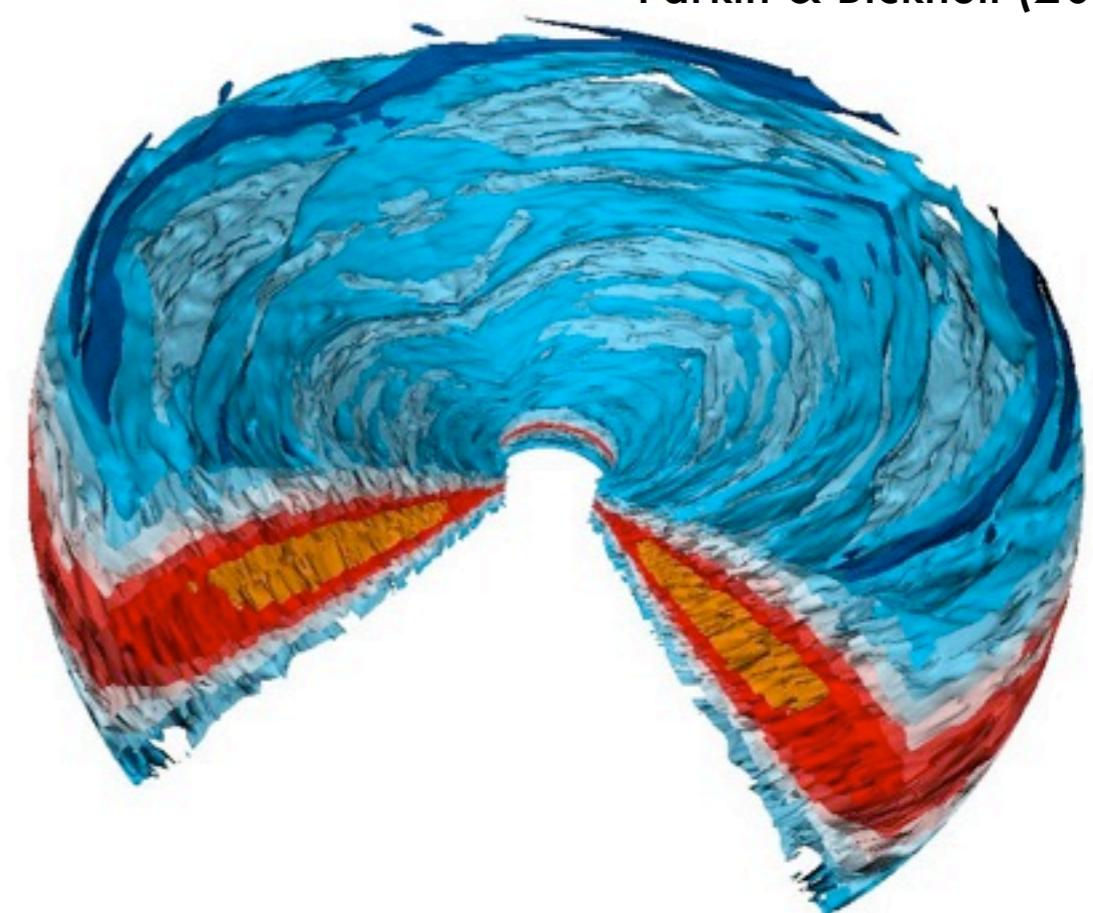
Klahr (2007)



See also: Brandenburg et al. 1995; Stone et al. 1996;
Miller & Stone 2000; Fleming et al. 2000; Brandenburg
2005; Johansen et al. 2009; Gressel 2010; Shi et al. 2010;
Davis et al. 2010; Simon et al. 2011; Guan & Gammie 2011;
Oishi & Mac Low 2011; Simon et al. 2012

Global simulations

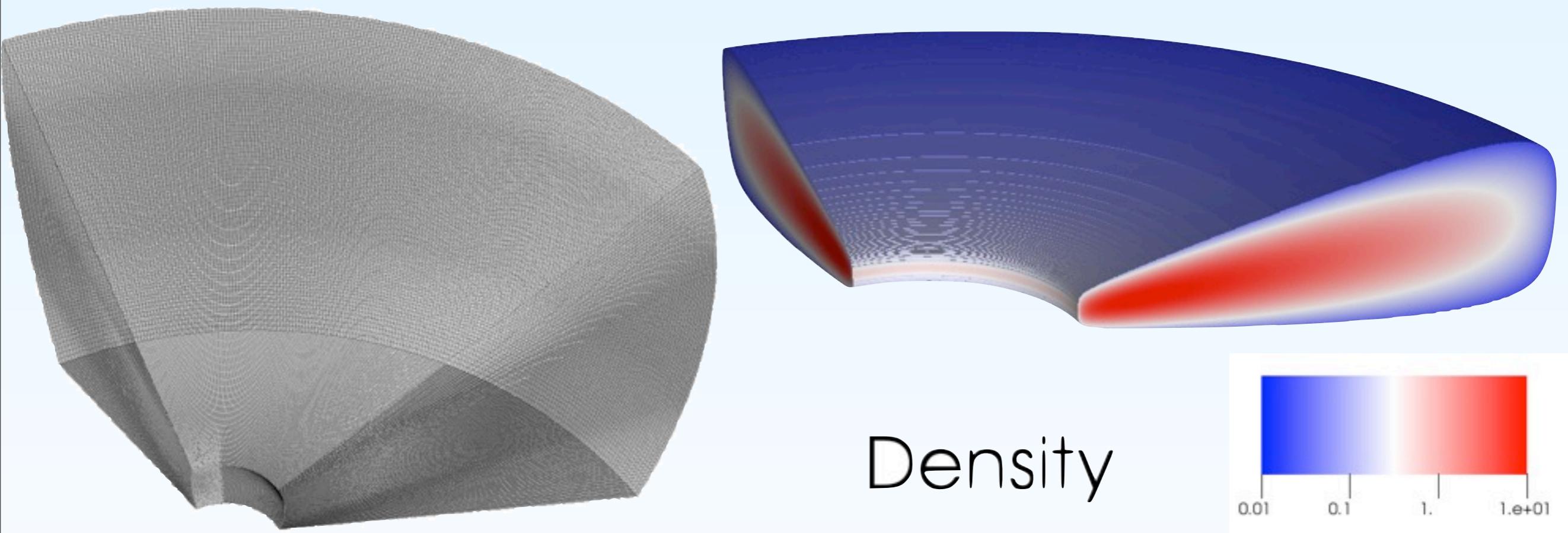
Parkin & Bicknell (2013a,b)

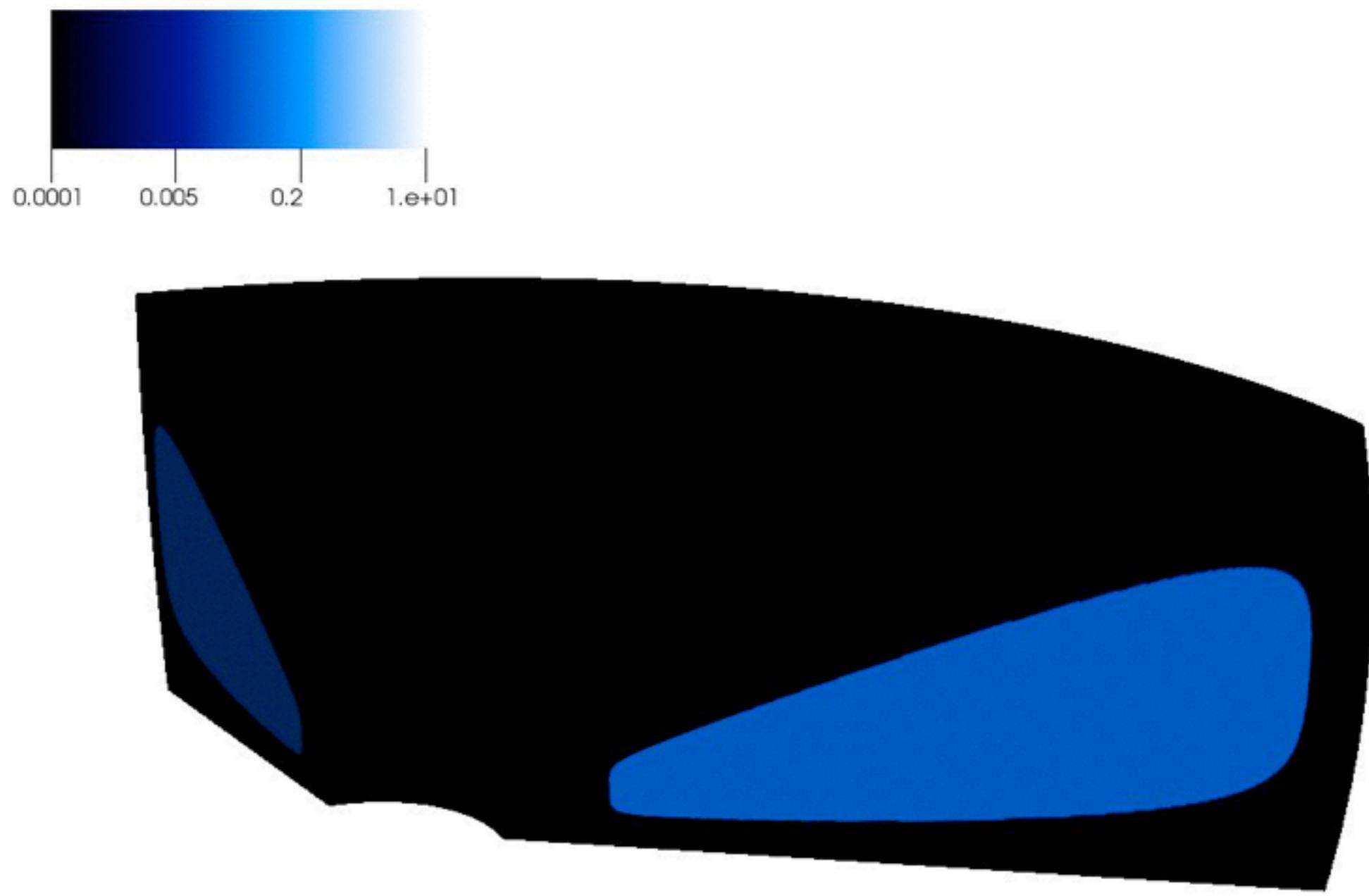


See also: Hawley 2000; Hawley & Krolik 2001; Arlt & Rudiger 2001;
Fromang & Nelson 2006, 2009, Fragile et al. 2007, 2009; Beckwith et al.
2008, 2011; Lyra et al. 2008; Reynolds & Fabian 2008; Sorathia et al. 2010;
O'Neill et al. 2011; Flock et al. 2011, 2012a,b; Noble et al. 2009, 2010, 2011,
Hawley et al. 2011, 2013; McKinney et al. 2012; Dexter et al. 2013

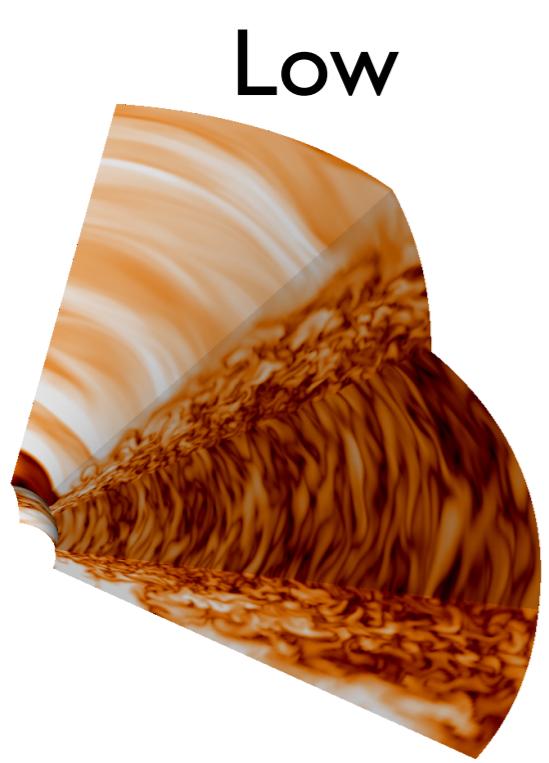
Global Simulations

- Equilibrium magnetized disk with purely toroidal field (Parkin & Bicknell 2013, ApJ, 763, 99)
- No unphysical periodic boundaries
- Performed on a 3D spherical grid using the PLUTO MHD code (Mignone+2007)



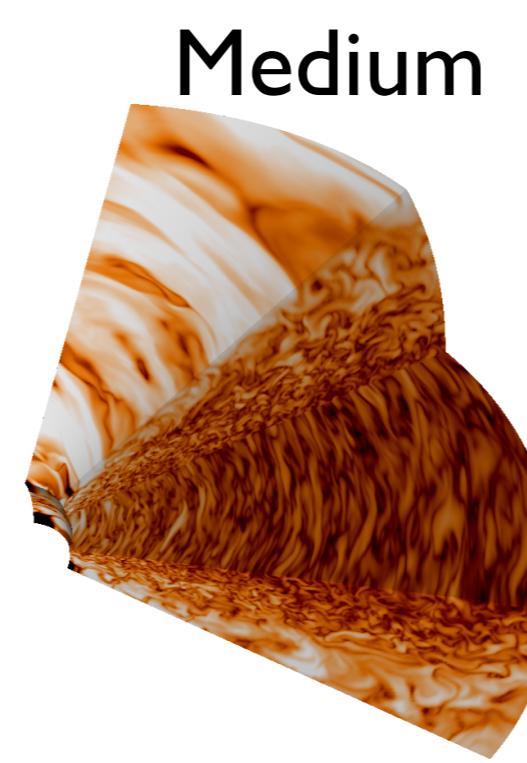


(Magnetic pressure)/(Gas pressure)



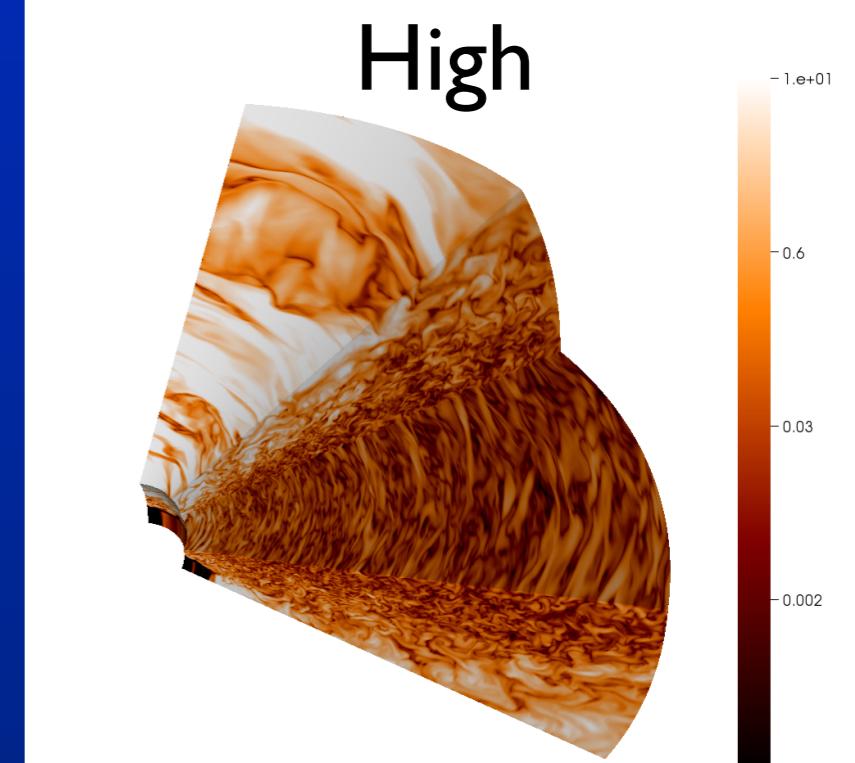
$340 \times 112 \times 128$ cells

$(n_r \times n_\theta \times n_\phi)$



$512 \times 170 \times 196$ cells

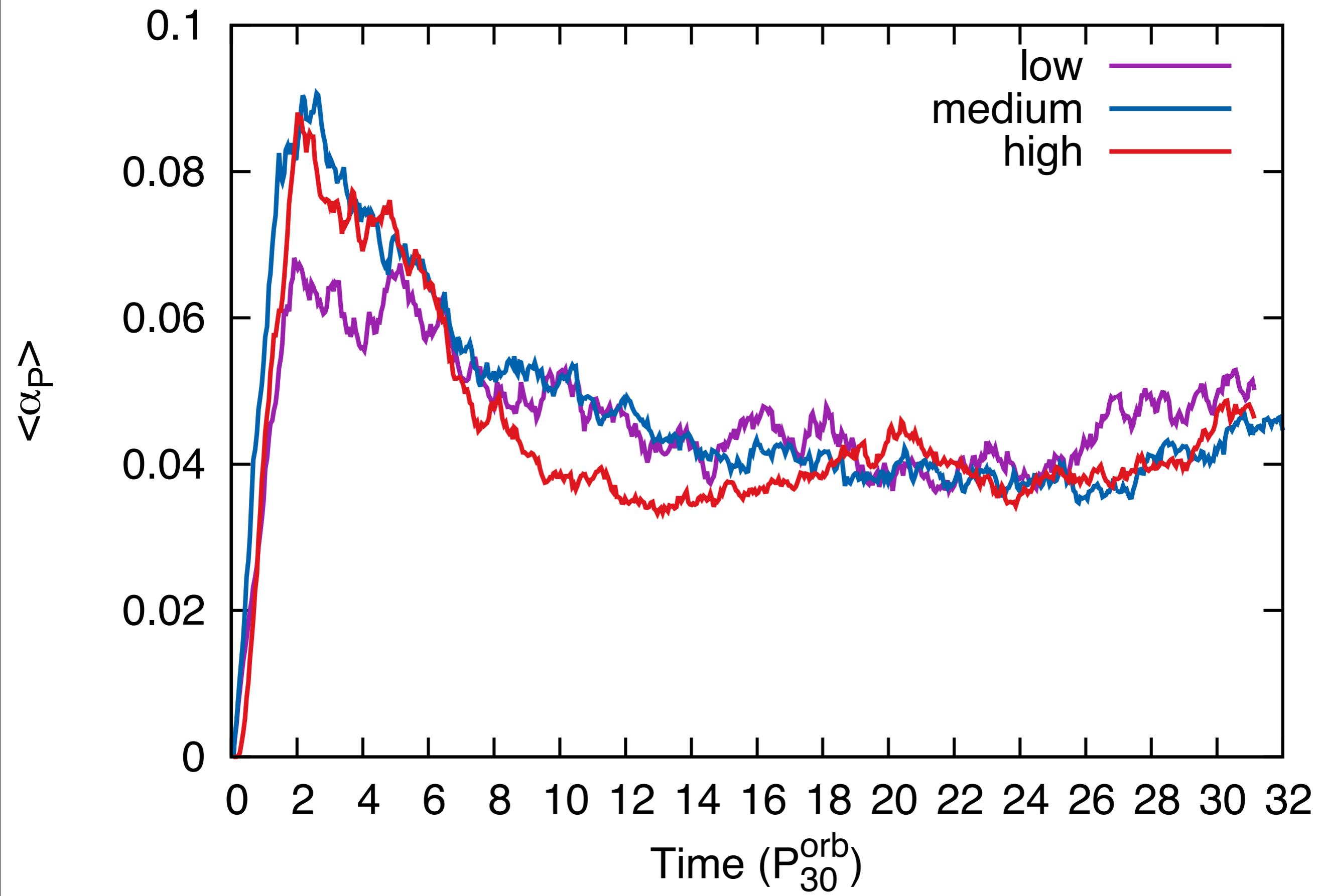
Plots show (magnetic pressure)/
(gas pressure)



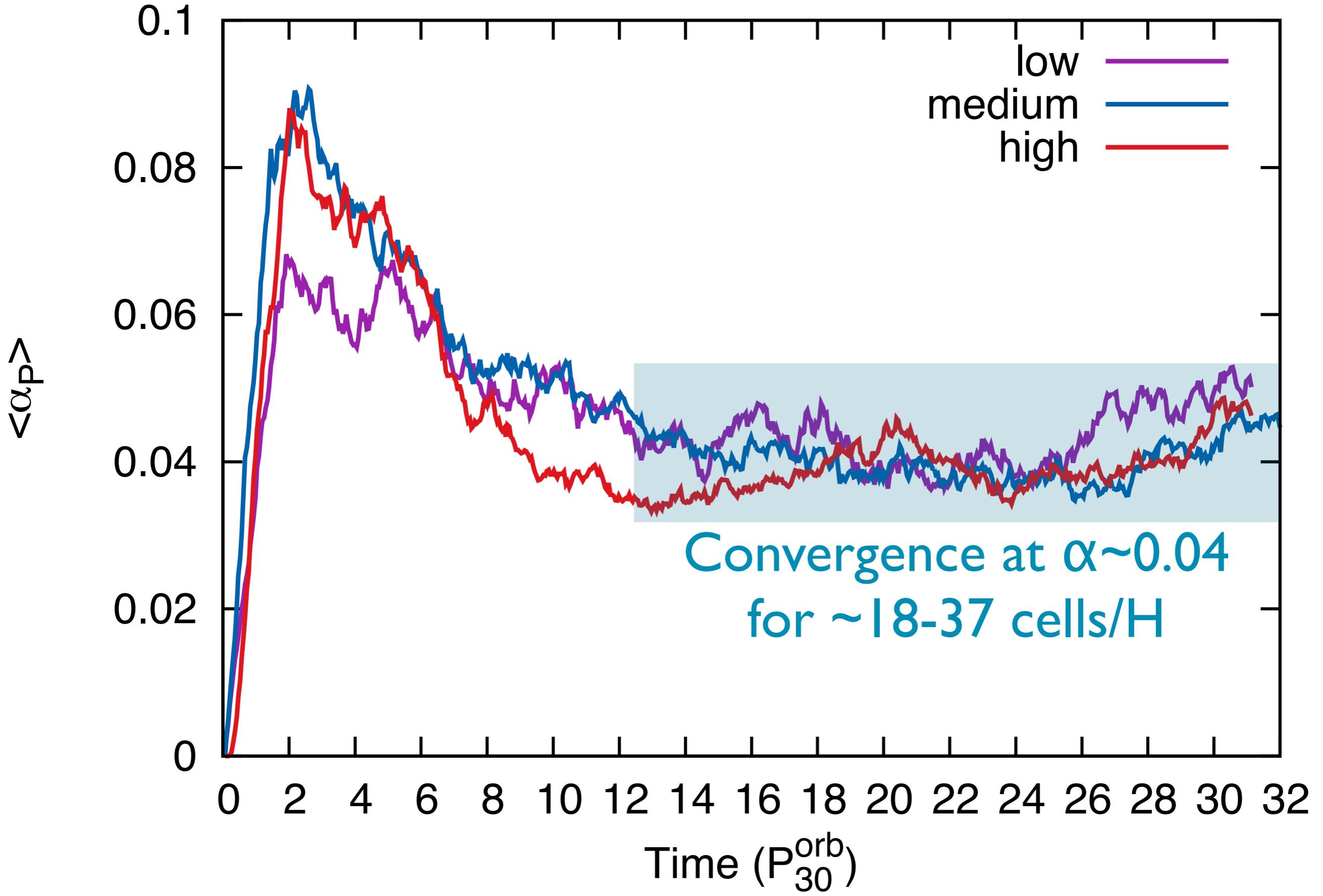
$768 \times 256 \times 256$ cells

Model	Resolution (n/H) $(r \times \theta \times \phi)$
low	$(9-36) \times 18 \times 8$
medium	$(12-51) \times 27 \times 13$
high	$(18-77) \times 37 \times 16$

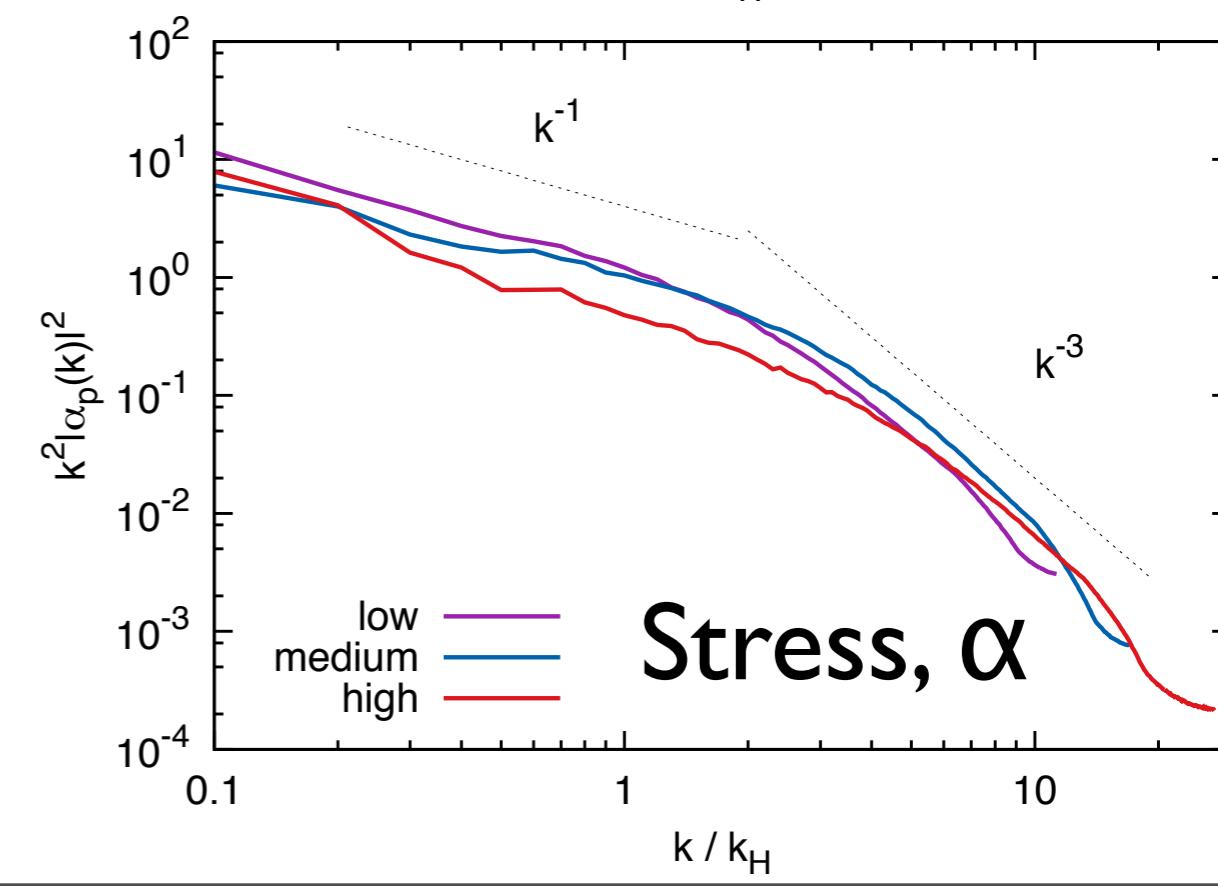
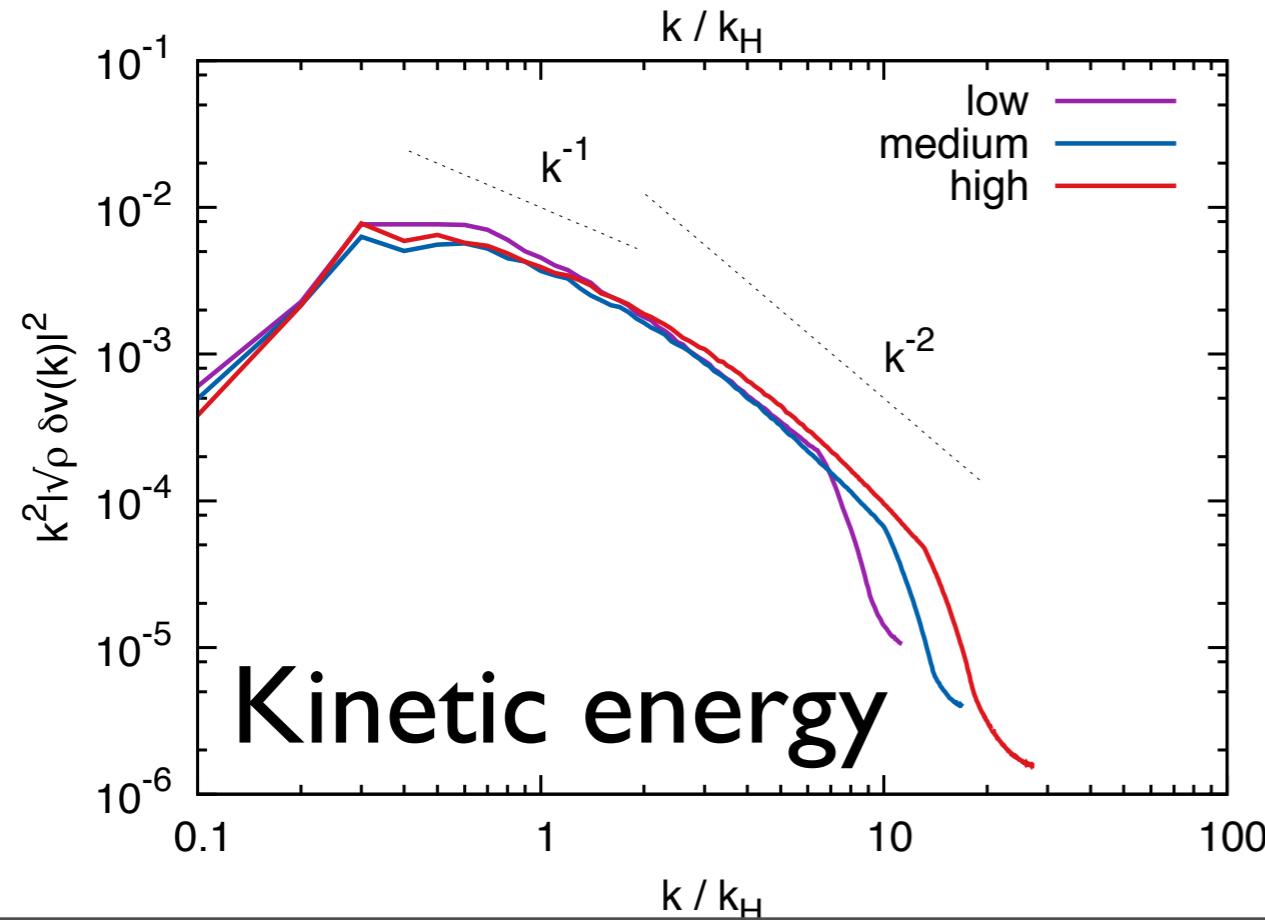
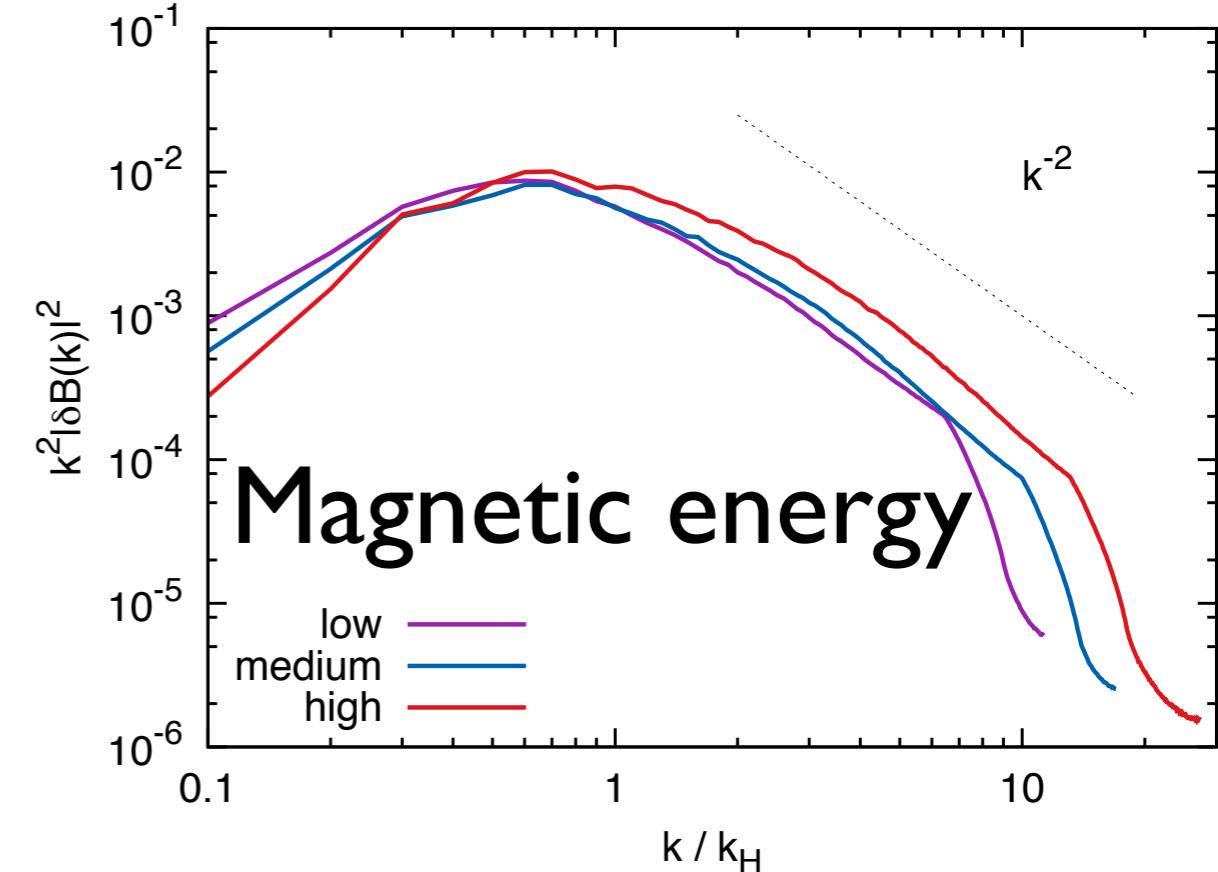
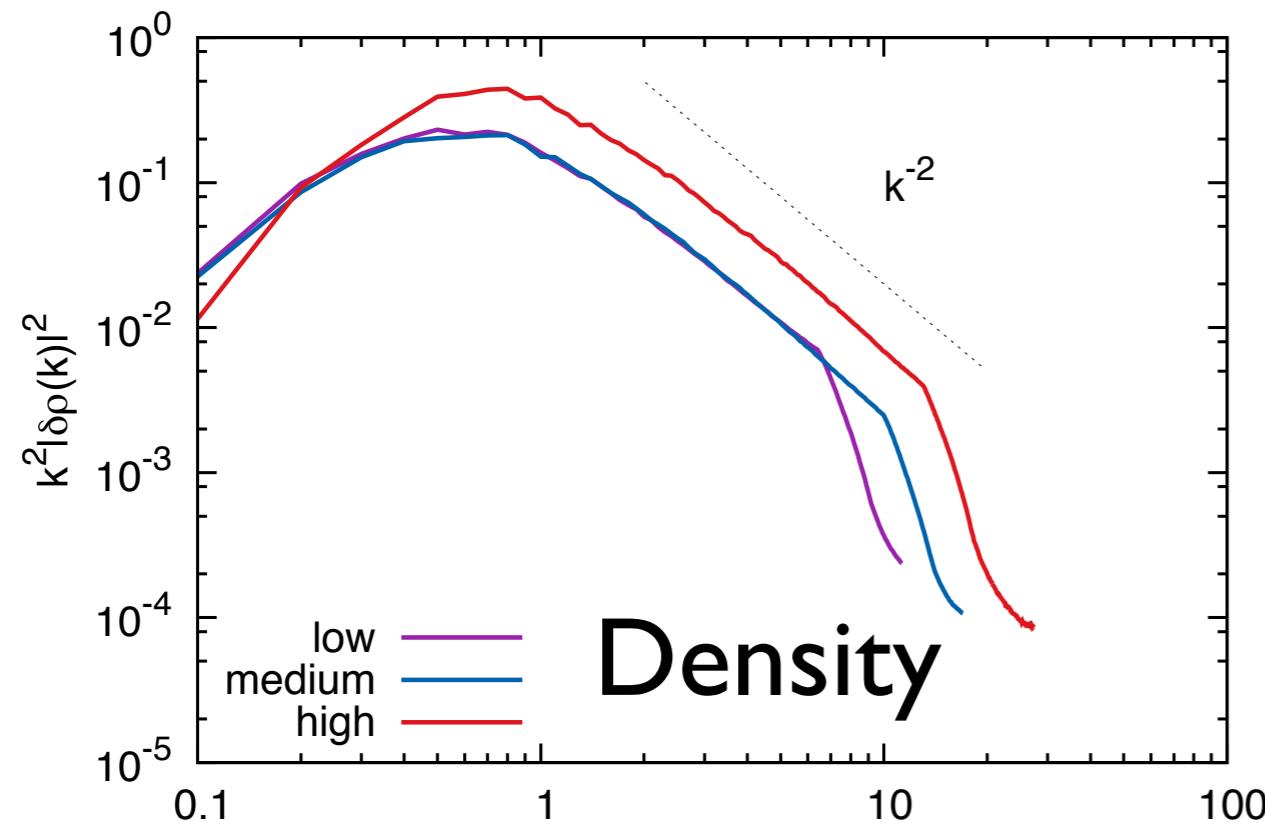
Convergence with resolution in global simulations



Convergence with resolution in global simulations

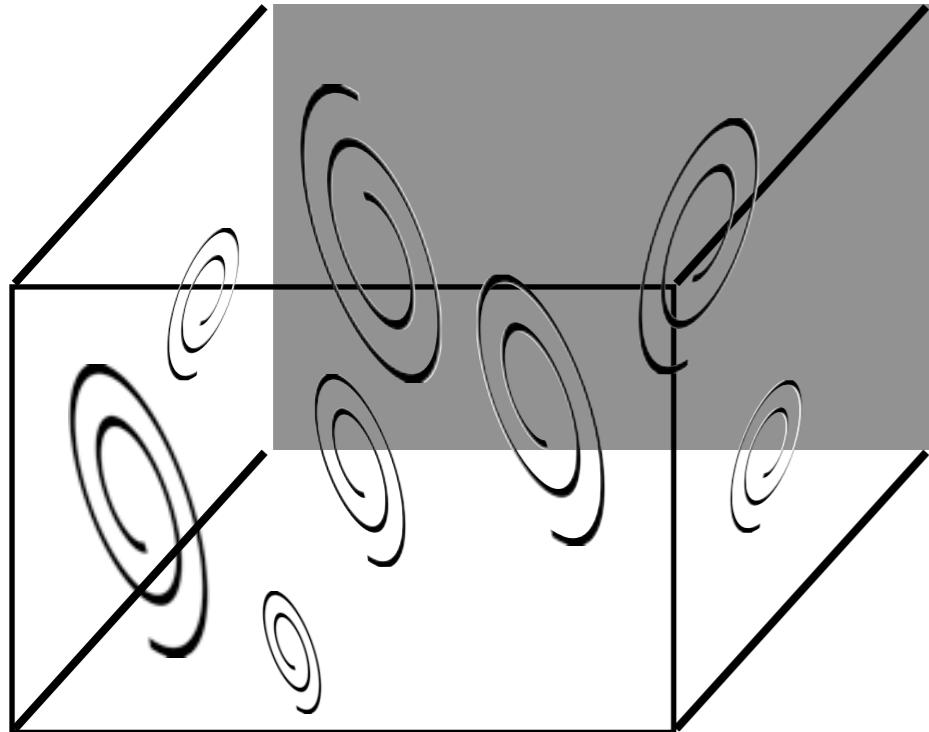


Power spectra



Magnetic energy maintenance

(Switch brain from real space to Fourier space)



Magnetic energy production must replenish energy on the largest scales.

Otherwise, the reservoir of energy at the largest scales will be drained by cascading of energy to smaller scales.

Convergence



Convergence



Convergence with increasing simulation resolution requires:

Convergence

Convergence with increasing simulation resolution requires:

- Convergence in magnetic energy input/injection on large scales

Convergence

Convergence with increasing simulation resolution requires:

- Convergence in magnetic energy input/injection on large scales
- Directly relates to the presence, or lack there-of, of magnetic field on large scales

Convergence

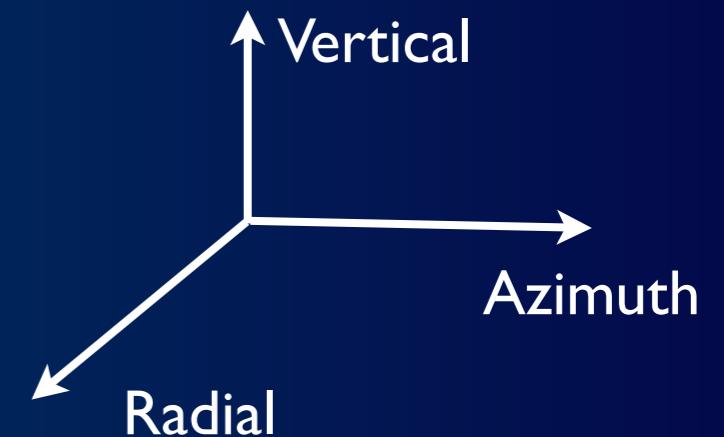
Convergence with increasing simulation resolution requires:

- Convergence in magnetic energy input/injection on large scales
- Directly relates to the presence, or lack there-of, of magnetic field on large scales
- Can assess these factors using a volume integrated analysis of the magnetic energy and induction equations with appropriate boundary conditions - see Parkin & Bicknell, 2013, arXiv:1306.1084

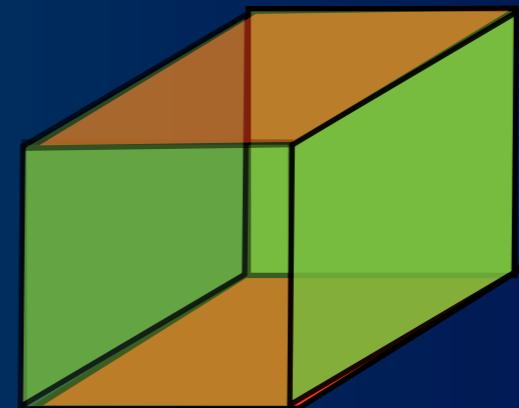
Boundary conditions for models

Periodic boundary

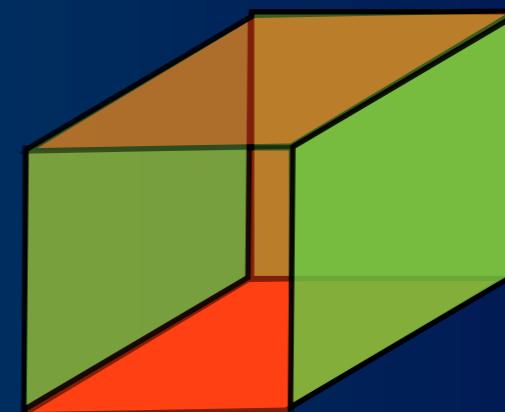
Open boundary



Stratified shearing box
(vertical surfaces are the disk-corona interface)



Global disk



Magnetic energy balance

The situation simplifies to,

$$\oint v_i M_{ij}^B n_j dS - \int v_i \frac{\partial M_{ij}^B}{\partial x_j} dV \approx \eta_{\text{num}} \int |j|^2 dV. \quad , \text{ where} \quad M_{ij}^B = B_i B_j - \delta_{ij} u_B$$

(Maxwell stress tensor)

Applying appropriate boundary conditions and preserving dominant terms, we have,

Shearing box

$$- q \Omega L_x \int_{x_1} B_x B_y dS_x - \int v_y B_x \frac{\partial B_y}{\partial x} dV \approx \eta_{\text{num}} \int |j|^2 dV.$$

Global disk

$$- \int_{r_1} B_r B_\phi v_\phi dS_r - \int v_\phi B_r \frac{\partial B_\phi}{\partial r} dV \simeq \eta_{\text{num}} \int |j|^2 dV.$$

Magnetic energy balance

The situation simplifies to,

$$\oint v_i M_{ij}^B n_j dS - \int v_i \frac{\partial M_{ij}^B}{\partial x_j} dV \approx \eta_{\text{num}} \int |j|^2 dV. \quad , \text{ where} \quad M_{ij}^B = B_i B_j - \delta_{ij} u_B$$

(Maxwell stress tensor)

Applying appropriate boundary conditions and preserving dominant terms, we have,

Shearing box

$$- q\Omega L_x \int_{x_1} B_x B_y dS_x - \int v_y B_x \frac{\partial B_y}{\partial x} dV \approx \eta_{\text{num}} \int |j|^2 dV.$$

Terms on LHS are larger in a global model due to **open radial boundaries** and **large scale radial gradients**

Global disk

$$- \int_{r_1} B_r B_\phi v_\phi dS_r + \int v_\phi B_r \frac{\partial B_\phi}{\partial r} dV \simeq \eta_{\text{num}} \int |j|^2 dV.$$

Summary

Summary

- Our initially purely toroidal field global disk models converge with $\alpha \sim 0.04$, in agreement with Beckwith+(2011) and Hawley +(2013)

Summary

- Our initially purely toroidal field global disk models converge with $\alpha \sim 0.04$, in agreement with Beckwith+(2011) and Hawley +(2013)
- Convergence at lower resolution in a global model (~ 30 cells/ H) than in a local model (stratified shearing-box $\sim 64\text{-}128$ cells/ H) (- see Davis+2010; Hawley+2011 and refs there-in)

Summary

- Our initially purely toroidal field global disk models converge with $\alpha \sim 0.04$, in agreement with Beckwith+(2011) and Hawley +(2013)
- Convergence at lower resolution in a global model (~ 30 cells/ H) than in a local model (stratified shearing-box $\sim 64\text{-}128$ cells/ H) (- see Davis+2010; Hawley+2011 and refs there-in)
- Arises because boundary conditions in global models allow more effective energy generation than in a shearing-box (Parkin & Bicknell, 2013, arXiv:1306.1084)