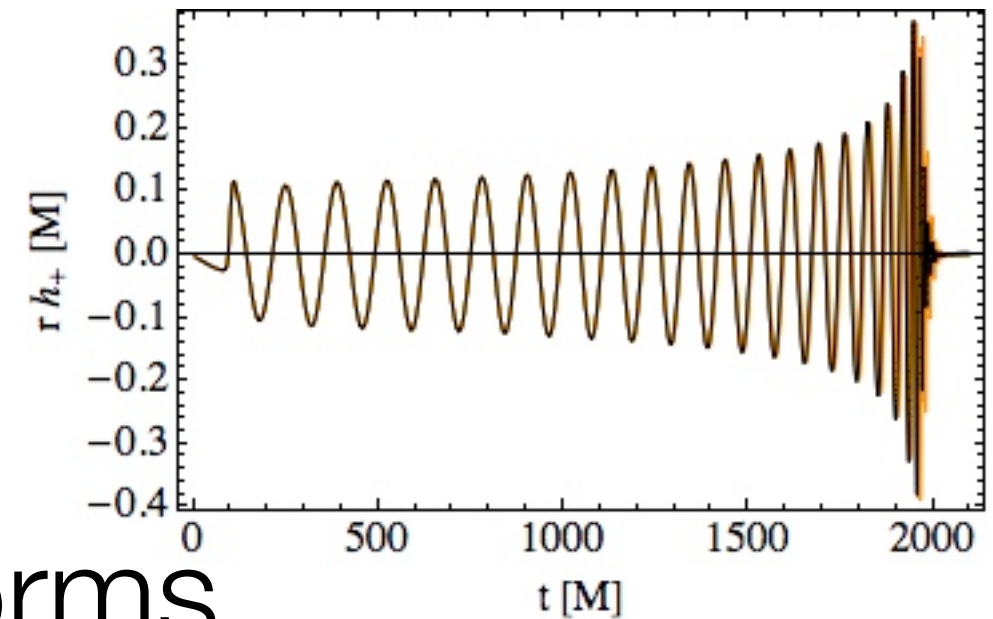


For a few digits more ...

Length and Accuracy of Numerical Relativity Waveforms



GW detectors cost \$\$\$ - make sure we find as many signals & identify sources as accurately as the hardware allows!

S. Husa

Universitat de les Illes Balears

Chirps, Mergers and Explosions,
KITP 2012

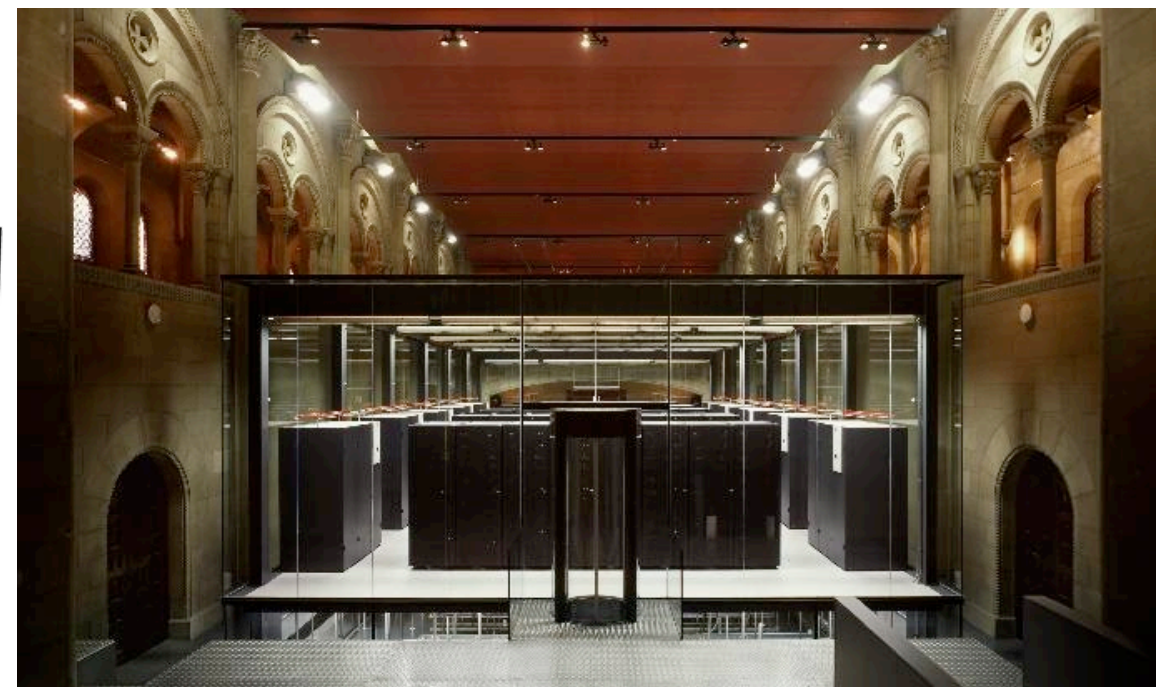
**Advanced detectors put NR on a tight timeline to show its worth:
~ 2015/2018 for early/design sensitivity aLIGO!**

**Theorists may be cheap,
computer time expensive**

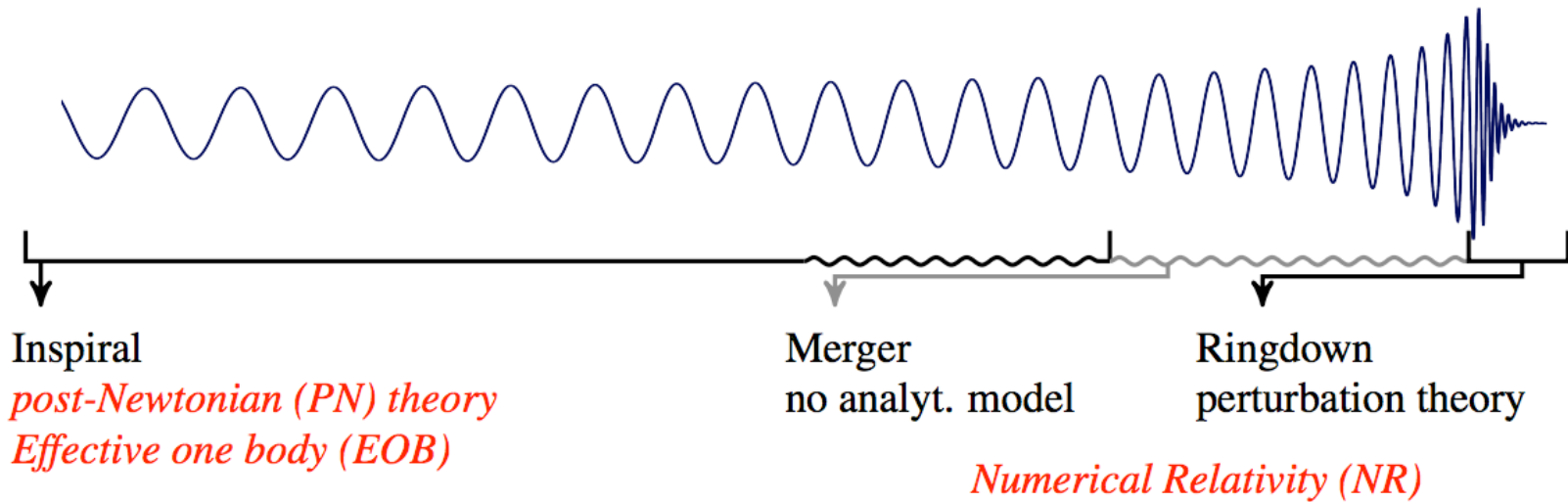
Acknowledgements



- Collaborators from: UIB, Cardiff, Jena, CalTech, AEI:
 - P Ajith, B Brüggmann, M Hannam, Nathan Johnson-McDaniel, F Ohme, D Pollney, M Pürrer, A Vaño Viñuales, C Reisswig, M Ruiz, P Schmidt, M Thierfelder
- Discussions with members of SXS collaboration
- Computertime: PRACE [Hermit, Curie], BSC, LRZ



Entire WFs & end-to-end errors



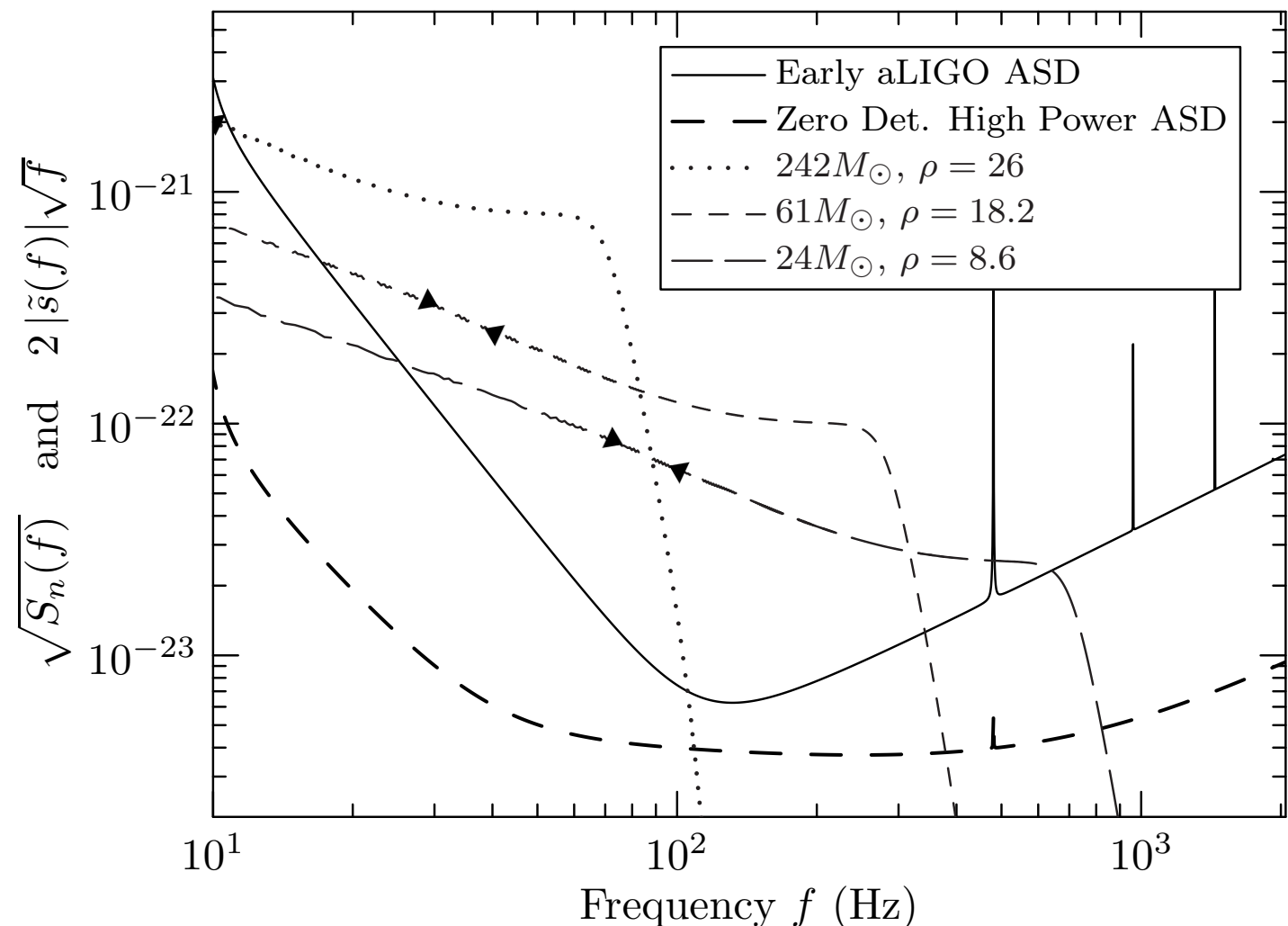
- Comparison of pN approximants [Buonanno+, PRD '09]: $M \geq 12M_{\odot}$ requires NR for construction of optimal detection templates.

- Unknown higher order PN terms ->

- zoo of PN approximants: TaylorT*, TaylorF*, EOB*, ...

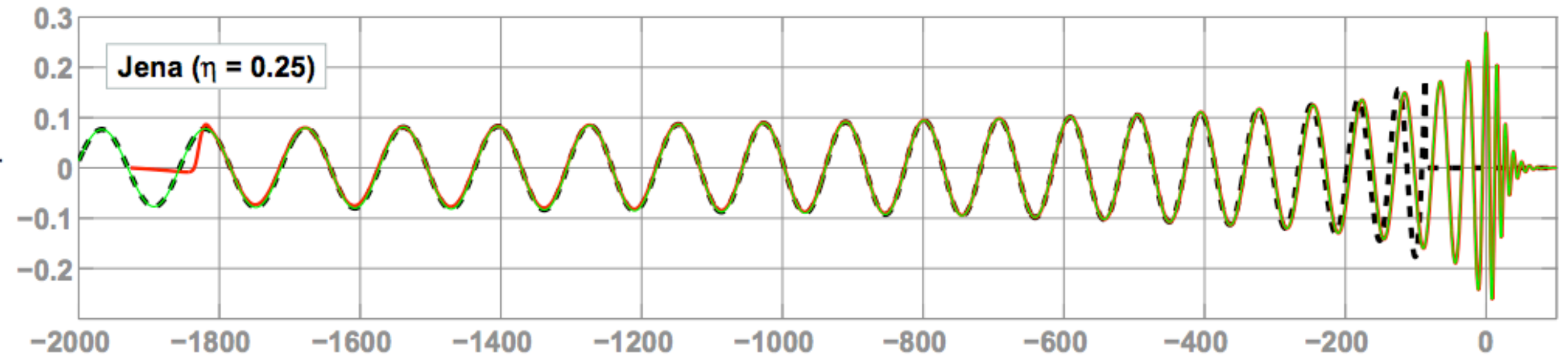
- Combined error in PN/NR/matching/parameter space modeling?

- Effect on detection & parameter estimation?



Hybrid PN-NR waveforms

Choose a frequency, least squares fit time and phase shift between NR and PN WFs in a suitable interval around that frequency.



Different hybridization methods appear to have comparable performance, e.g. Santamaría+ '10 compares time and freq. domain methods.

Main influence on hybridization error from fitting window.

Tradeoff:

fit early: PN errors minimized

fit late: fitting problem is better conditioned (stronger WF variation)

Alternative approach: tuning of Effective-One-Body version of PN (EOBNR)

Waveform Overlap

- WF error in matched filter context is naturally defined in terms of overlap:

$$\langle h_1, h_2 \rangle = \max_{\phi_0, t_0} 4\Re \int_{f_1}^{f_2} \frac{\tilde{h}_1(f) \tilde{h}_2^*(f)}{S_n(f)} df$$

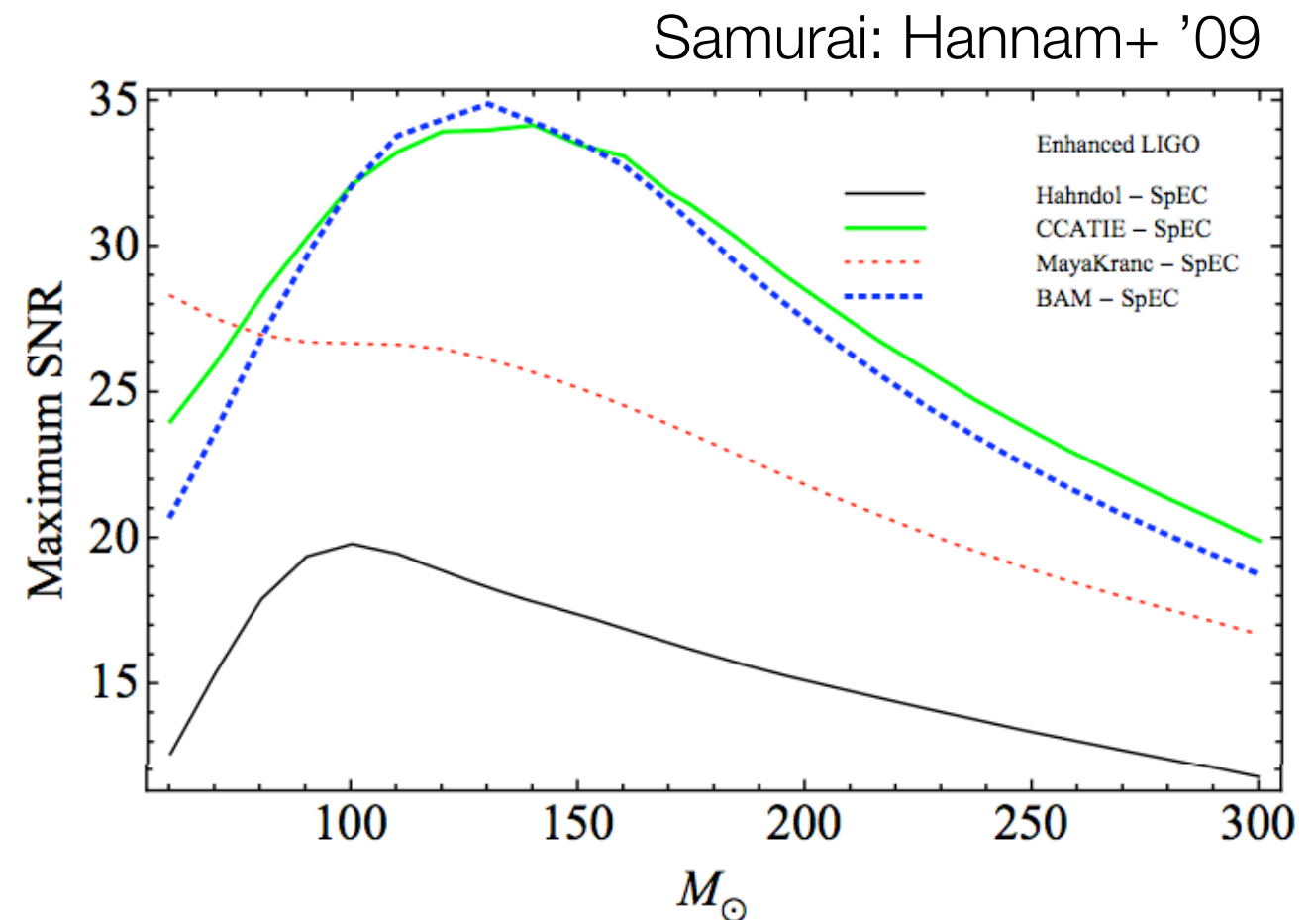
$$\|\Delta h\|^2 = \langle h_1 - h_2, h_1 - h_2 \rangle$$

$$\mathcal{M} = 1 - \langle h_1, h_2 \rangle / (\|h_1\| \|h_2\|)$$

$$\text{SNR: } \rho = \|h\|$$

indistinguishable: $\|\Delta h\|^2 < 1$ Fairhurst, KITP 2008

$$\|h_1\| \approx \|h_2\| \Rightarrow \|\Delta h\|^2 = 2\rho^2 \mathcal{M}$$

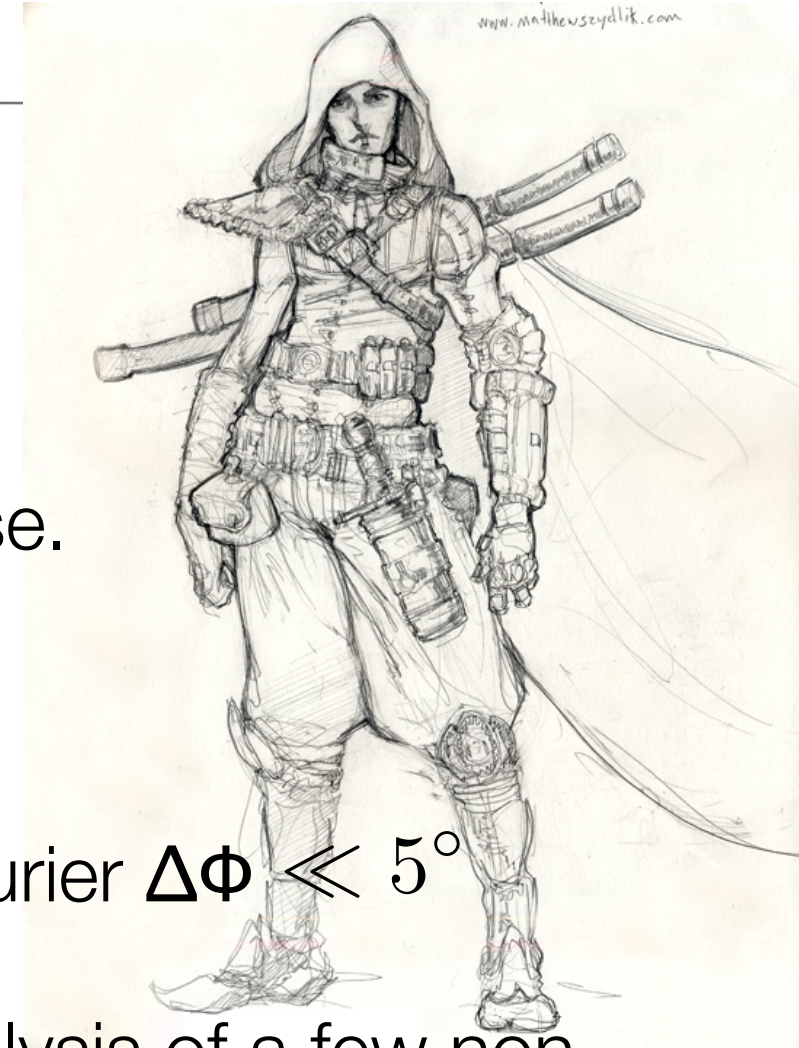


M=3% \approx 10 % signal loss, M=0.5 %, 0.2 % undistinguishable @ SNR 10,16.

- Searches & parameter estimation use WF families - maximize over mass, spins, ...
- Computing M with fixed physical parameters can drastically overestimate accuracy requirements: small bias in physical parameters may have large effect on match.

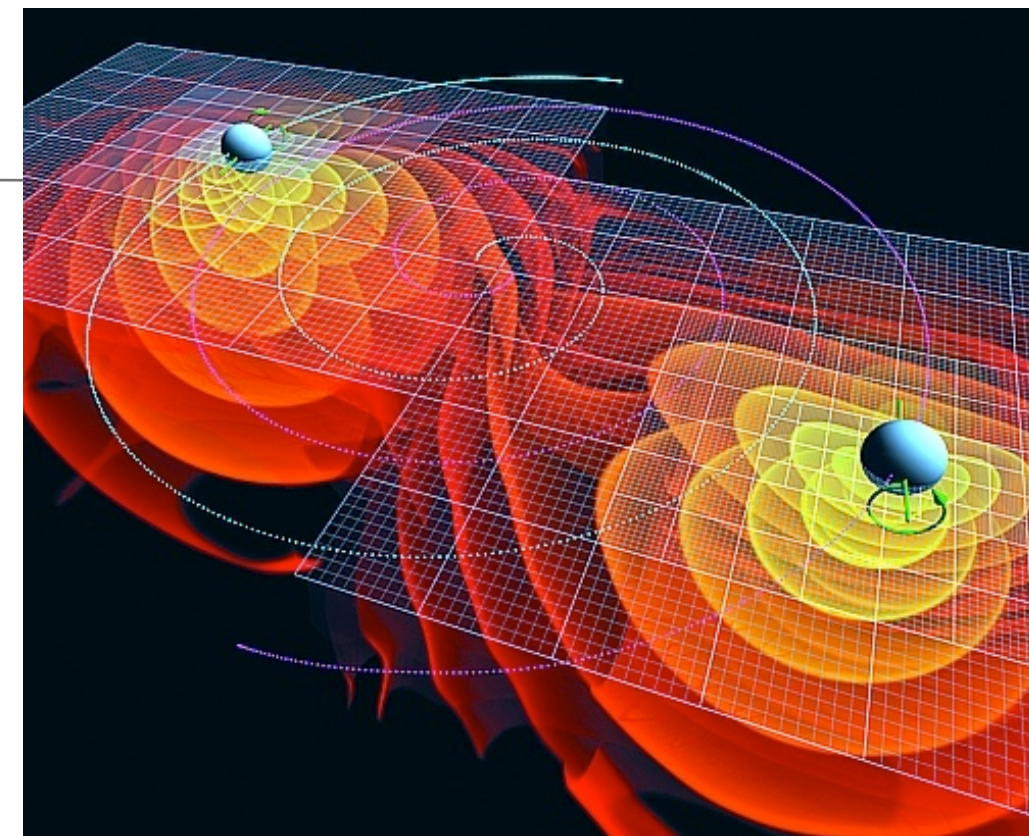
Conclusions

- Ultimately: want to understand WF errors in the context of actual LIGO/Virgo noise and GW searches.
- **ninja-project.org**: NR+PN WFs -> S6/VSR23 noise.
- Now: theoretical results, based on Gaussian noise.
- May account for calibration error by demanding Fourier $\Delta\phi \ll 5^\circ$
- So far our understanding is based on simplified analysis of a few non-precessing cases [**trust me and die**]:
 - NR & hybridization errors much smaller than PN uncertainty.
 - > 5-10 NR orbits help detection significantly, parameter bias ok < 2018?
 - “slow inspiral”: much better accuracy requires **much longer** WFs.
 - **A lot more work is required** [Perfect! More papers, students, ...]



Cost & error

- computational cost in 3+1 D: $\propto \Delta x^{-3} \Delta t^{-1}$
 - x 2 resolution -> x 16 computational cost
- convergence: $X(\Delta x) = X_0 + e\Delta x^n + O(\Delta x^{n+1})$
 - 3 resolutions determine X_0, e, n

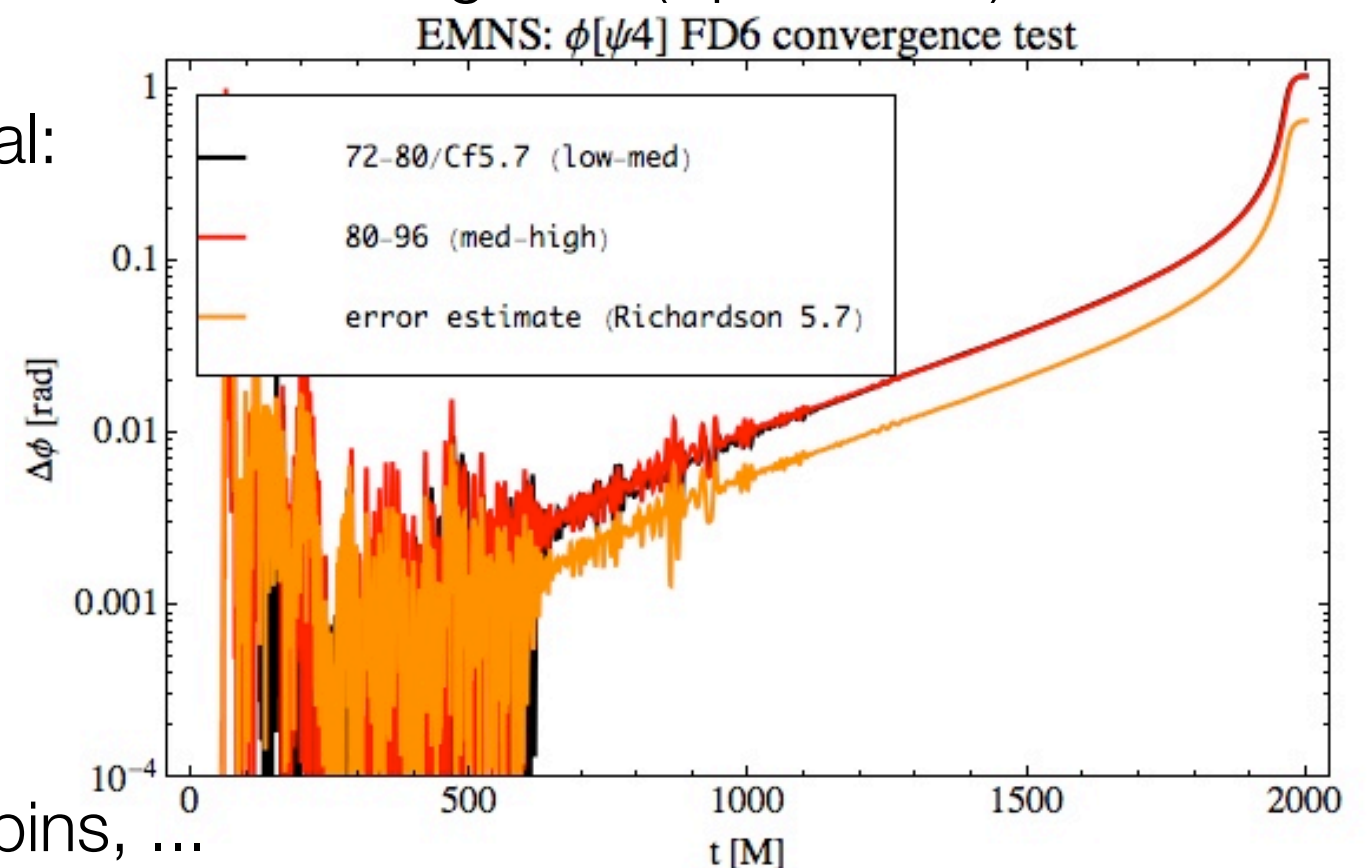


- typical n: 6-10; spectral code: exponential convergence (SpEC/SXS)
- dominant error at least for BBH inspiral:
 - dephasing

- neglected in this talk:

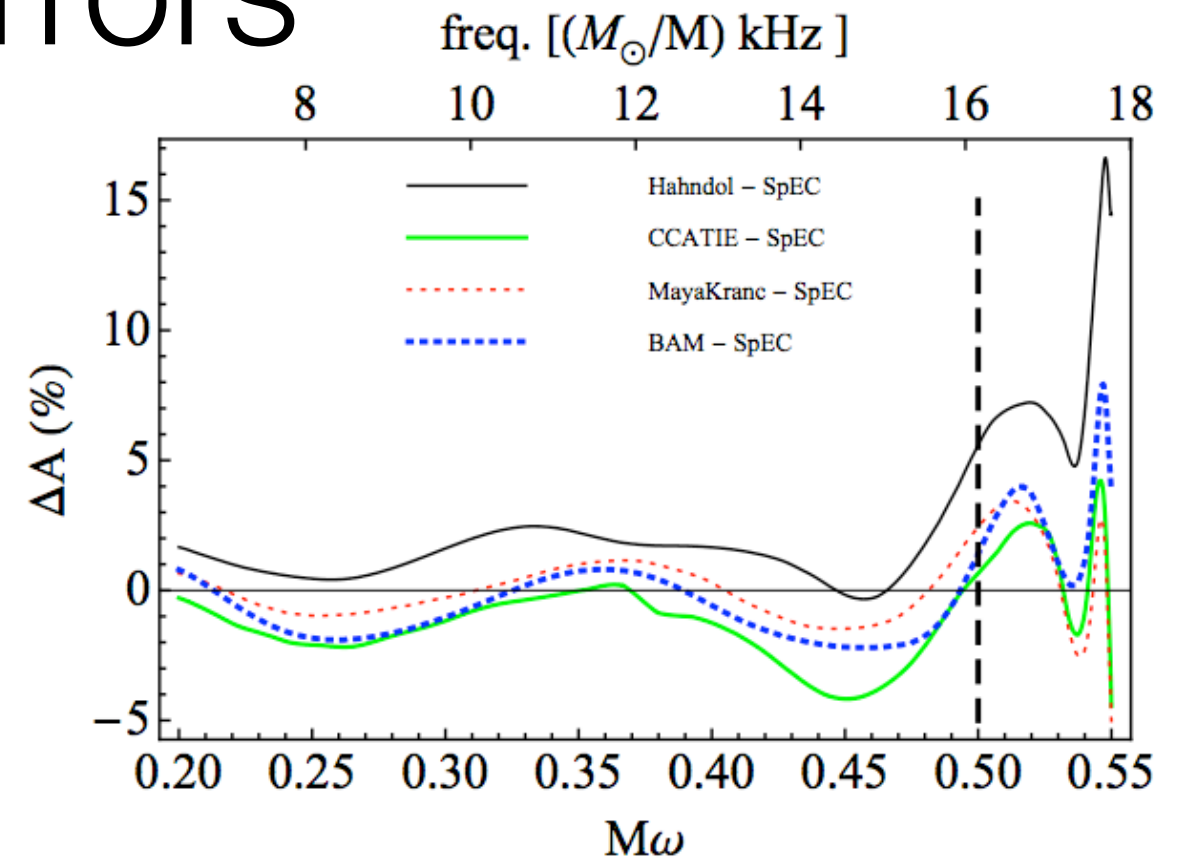
- WF extraction error, higher modes

- systematics: initial data, defining spins, ...



Numerical relativity errors

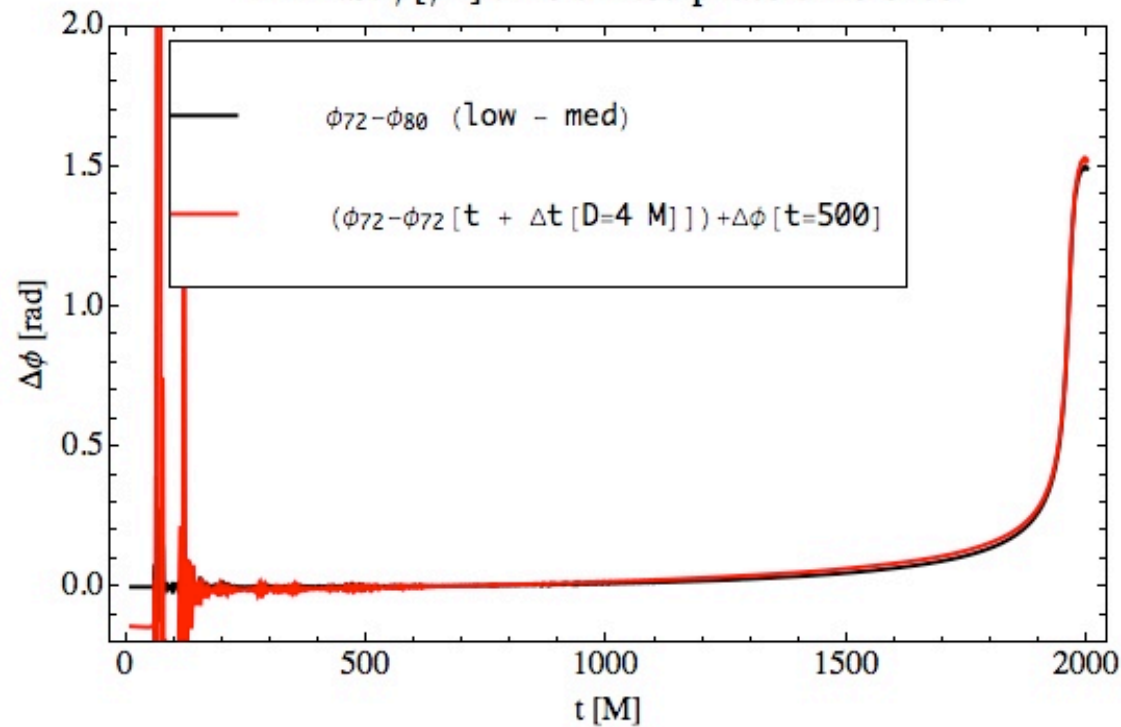
- consistency check: compare different codes
- Samurai, Ninja-2 [hybrids] projects
- SAMURAI [Hannam+ '09]: $q=1$ nonspinning NR WFs from different codes: **$M < 0.1\%$** .



- [Santamaría+ '10]: nonspinning, $q = 2$ hybrids for Llama/BAM: **$M < 0.2\%$** .
- [MacDonald+ '11]: Effect of low vs. high resolution (SpEC), $q=1$ nonspinning: **$M < 0.1\%$** .
- [Pan+ '11]: EOBNR-model agrees with NR data for $q = 6$ with **$M 0.5\%$** .
- Want to quantify errors independent of match/noise/mass, see how error develops as a function of time/frequency/separation, ..

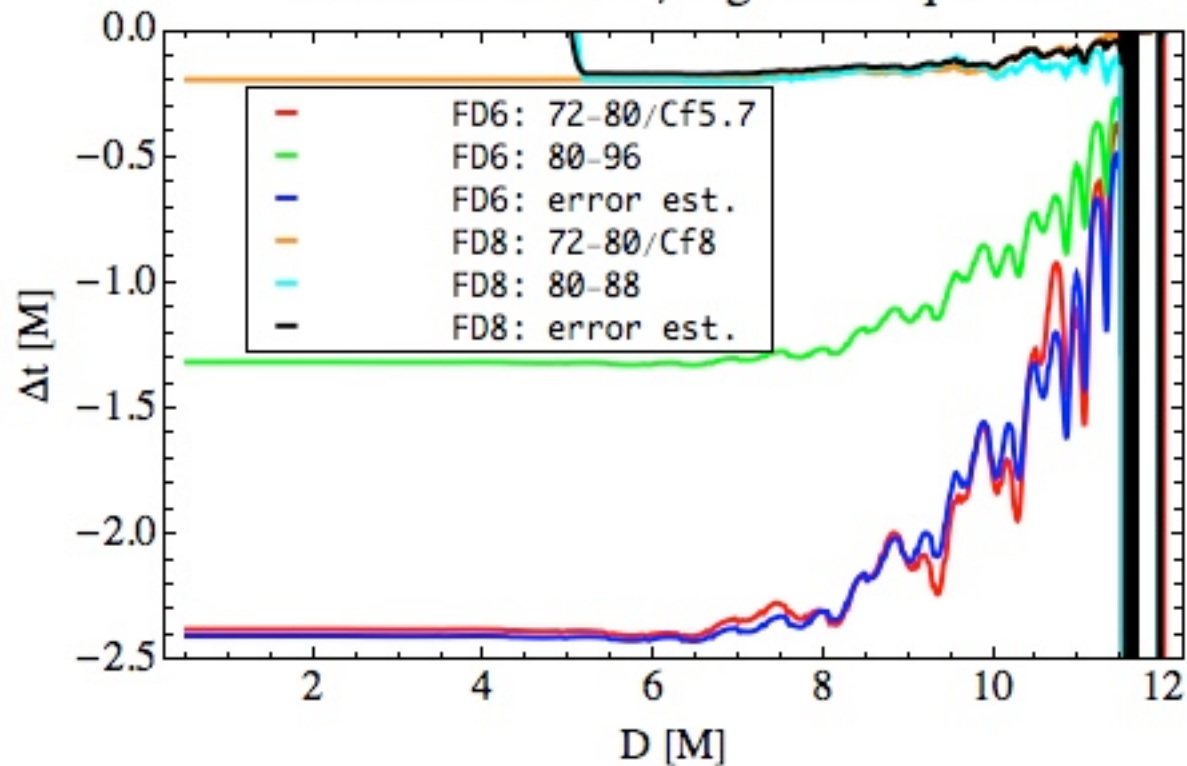
time shift vs. phase shift

EMNS: $\phi[\psi_4]$ time shifted phase difference

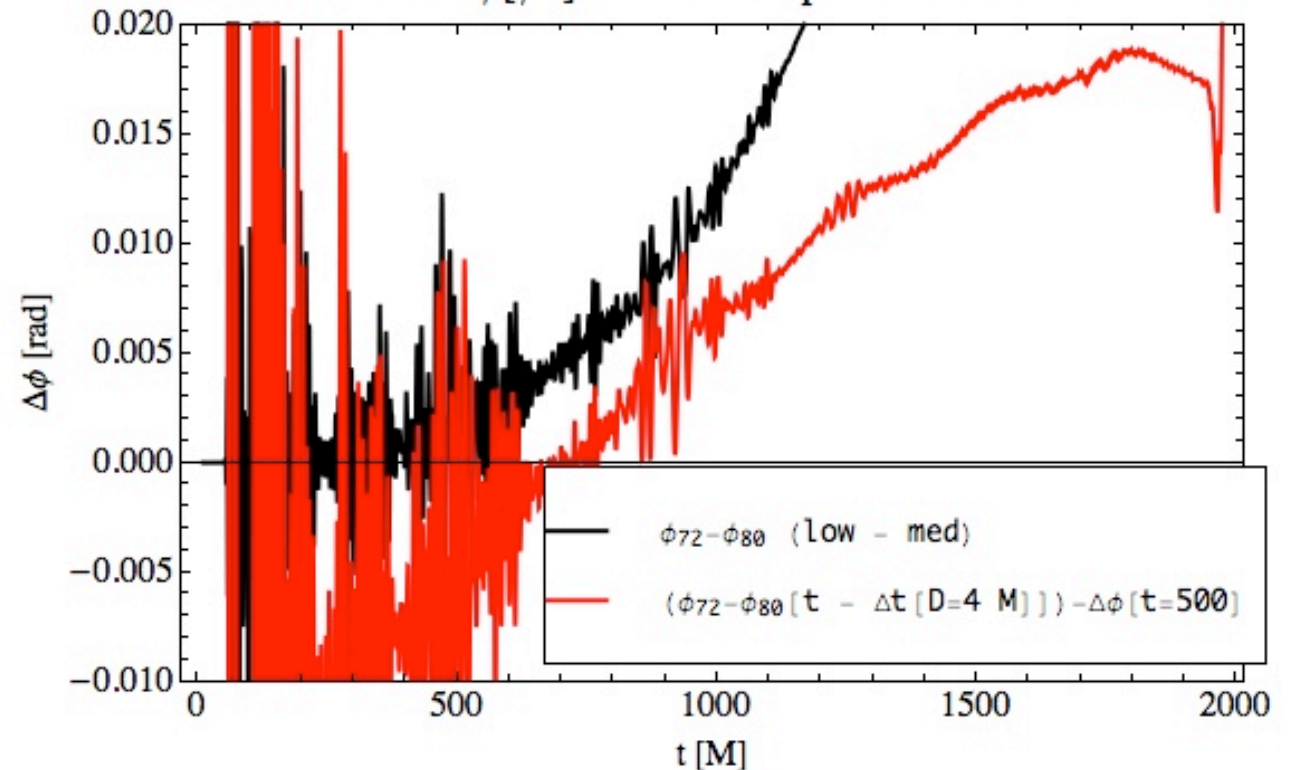


- Idea: express “dephasing” in terms of time-difference between different resolutions (compare e.g. events of same separation, frequency, ...)
- No significant error in last orbits, can estimate phase error at merger a few orbits early.

EMNS: time shift/aligned @ equal D

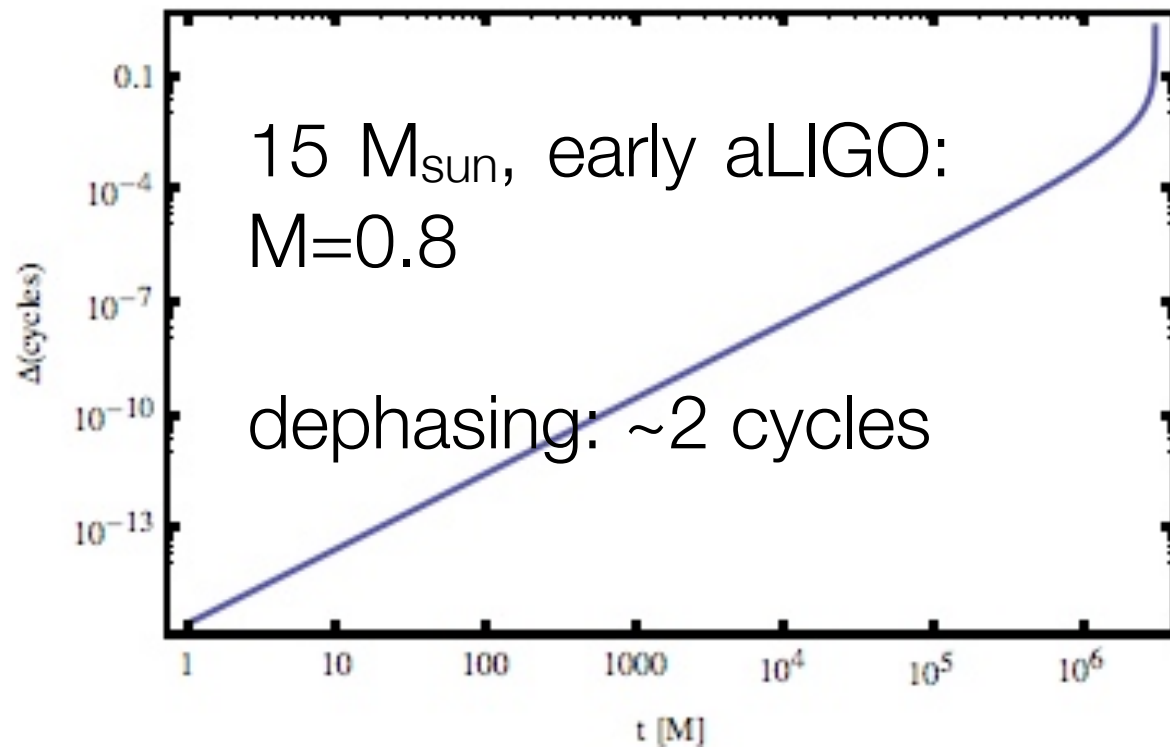


EMNS: $\phi[\psi_4]$ time shifted phase difference

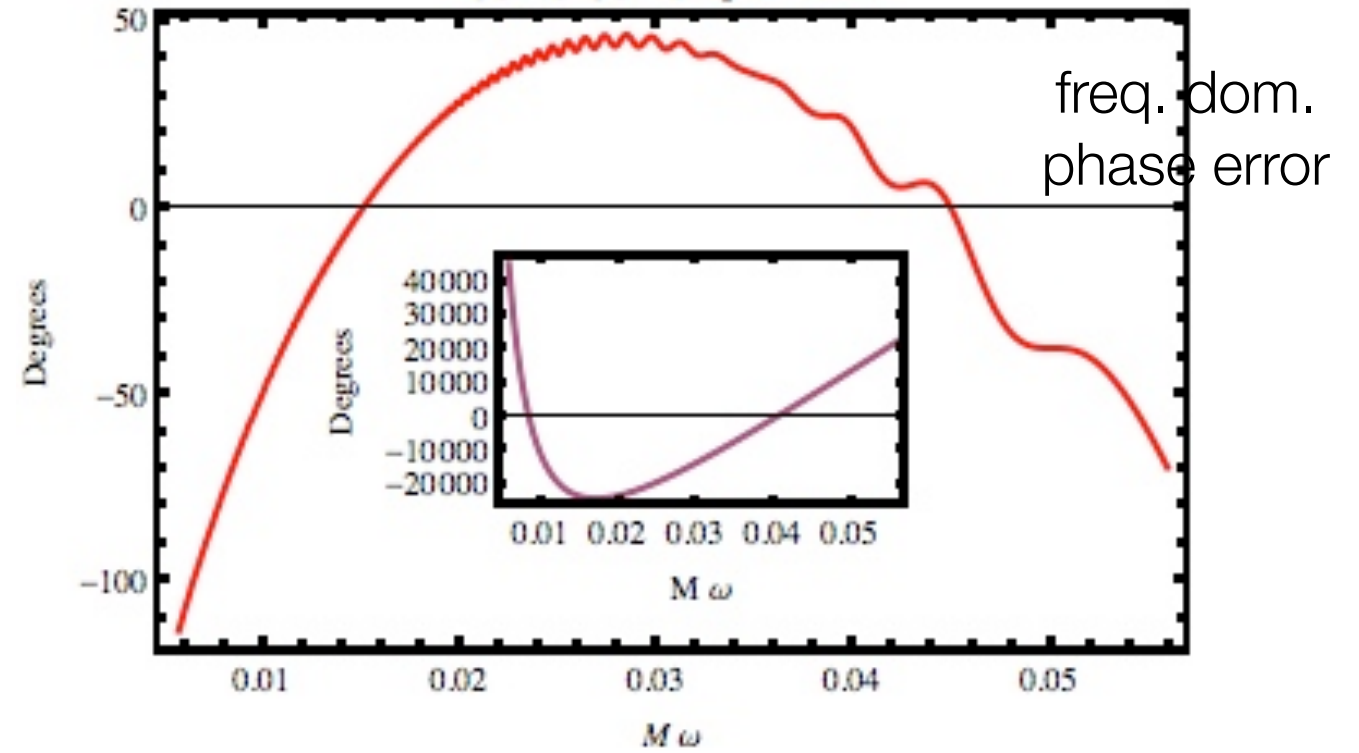


post-Newtonian errors: examples

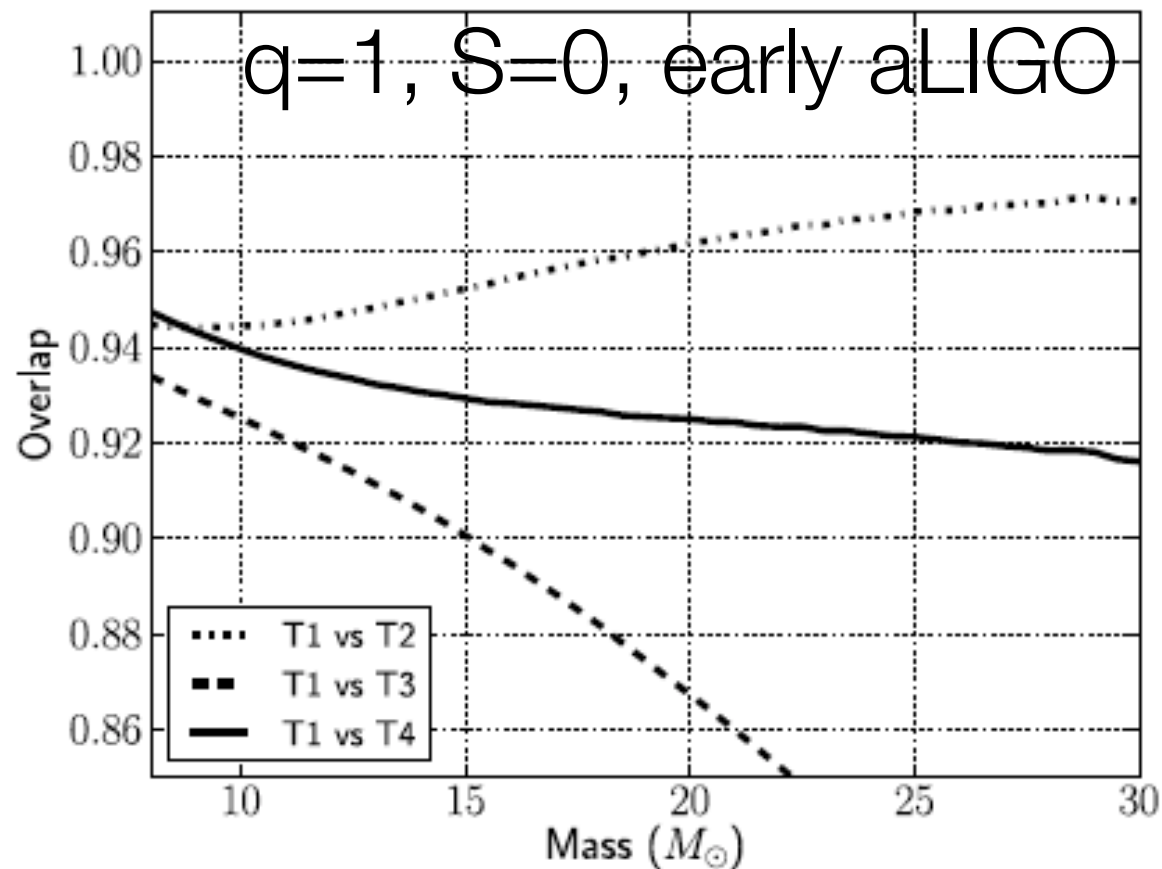
q2--0.75, T1-T4 accumulated time domain phase error



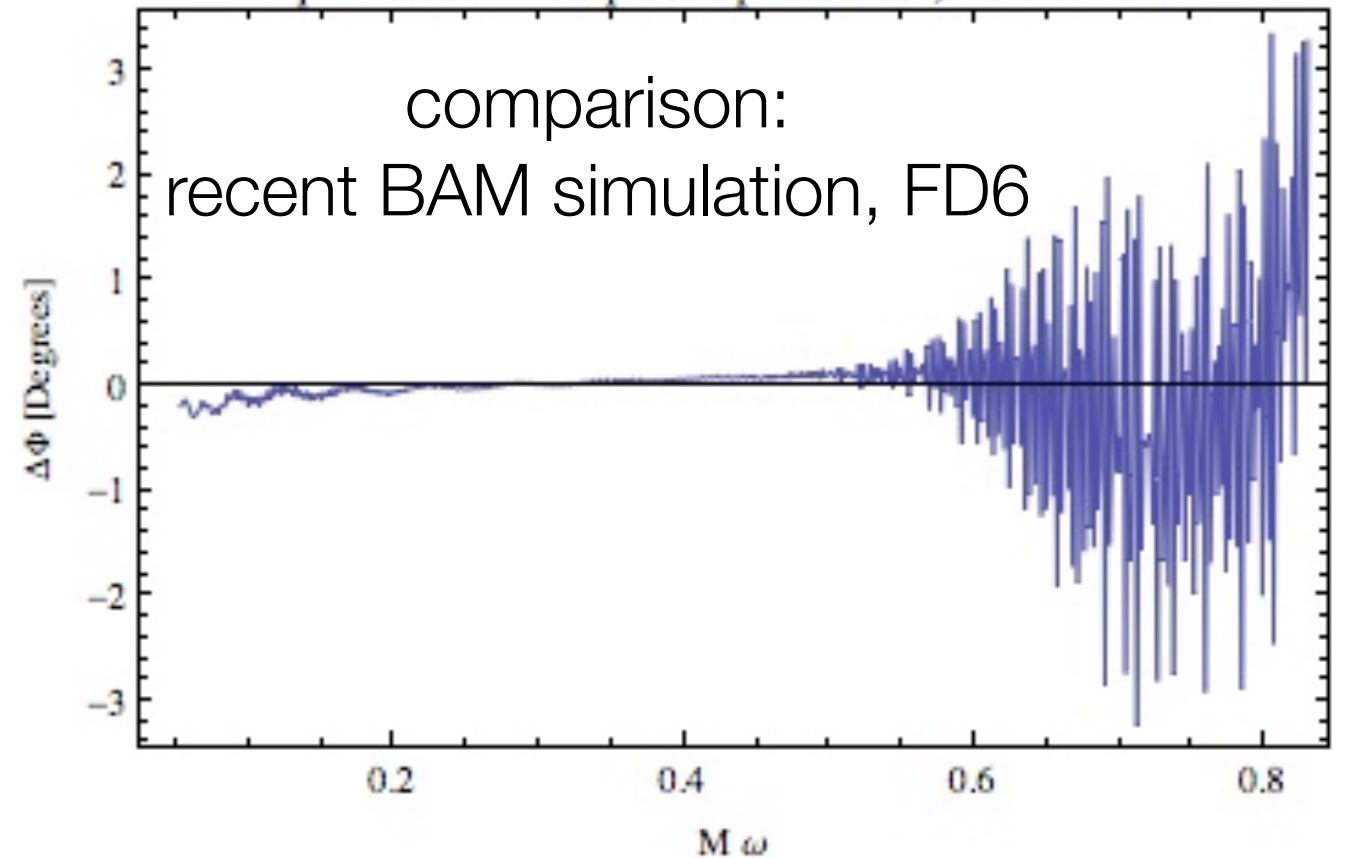
$\phi[T1]-\phi[T4] : q2--0.75$



q=1, S=0, early aLIGO



q2--0.75 NR freq. dom. phase error, LOW-MED

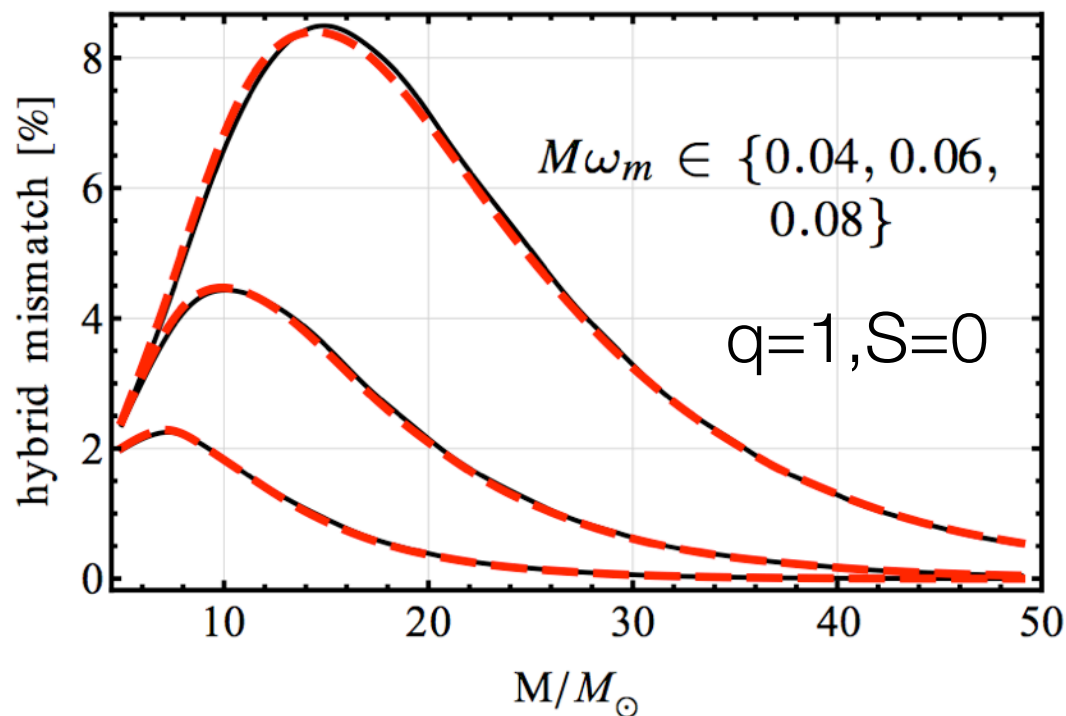


Total error: PN+NR+Hybridisation

- Boyle '11, Ohme+ '11: NR phase error is small -> estimate of NR amplitude is sufficient to compute approximate matches of hybrids with different PN versions:

$$\langle h_1, h_2 \rangle = \max_{\phi_0, t_0} \left[4 \Re \int_{f_1}^{f_2} \frac{\tilde{h}_1(f) \tilde{h}_2^*(f)}{S_n(f)} \frac{df}{\|h_1\| \|h_2\|} \right]$$

$$= \max_{\phi_0, t_0} \left[4 \Re \int_{f_1}^{f_2} \frac{|A_1 A_2|}{S_n} e^{i(\phi_1 - \phi_2)} e^{i(2\pi f t_0 + \phi_0)} \frac{df}{\|h_1\| \|h_2\|} \right] \quad \phi_1 - \phi_2 = \begin{cases} \phi_{\text{PN1}} - \phi_{\text{PN2}} & , f < f_m \\ 0 & , f \geq f_m \end{cases}$$



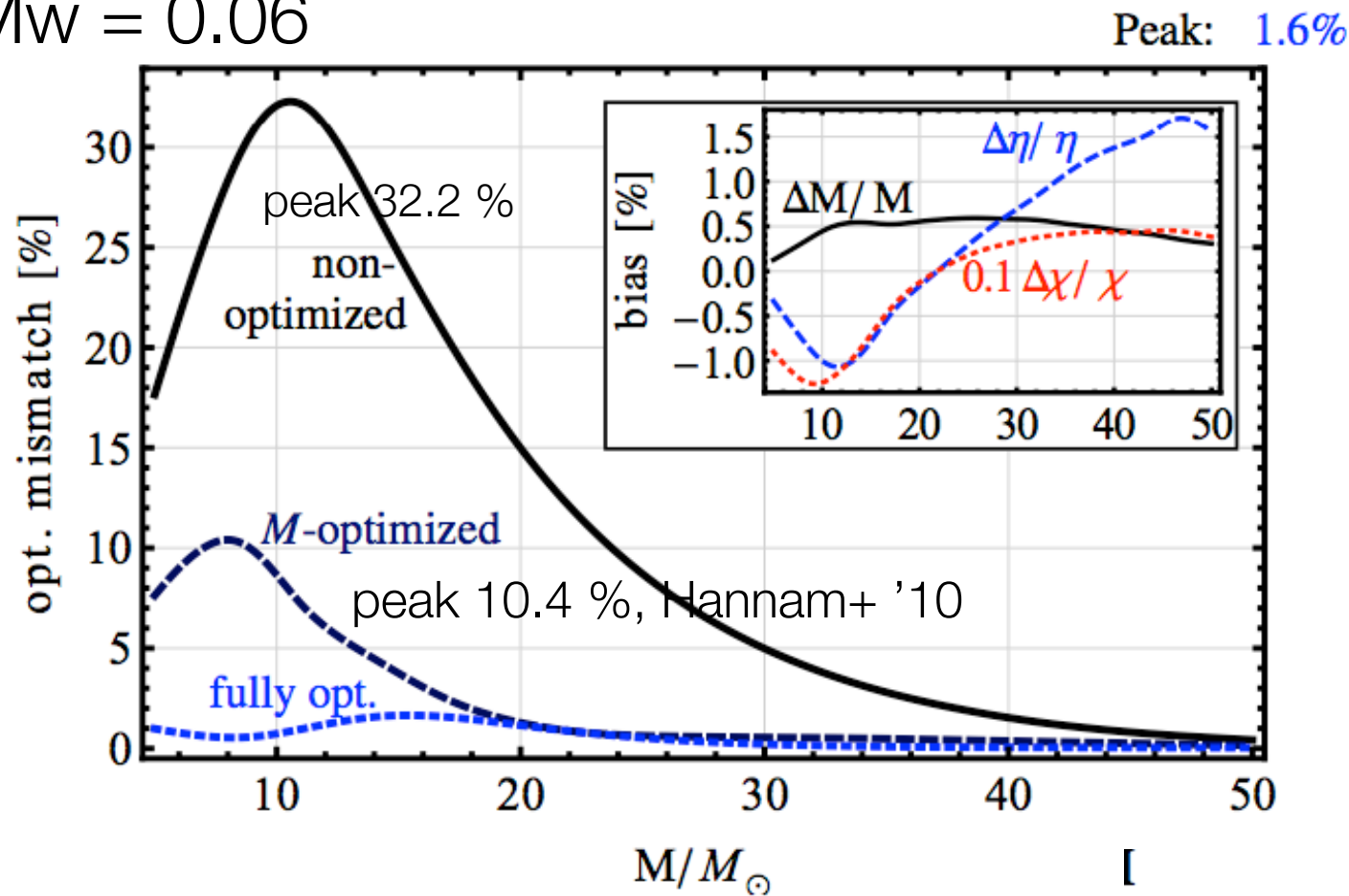
Ohme+ '11: Results consistent with previous studies: many more NR orbits [$O(10^3)$] are needed so that PN disagreement is indistinguishable!

Are current PN+NR WFs useless?

No - we need to compute matches optimized over physical parameters and check parameter bias!

Examples: Mismatch optimized over physical parameters

$M_w = 0.06$

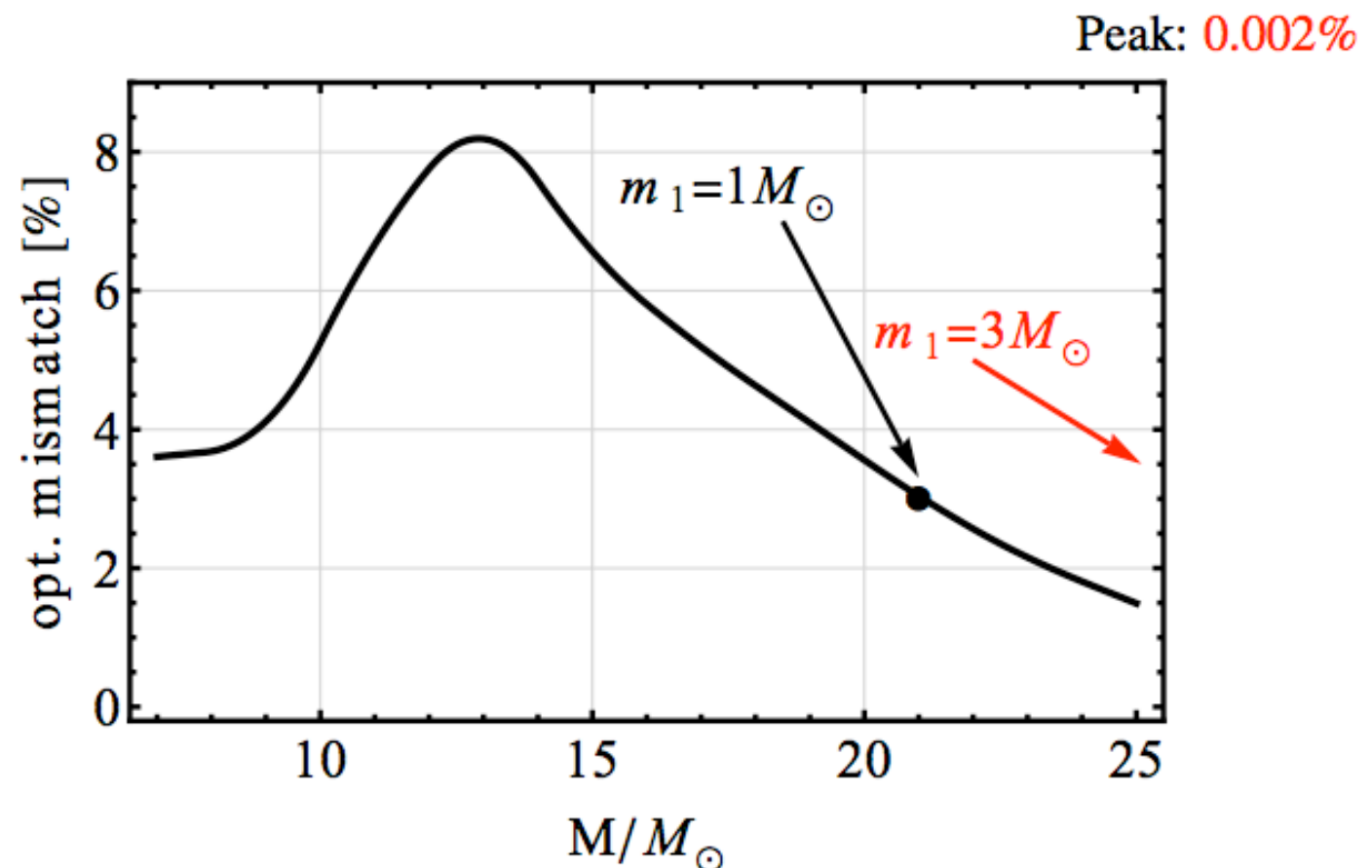


$$q=4, \chi_1=\chi_2=0.5$$

Comparison of T1 vs F2 approx.

$$q=20, \chi_1=\chi_2=0$$

Boyle '11, Ohme+ '11:
With astrophysical bias,
larger mass ratios can
be easier to model!

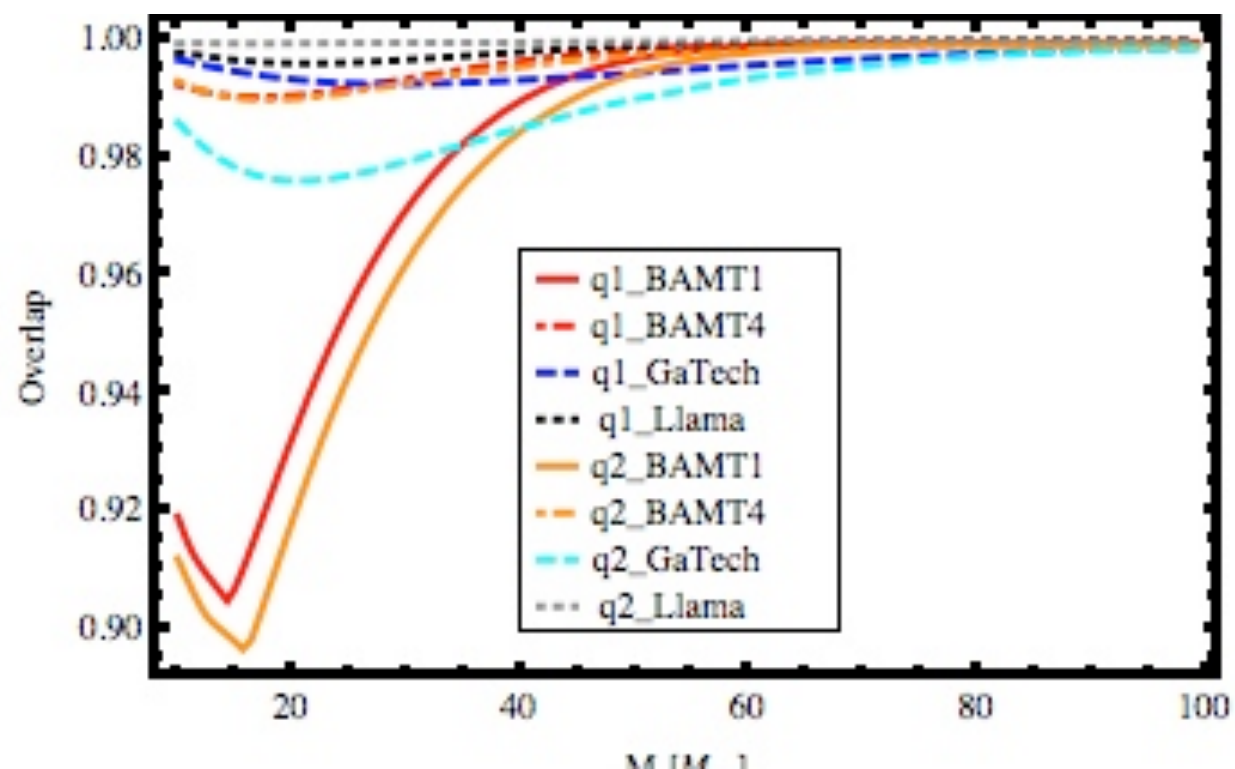
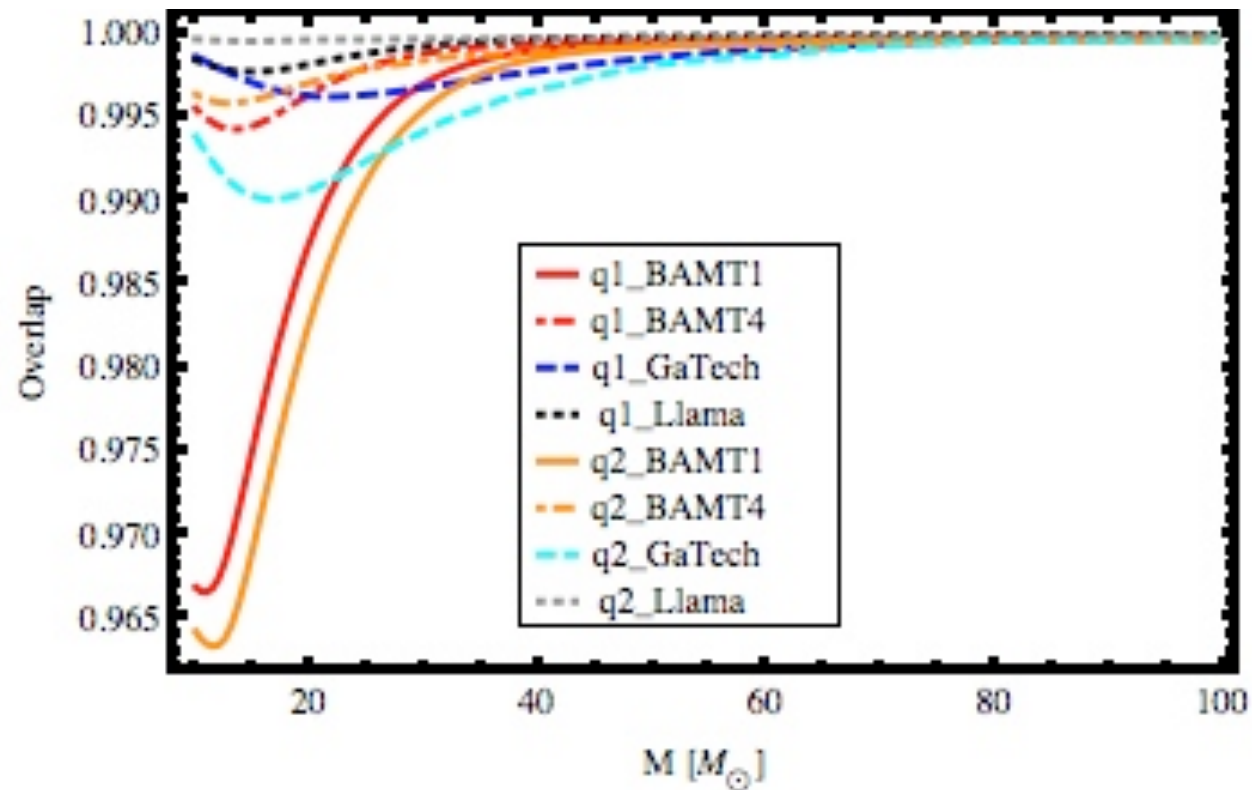


orbits	mass-ratio	$q = 20$
5	3.0%: $q < 8.9$	$\max_M \mathcal{M}_{\text{FF}} \approx 15\%$ ($19M_\odot$)
	1.5%: $q < 6.8$	$21M_\odot : 12\%$, $63M_\odot : 0.3\%$
10	3.0%: $q < 11.4$	$\max_M \mathcal{M}_{\text{FF}} \approx 8.2\%$ ($13M_\odot$)
	1.5%: $q < 8.6$	$21M_\odot : 3.0\%$, $63M_\odot : 1.6 \times 10^{-5}$
20	3.0%: $q < 14.8$	$\max_M \mathcal{M}_{\text{FF}} \approx 5.7\%$ ($11M_\odot$)
	1.5%: $q < 10.7$	$21M_\odot : 0.8\%$, $63M_\odot : 6.4 \times 10^{-6}$

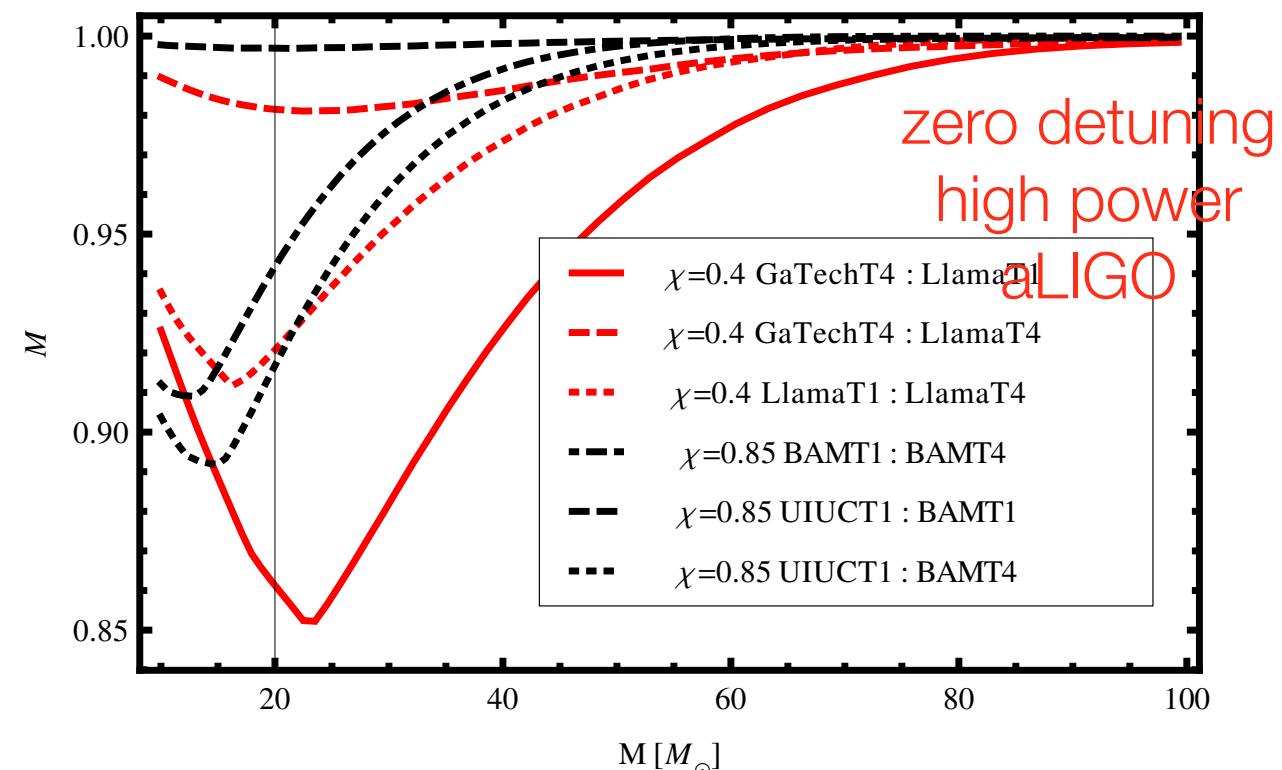
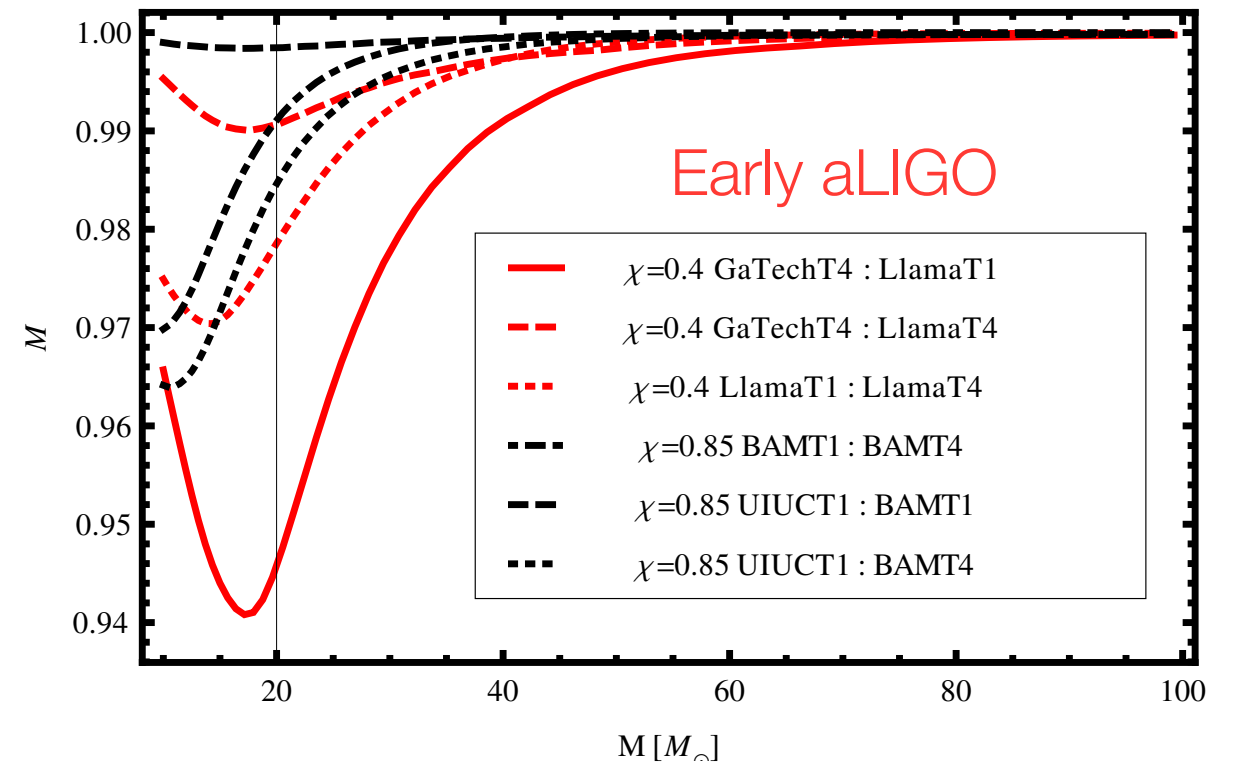
TABLE III. Accuracy of nonspinning hybrid waveforms, based on combining PN TaylorT4 or TaylorF2 data with NR waveforms of specified length (defined by the number of orbits before merge = number of GW cycles divided by 2). *Left column:* Range in mass-ratio where a given accuracy requirement ($\max_M \mathcal{M}_{\text{FF}} < 3\%$ or 1.5%) is fulfilled. *Right column:* Mismatch error for $q = 20$, both at maximum of all masses (location indicated in parentheses) and at astrophysically motivated minimal values of the total mass (see text).

Ninja-2 catalog: Hybrid comparisons between NR groups

$q = 1, 2 \quad \chi_i = 0$



$q = 1 \quad \chi_i = 0.4, 0.85$



Conclusions

- Waveform errors dominated by PN uncertainty/computational cost to produce far longer NR WFs. Modelling errors dominated by lack of NR waveforms.
- Current PN+NR combinations are good enough for detection (~ 10 NR orbits) for comparable masses or moderate spins.
- We are not able to make NR waveforms long enough to make PN uncertainty disappear.
- Parameter uncertainties may be small ($\sim 1\%$ for M & η , 10 % for spin)
- For “design sensitivity” advanced detectors we will need more accurate/longer NR waveforms.
- NR should be able to prevent loss of detections due to waveform errors for most BBH systems, and contribute significantly to parameter estimation, but this will require major efforts: computational exploration of parameter space, analytic waveform models, error analysis, implementation in searches.