

Constraint release and chain stretch in fast flows of linear polymer melts.

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April 2002

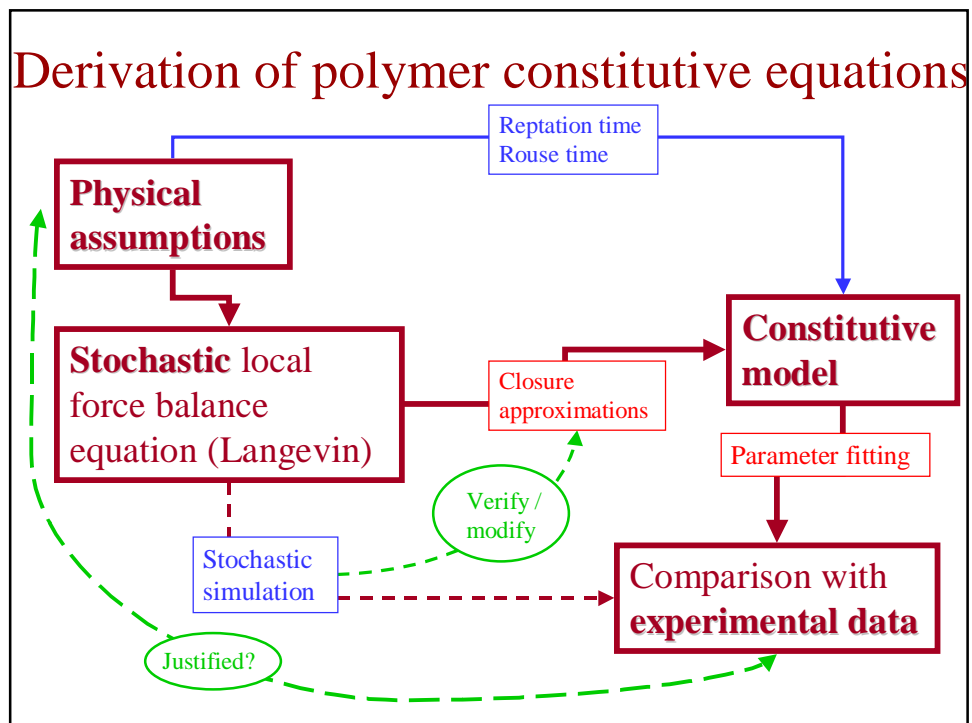
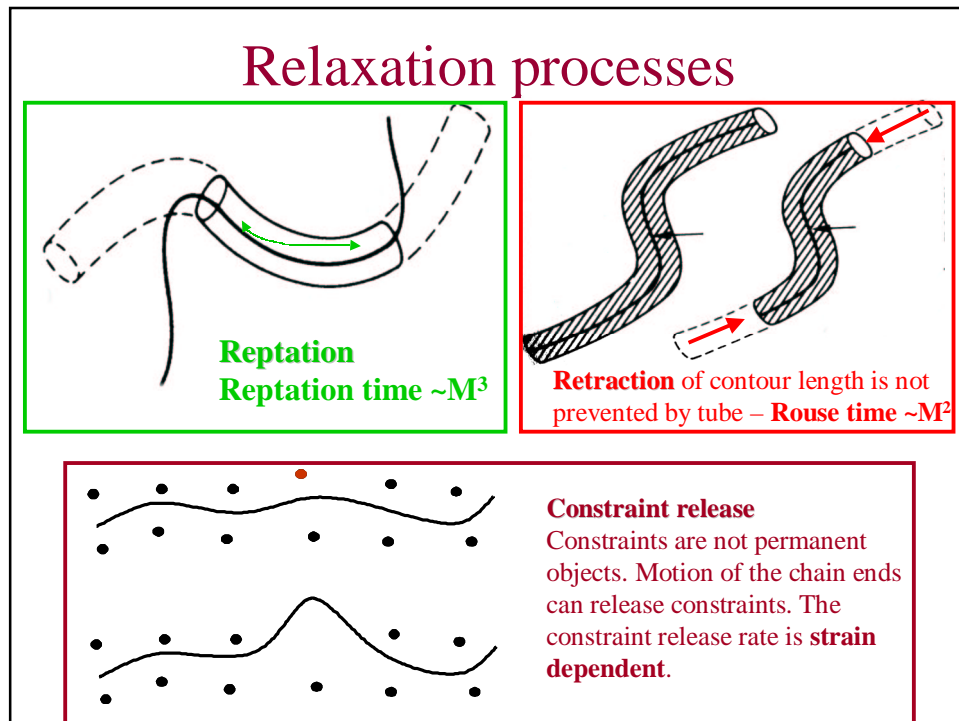
Acknowledgement: BP Amoco

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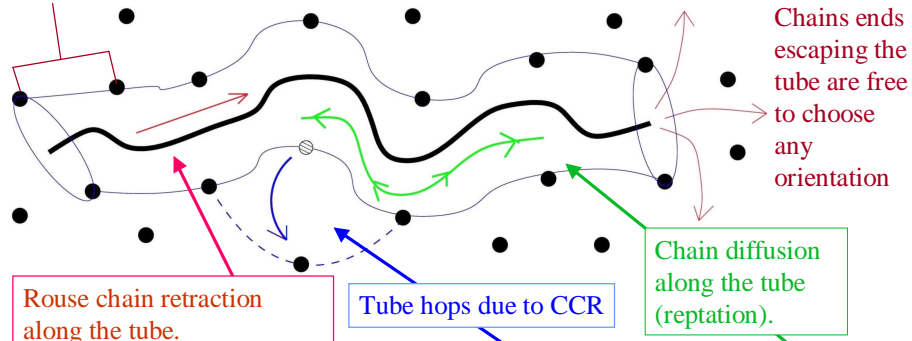
Outline

- Overview of derivation methods
- Introduction to Leeds model
- Method of solution
- Model parameters
- Comparison with experimental data
 - Shear transients
 - Steady state in extension
- Summary
- Questions



Stretching CCR model

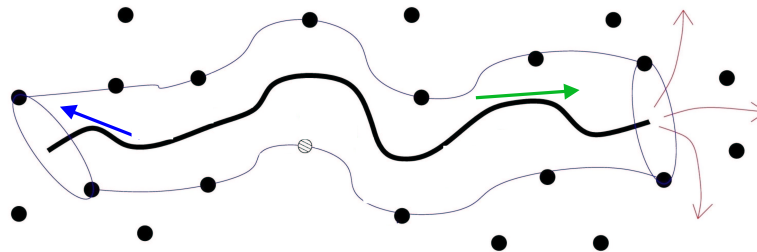
Tube diameter fixed under deformation.



$$\mathbf{R}(s, t + \Delta t) = \Delta t \left(D \frac{\mathbf{R}'' \cdot \mathbf{R}'}{|\mathbf{R}'|^2} \mathbf{R}' + \mathbf{k} \cdot \mathbf{R} + \frac{3\nu}{2} \frac{1}{|\mathbf{R}'|} \frac{\partial^2 \mathbf{R}}{\partial s^2} + \mathbf{g}(s, t) \right) + \mathbf{R}(s + \Delta \xi(t), t)$$

$\mathbf{R}(s, t)$ = Space curve equation of chain contour parameterised by s .

Tube tangent correlation function



$$\mathbf{f}(s, s', t) = \left\langle \frac{\partial \mathbf{R}(s)}{\partial s} \frac{\partial \mathbf{R}(s')}{\partial s'} \right\rangle$$

Stress tensor
Single chain structure factor

$$\mathbf{f}(s, s', t) = \left\langle \frac{\partial \mathbf{R}(s)}{\partial s} \frac{\partial \mathbf{R}(s')}{\partial s'} \right\rangle$$

$$\frac{\partial^2}{\partial t} f_{\alpha\beta}(s, s', t) = \frac{\partial^2}{\partial s \partial s'} \left(\left\langle \frac{\partial R_\alpha(s)}{\partial t} R_\beta(s') \right\rangle - \left\langle R_\alpha(s) \frac{\partial R_\beta(s')}{\partial t} \right\rangle \right)$$

Langevin equation
Just the CCR term in this example

$$\frac{\partial^2}{\partial s \partial s'} \left\langle \frac{\partial R_\alpha(s)}{\partial t} R_\beta(s') \right\rangle = \dots + \frac{\partial^2}{\partial s \partial s'} \left(\left\langle \frac{3\nu}{2} R''_\alpha(s) R_\beta(s') \right\rangle \right)$$

$$= \frac{3\nu}{2} \frac{\partial^2}{\partial s^2} f_{\alpha\beta}(s, s') \quad \dots \text{repeat for other terms}$$

Langevin equation

Closure approximations
 $\left\langle \frac{\mathbf{R}'(s) \mathbf{R}'(s')}{|\mathbf{R}'(s)|} \right\rangle \approx \frac{\langle \mathbf{R}'(s) \mathbf{R}'(s') \rangle}{\sqrt{\langle \mathbf{R}'(s) \cdot \mathbf{R}'(s) \rangle}}$

$\langle \ln(\mathbf{R}'(s) \cdot \mathbf{R}'(s')) \rangle \approx \ln(\langle \mathbf{R}'(s) \cdot \mathbf{R}'(s') \rangle)$

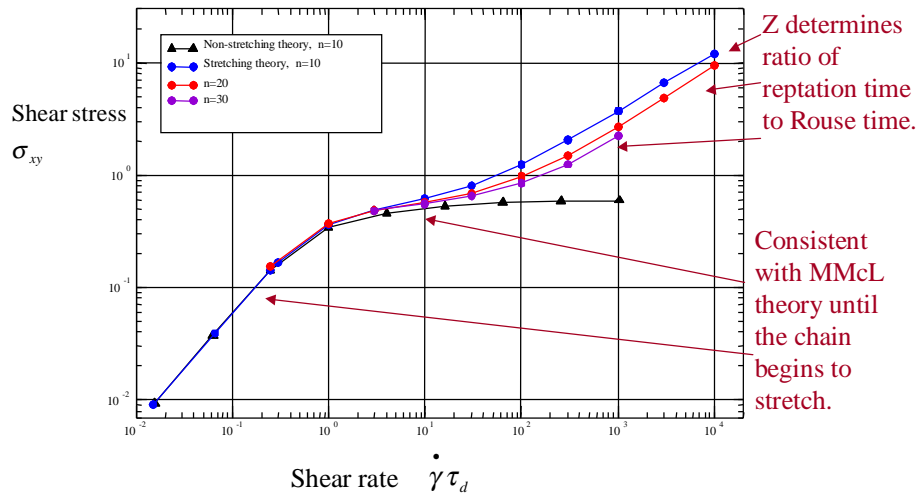
$$\frac{\partial \mathbf{G}}{\partial t} = \boldsymbol{\kappa} \cdot \mathbf{G} + \mathbf{G} \cdot \boldsymbol{\kappa}^T + \frac{1}{3}(\boldsymbol{\kappa} + \boldsymbol{\kappa}^T) \delta(s - s') + \left[\frac{D}{Z} \left(\frac{Z}{Z^*(t)} \right)^2 \left(\frac{\partial}{\partial s} + \frac{\partial}{\partial s'} \right)^2 \mathbf{G} \right]$$

$$+ \frac{3\nu}{2} \left(\frac{\partial}{\partial s} \left[\frac{1}{\sqrt{\text{Tr} \mathbf{G}(s, s) + 1}} \frac{\partial}{\partial s} \right] + \frac{\partial}{\partial s'} \left[\frac{1}{\sqrt{\text{Tr} \mathbf{G}(s', s') + 1}} \frac{\partial}{\partial s'} \right] \right) \mathbf{G}$$

$$+ \frac{3D}{2} \left(\frac{\partial}{\partial s} \left(\frac{\partial}{\partial s} [\ln(\text{Tr} \mathbf{G}(s, s) + 1)] \right) + \frac{\partial}{\partial s'} \left(\frac{\partial}{\partial s'} [\ln(\text{Tr} \mathbf{G}(s', s') + 1)] \right) \right) (\mathbf{G} + \delta(s - s') \mathbf{I}/3)$$

$$\mathbf{G}(s, s') = \left\langle \frac{\partial \mathbf{R}(s)}{\partial s} \frac{\partial \mathbf{R}(s')}{\partial s'} \right\rangle - \frac{1}{3} \mathbf{I} \delta(s - s')$$

Steady state in simple shear



Contour length fluctuations

- Easy to add to Langevin equation, in principle.
- Solution to system becomes very difficult!
- Modify reptation term to obtain an approximate treatment which agrees with the linear theory at low rates.

Derived reptation term

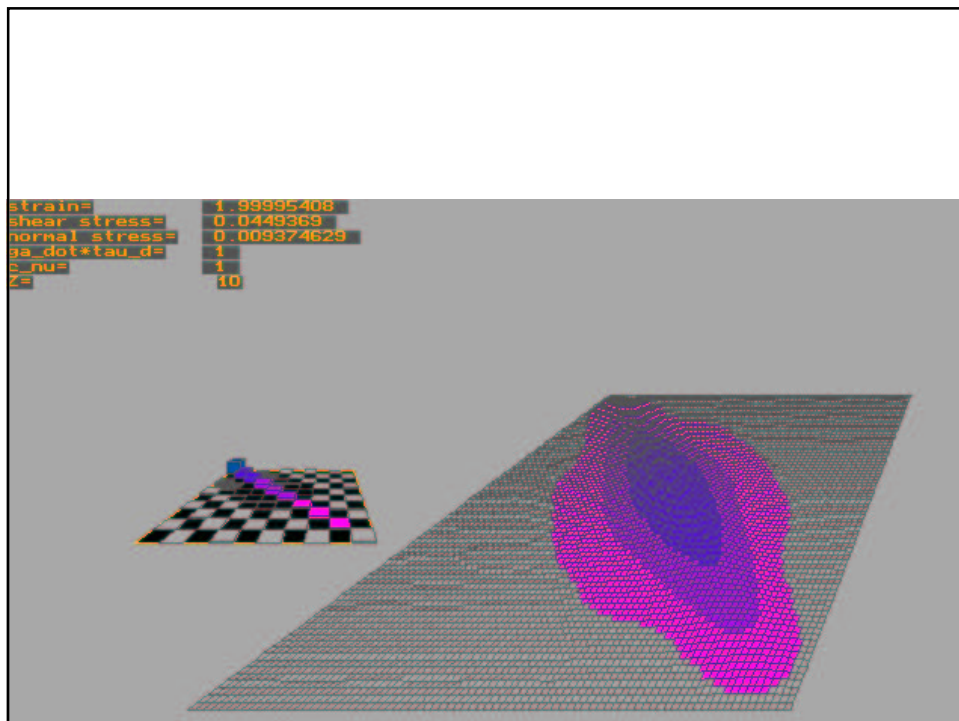
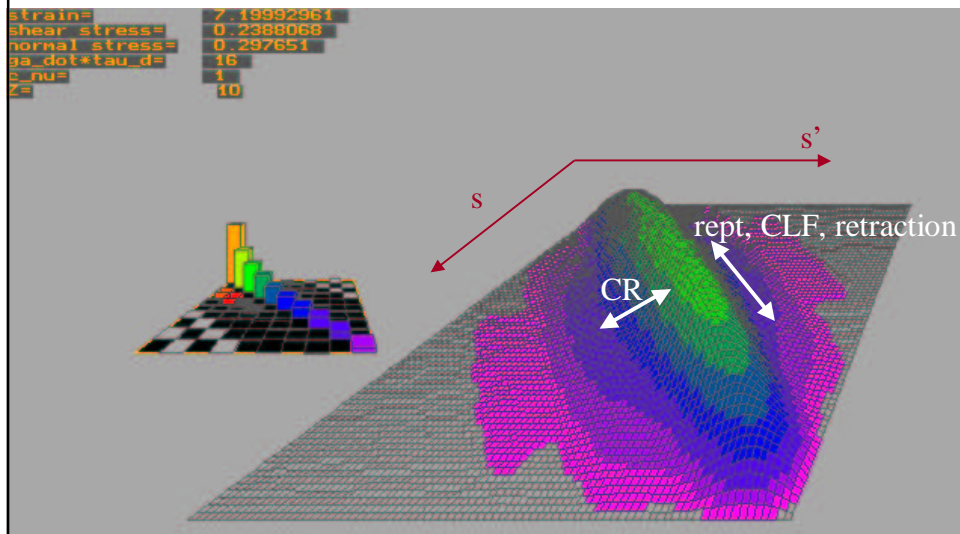
Approximate CLF term

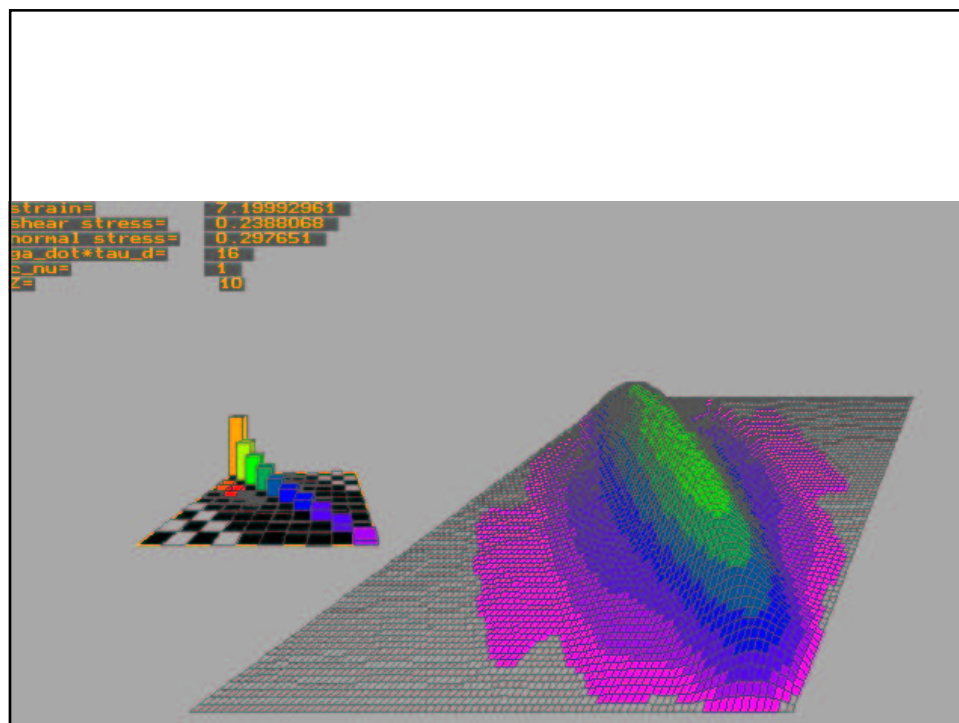
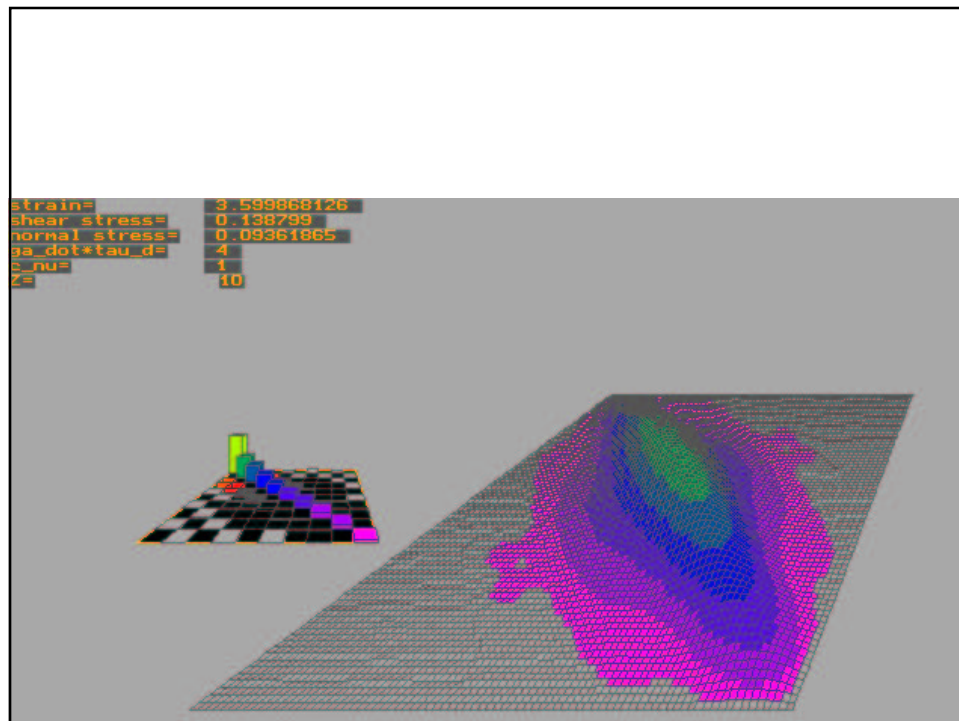
$$D \left(\frac{\partial}{\partial s} + \frac{\partial}{\partial s'} \right)^2 (\mathbf{f} - \mathbf{f}_{eq}) \mapsto \left(\frac{\partial}{\partial s} + \frac{\partial}{\partial s'} \right) D_{CLF}(s, s') \left(\frac{\partial}{\partial s} + \frac{\partial}{\partial s'} \right) (\mathbf{f} - \mathbf{f}_{eq})$$

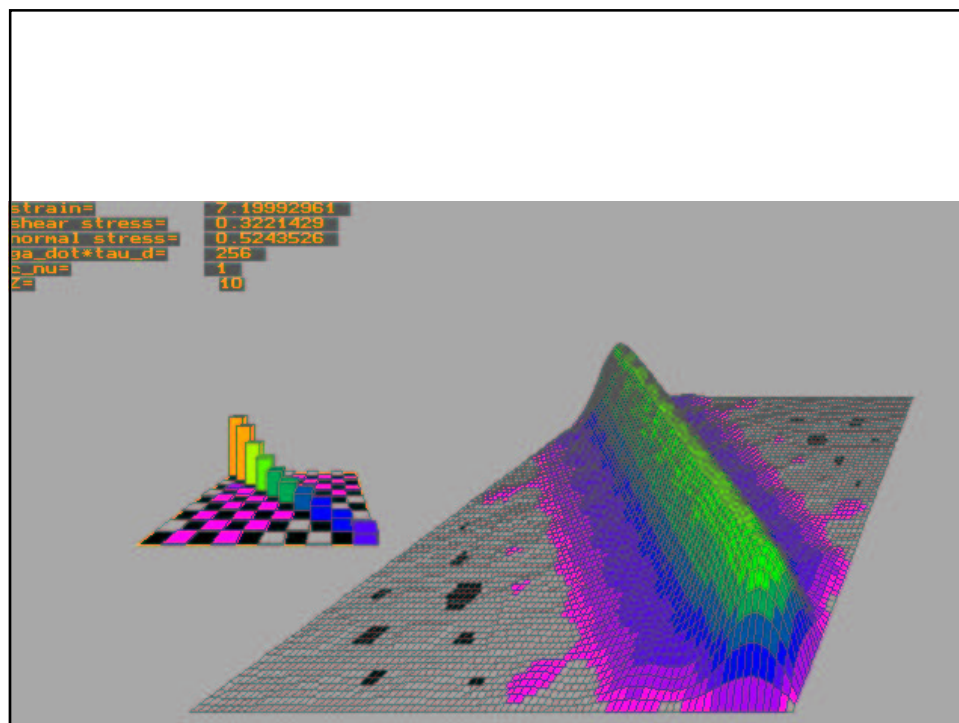
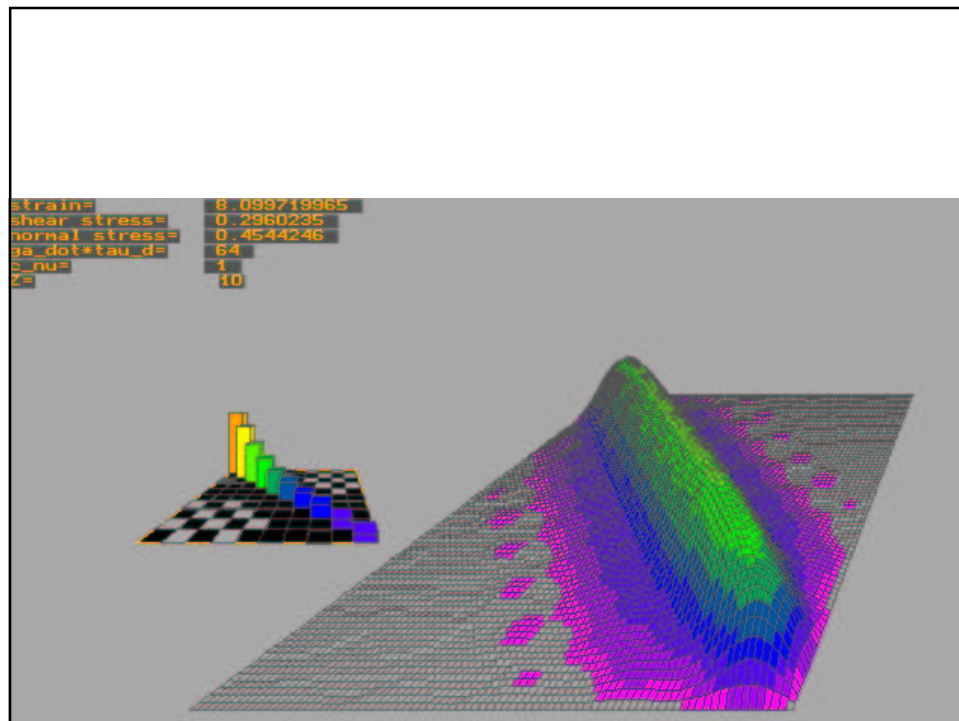
- Choose a form for $D_{CLF}(s, s')$ which agrees with the linear theory for a wide range of values of Z .

Tangent correlation function

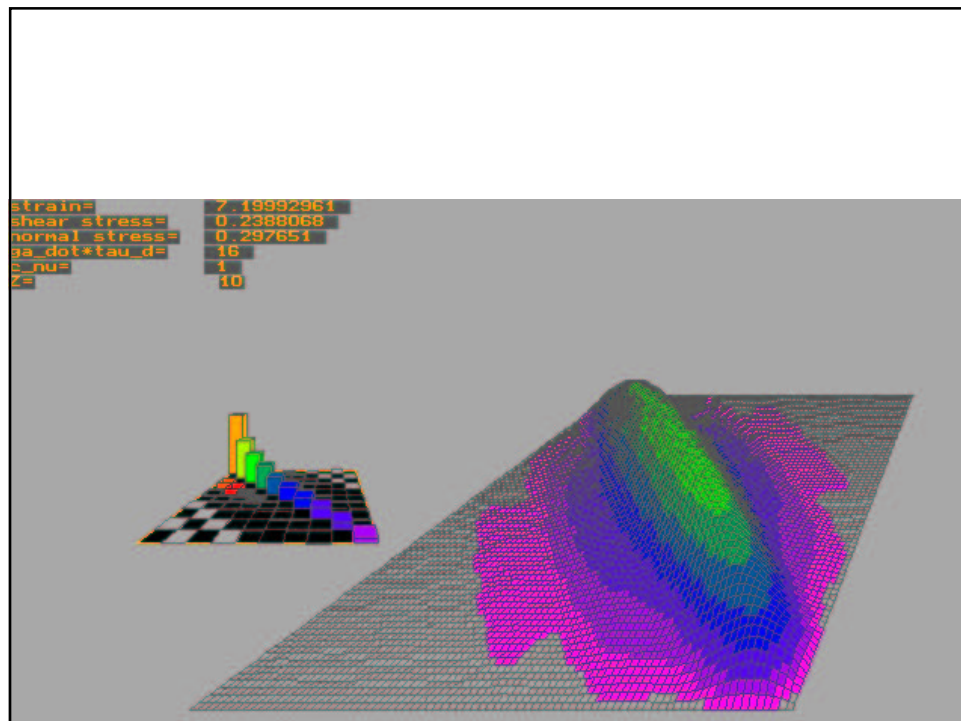
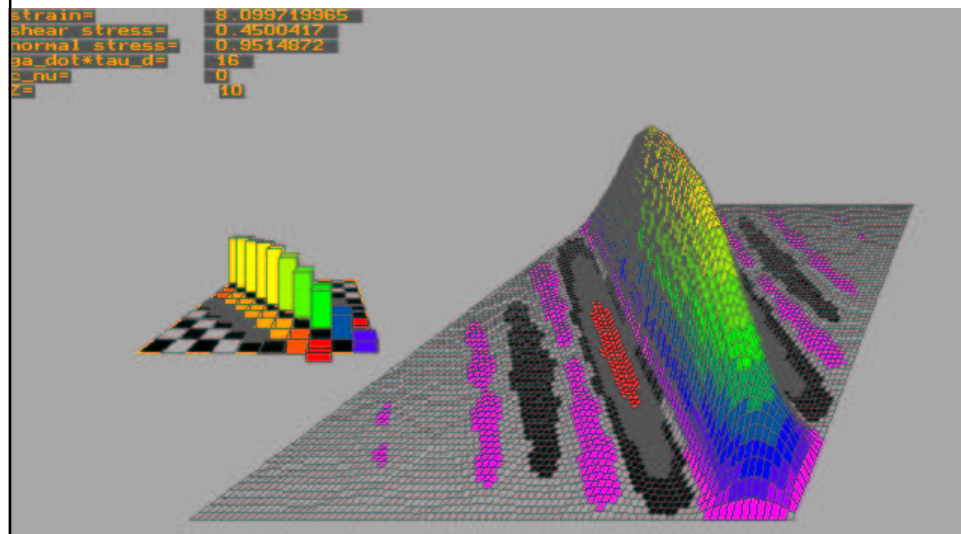
$$f_{\alpha\beta}(s, s') = \left\langle \frac{\partial R_\alpha}{\partial s} \frac{\partial R_\beta}{\partial s'} \right\rangle$$



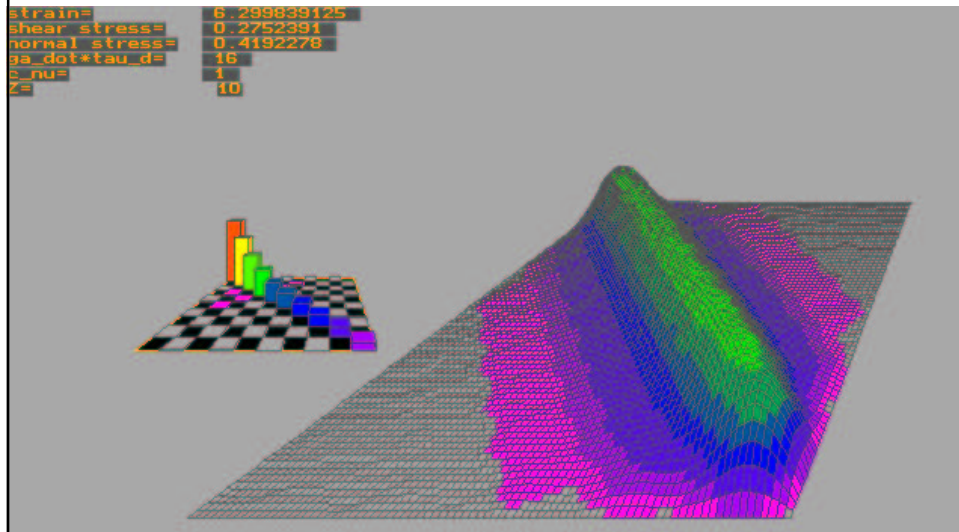




NO CCR



NO CLF - pure reptation



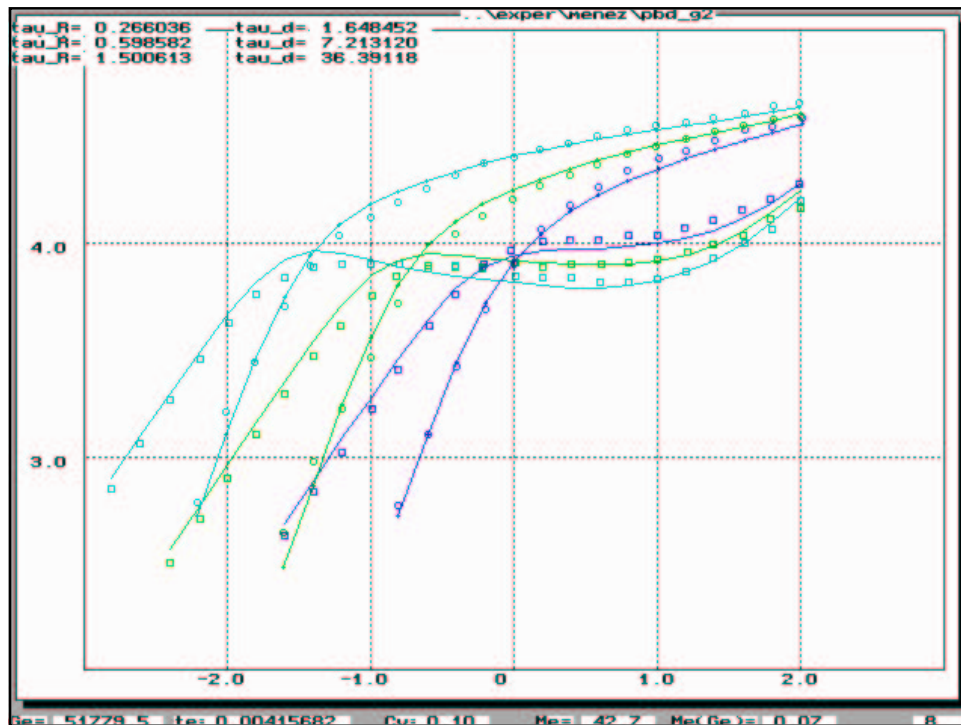
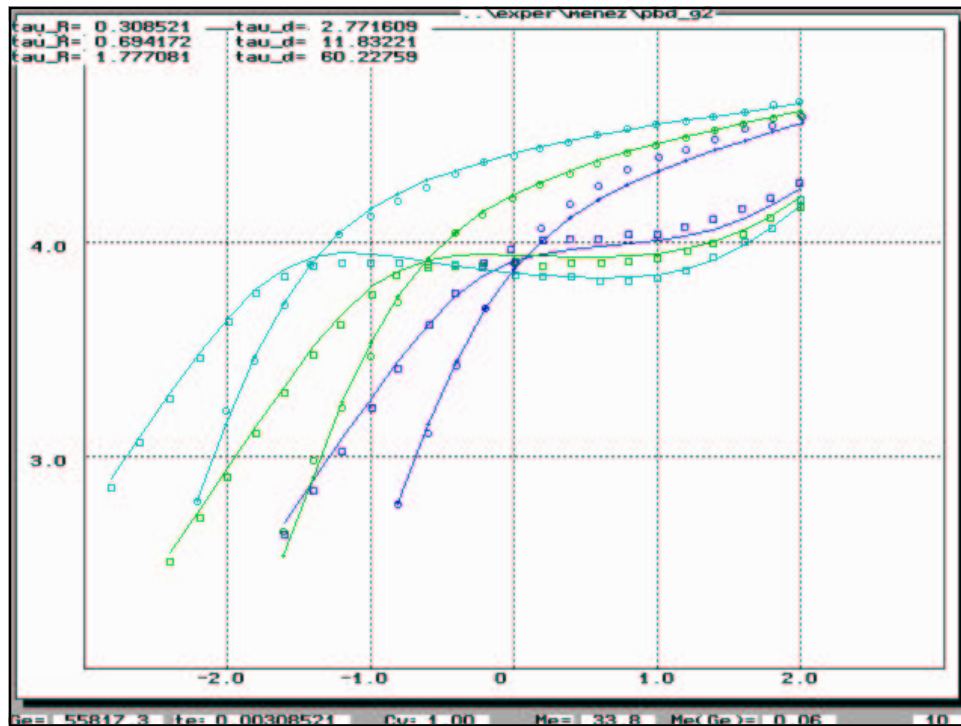
Procedure for obtaining model parameters

Require:

- Entanglement mass, M_e
- Entanglement modulus, G_e
- Rouse time of an entanglement segment, τ_e
- Constraint release parameter, C_v

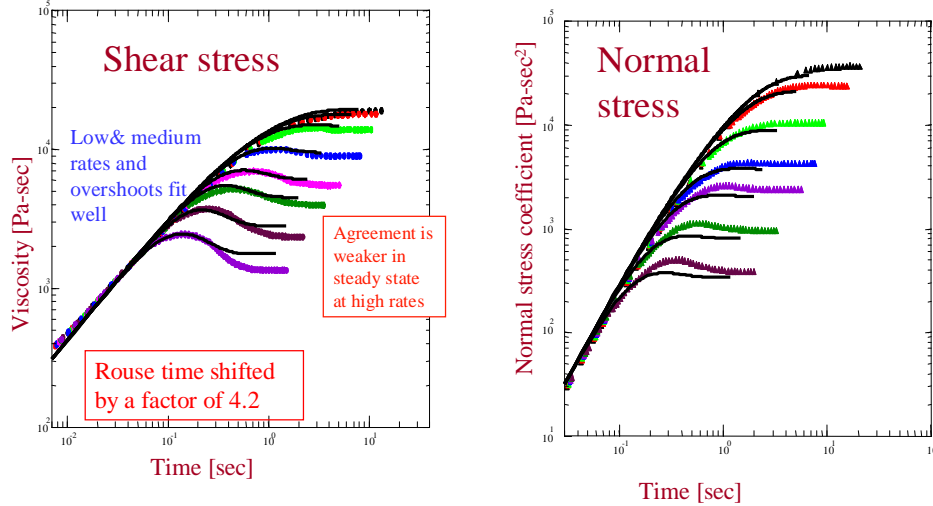
} Obtained from fitting
linear theory of
Likhtman and McLeish
to G' and G''

Linear rheology of solutions suggests $C_v \sim 2-5$.
Non-linear steady shear predictions improved
when $C_v = 0.1$



Comparison with data

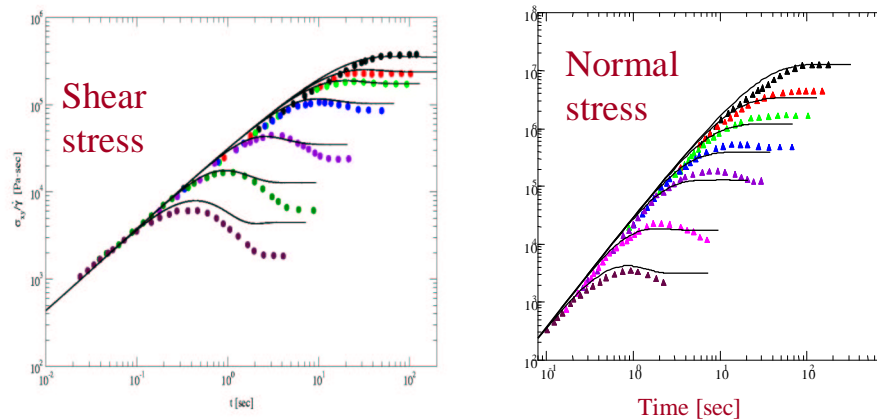
Shear of monodisperse linear entangled PB solution. (Menezes & Graessley)



Mw=350K, 7% solution

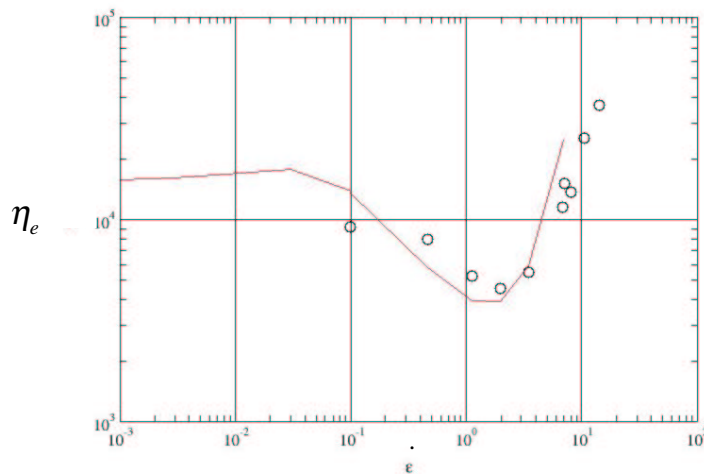
Extension to a higher molecular weight

Mw=813K, 7% solution



No further parameter fitting

Steady state extension data



Summary

- We have derived a molecularly based non-linear constitutive model starting from a Langevin equation for the local dynamics of a chain in a tube.
- The model has no shear stress maximum for any separation of τ_{rept} and τ_{Rouse} .
- Taking most of the model parameters from linear rheology gives agreement with experimental data subject to a shift in Rouse time.
- The required Rouse shift is the same when the molecular weight, the polymer species and the non-linear flow geometry are changed!!!!!! (For the data modeled so far.)
- For solutions G'' suggests a larger value for C_n than expected whereas lowering C_n improves the agreement with high rates at large strains.

Current questions

Other measurements

- What about damping function and other shear histories (double step etc)?
- Will the model capture behaviour of other molecular probes (SANS, dielectric, NMR)?

Issues with current comparisons

- What is the reason for the need to shift the Rouse time and why do the data suggest a consistent change?
- Under which circumstances are the closure approximations valid? - can we improve them?
- Why does the model over-predict steady state shear stress? - can this be rectified?
- Why does G'' for solutions suggest such a large value for C_v ?