

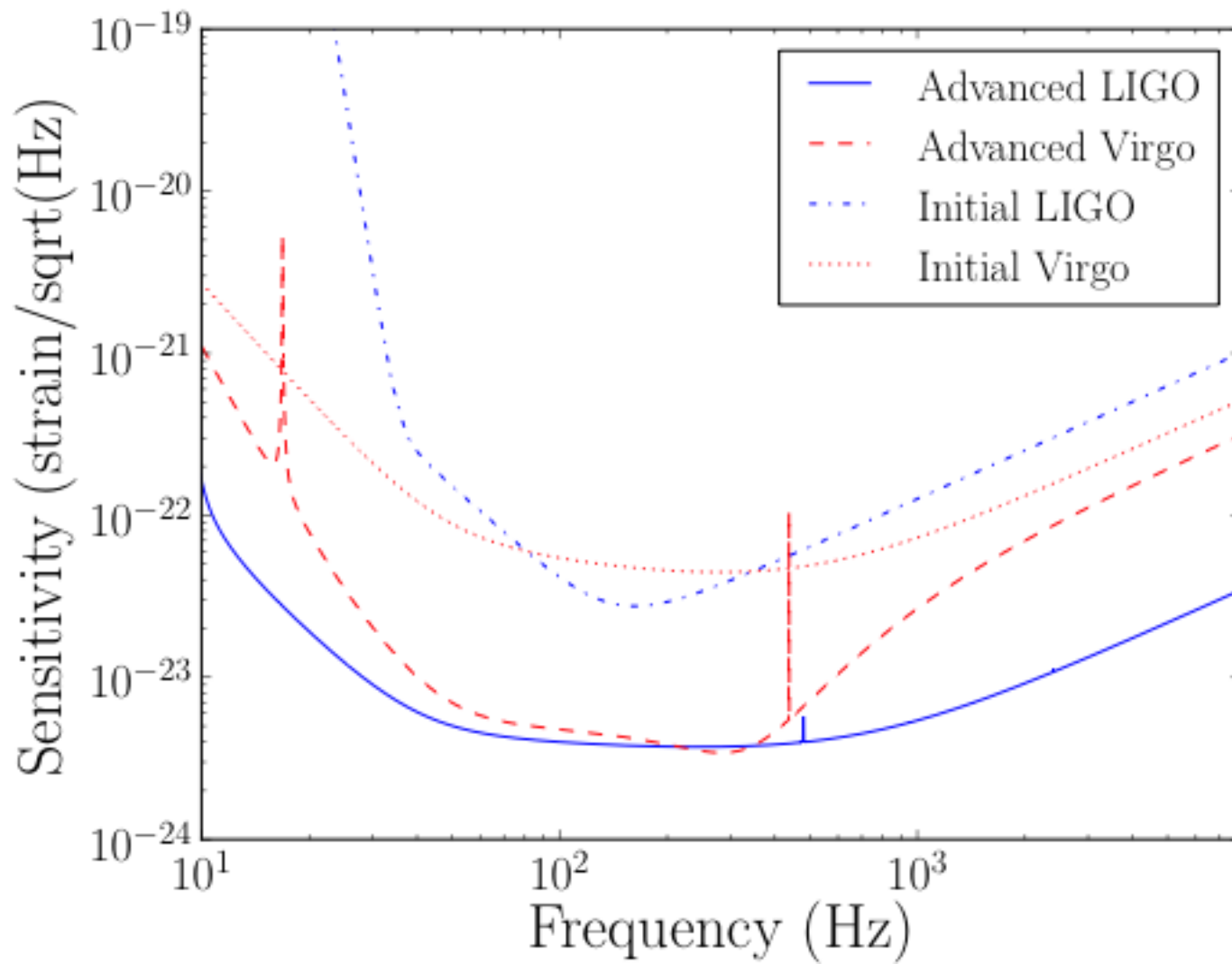
# Searching for binaries with spin with Advanced LIGO and Advanced Virgo

Ian Harry  
Syracuse University

# Motivation

- We have a well established method for searching for systems that do not have spin.
  - Matched filtering with non-spinning waveforms
  - Good for binary neutron stars
- Also has some sensitivity to spinning systems
  - NSBH, BBH
- We don't want to miss binaries where spin matters!
  - Need to quantify the effects of spin and improve search

# Motivation



# Talk Overview

- What changes when the components of the binary have spin?
- Why is it a challenge to search for objects with spin?
- Searching for aligned-spin waveforms?
- Searching for precessing waveforms?
- What about other effects?
  - Sub-dominant modes, matter effects, eccentricity ....

# What changes with spin?

- The coupling between the spinning bodies and the orbital angular momentum cause:
  - Changes in the frequency evolution of the system (and thus frequency of emitted GWs)
  - Changes in the energy lost to GWs (and thus amplitude of emitted GWs)
  - Precession

Apostolatos et al, Phys. Rev. D 49, 6274

Kidder et al, Phys Rev D 47, 4183

Kidder, Phys Rev D 52, 821

Buonanno et al, Phys Rev D 67, 104025

# Frequency evolution

- Spin affects the frequency evolution of a CBC

No spin: -

$$\frac{\dot{\omega}}{\omega^2} = \frac{96}{5} (\mathcal{M}\omega)^{5/3} \left\{ 1 + A(\mathcal{M}, \eta) (\mathcal{M}\omega)^{2/3} + B(\mathcal{M}, \eta) (\mathcal{M}\omega)^{3/3} + (C(\mathcal{M}, \eta)) (\mathcal{M}\omega)^{4/3} + (D(\mathcal{M}, \eta)) (\mathcal{M}\omega)^{5/3} + \dots \right\}$$

Chirp mass:  $\mathcal{M} = \frac{(m_1 m_2)^{3/5}}{(m_1 + m_2)^{1/5}}$

Symmetric mass ratio:  $\eta = \frac{(m_1 m_2)}{(m_1 + m_2)^2}$

# Frequency evolution

- Spin affects the frequency evolution of a CBC

With spin:

$$\frac{\dot{\omega}}{\omega^2} = \frac{96}{5} (\mathcal{M}\omega)^{5/3} \left\{ 1 + A(\mathcal{M}, \eta) (\mathcal{M}\omega)^{2/3} + B(\mathcal{M}, \eta) (\mathcal{M}\omega)^{3/3} + (C(\mathcal{M}, \eta) + \text{SO}) (\mathcal{M}\omega)^{4/3} + (D(\mathcal{M}, \eta) + \text{SS}) (\mathcal{M}\omega)^{5/3} + \dots \right\}$$

Chirp mass:  $\mathcal{M} = \frac{(m_1 m_2)^{3/5}}{(m_1 + m_2)^{1/5}}$

Symmetric mass ratio:  $\eta = \frac{(m_1 m_2)}{(m_1 + m_2)^2}$

# What changes with spin?

- The coupling between the spinning bodies and the orbital angular momentum cause:
  - Changes in the frequency evolution of the system (and thus frequency of emitted GWs)
  - Changes in the energy lost to GWs (and thus amplitude of emitted GWs)
  - Precession

Apostolatos et al, Phys. Rev. D 49, 6274

Kidder et al, Phys Rev D 47, 4183

Kidder, Phys Rev D 52, 821

Buonanno et al, Phys Rev D 67, 104025



# What changes with spin?

- The interactions of the spinning bodies with the orbital angular momentum, each other and themselves cause:
  - Changes in the frequency evolution of the system (and thus frequency of emitted GWs)
  - ~~- Changes in the energy lost to GWs (and thus amplitude of emitted GWs)~~
  - Precession

Apostolatos et al, Phys. Rev. D 49, 6274

Kidder et al, Phys Rev D 47, 4183

Kidder, Phys Rev D 52, 821

Buonanno et al, Phys Rev D 67, 104025

# Simple Precession

- Most precessing binaries undergo “simple precession”
  - $\mathbf{L}$  and  $\mathbf{S}_{1,2}$  precess around  $\mathbf{J}$
  - $\mathbf{L}$ : orbital angular momentum
  - $\mathbf{S}_i$ : Spin (component’s angular momentum)
  - $\mathbf{J}$ : Total angular momentum

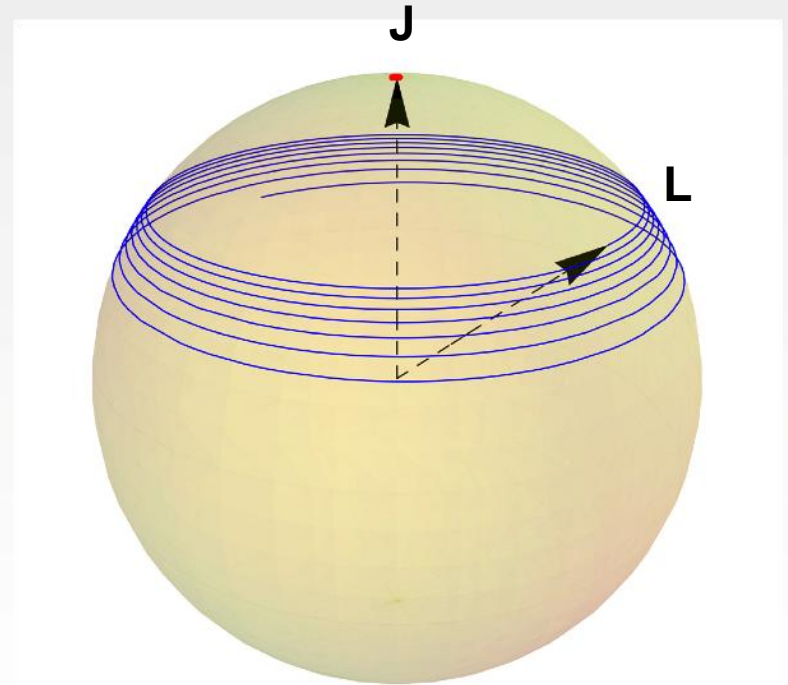


Figure from Schmidt, Hannam and Husa. arXiv:1207.3088

# Transitional Precession

- When  $\mathbf{J}$  becomes very small “transitional precession” can occur
- $\mathbf{S}$  and  $\mathbf{L}$  “tumble” during the transition
- Simple precession resumes once  $\mathbf{J}$  becomes larger
- Very rarely occurs

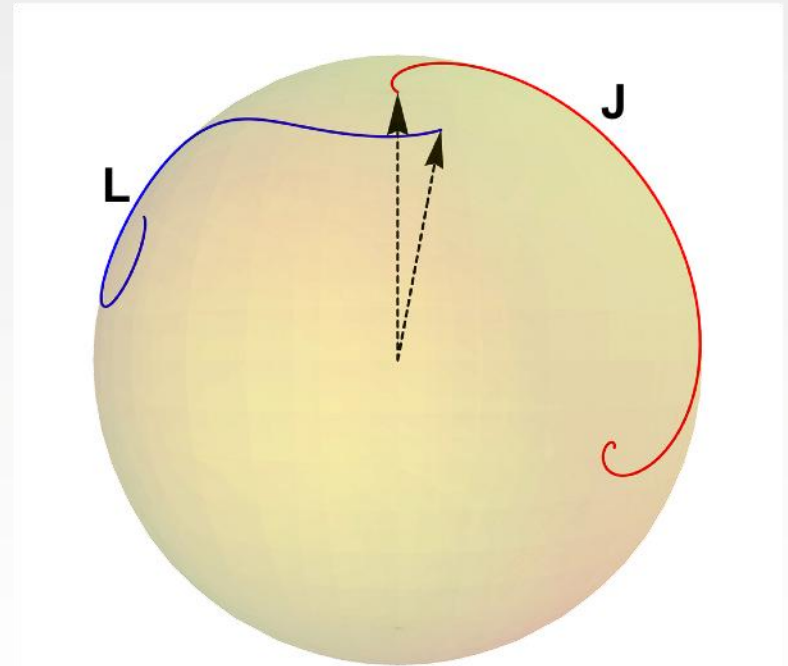
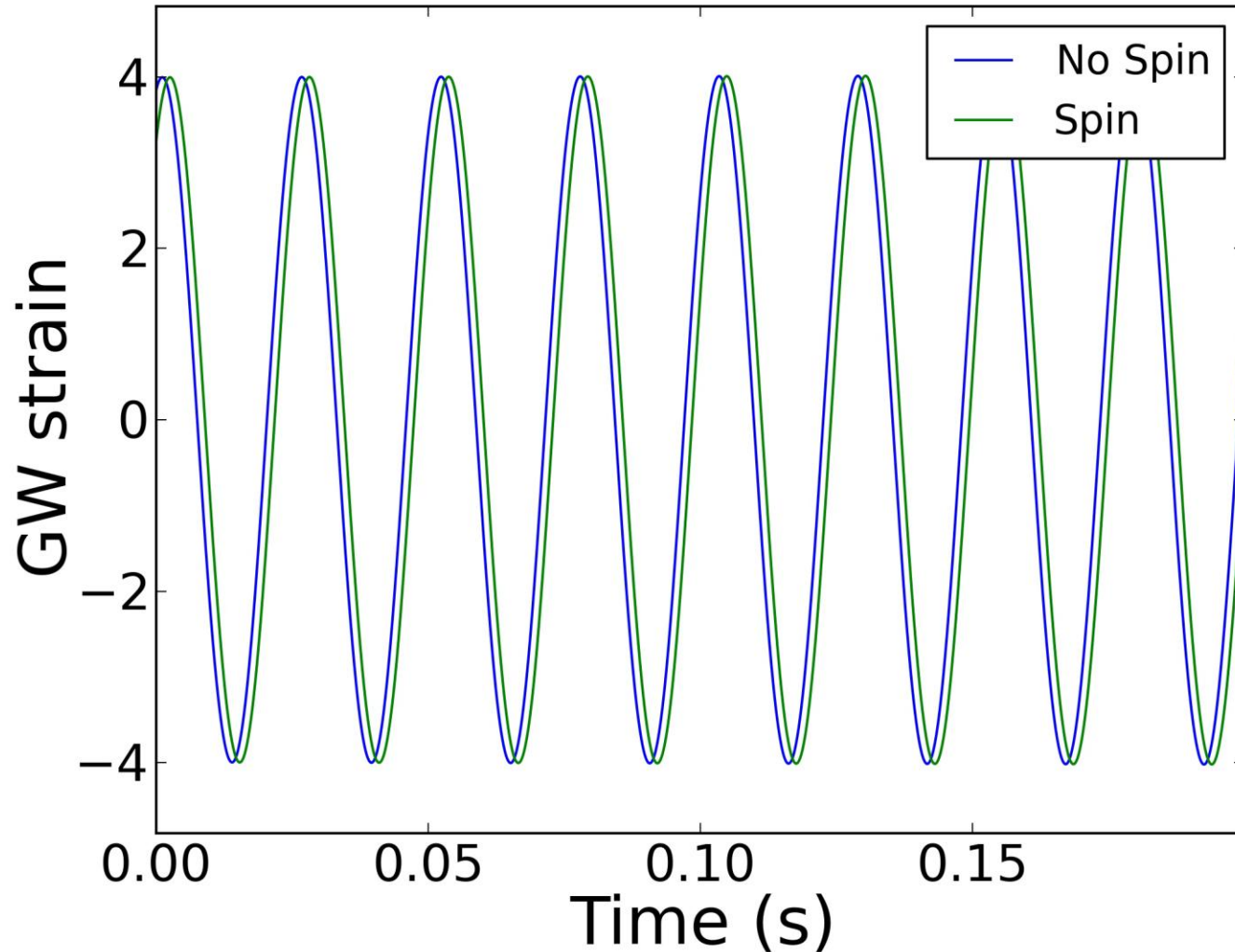


Figure from Schmidt, Hannam and Husa. arXiv:1207.3088

# Phase changes



$$m_1 = m_2 = 3M_{\odot}$$

For spin:

$$\chi_1 = \chi_2 = 1$$

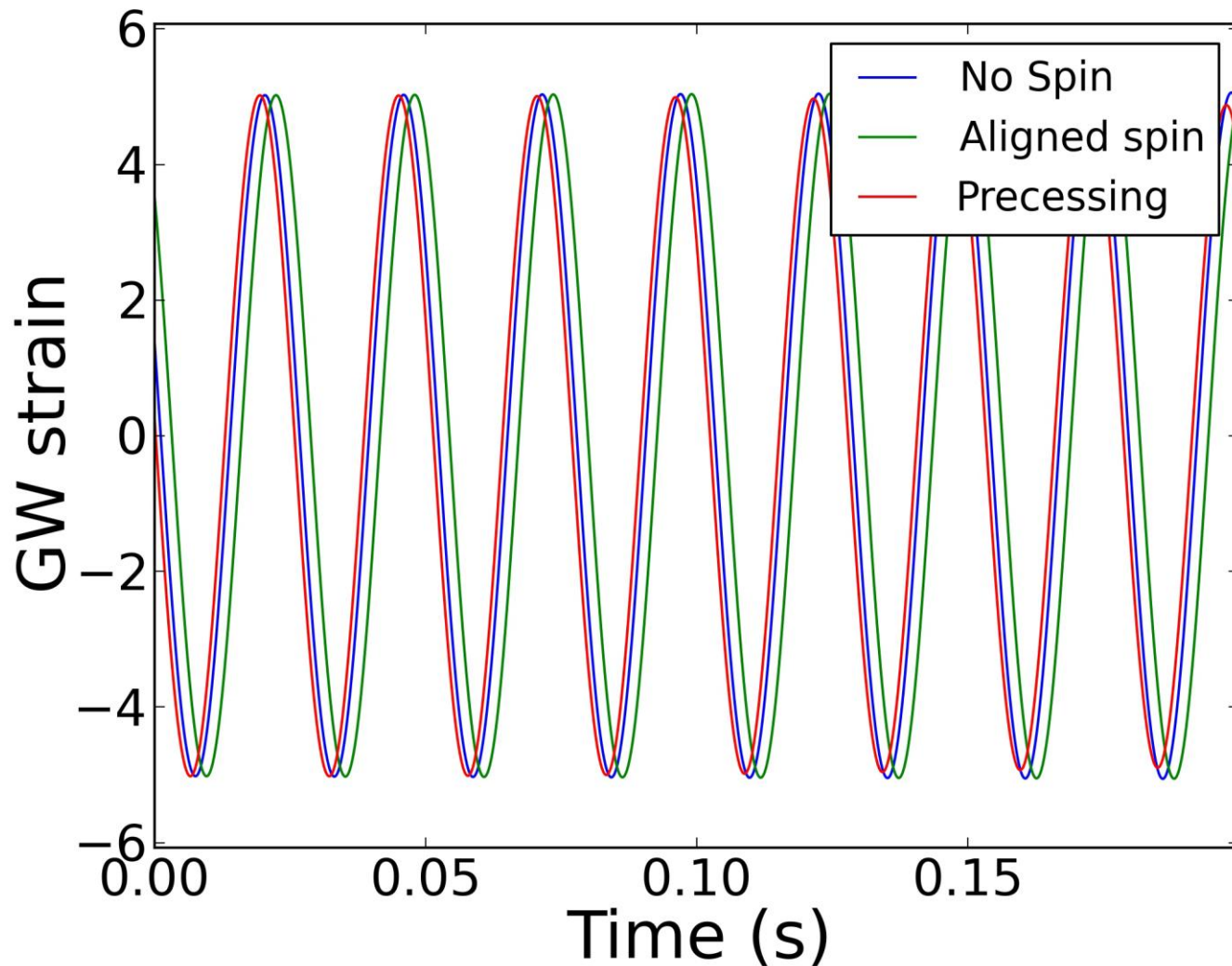
$$\chi_{1,2} = \mathbf{S}_{1,2} / m_{1,2}^2$$

$$\mathbf{S}_1 \cdot \mathbf{L} = \mathbf{S}_2 \cdot \mathbf{L} = 1$$

At  $t=0$ , frequency of GWs for both traces is 40Hz

# Precession

$$m_1 = 1.4M_{\odot}, \quad m_2 = 10M_{\odot}$$



For aligned spin:

$$\chi_1 = \chi_2 = 1$$

$$\chi_{1,2} = \mathbf{S}_{1,2} / m_{1,2}^2$$

$$\mathbf{S}_1 \cdot \mathbf{L} = \mathbf{S}_2 \cdot \mathbf{L} = 1$$

For precessing:

$$\chi_1 = \chi_2 = 1$$

$$\mathbf{S}_1 \cdot \mathbf{L} = \mathbf{S}_2 \cdot \mathbf{L} = 0$$

$$\mathbf{S}_1 \cdot \mathbf{S}_2 = 0$$

At  $t=0$ , frequency of GWs for all traces is 40Hz

# Spin effects

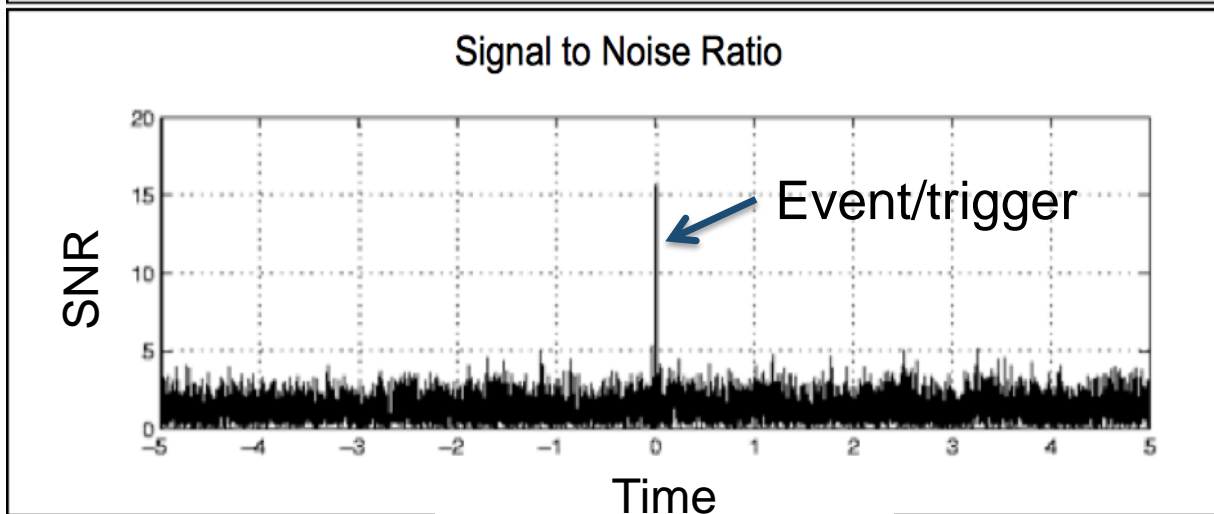
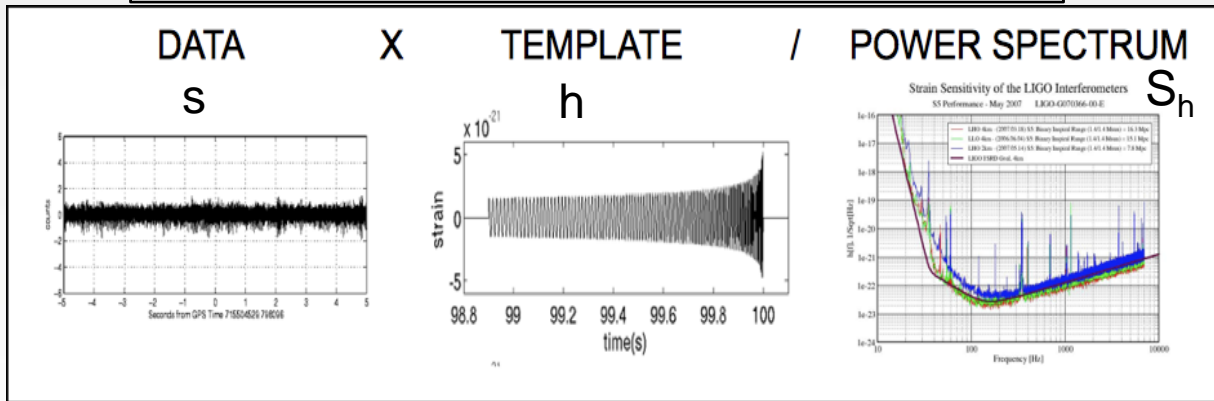
- Spin will also affect the merger, ringdown etc.
- See talks by:
  - Yi Pan (Analytical modeling of spinning systems)
  - Geoffrey Lovelace (Numerical modeling of spin systems)

**How do we search for non-spinning systems?**

**How does this non-spinning search do with spinning signals?**

# Matched-filtering

$$(s|h) = 4 \operatorname{Re} \int_0^\infty \frac{\tilde{s}(f)\tilde{h}^*(f)}{S_h(f)}$$





# Matched-filtering

- Restricting to dominant mode:

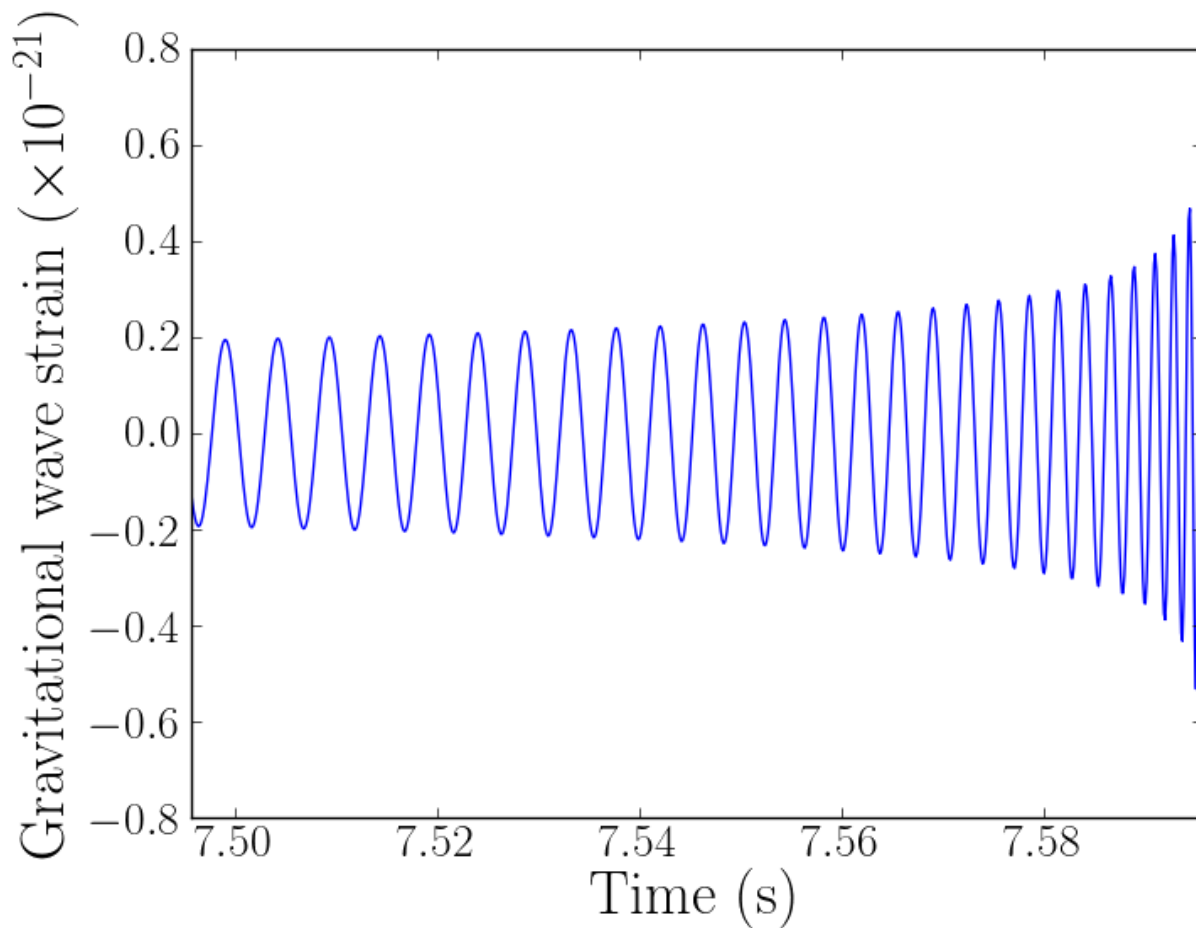
$$\bar{h}(f) = \bar{A}(D, \iota, \theta, \psi, \phi) \mathcal{M}^{5/6} f^{-7/6} \exp \left[ i \left( \Phi(\mathcal{M}, \eta, f) + \bar{\Phi}_0(\iota, \varphi, \theta, \psi, \phi) \right) \right]$$

Orientation and location parameters

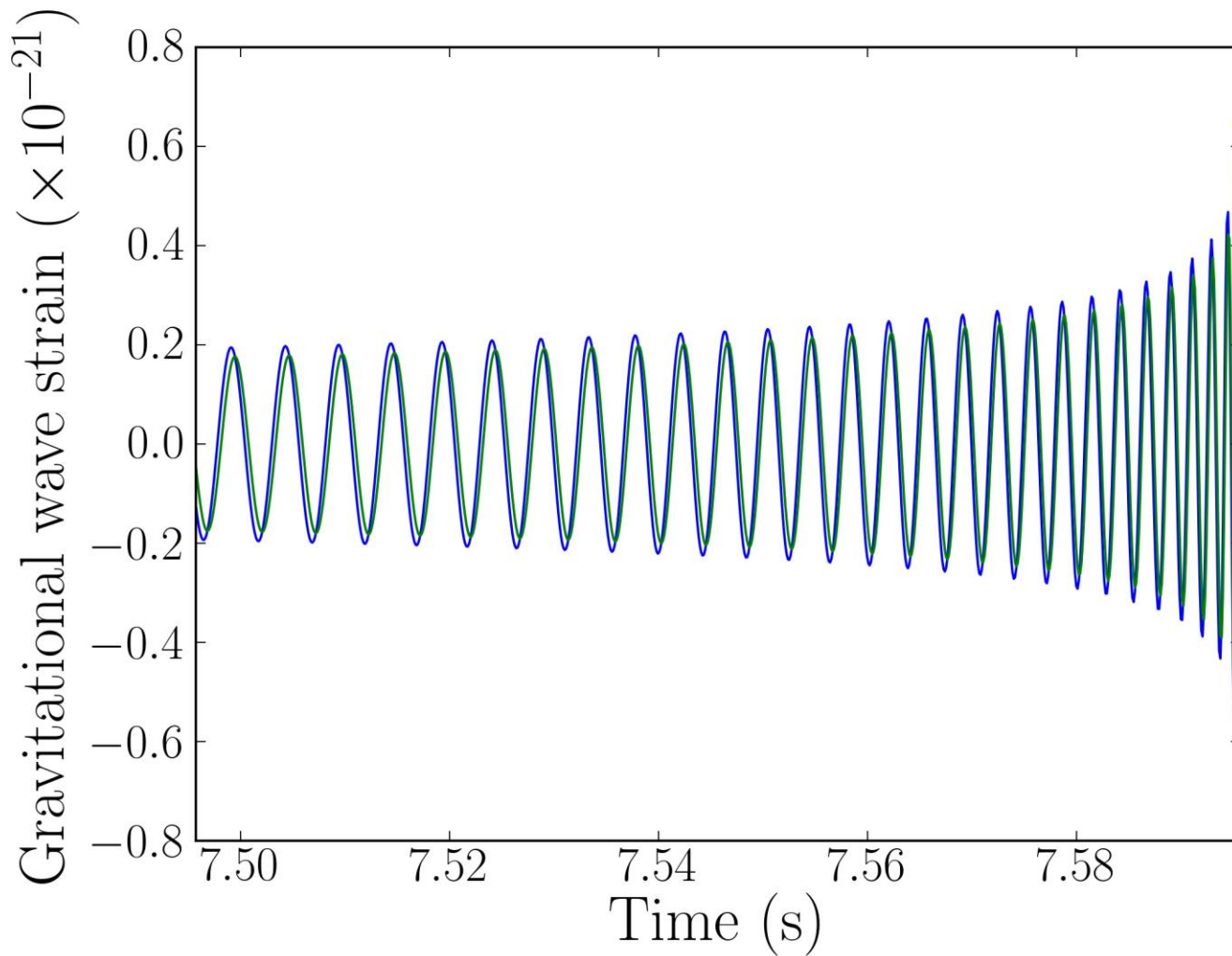


- Orientation and location parameters enter only as amplitude or phase shifts

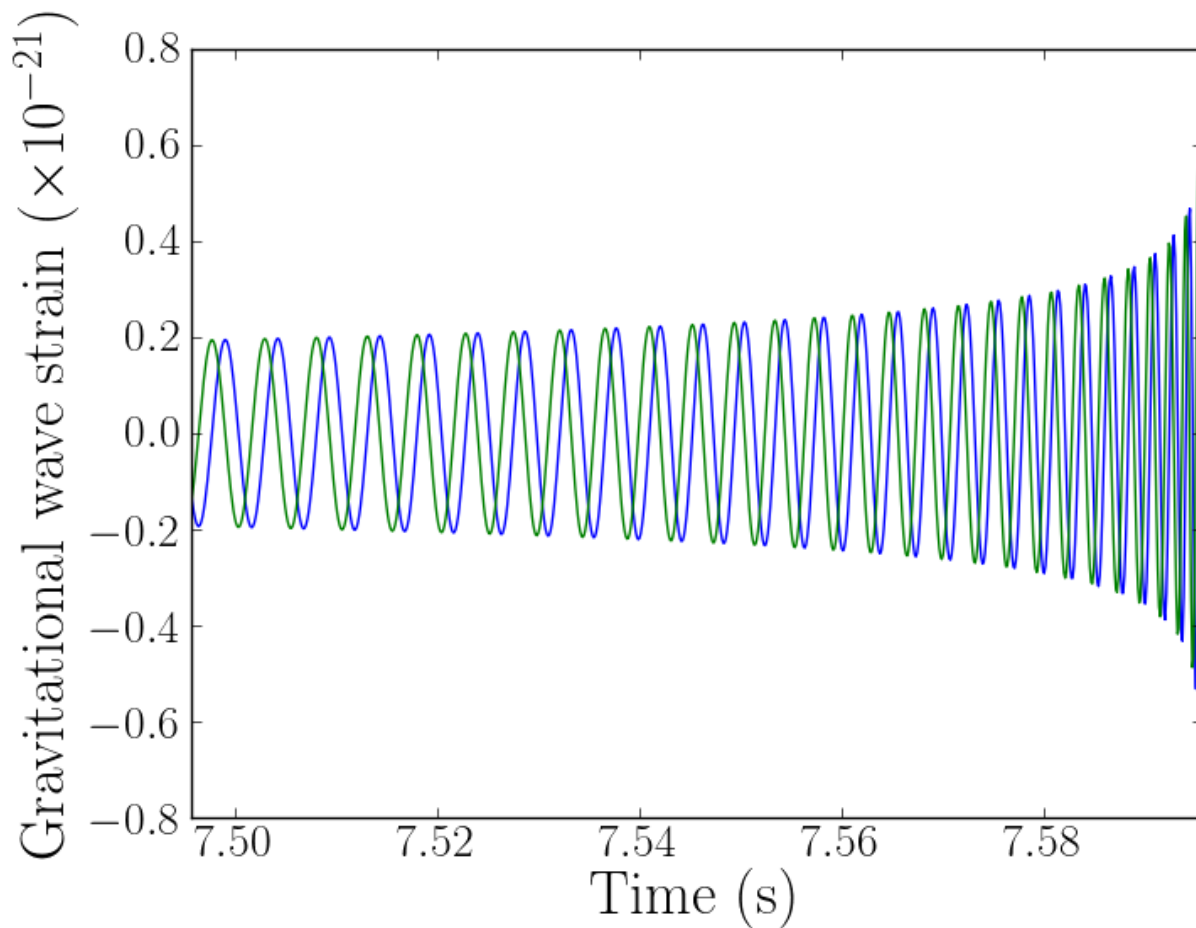
# Non-spin search



# Non-spin search



# Non-spin search



# Maximised SNR

$$(s|h) = 4 \operatorname{Re} \left( \int_0^{\infty} \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right)$$

# Maximised SNR

$$(s|h) = 4 \operatorname{Re} \left( \int_0^{\infty} \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right)$$

Maximise over orientation  and location parameters

$$(s|h)_{\text{maximized}} = 4 \left| \int_0^{\infty} \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right|$$

# Maximised SNR

$$(s|h) = 4 \operatorname{Re} \left( \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right)$$

Maximise over orientation and location parameters

$$(s|h)_{\text{maximised}} = 4 \left| \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right|$$

As a function of the coalescence time

$$(s|h)_{\text{maximised}}(t_c) = 4 \left| \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} e^{-2\pi i f t_c} df \right|$$

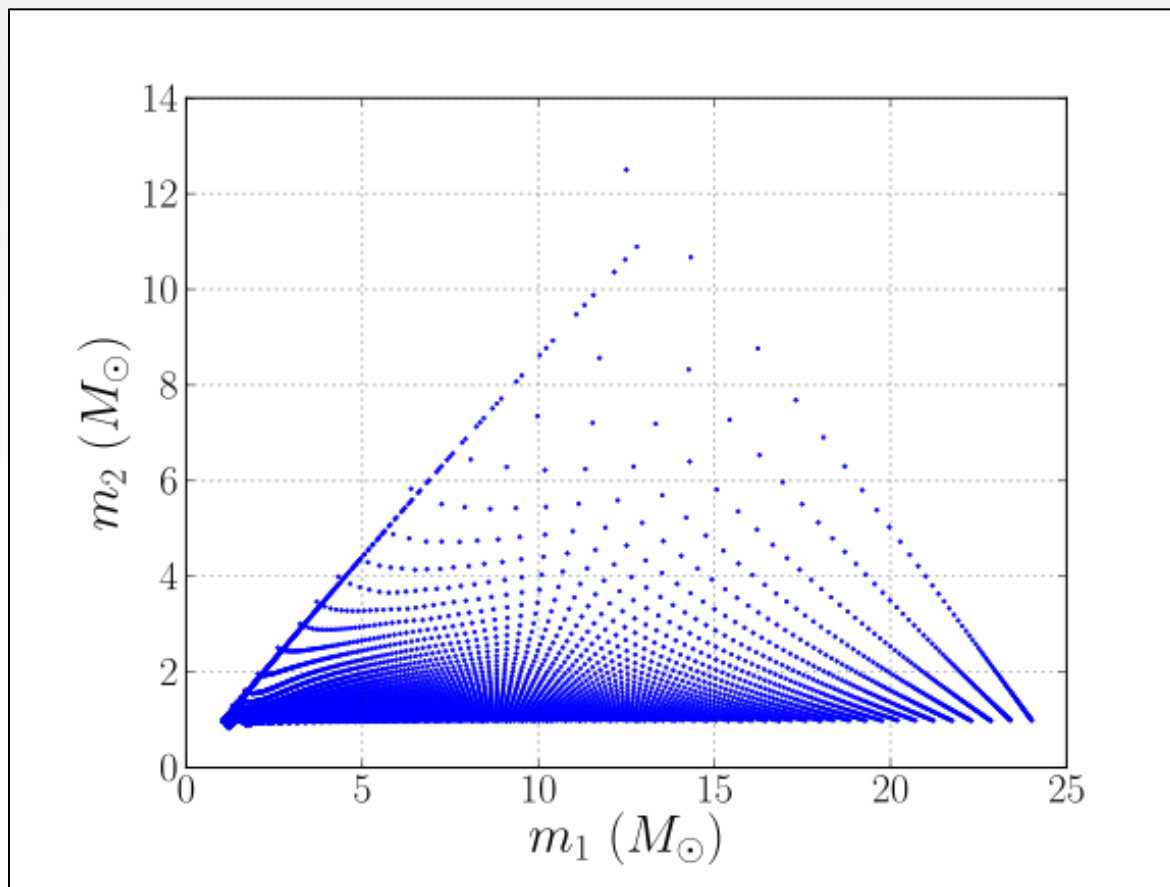
# Masses

- No trick to deal with the mass range – use a bank of filters



# Masses

- No trick to deal with the mass range – use a bank of filters

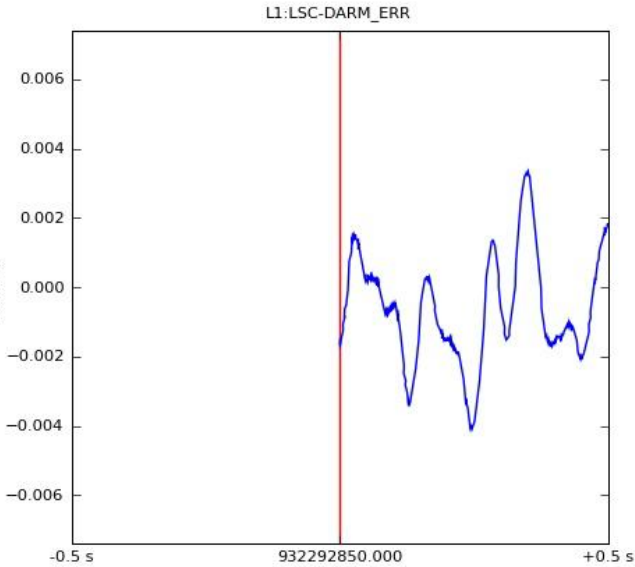
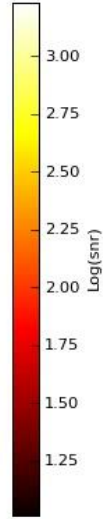
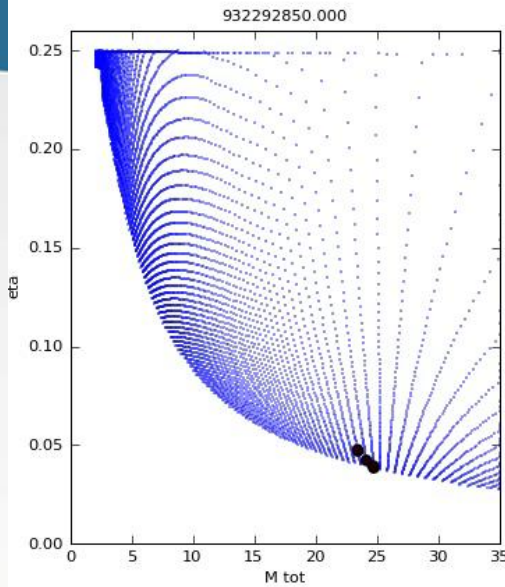


# Mitigating non-Gaussianity

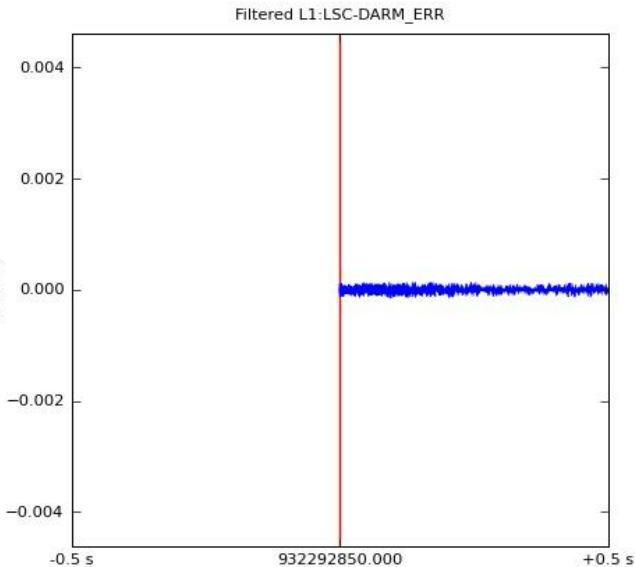
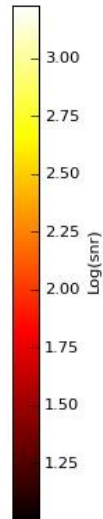
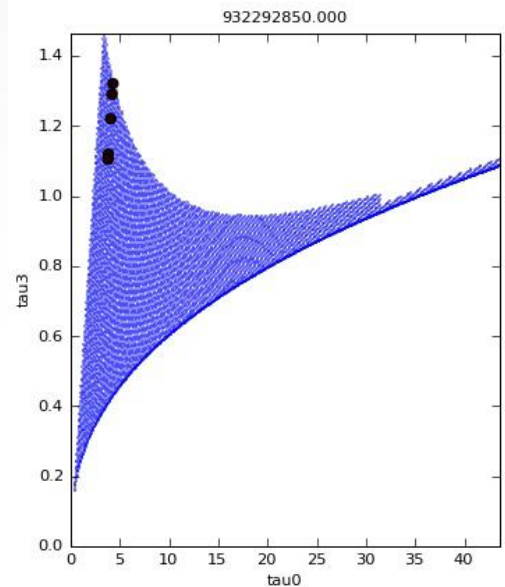
- Non-Gaussian background will cause loud SNR events
- The effect of this is mitigated by:
  - Coincidence test
  - Removing times of poor data quality
  - A set of signal based vetoes, such as chi-squared tests

# Data Analysis – A movie

Bank templates →



Raw data



High-pass filtered data



THANKS to  
Larne  
Pekowsky for  
making this  
movie

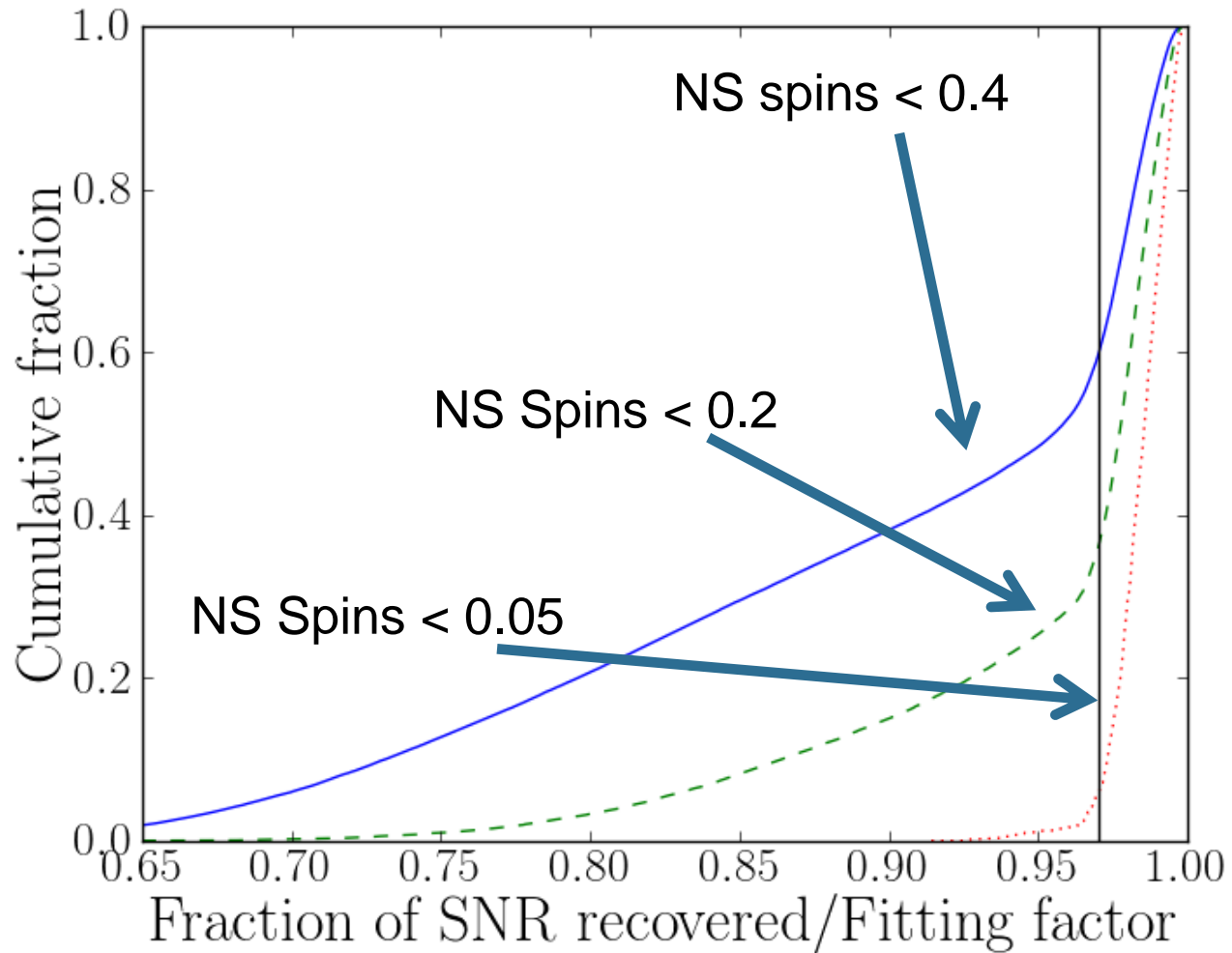
# Is a spinning search needed?

- How well would we do if we used the non-spinning search to search for generic systems?
  - Some SNR would be lost, but how much?
- We can measure this:
  - Create generic waveforms
  - Search for them using the non-spinning bank
  - Determine largest SNR
  - Compare to SNR obtained using exact waveform
  - Known as Fitting Factor

# BNS signal distribution

- Uniform in component masses:
  - Both NSs between 1 and 3 solar masses
- Uniform in component spin magnitudes:
  - Both NSs spin from 0 – 0.05 or 0 – 0.4
- Isotropic in all orientation/location angles
- Analytical inspiral only waveforms (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# BNS non-spinning search

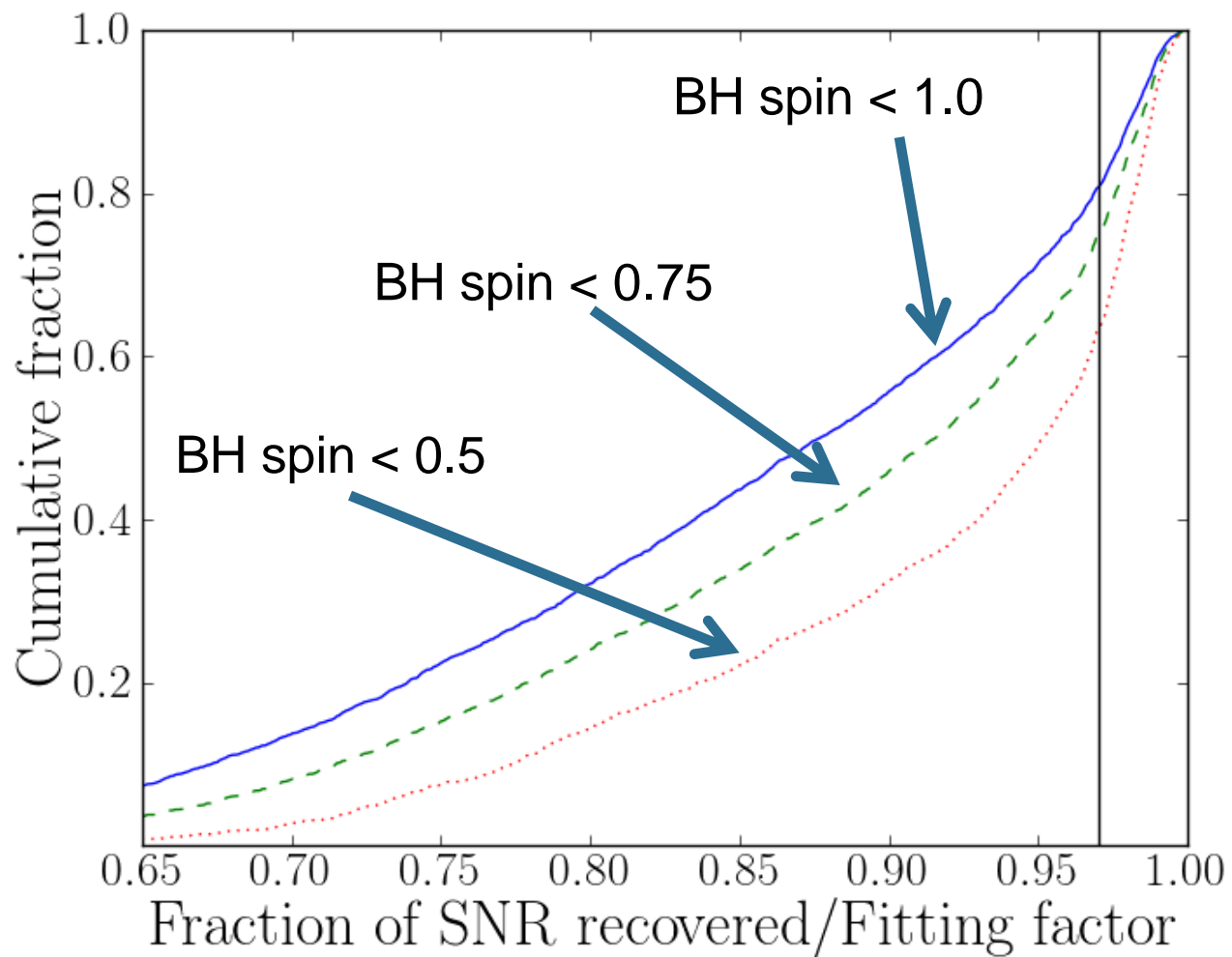


Plot from Brown, IH, Lundgren and Nitz (arXiv:1207.6406)

# NSBH signal distribution

- Uniform in component masses:
  - NSs between 1 and 3 solar masses
  - BHs between 3 and 25 solar masses
- Uniform in component spin magnitudes:
  - NS spin from 0 – 0.4
  - BH spin from 0 - 1
- Isotropic in all orientation/location angles
- Analytical inspiral only waveforms (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# NSBH non-spinning search



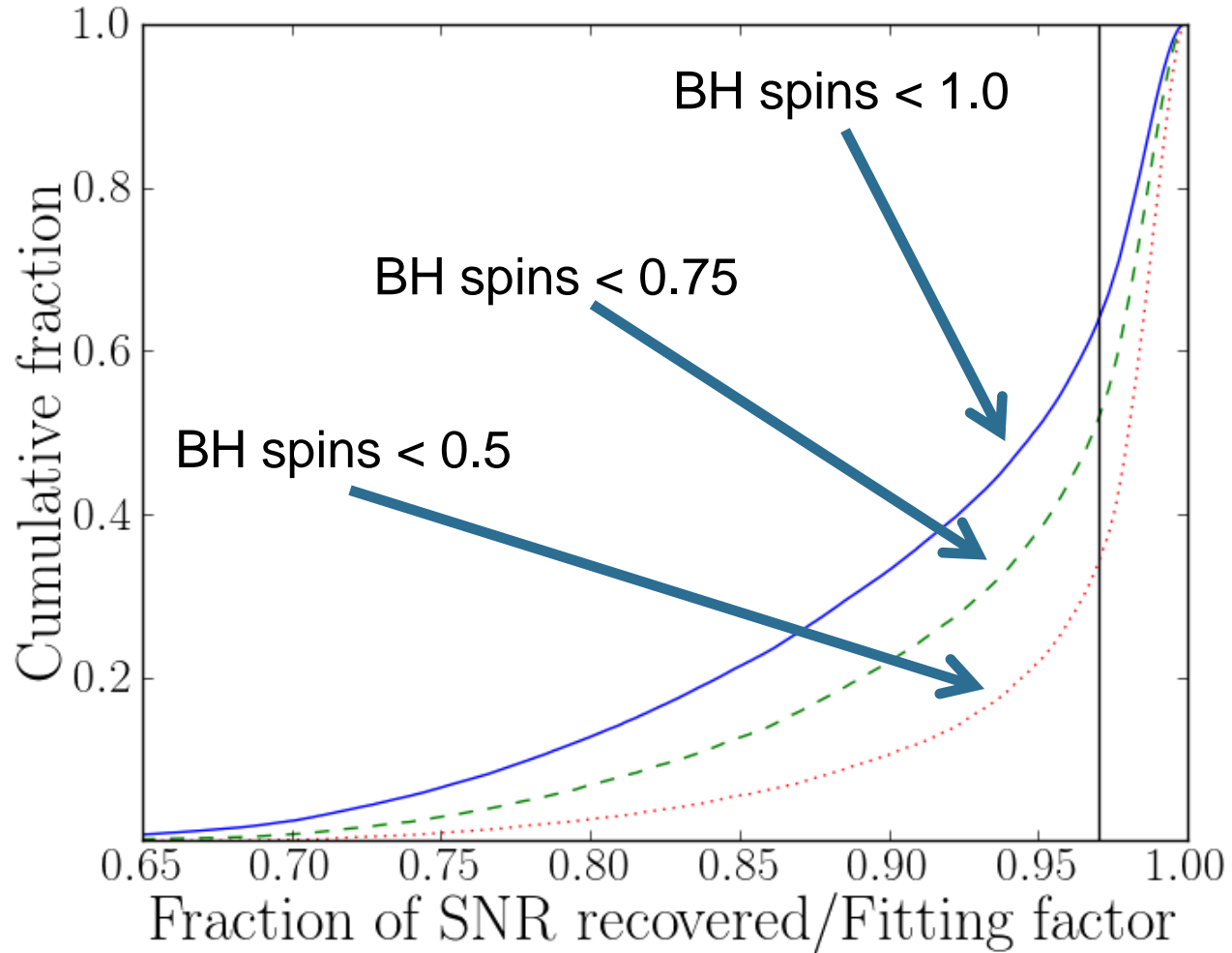
Plot from Brown, IH, Lundgren and Nitz (In preparation)



# BBH signal distribution

- Uniform in component masses:
  - Both BHs between 3 and 25 solar masses
- Uniform in component spin magnitudes:
  - Both BHs spin from 0 – 1
- Isotropic in all orientation/location angles
- **Analytical inspiral only waveforms** (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# BBH non-spinning search



Plot from Brown, IH, Lundgren and Nitz (In preparation)

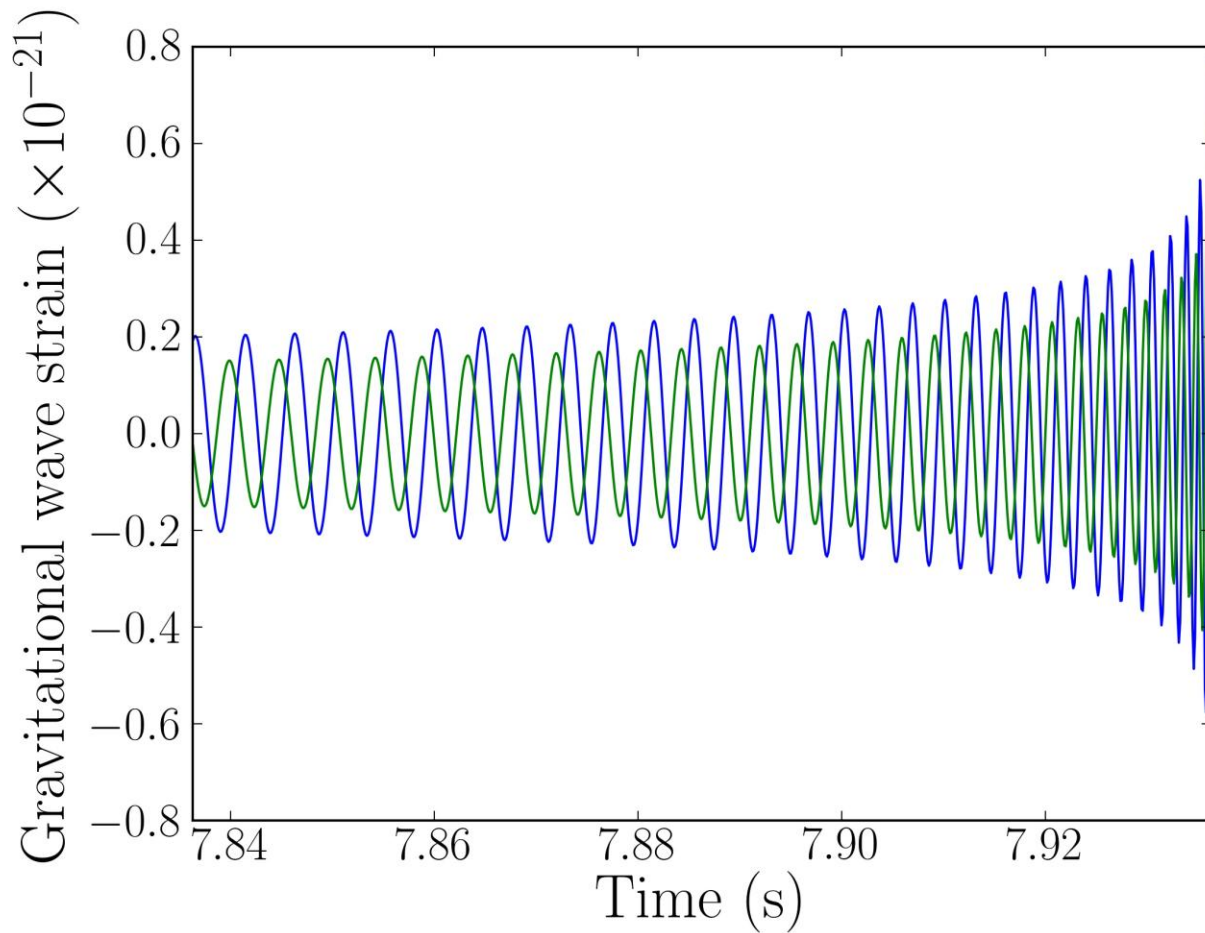
# Summary and caveats

- Employing the non-spinning search in the advanced detector era will result in regions of parameter space where spin will reduce our detection ability
- Results are only as good as the waveforms we have
  - To evaluate BBH performance we really need precessing waveforms with merger and ringdown
  - We did not include any mismatch between the template waveforms and the “signals”
- Results depend on the chosen distribution of signals
  - Restricting the parameter space will help us

**How can we search with aligned-spinning waveforms?**

**How does an aligned-spinning search do with generic signals?**

# Aligned spin



# Maximised SNR

$$(s|h) = 4 \operatorname{Re} \left( \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right)$$

Maximise over orientation and location parameters

$$(s|h)_{\text{maximised}} = 4 \left| \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} df \right|$$

As a function of the coalescence time

$$(s|h)_{\text{maximised}}(t_c) = 4 \left| \int_0^\infty \frac{\bar{s}(f) \bar{h}^*(f)}{S_h(f)} e^{-2\pi i f t_c} df \right|$$

# Aligned spin challenges

- Now have 4 intrinsic parameters (masses **and** spins)

# Aligned spin challenges

- Now have 4 intrinsic parameters (masses **and** spins)
  - Bank of waveforms must be 4 dimensional
  - Geometric placement
    - Brown, IH, Lundgren and Nitz (arXiv:1207.6406)
    - See poster by Alex Nitz
  - Stochastic placement
    - See poster by Stephen Privitera
    - See also: IH, Allen and Sathyaprakash (Phys Rev D 80, 104014)  
Babak (Class.Quant.Grav. 25,195011)



# Aligned spin challenges

- Now have 4 intrinsic parameters (masses **and** spins)
  - **Determining multi-detector coincidence**
    - Demand that the **same** waveform is significant in  $>1$  observatories
    - Cannon et al (Astrophys.J. 748,136)
    - West et al (In progress)

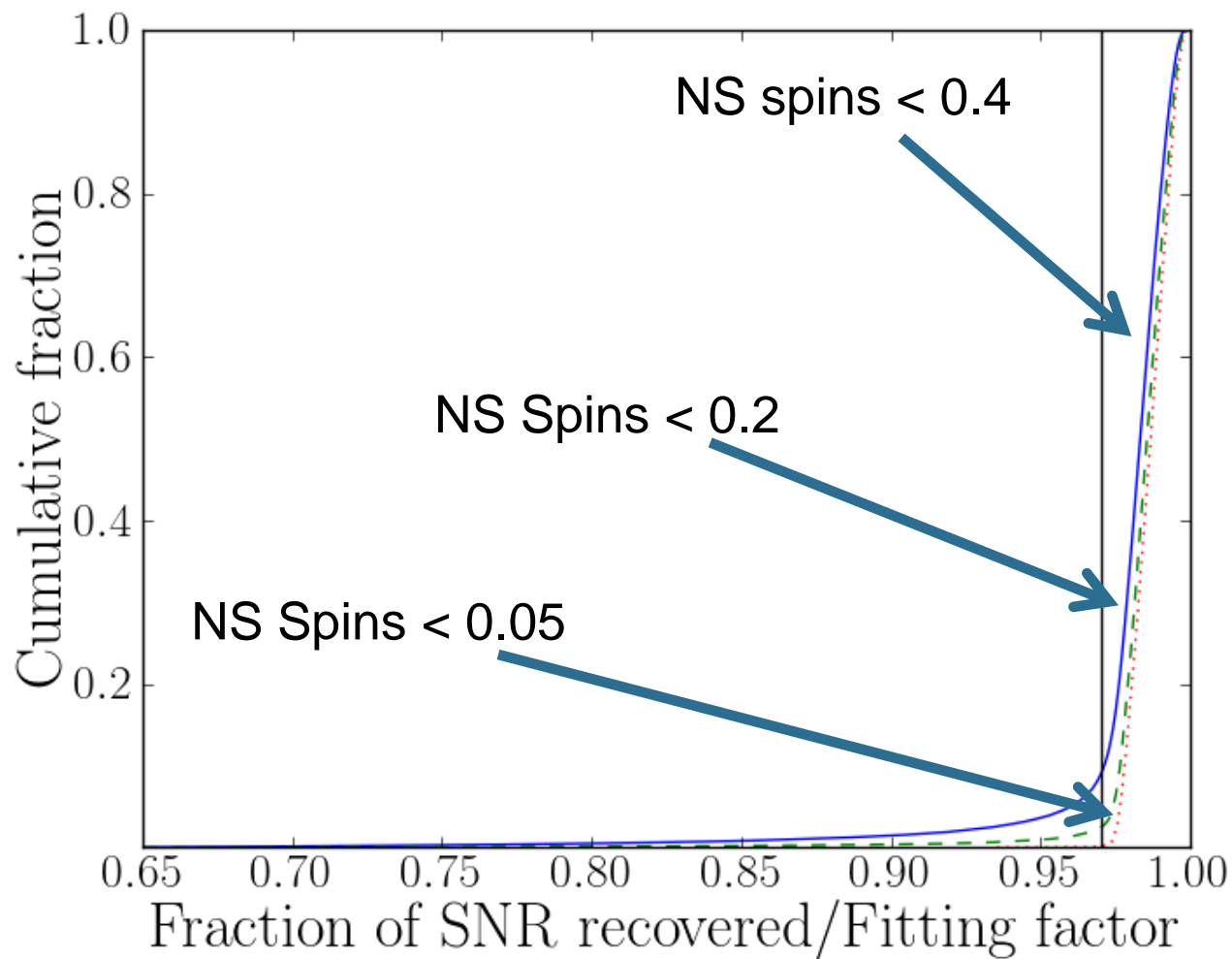
# Aligned spin challenges

- Now have 4 intrinsic parameters (masses **and** spins)
  - More templates = more background events
  - More templates = more computational cost

# BNS signal distribution

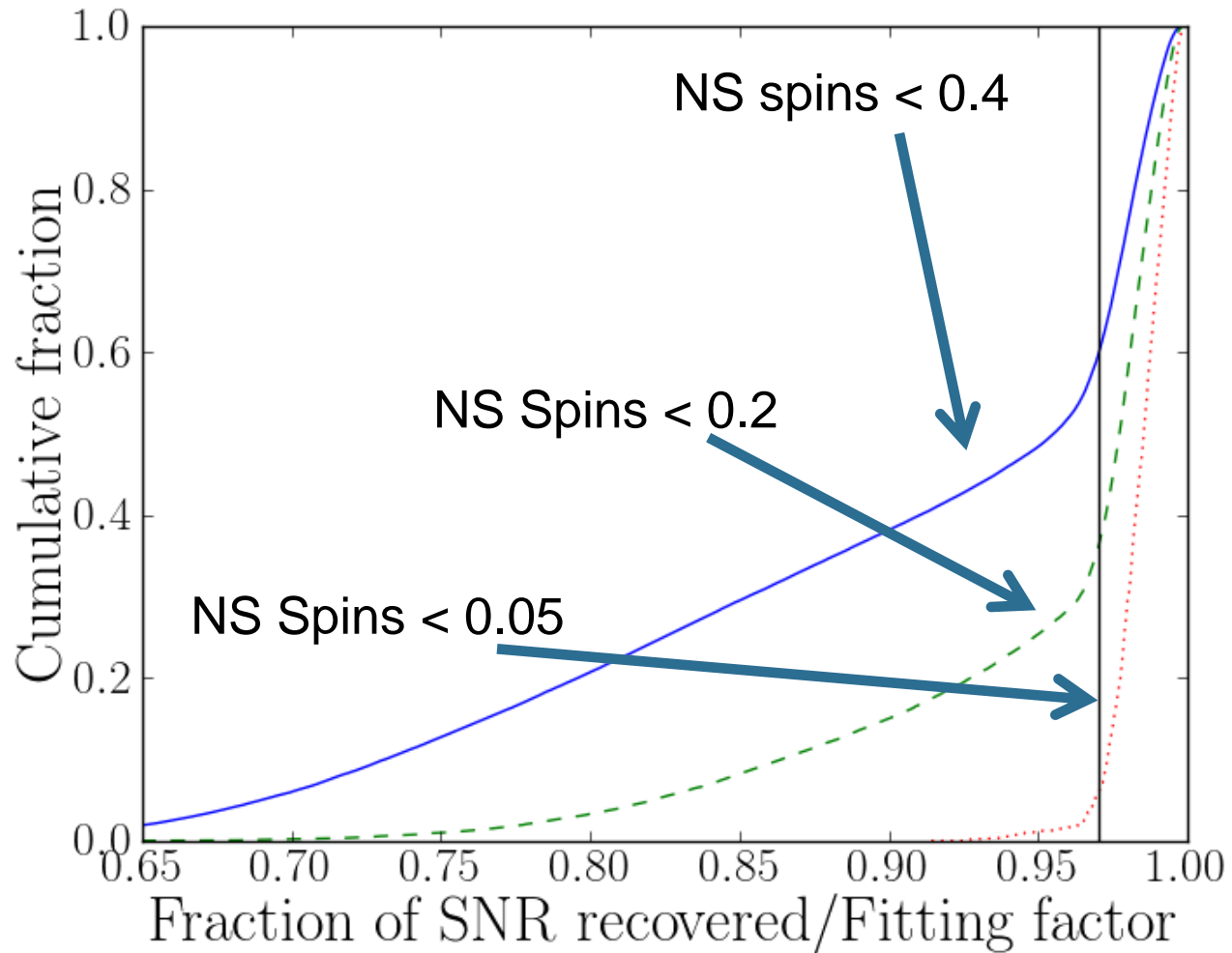
- Uniform in component masses:
  - Both NSs between 1 and 3 solar masses
- Uniform in component spin magnitudes:
  - Both NSs spin from 0 – 0.05 or 0 – 0.4
- Isotropic in all orientation/location angles
- Analytical inspiral only waveforms (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# BNS aligned-spinning search



Plot from Brown, IH, Lundgren and Nitz (arXiv:1207.6406)

# BNS non-spinning search

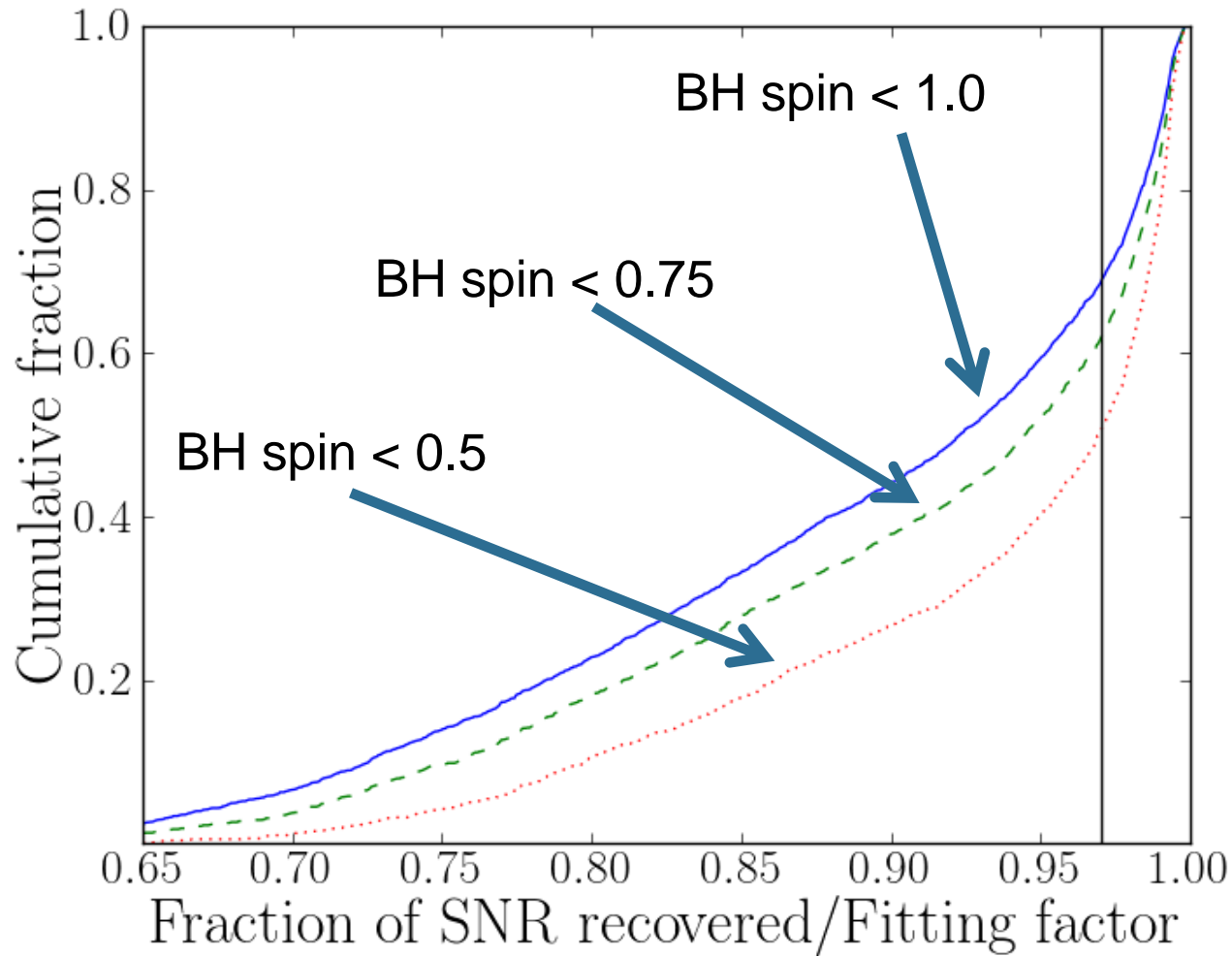


Plot from Brown, IH, Lundgren and Nitz (arXiv:1207.6406)

# NSBH signal distribution

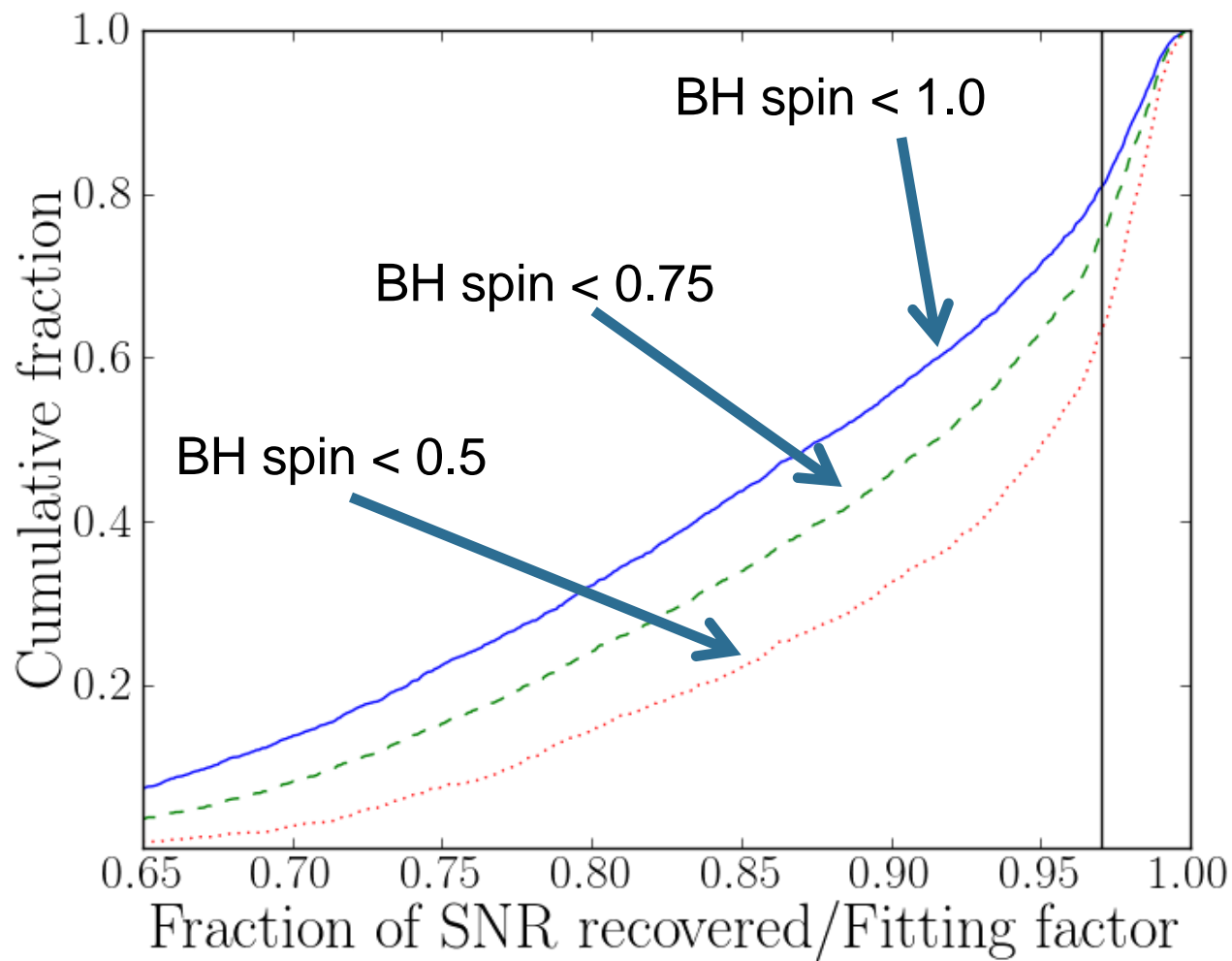
- Uniform in component masses:
  - NSs between 1 and 3 solar masses
  - BHs between 3 and 25 solar masses
- Uniform in component spin magnitudes:
  - NS spin from 0 – 0.4
  - BH spin from 0 - 1
- Isotropic in all orientation/location angles
- Analytical inspiral only waveforms (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# NSBH aligned-spinning search



Plot from Brown, IH, Lundgren and Nitz (In preparation)

# NSBH non-spinning search



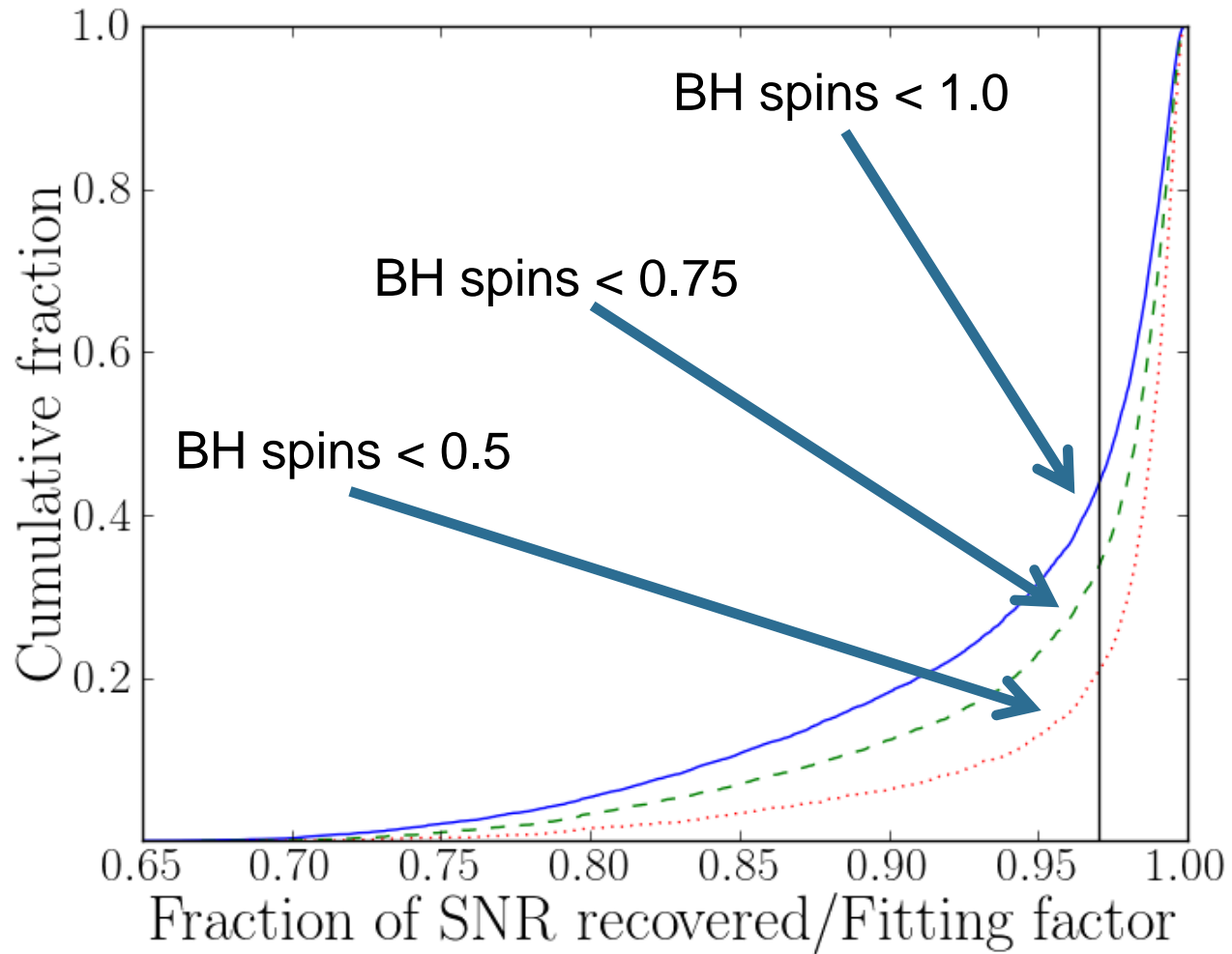
Plot from Brown, IH, Lundgren and Nitz (In preparation)



# BBH signal distribution

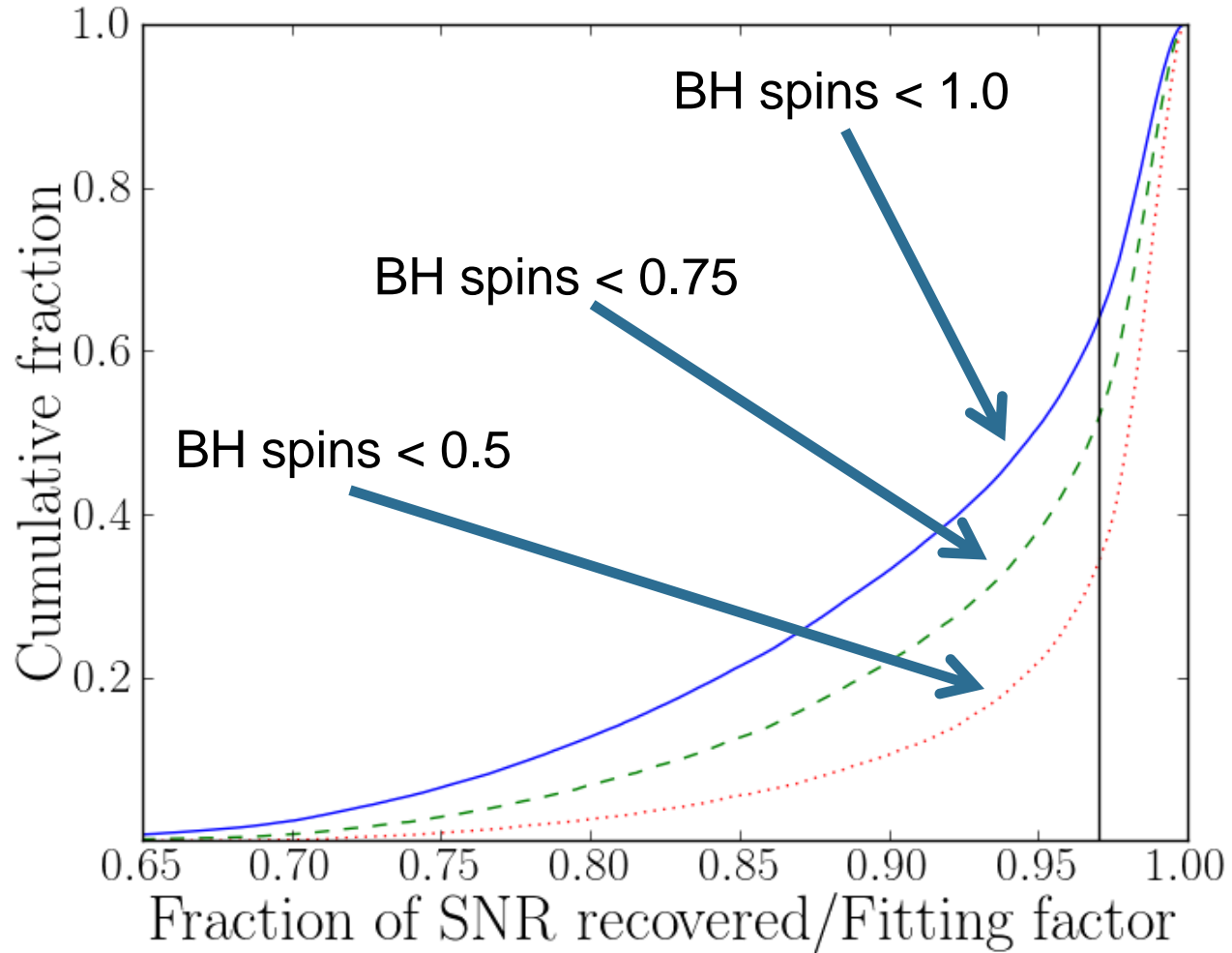
- Uniform in component masses:
  - Both BHs between 3 and 25 solar masses
- Uniform in component spin magnitudes:
  - Both BHs spin from 0 – 1
- Isotropic in all orientation/location angles
- **Analytical inspiral only waveforms** (“TaylorT4”)
- Use aLIGO zero-detuned, high-power sensitivity curve

# BBH aligned-spinning search



Plot from Brown, IH, Lundgren and Nitz (In preparation)

# BBH non-spinning search



Plot from Brown, IH, Lundgren and Nitz (In preparation)

# Aligned spin summary

- With an aligned spin search, signals are picked up with larger SNR.
- BUT precession matters in a significant region of the NSBH and BBH parameter space
- More templates = more background events
- More templates = more computational cost

**How can we search with  
preprocessing waveforms?**

# Dealing with precession?

- If we ignore precession, we will miss systems with certain spin configurations
- To date, no search for precessing systems has been run and published using data from our observatories and has increased detection efficiency relative to a non-spinning search
- Ideas have been proposed and tested!

# Naïve approach

- Why is a precessing search not simply an extension of an aligned spin search?

	<b>Intrinsic Parameters</b>	<b>Number of templates</b>
Non-spin search	Masses (2)	$\sim 10^5$
Aligned-spin search	Masses, Spin amplitudes (4)	$\sim 10^6$
Precessing search	Masses, Spin amplitudes and orientations, inclination, polarization (>8)	????

# Phenomenological templates

- Idea: Use unphysical templates that match well with real, precessing templates
- Reality: Tried in searches in S4 and S5, efficiency less than that of a non-spinning search
- Why?
  - Increased freedom meant background triggers were louder
  - No adequate glitch-rejection technique was available

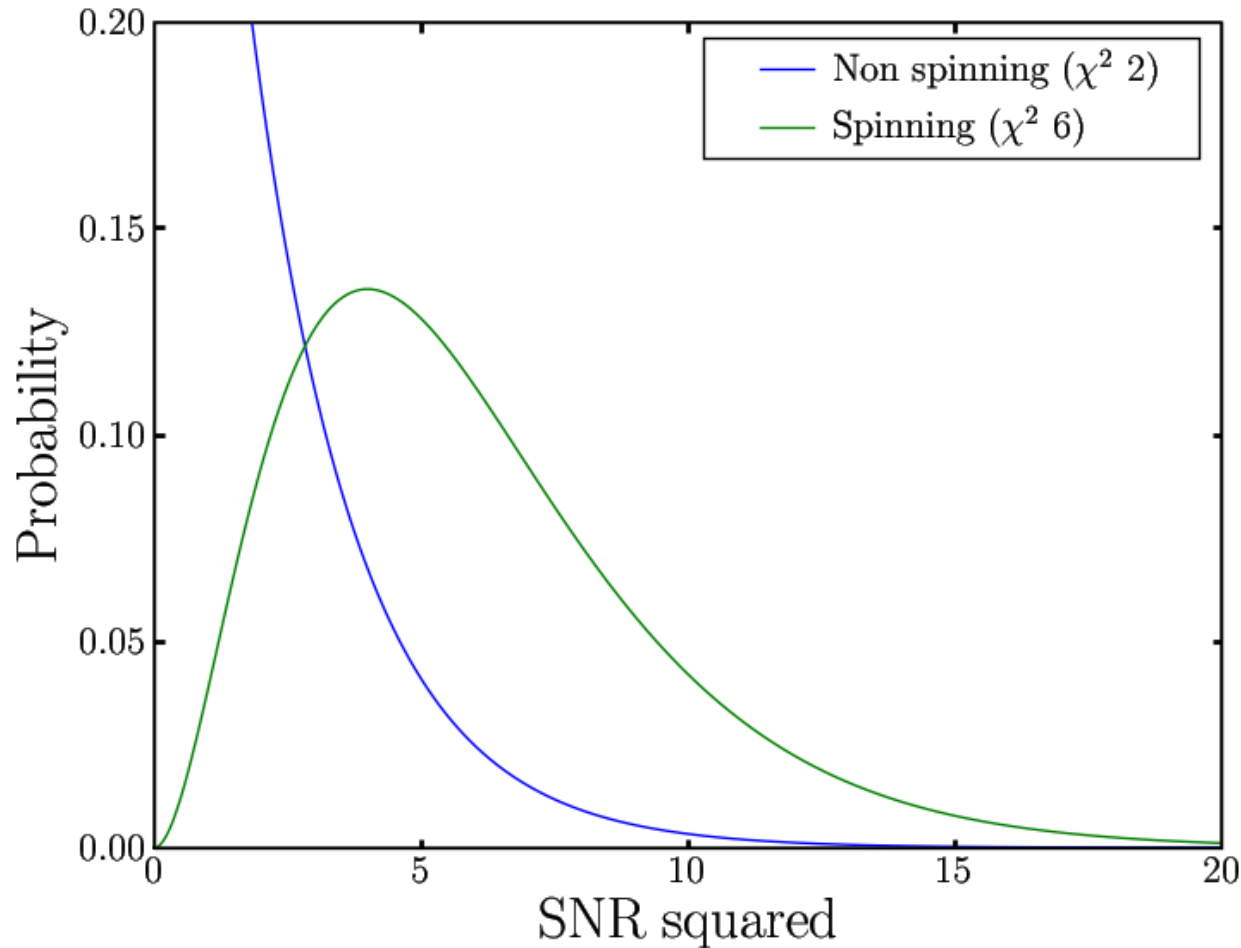


# Physical template family

- Idea:

- Restrict to single spin systems; good for NSBH
- Decompose waveform into 5 basis vectors to reduce to 4 intrinsic parameters:
  - masses,  $|\mathbf{S}|$  and  $\mathbf{S}\cdot\mathbf{L}$
- Different combinations of the 5 basis vectors correspond to different values of extrinsic parameters

# Physical template family



- Background events will be louder
- Only useful if aligned-spin search recovers  $< 88\%$  of SNR

# Other effects

- What about sub-dominant amplitude modes?
- What about eccentricity?
- What about matter effects?
- Are our waveform models accurate in all regimes?
- What if the signal is not quite what we expect

# Conclusions

- We have a lot of experience with non-spinning searches
- We know how to conduct aligned spinning searches
- There are ideas for how to conduct a precessing search, but so far nothing that increases efficiency
- Detecting all possible systems is vital if we want to do astrophysics in the coming years

**END**

A decorative blue wave graphic at the top of the page, consisting of two overlapping curved bands in shades of blue. The top band is a lighter blue, and the bottom band is a darker blue. The wave starts on the left and curves upwards towards the right.

# Phase changes

- Spin affects the frequency evolution of a CBC

$$\begin{aligned}
 \frac{\dot{\omega}}{\omega^2} = & \frac{96}{5} \eta (M\omega)^{5/3} \left\{ 1 - \frac{743 + 924\eta}{336} (M\omega)^{2/3} - \left( \frac{1}{12} \sum_{i=1,2} \left[ \chi_i (\hat{\mathbf{L}}_N \cdot \hat{\mathbf{S}}_i) \left( 113 \frac{m_i^2}{M^2} + 75\eta \right) \right] - 4\pi \right) (M\omega) \right. \\
 & + \left\{ \left( \frac{34103}{18144} + \frac{13661}{2016} \eta + \frac{59}{18} \eta^2 \right) - \frac{1}{48} \eta \chi_1 \chi_2 \left[ 247 (\hat{\mathbf{S}}_1 \cdot \hat{\mathbf{S}}_2) - 721 (\hat{\mathbf{L}}_N \cdot \hat{\mathbf{S}}_1) (\hat{\mathbf{L}}_N \cdot \hat{\mathbf{S}}_2) \right] \right\} (M\omega)^{4/3} \\
 & - \frac{1}{672} (4159 + 15876\eta) \pi (M\omega)^{5/3} + \left[ \left( \frac{16447322263}{139708800} - \frac{1712}{105} \gamma_E + \frac{16}{3} \pi^2 \right) + \left( -\frac{273811877}{1088640} + \frac{451}{48} \pi^2 - \frac{88}{3} \hat{\theta} \right) \eta \right. \\
 & \left. + \frac{541}{896} \eta^2 - \frac{5605}{2592} \eta^3 - \frac{856}{105} \log [16(M\omega)^{2/3}] \right] (M\omega)^2 + \left( -\frac{4415}{4032} + \frac{358675}{6048} \eta + \frac{91495}{1512} \eta^2 \right) \pi (M\omega)^{7/3} \left. \right\},
 \end{aligned}$$

Extra terms due to spin of system

# Precession

- If spins and orbital angular not aligned the system will precess

$$\dot{\mathbf{S}}_1 = \alpha(m_1, m_2, \mathbf{S}_2) \mathbf{S}_1 \times \mathbf{L}_N + \beta(m_1, m_2) \mathbf{S}_1 \times \mathbf{S}_2$$

$$\dot{\mathbf{S}}_2 = \alpha(m_2, m_1, \mathbf{S}_1) \mathbf{S}_2 \times \mathbf{L}_N + \beta(m_2, m_1) \mathbf{S}_2 \times \mathbf{S}_1$$

$$\dot{\mathbf{L}}_N = \gamma(m_1, m_2, \mathbf{S}_2) \mathbf{S}_1 \times \mathbf{L}_N + \gamma(m_2, m_1, \mathbf{S}_1) \mathbf{S}_2 \times \mathbf{L}_N$$

$\dot{\mathbf{L}}_N$  -> orbital angular momentum (to dominant order)