

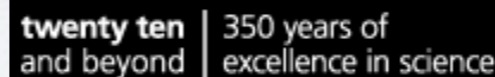


GRAVITATIONAL WAVE ASTRONOMY WITH COMPACT BINARIES: LOCALISATION AND LATENCY

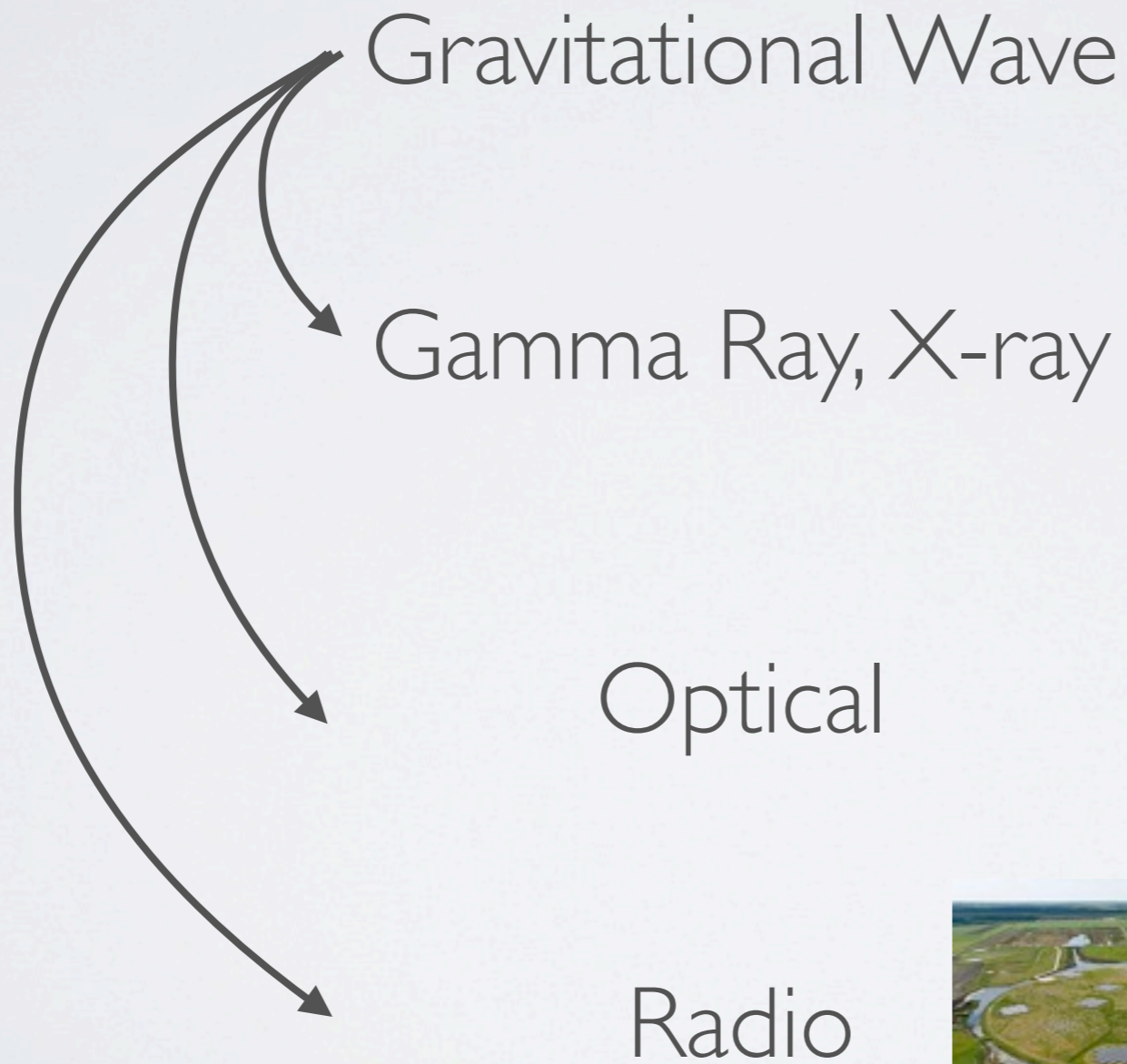
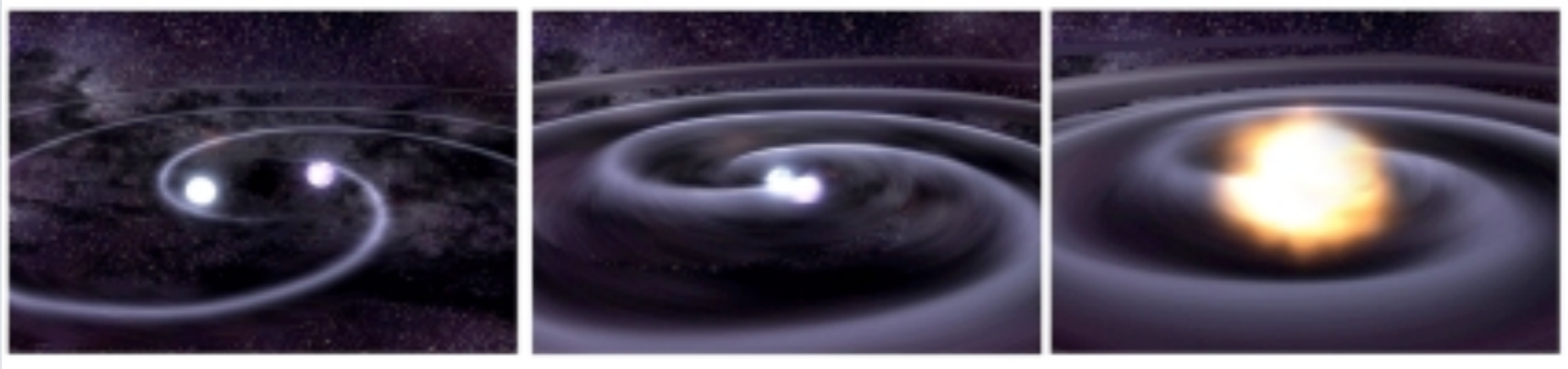
Stephen Fairhurst
Royal Society University Research Fellow
Cardiff University

LIGO-G1200760

Refs: arXiv:0908.2356;
1010.6192; 1205.6611



And new results,
in collaboration with
D. Brown and P. Sutton

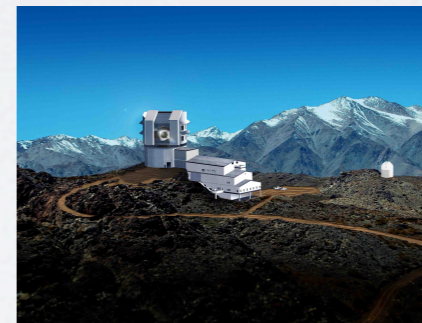
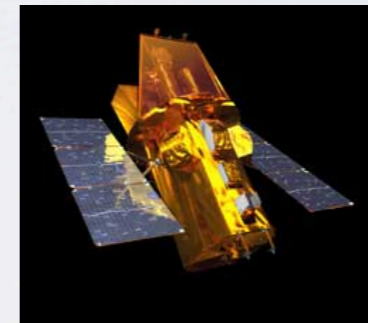


Gravitational Wave

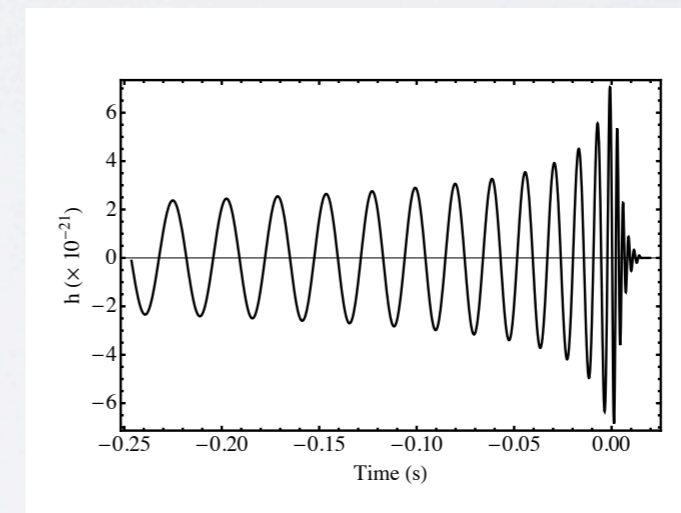
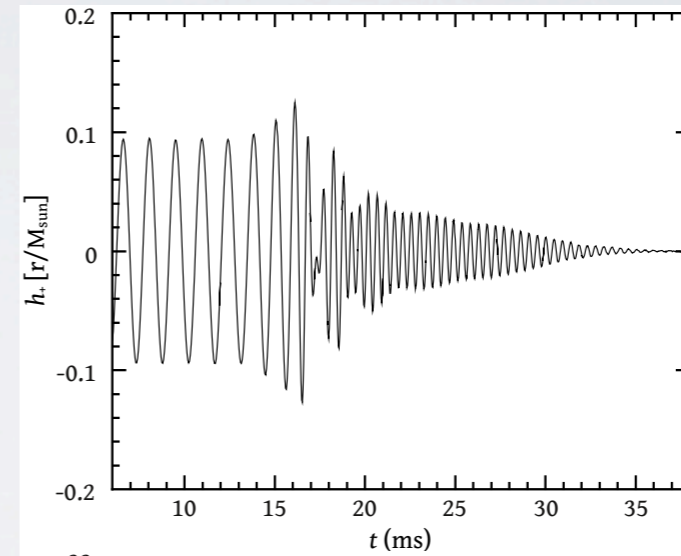
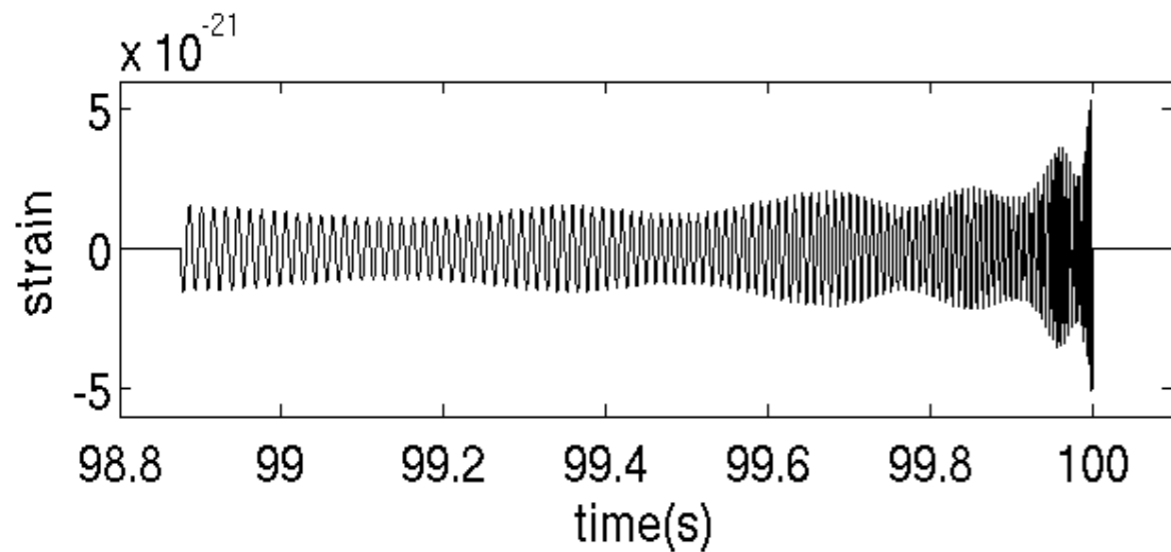
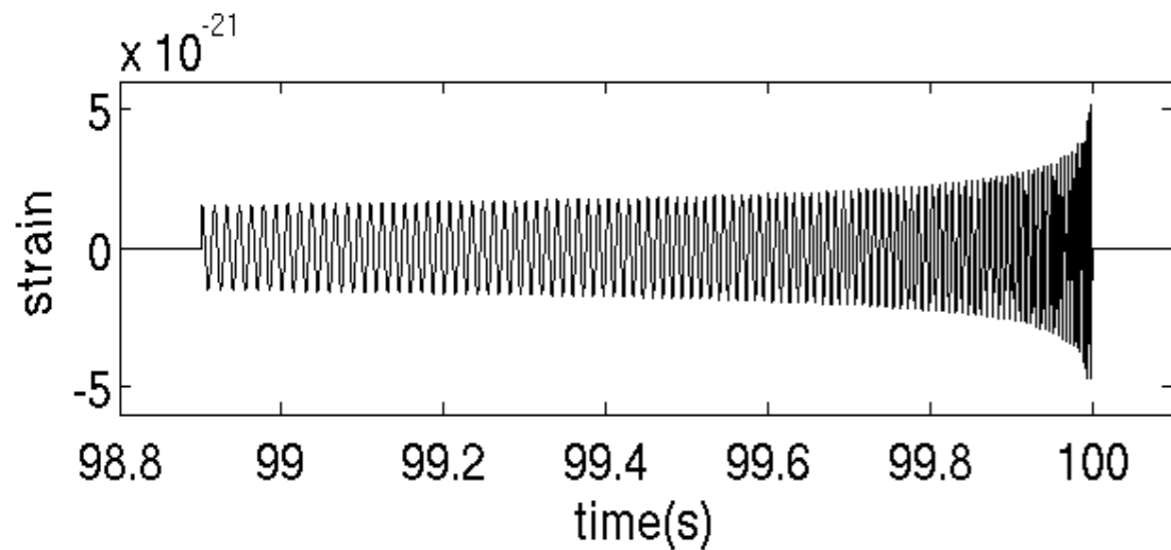
Gamma Ray, X-ray

Optical

Radio



BINARY COALESCENCE WAVEFORMS



BNS
Merger

Stergioulas et. al.
arXiv 1105:0368

BBH
Merger

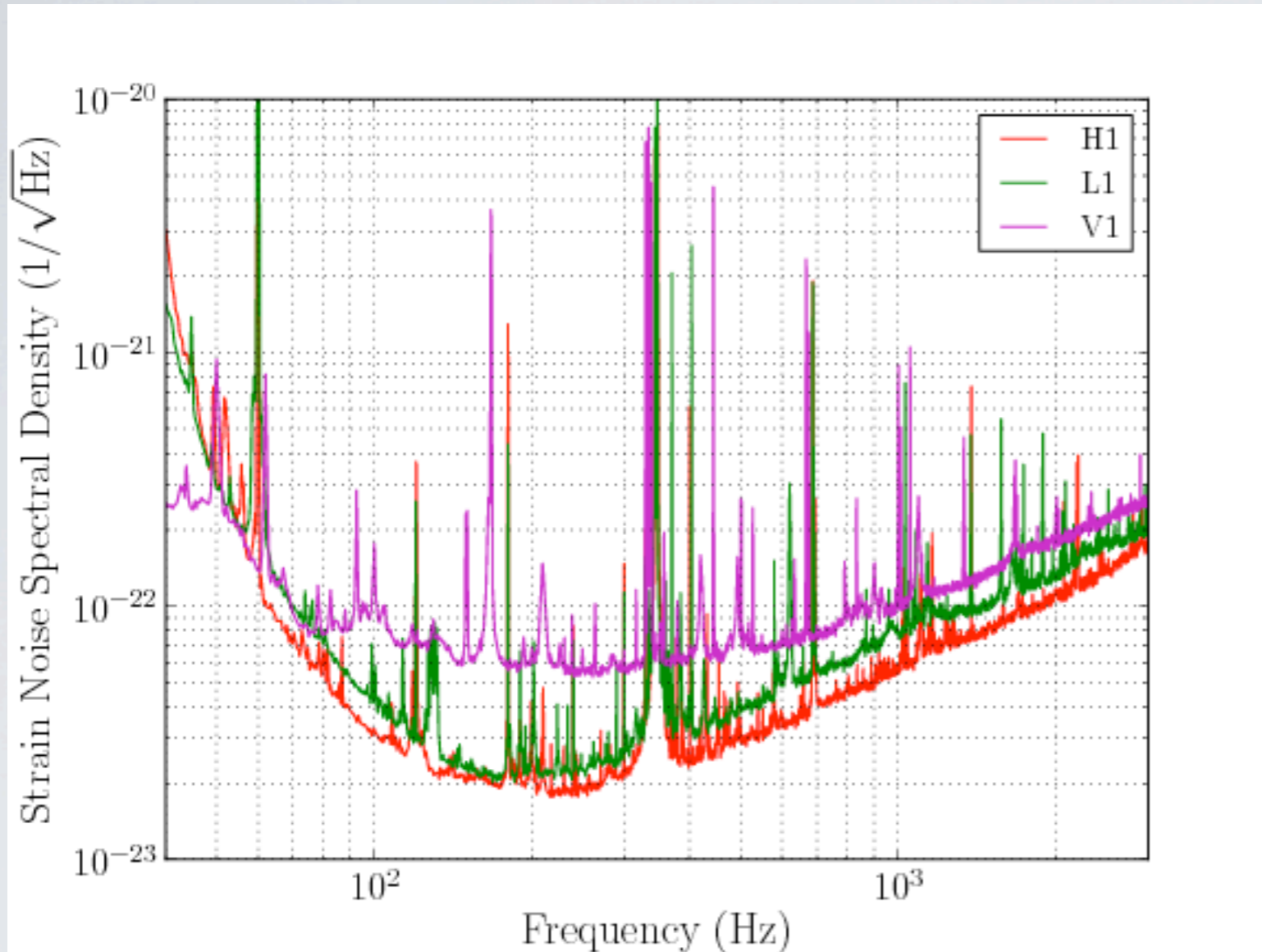
Hannam et. al.
arXiv0901:2437

Post-Newtonian Inspiral

Numerical Merger

2009-10 Sensitivity (S6-VSR2/3)

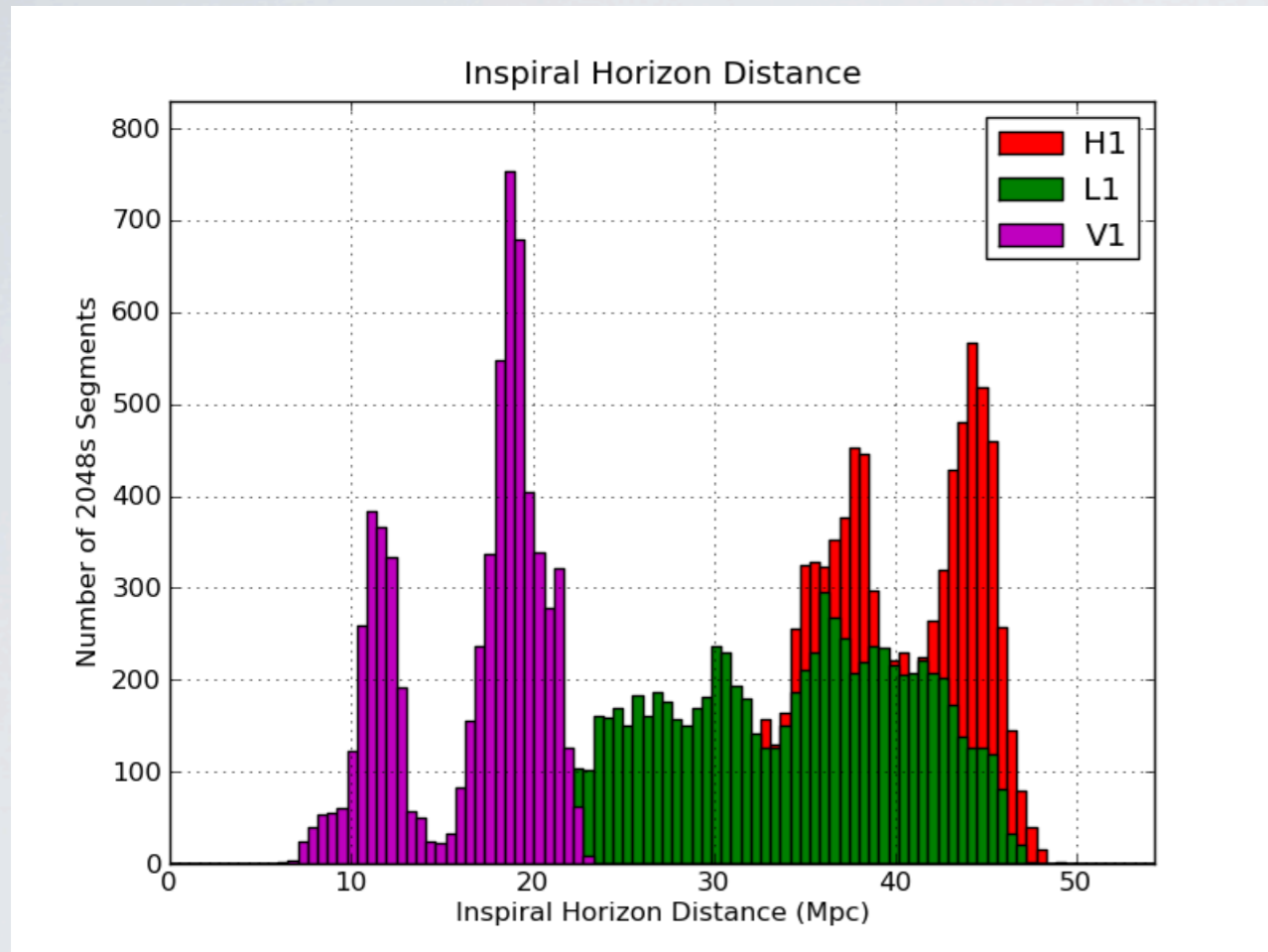
Directional Sensitivity



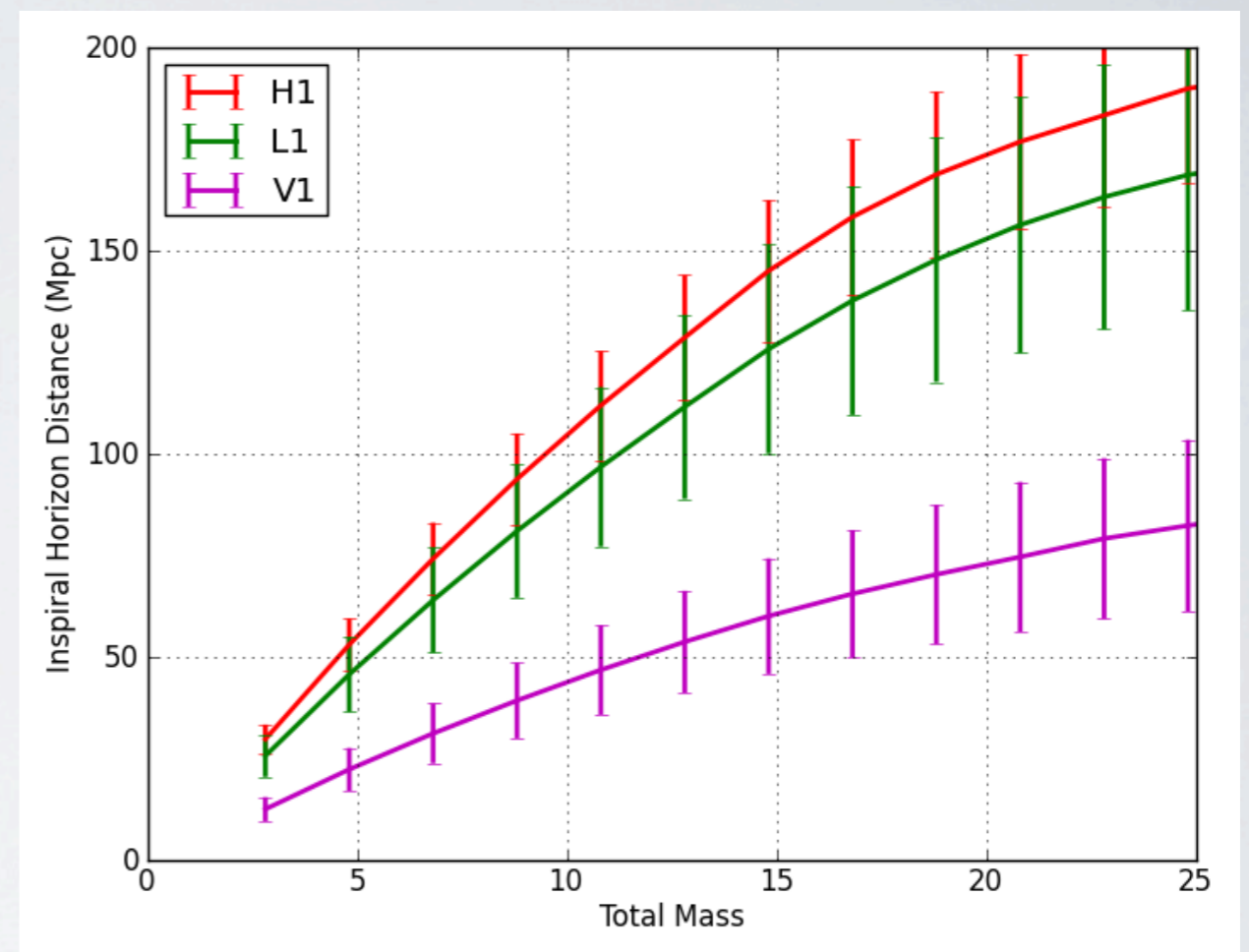
Abadie et al
arXiv:1203.2674

DETECTOR SENSITIVITY

BNS Horizon



Horizon vs Mass



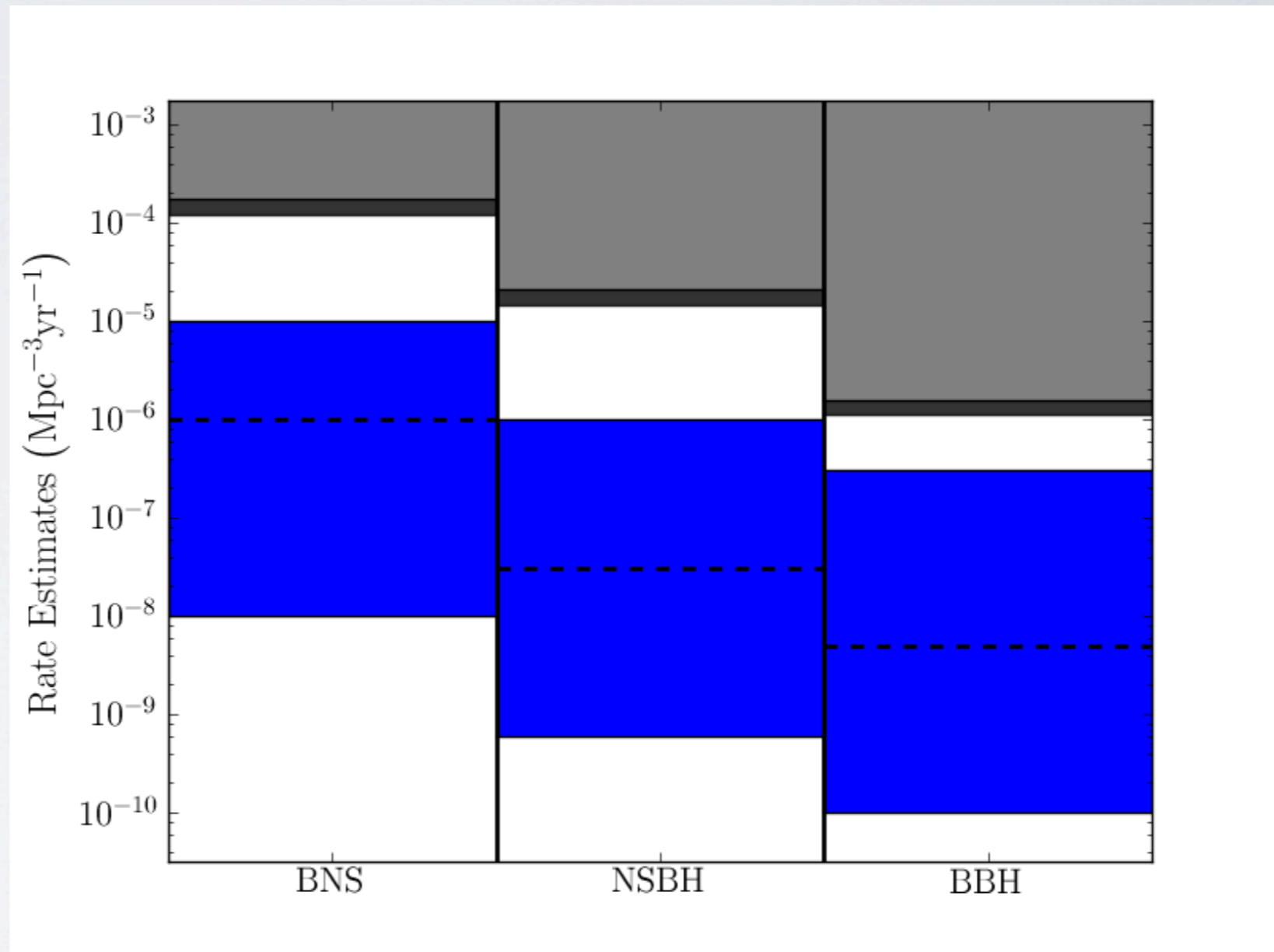
Horizon = 2.26 x Average Range

Abadie et al
arXiv:1203.2674

DETECTOR SENSITIVITY

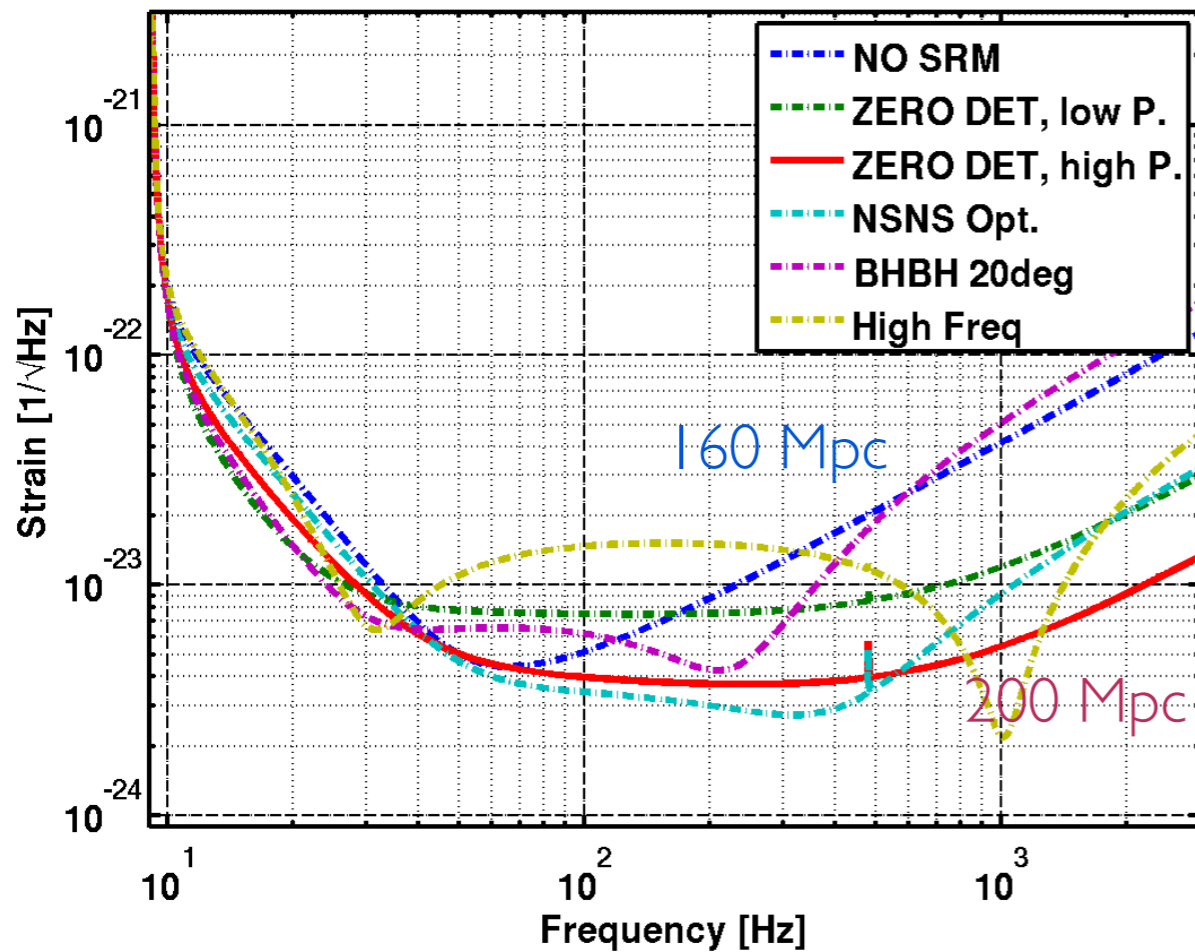
COALESCENCE RATES

- Latest rate exclusions from LIGO-Virgo data
Abadie et al PRD (2012)
- Astrophysical predictions
See, e.g. Abadie et al CQG (2010)
- A range of about 100 Mpc likely to provide events

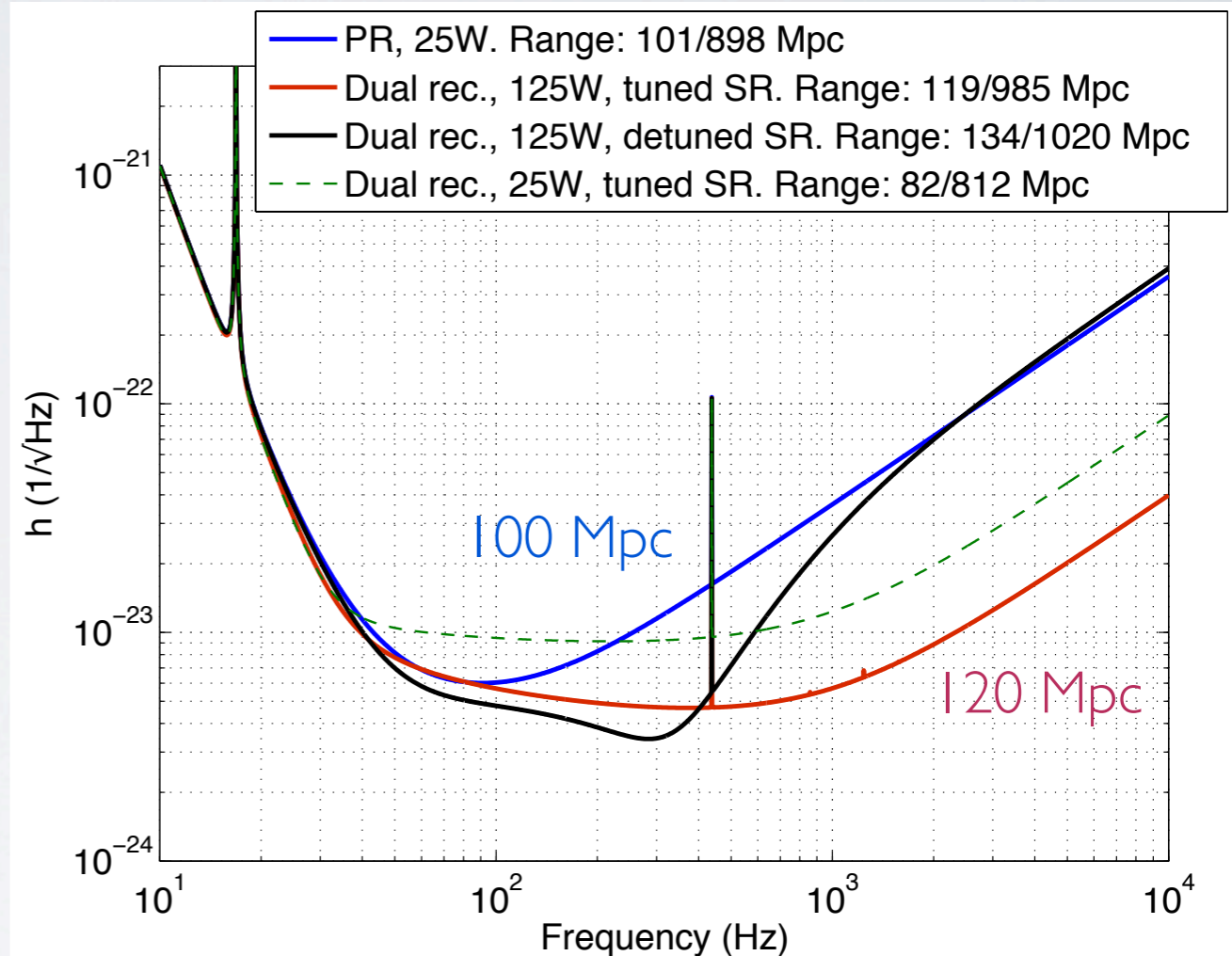


ADVANCED DETECTORS

AdvLIGO tunings



Advanced LIGO design
LIGO-M060056-v2

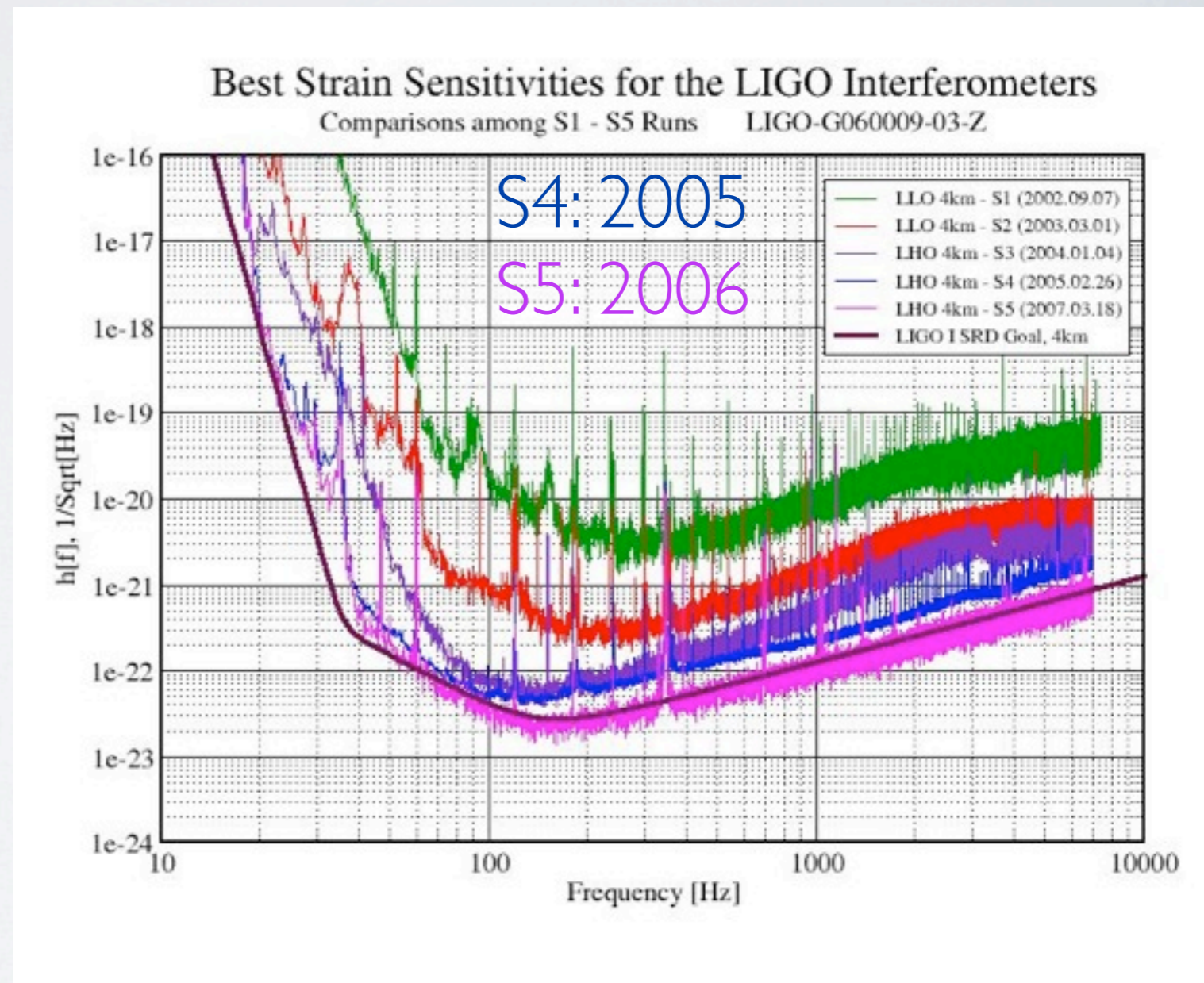


Advanced Virgo design
VIR-0128A-12

SENSITIVITY EVOLUTION

- Advanced detectors:
first lock in 2014
- Will take several years to
achieve design sensitivity
- Commissioning &
Observing roadmap in
preparation
- For now, take lessons
from initial detectors ...

LIGO: first lock 2000



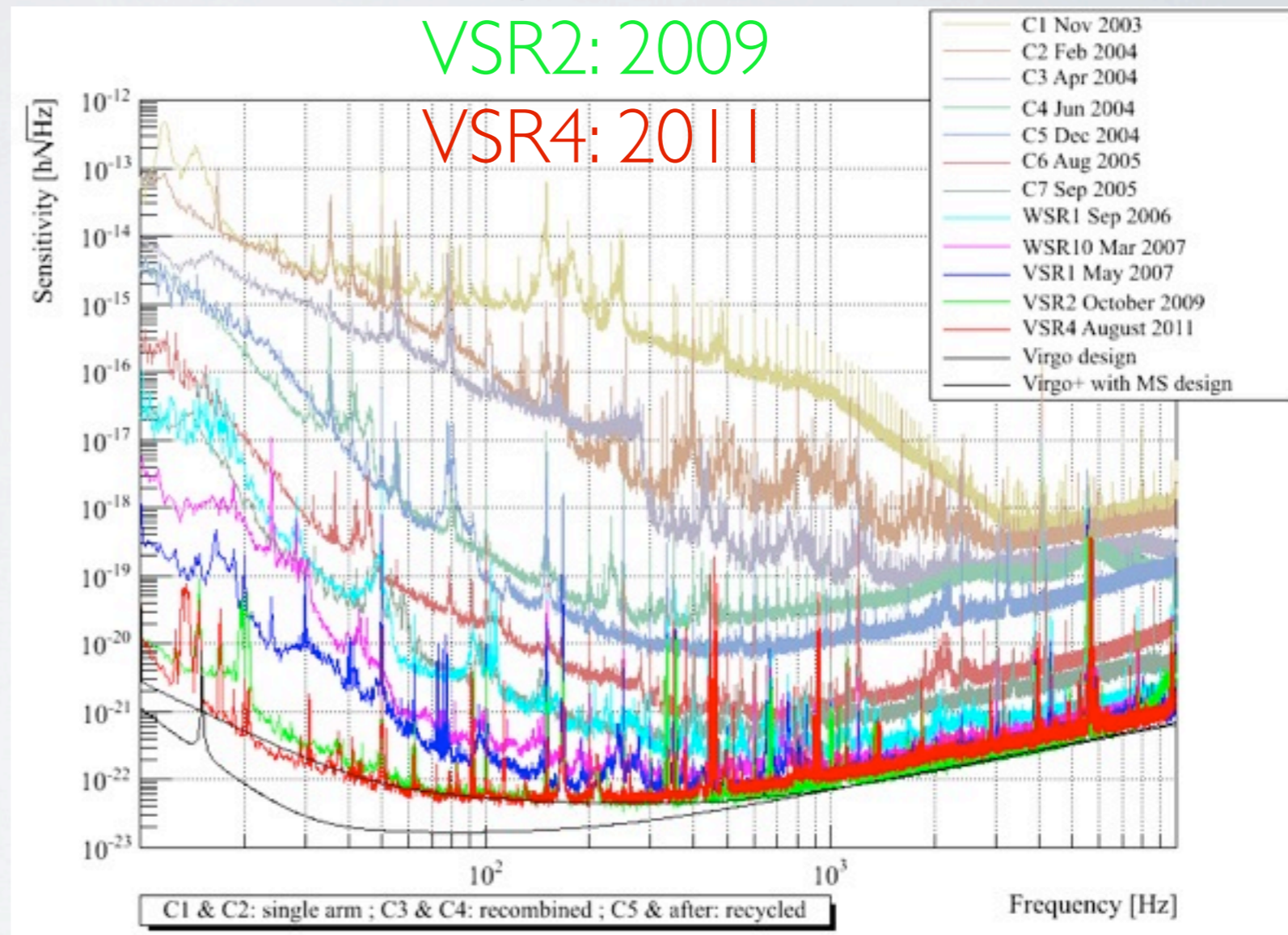
SENSITIVITY EVOLUTION

- Advanced detectors: first lock in 2014
- Will take several years to achieve design sensitivity
- Commissioning & Observing roadmap in preparation
- For now, take lessons from initial detectors ...

Virgo: first lock 2004

VSR2: 2009

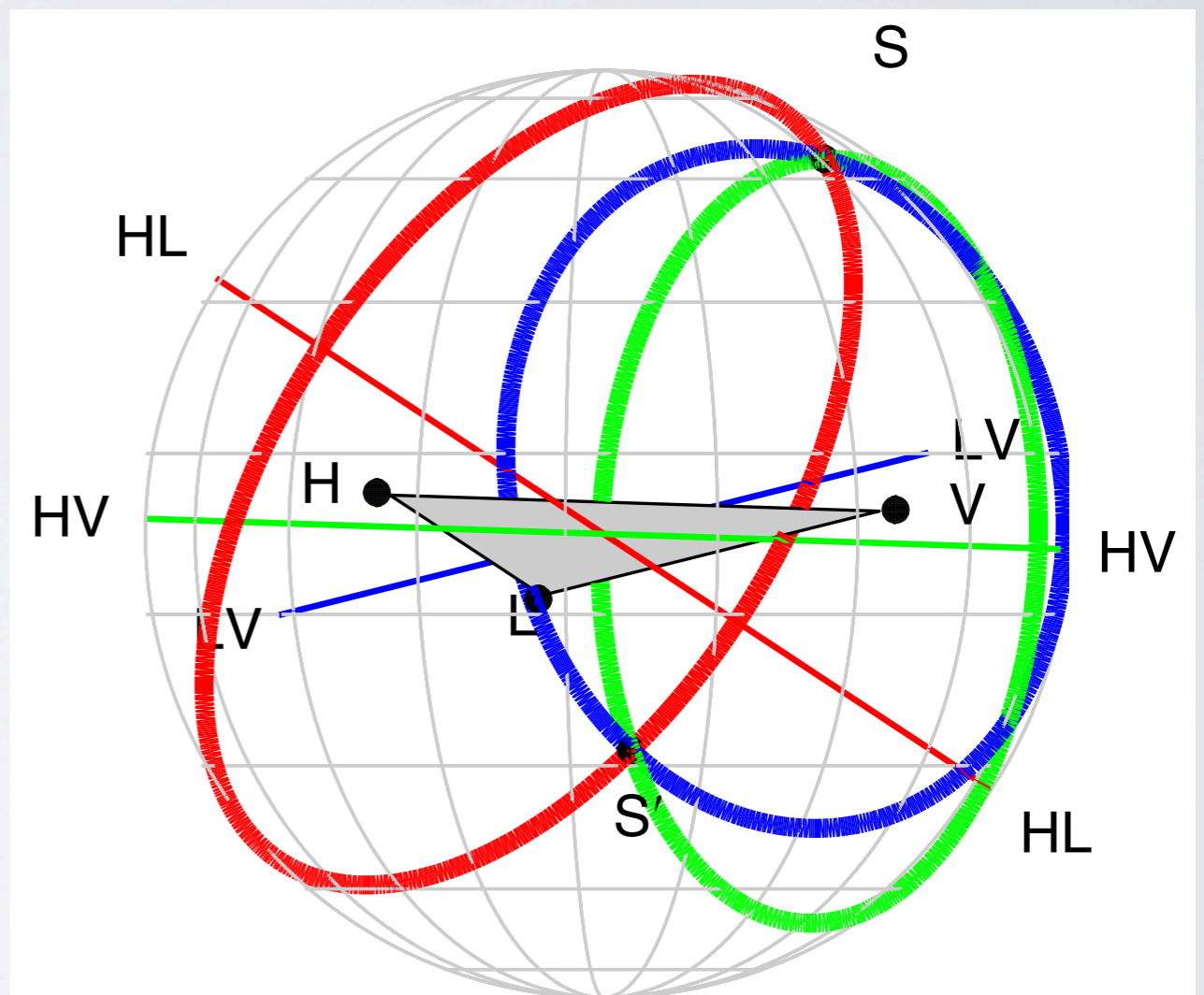
VSR4: 2011



LOCALISATION

LOCALISATION FROM TIMING

- A pair of detectors localises to a ring on the sky



LOCALISATION FROM TIMING

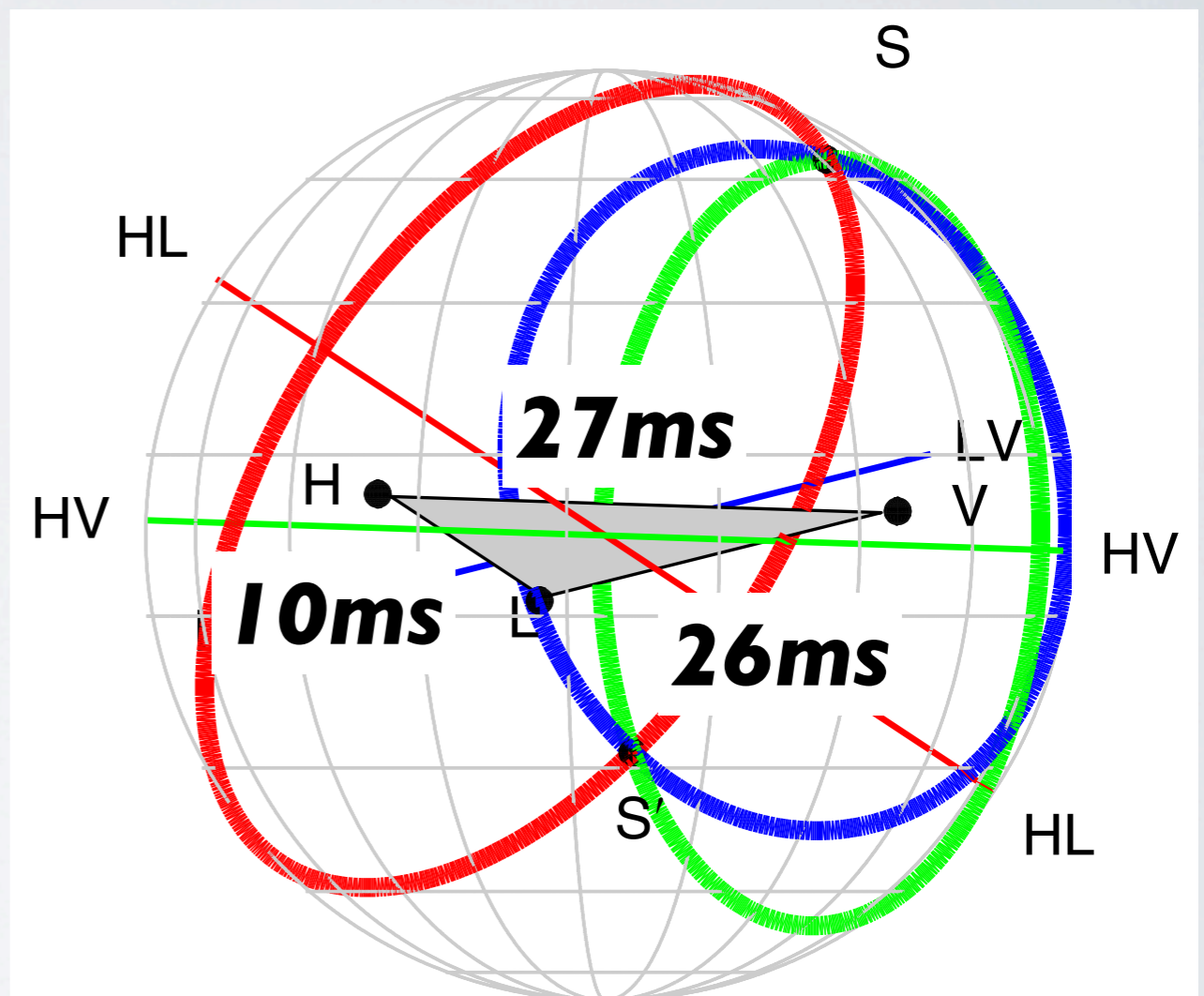
- A pair of detectors localises to a ring on the sky

- Width of rings given by

$$\sin \theta d\theta = \frac{\sqrt{\sigma_1^2 + \sigma_2^2}}{\Delta t}$$

- where $\sigma_t = \frac{1}{2\pi\rho\sigma_f}$

Δt detector baseline



SNR AND BANDWIDTH

Ajith et al arXiv:1201.5319

- Timing accuracy:

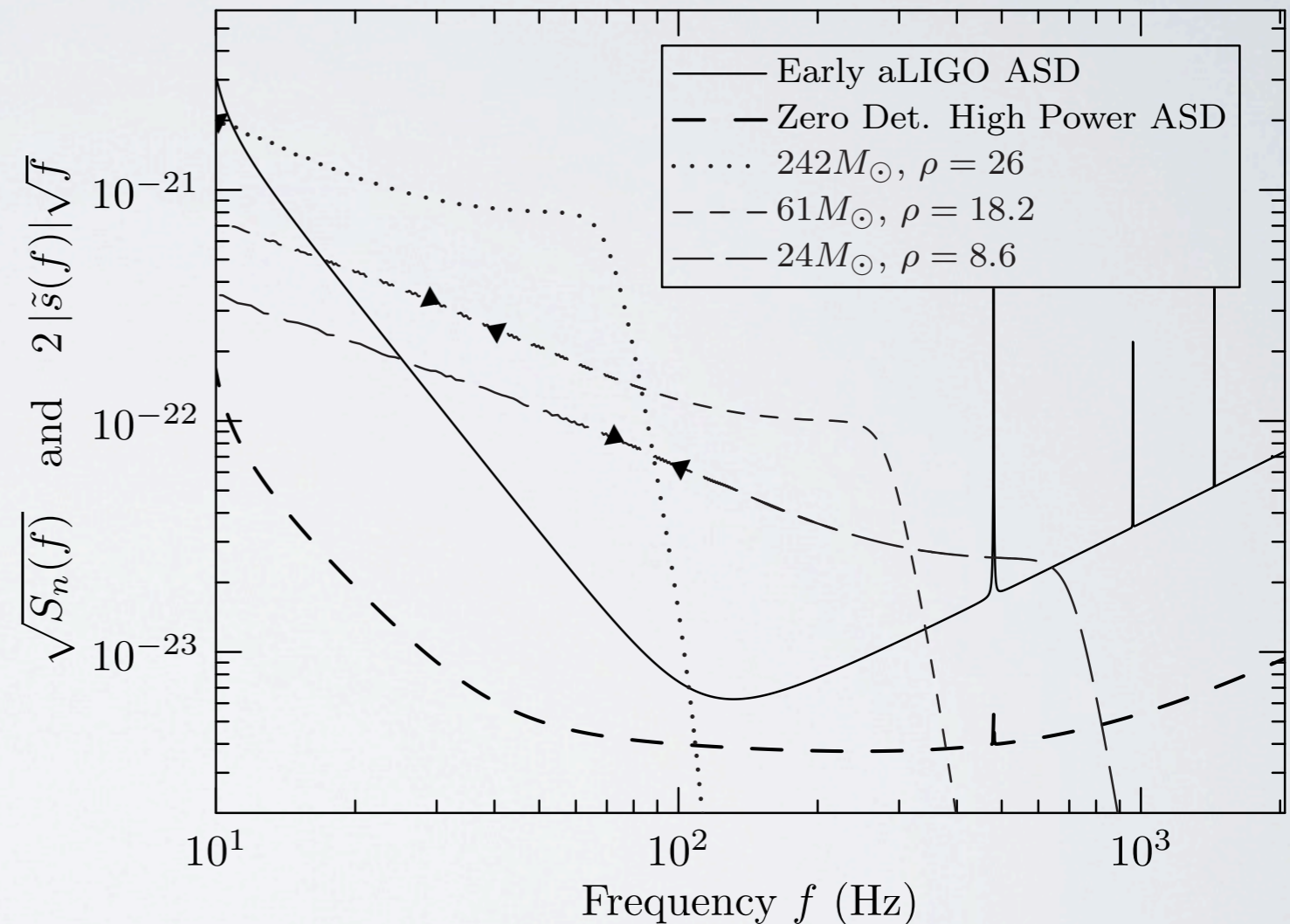
$$\sigma_t = \frac{1}{2\pi\rho\sigma_f}$$

- SNR:

$$\rho^2 = 4 \int_0^\infty \frac{|h(f)|^2}{S(f)} df ,$$

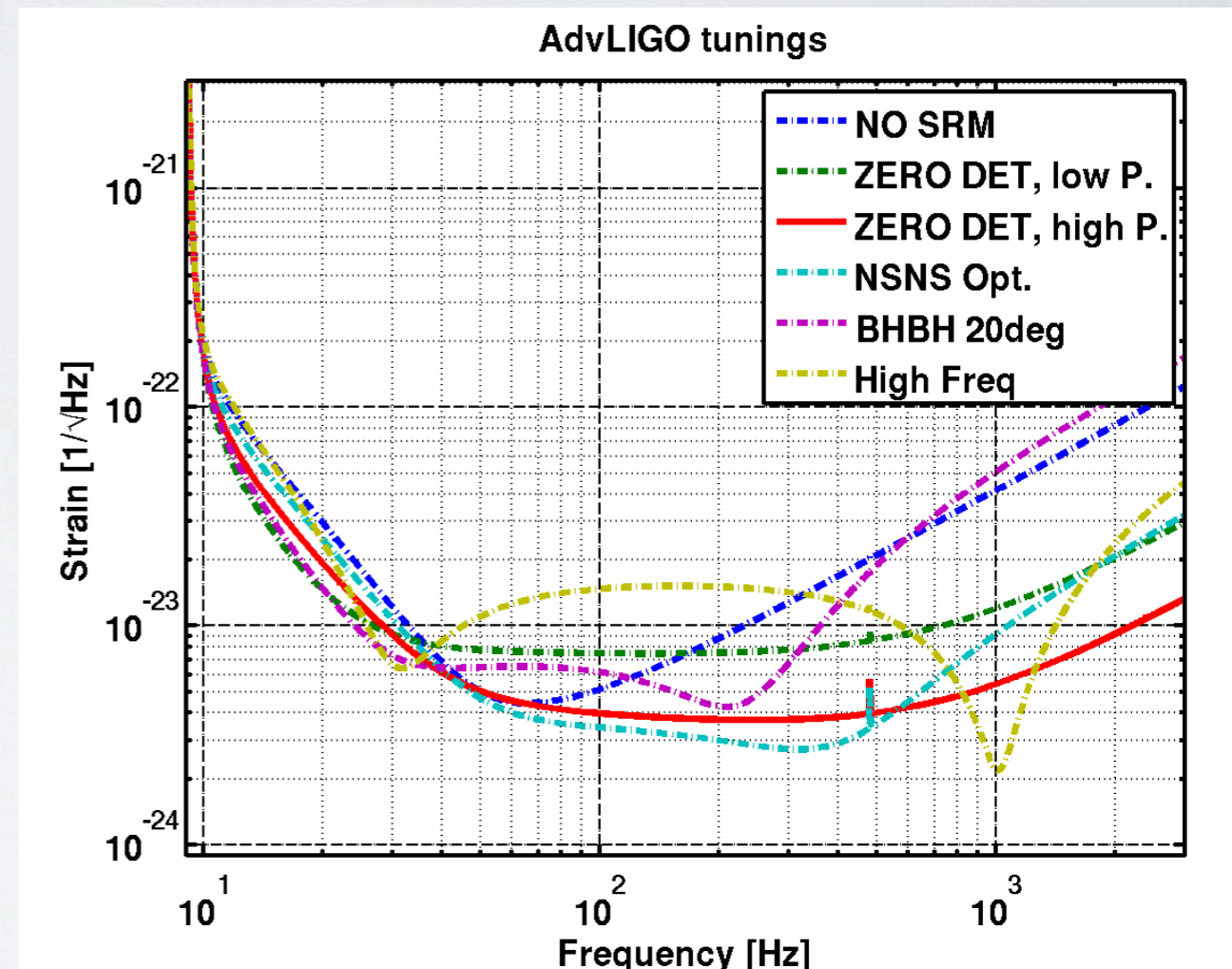
- Bandwidth:

$$\sigma_f^2 = \left(\frac{4}{\rho^2} \int_0^\infty f^2 \frac{|h(f)|^2}{S(f)} df \right) - \left(\frac{4}{\rho^2} \int_0^\infty f \frac{|h(f)|^2}{S(f)} df \right)^2 ,$$



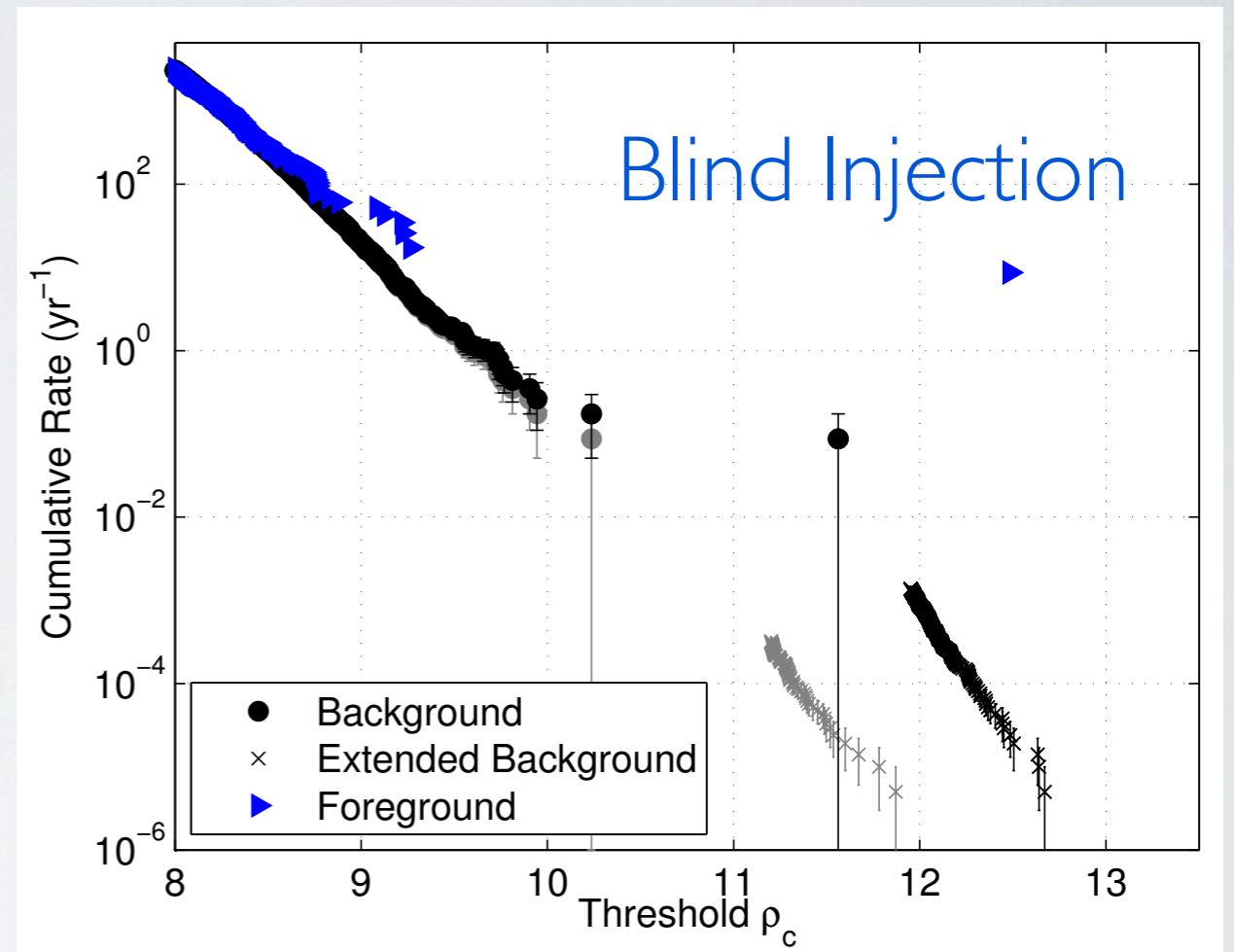
FREQUENCY BANDWIDTH

- 100 Hz as a rule of thumb
- Does depend upon high frequency sensitivity
 - No SRM: 60 Hz
 - Zero Det, High P: 120 Hz
- Significant impact on localisation



NOISE BACKGROUND

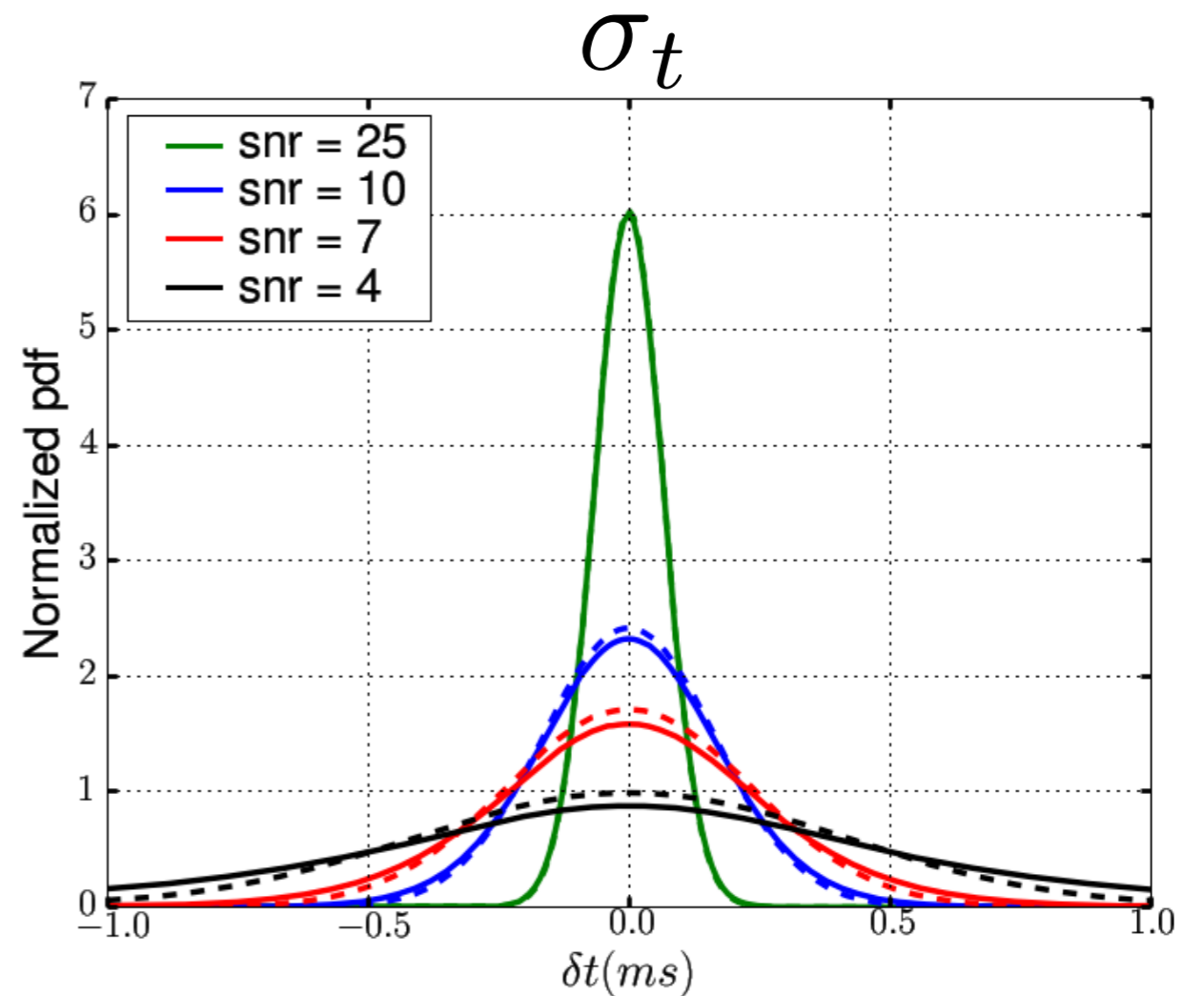
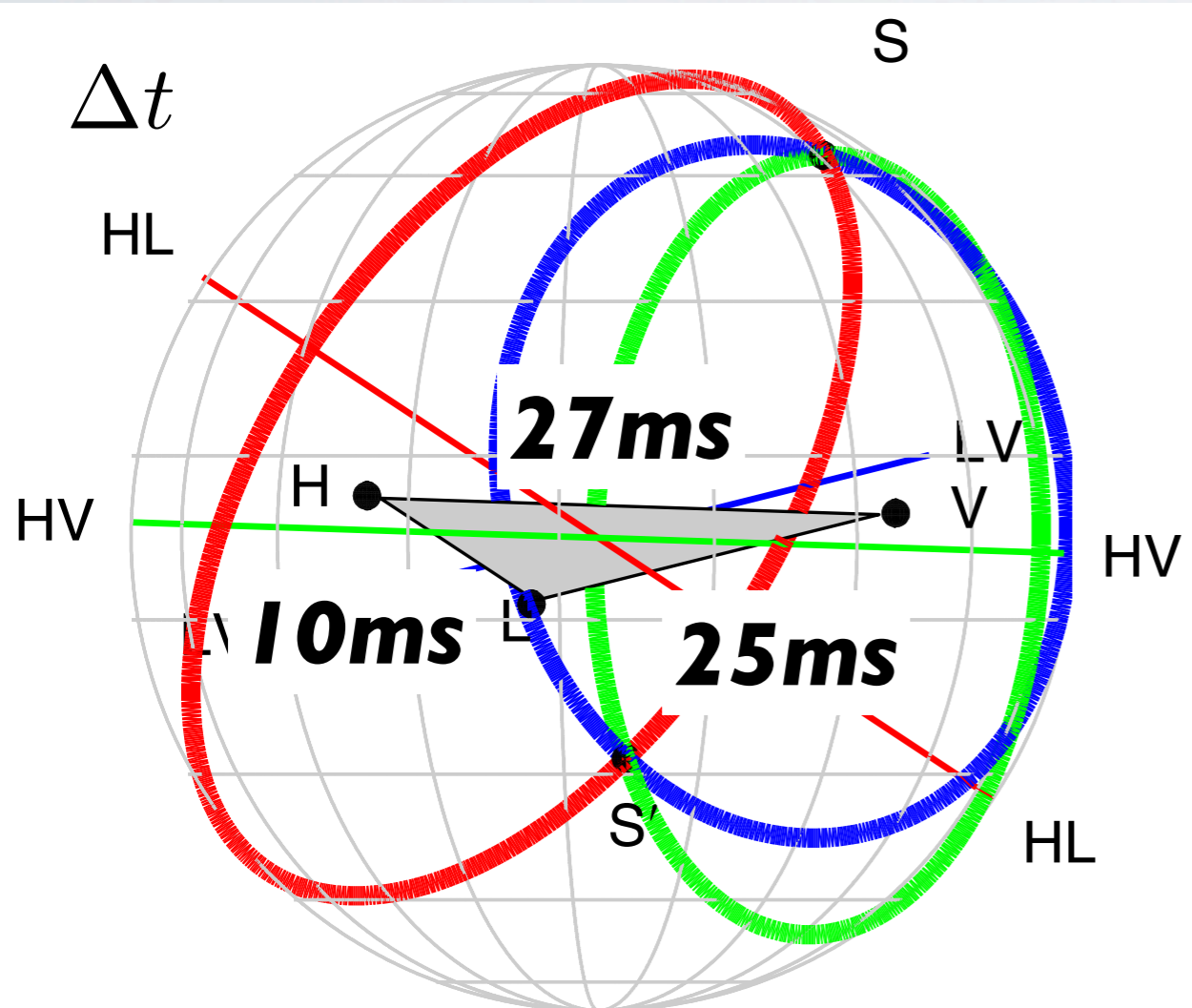
- Noise background falls off rapidly at high SNR, due to sophisticated analysis pipeline Babak et al, arXiv:1208
- Matched filtering analysis
- Signal consistency tests
- Data quality cuts
- For following examples:
 - Require combined SNR > 12 for detection
 - SNR > 5 in two detectors
 - SNR > 3 to contribute to localisation



Abadie et al PRD (2012)

LOCALISATION FROM TIMING

$$\sin \theta d\theta = \frac{\sqrt{\sigma_1^2 + \sigma_2^2}}{\Delta t} \sim \frac{10^{-4} s}{10^{-2} s}$$



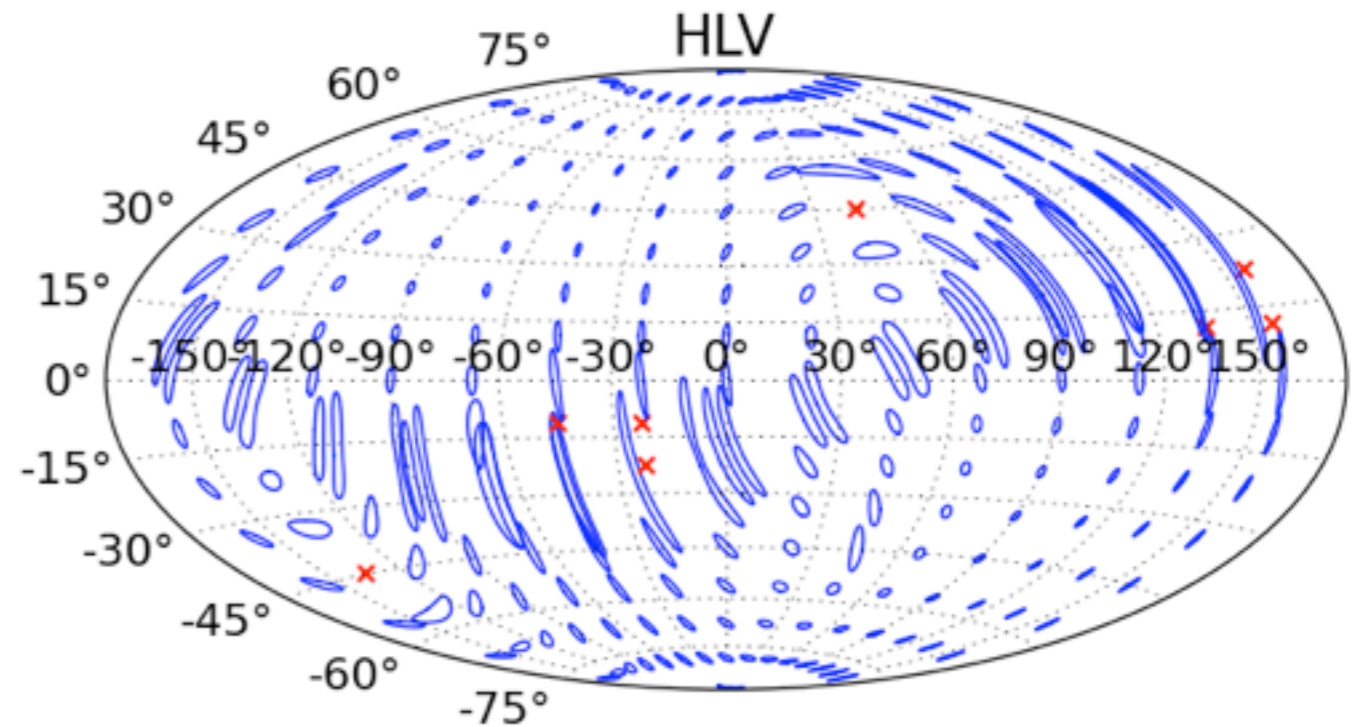
CAVEATS

- Results use only timing information, but assuming can break reflection degeneracy for 3 sites [Veitch talk]
- Use Gaussian approximation to localisation (breaks down at low SNR)
- Have neglected effects of discrete “template bank”
- Have neglected spin (precession) effects [Harry, Raymond talks]

LIGO-VIRGO AT DESIGN

- LIGO 200 Mpc
- Virgo 120 Mpc
- Assume 80% duty cycles
- 0.2 - 200 BNS signals per year

Face on BNS @ 160 MPc

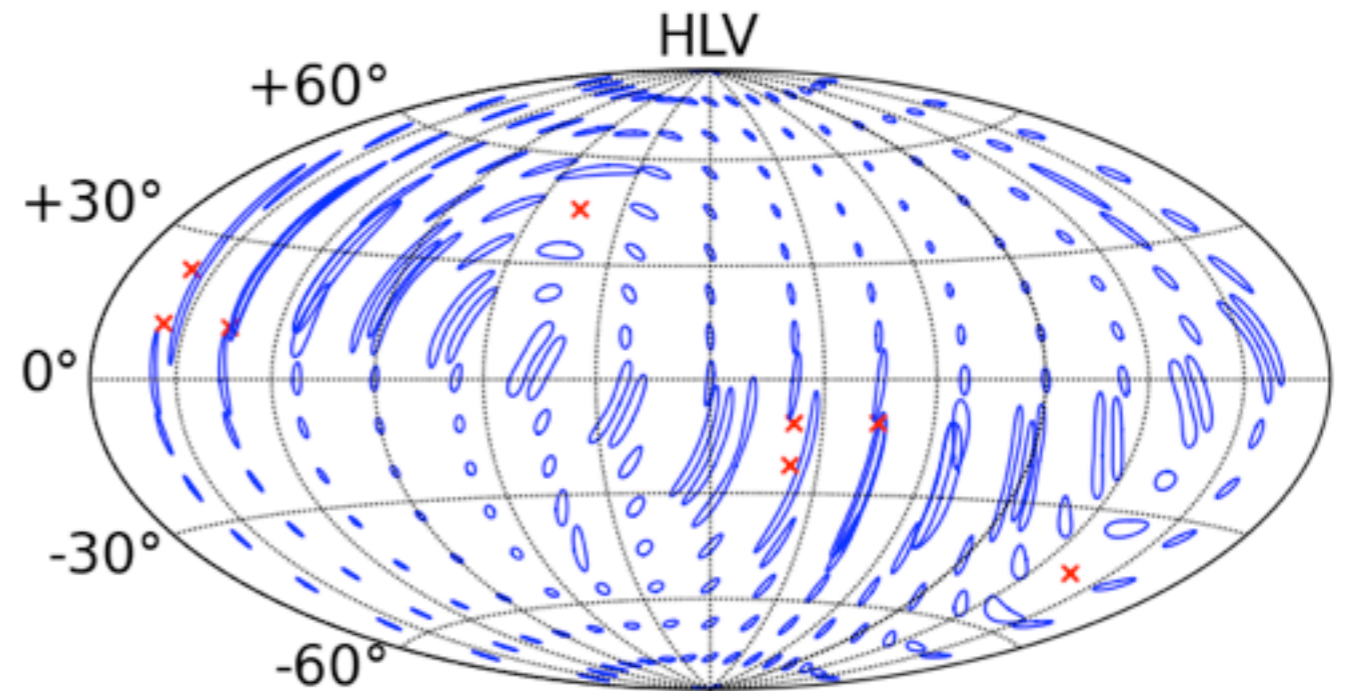


90% confidence regions

LIGO-VIRGO AT DESIGN

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Face on BNS @ 160 MPc

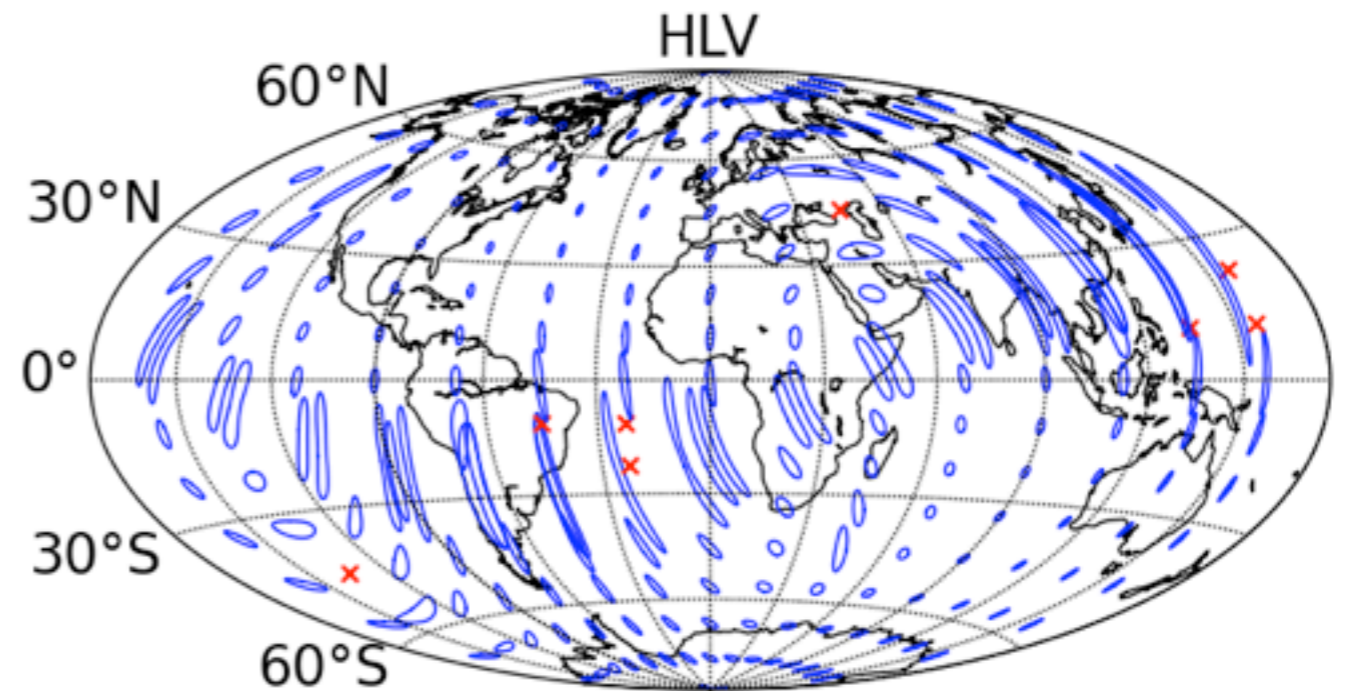


90% confidence regions

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Face on BNS @ 160 MPc

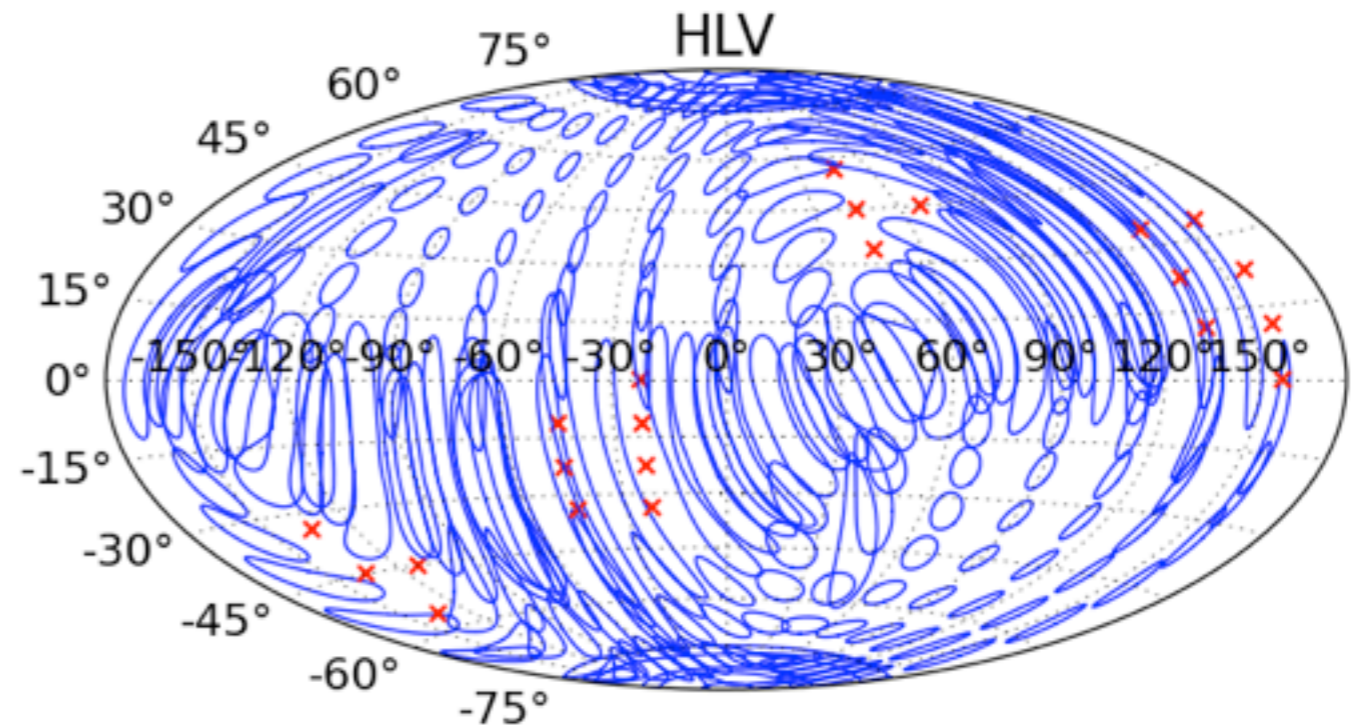


90% confidence regions

NO SIGNAL RECYCLING

- LIGO 160 Mpc
- Virgo 100 Mpc
- Assume 80% duty cycles
- 0.1 - 100 BNS signals per year

Face on BNS @ 160 MPc

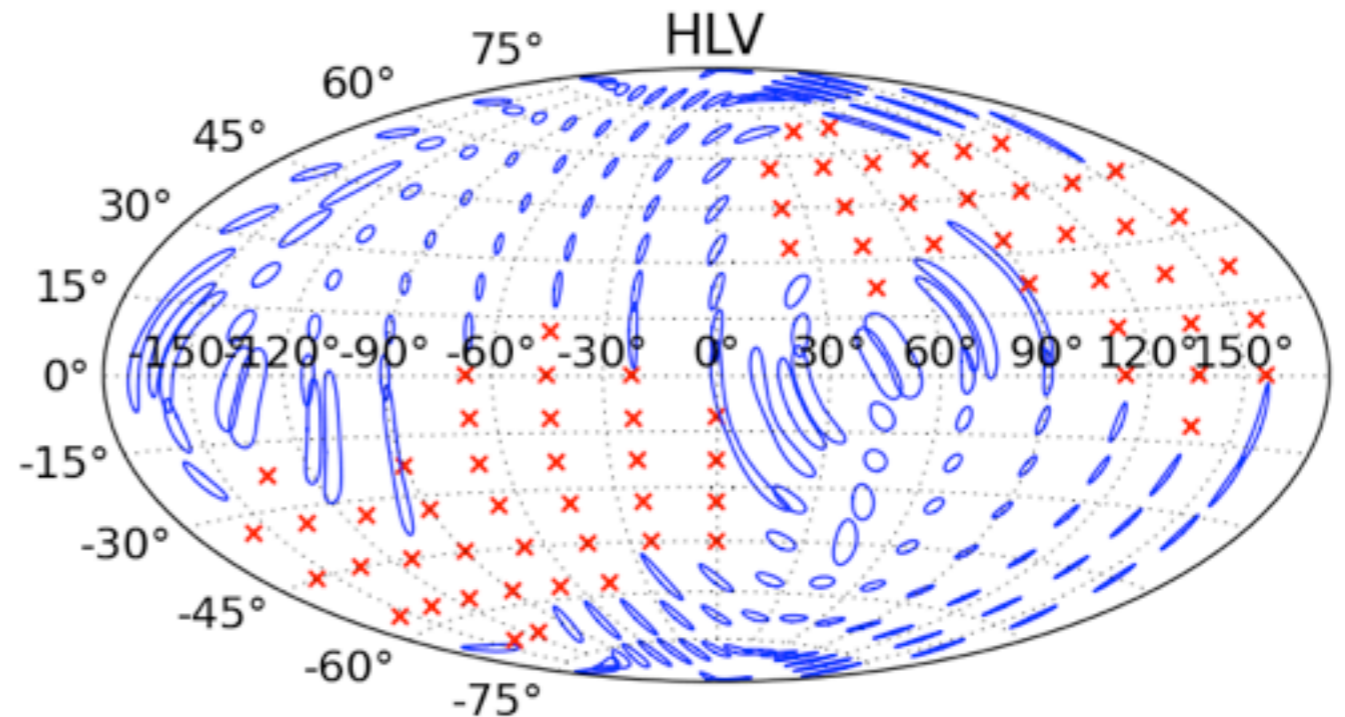


90% confidence regions

LIGO (half commissioned) - VIRGO

- LIGO ~~200 Mpc~~ 100 Mpc
- Virgo 120 Mpc
- Assume 80% duty cycles
- 0.05 - 50 BNS signals per year

Face on BNS @ 160 MPc

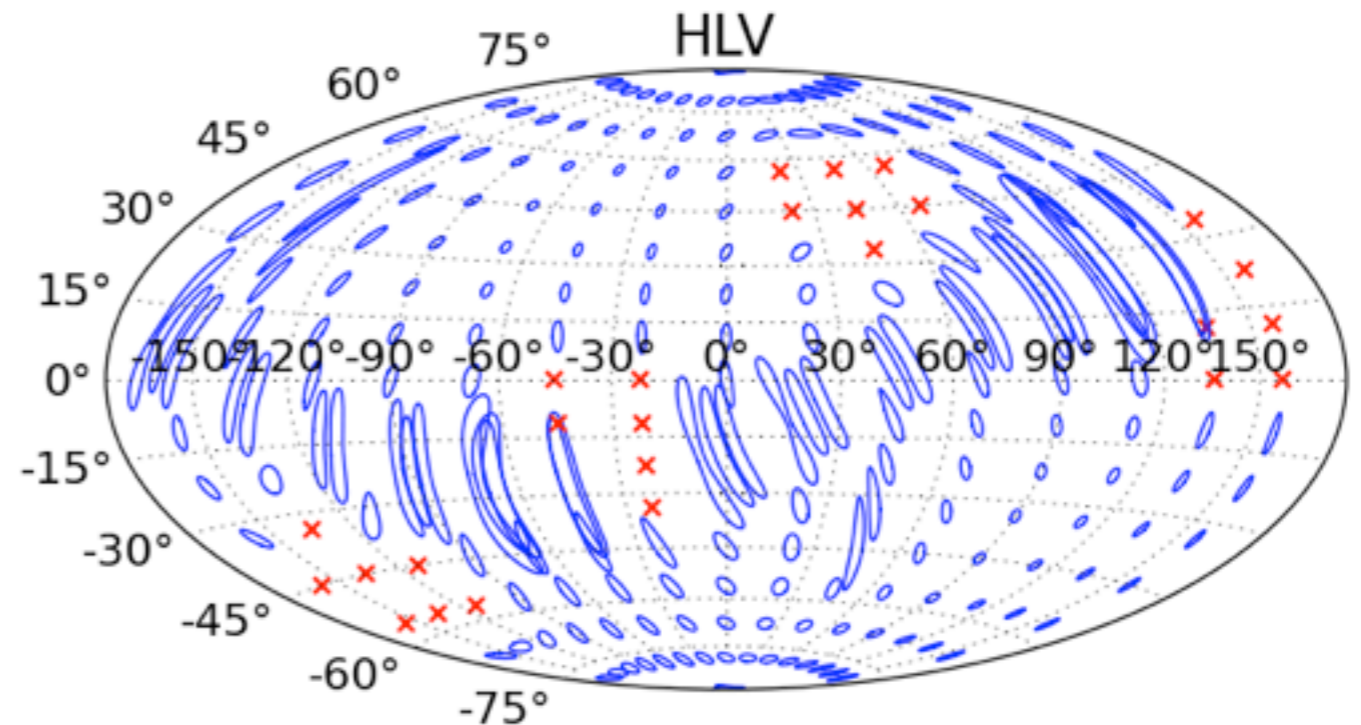


90% confidence regions

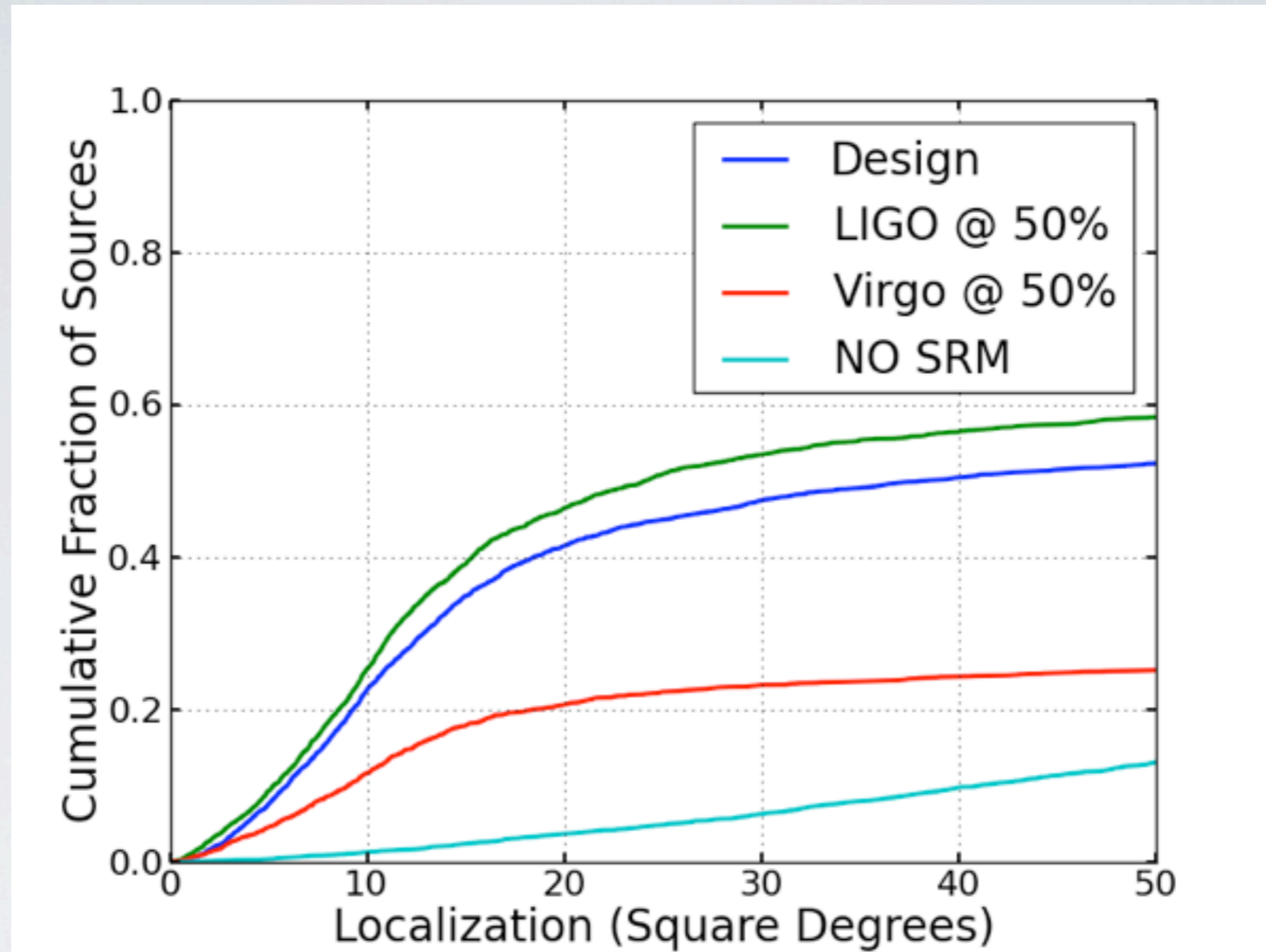
LIGO-VIRGO (half commissioned)

- LIGO 200 Mpc
- Virgo ~~+20 Mpc~~ 60 Mpc
- Assume 80% duty cycles
- 0.2 - 200 BNS signals per year

Face on BNS @ 160 MPc



90% confidence regions

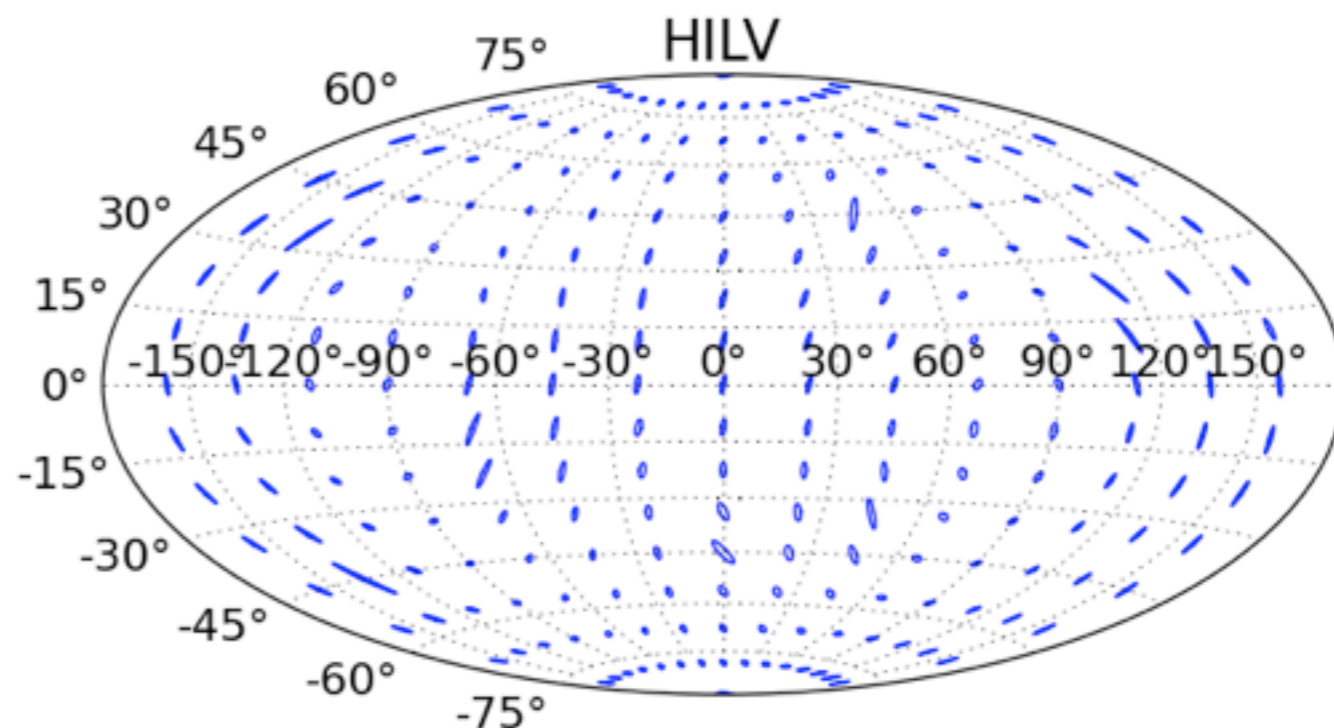


LOCALISATION OF SOURCES

WITH LIGO INDIA

- LIGO (inc India) 200 Mpc
- Virgo 120 Mpc
- Assume 80% duty cycle
- 0.4 -400 BNS signals per year

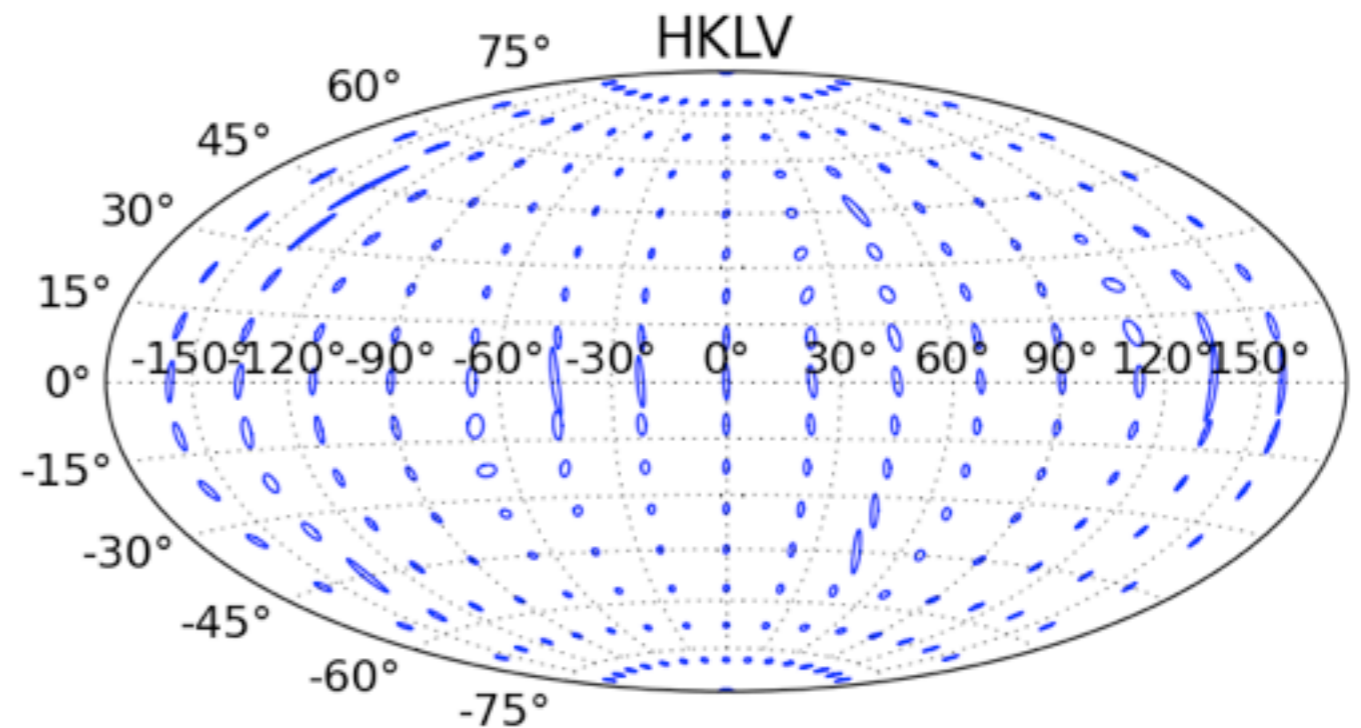
Face on BNS @ 160 MPc



WITH KAGRA

- LIGO 200 Mpc
- Virgo 120 Mpc
- KAGRA 160 Mpc
- Assume 80% duty cycle
- 0.3-300 BNS signals per year

Face on BNS @ 160 MPc

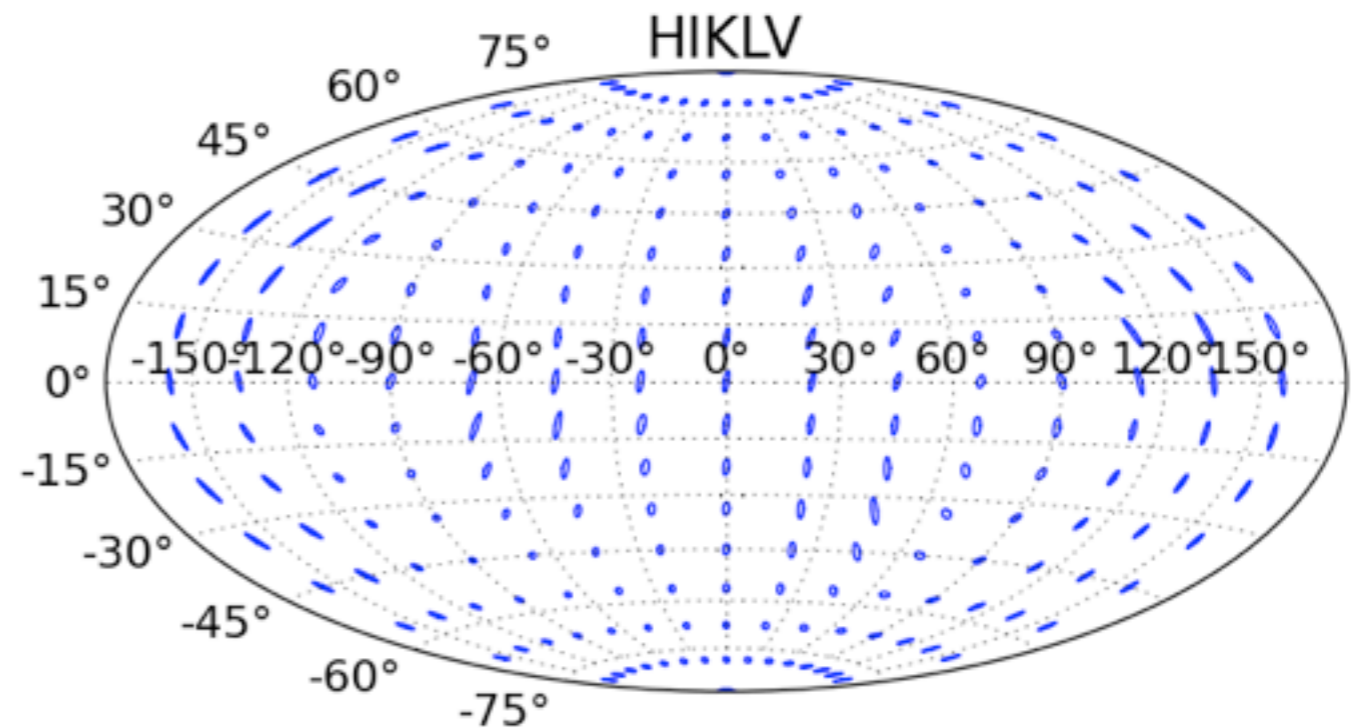


90% confidence regions

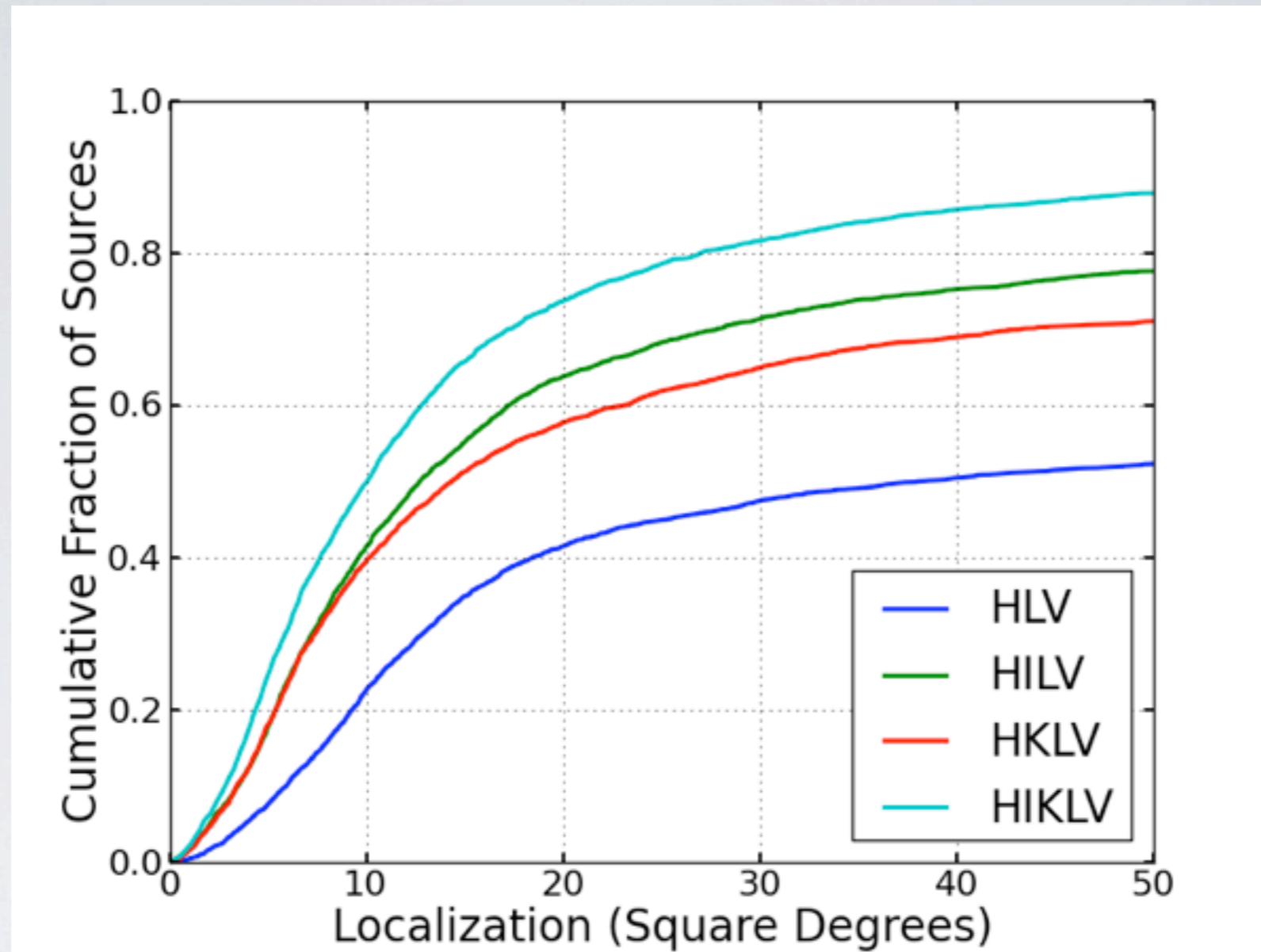
5 SITES

- LIGO (inc India) 200 Mpc
- Virgo 120 Mpc
- KAGRA 160 Mpc
- Assume 80% duty cycle
- 0.5-500 BNS signals per year

Face on BNS @ 160 MPc



90% confidence regions



LOCALISATION OF SOURCES

WAVEFORMS AND CALIBRATION

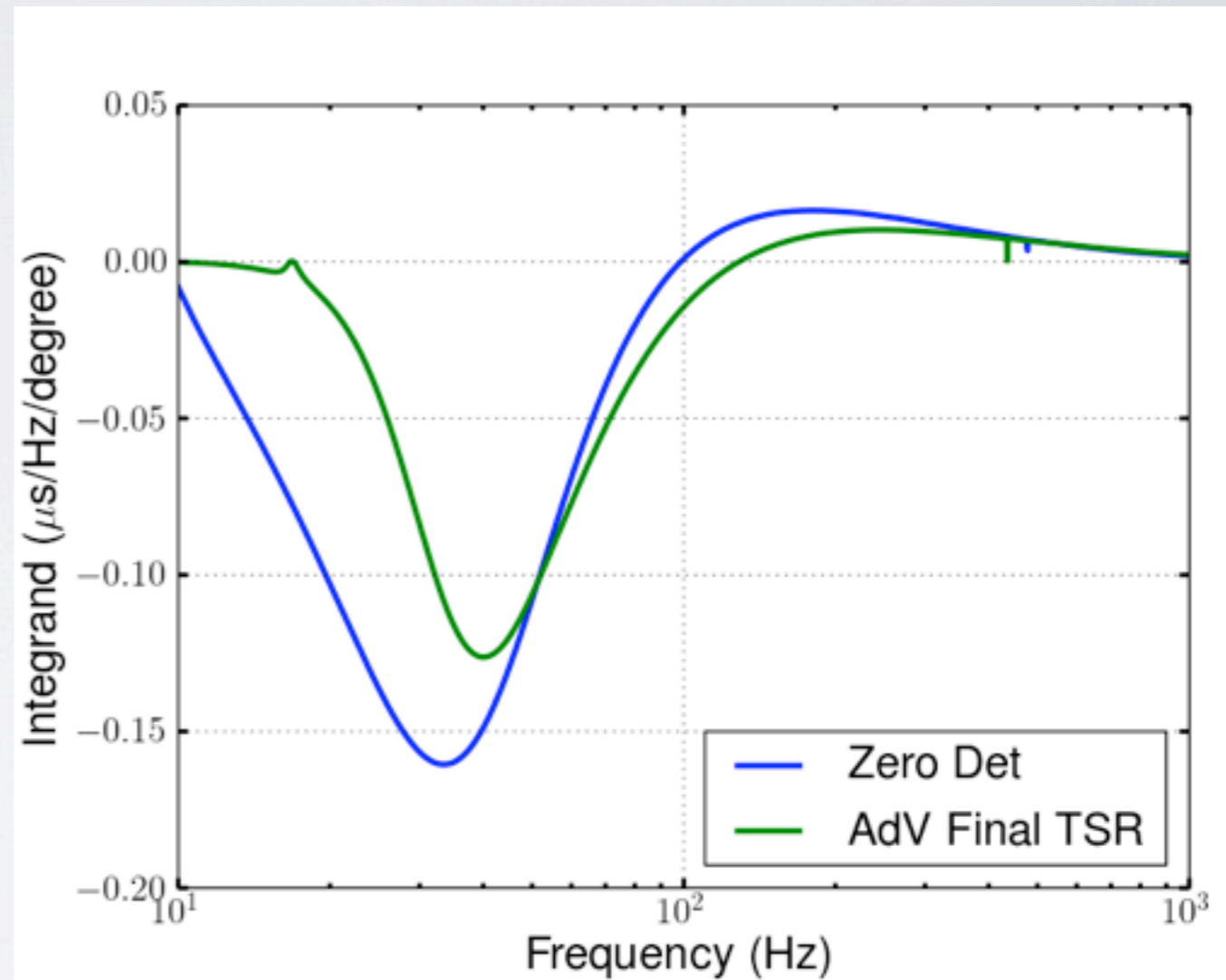
- Phase error introduces a timing systematic

$$|\delta t| \leq \frac{1}{\sigma_f} \left[\frac{\delta\phi_{\max}}{2\pi} \right]$$

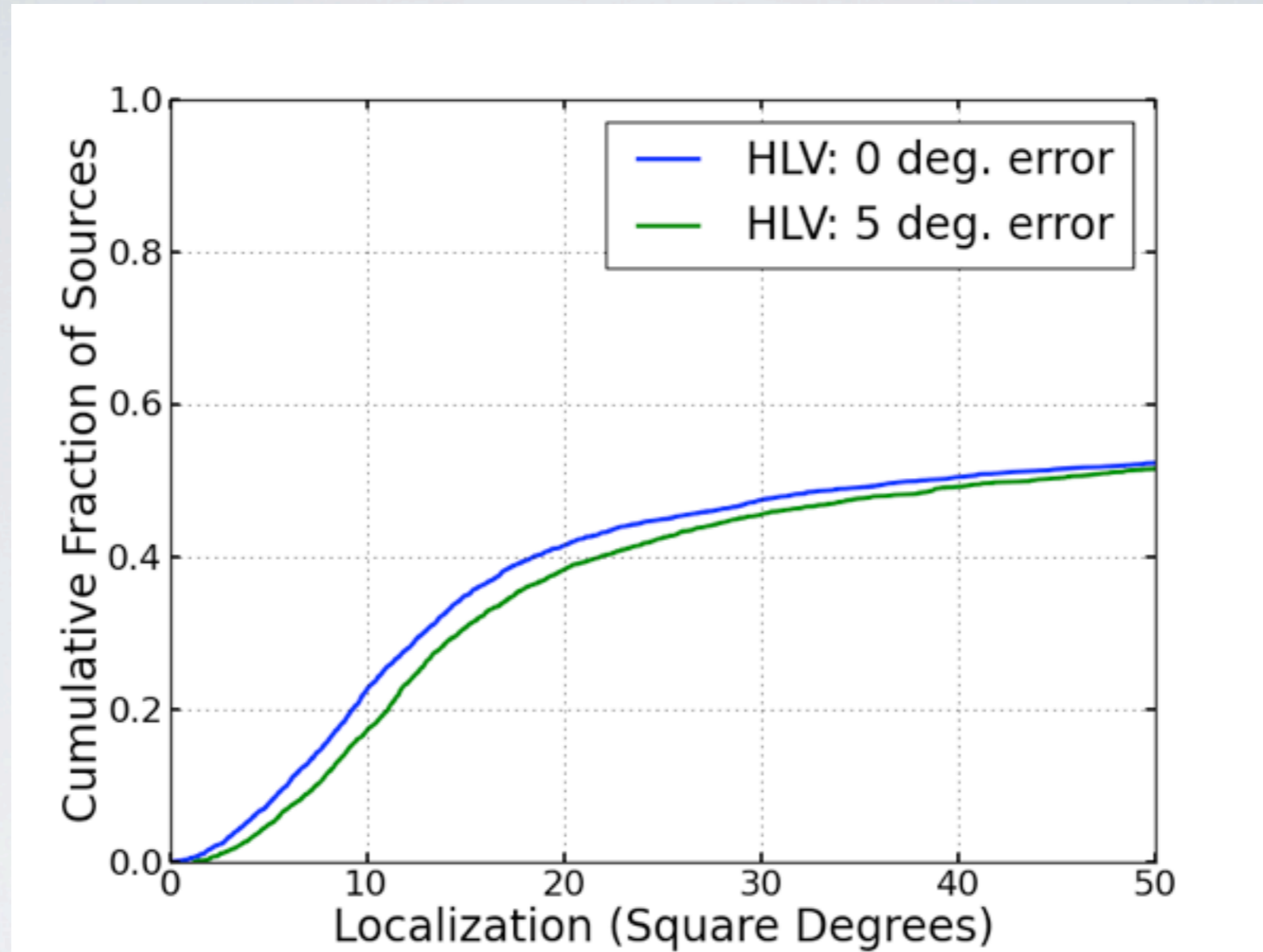
- True for all PSDs; for realistic ones, typically factor of 2 better
- Compare to statistical error

$$\sigma_t = \frac{1}{2\pi\rho\sigma_f}$$

- 5° systematic subdominant below SNR of 20



Contribution to phase error
(multiply by $\delta\phi$ and integrate)

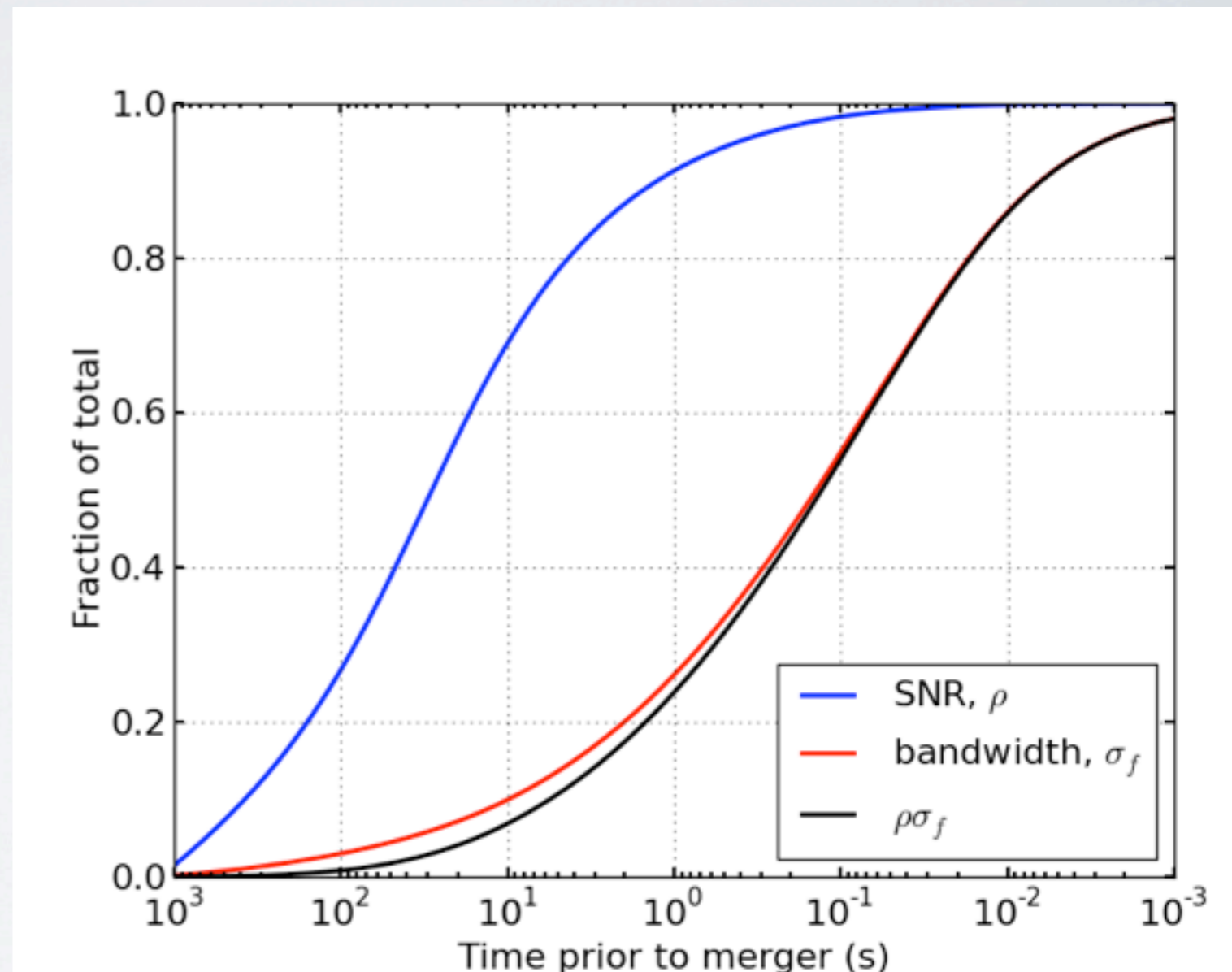


EFFECT ON LOCALISATION

LATENCY

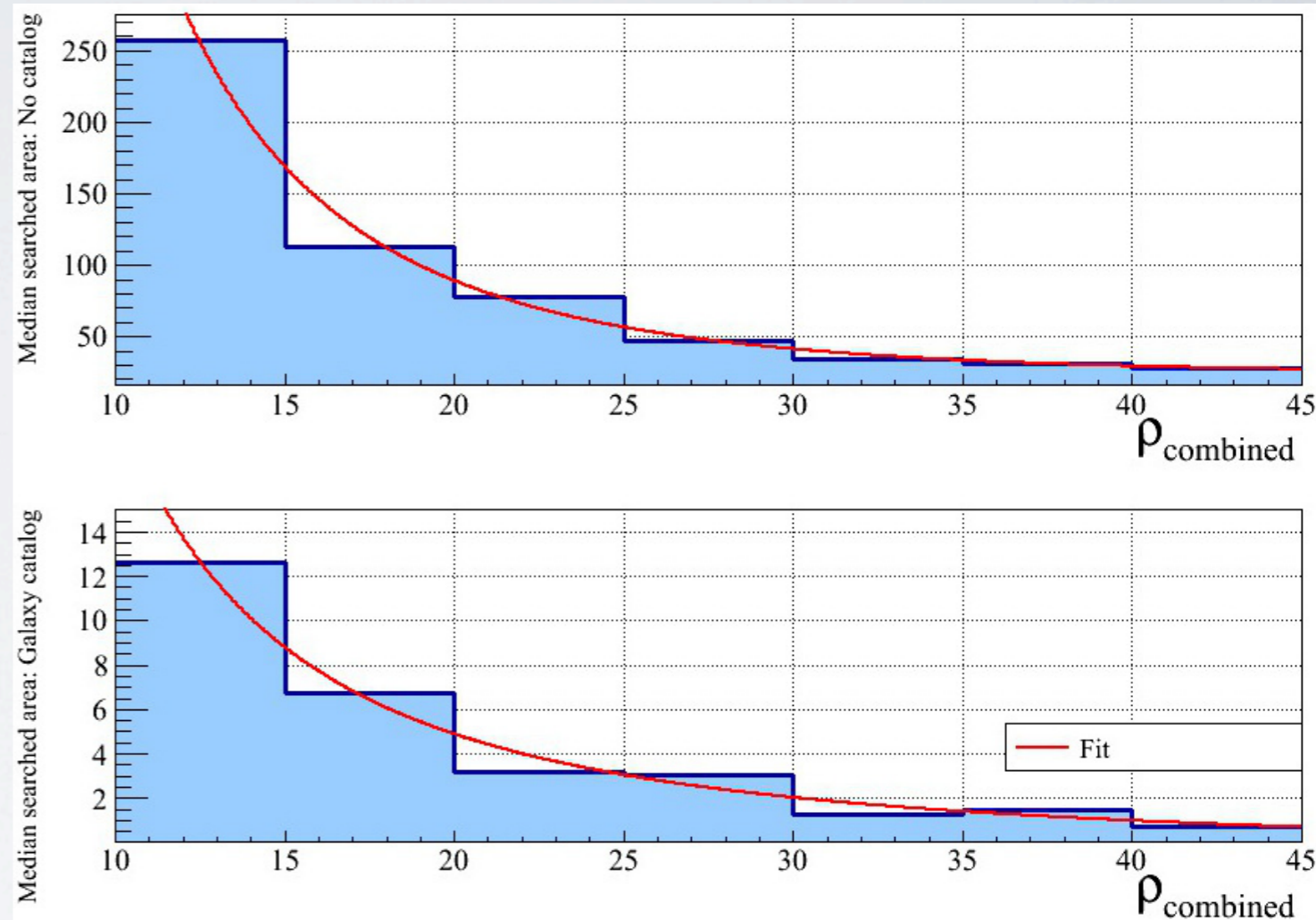
LOCALISATION BEFORE MERGER?

- In advanced detectors, BNS signals spend minutes in band
- Might detect a loud signal a minute ahead.
- But localisation comes in the last second.



S6-VSR3 LOW LATENCY

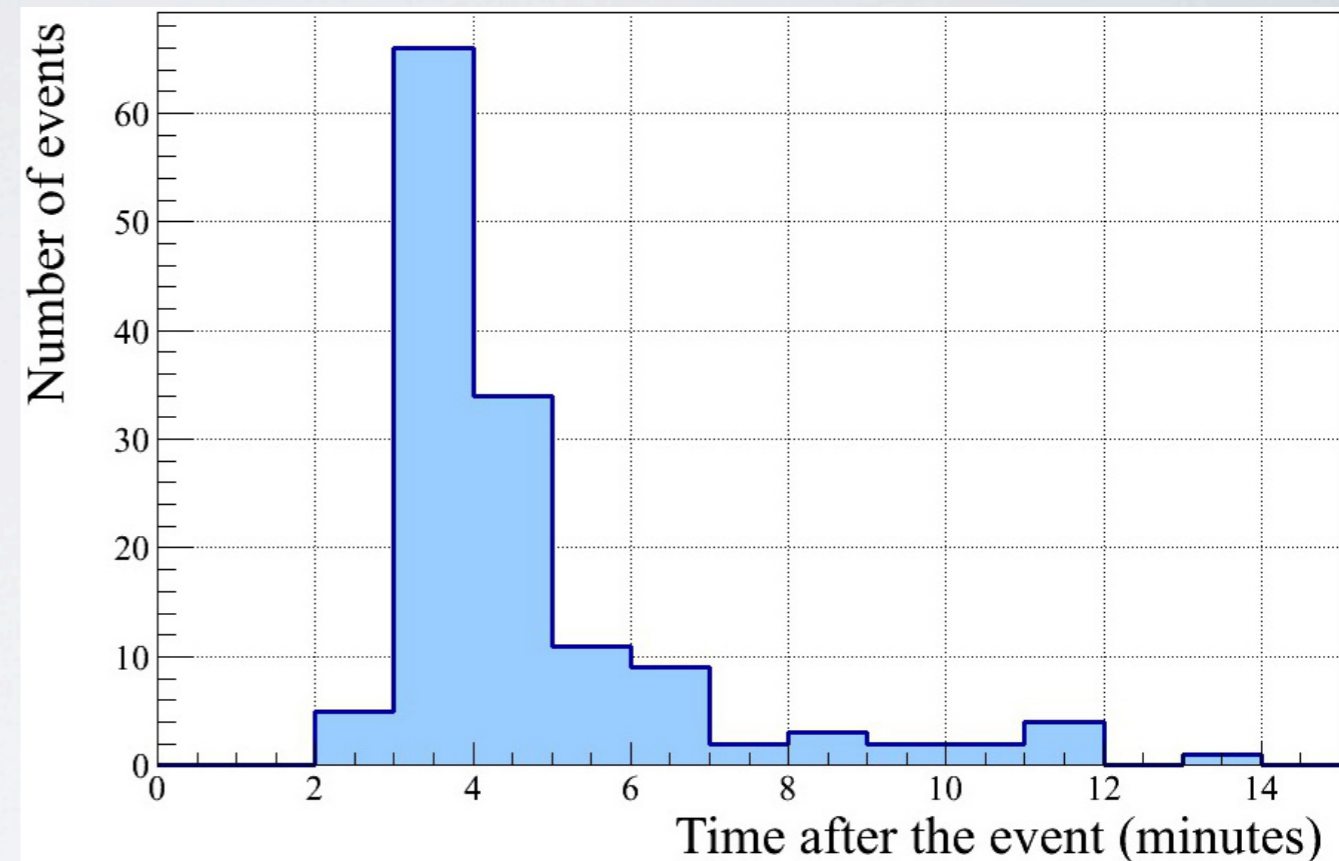
- Low latency search was done in S6-VSR2/3
- Used timing and amplitude information for rapid localisation
- Areas comparable to theoretical predictions



Abadie et al, A&A 2012

S6-VSR3 LOW LATENCY

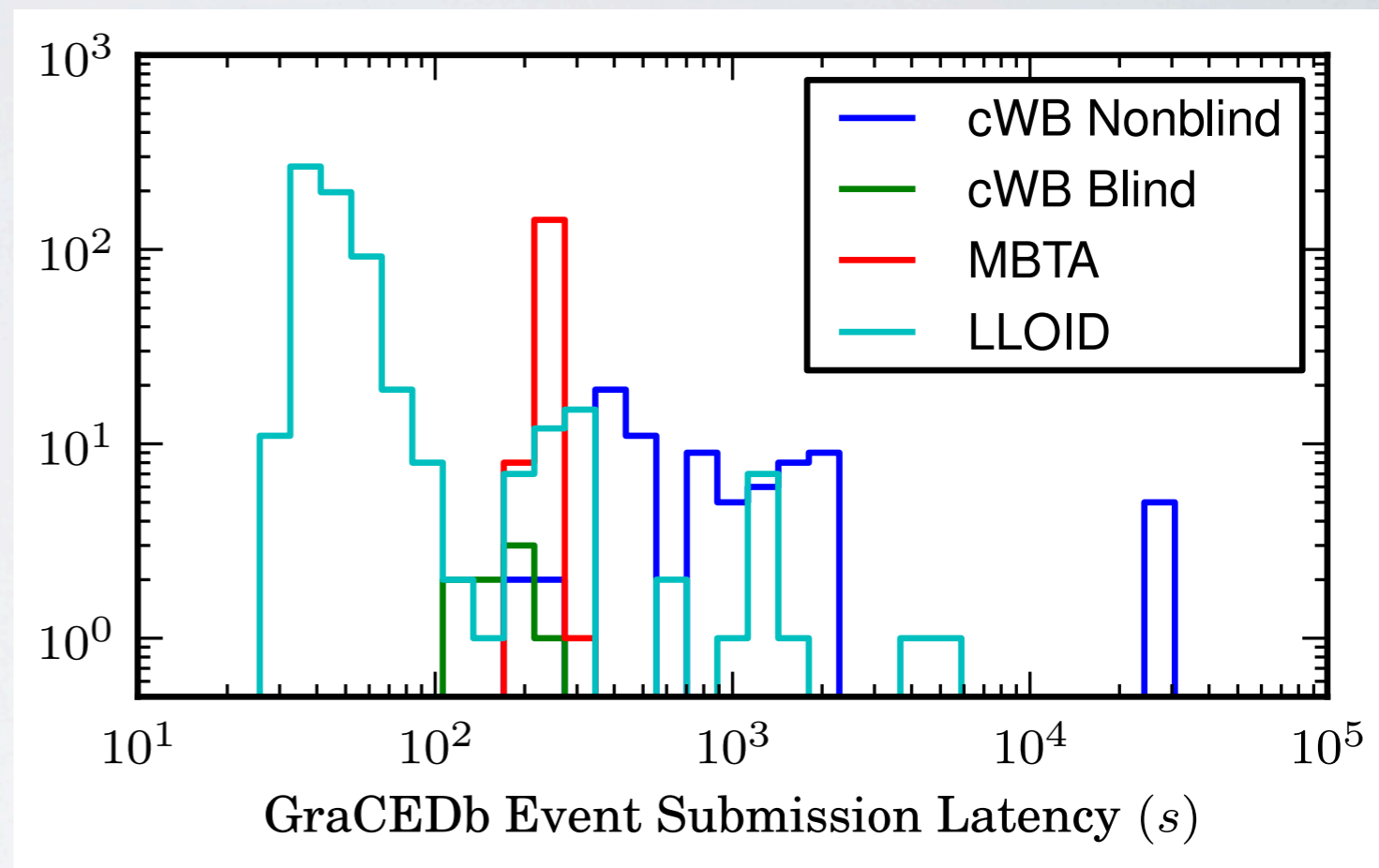
- Latencies of minutes for the analysis were achieved
- There was then a human check of instrumental performance



Abadie et al, A&A 2012

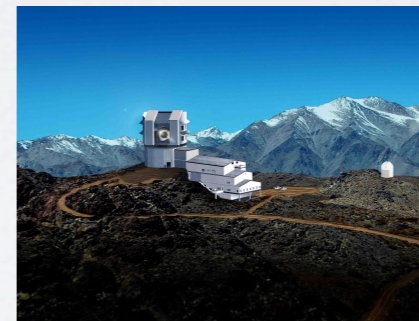
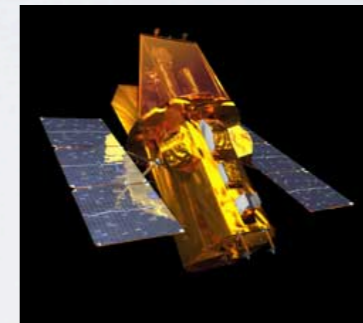
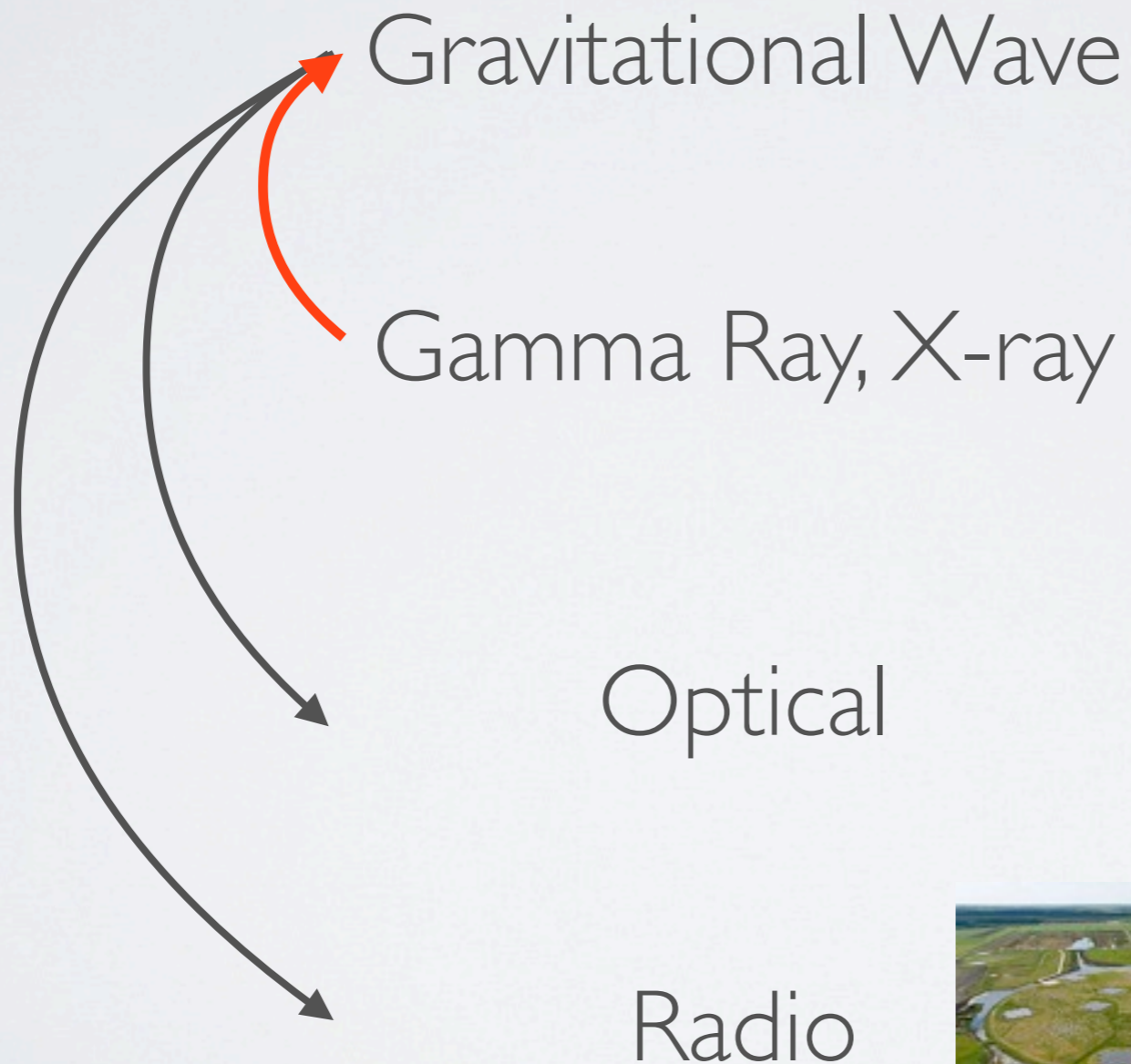
ADVANCED DETECTOR LATENCY

- Low latency much harder
 - 10x longer templates
 - 10x as many templates
- Significant effort to achieve minutes latency
- Achieved in recent “engineering runs” using simulated data at advanced detector design



Keppel for the LSC and Virgo, GWPAW 2012 poster

ALTERNATIVE LOCALISATION ROUTE



SUMMARY

- Advanced detectors will approach their design sensitivities toward the end of the decade
- Localisation areas of 10s of deg^2 with three sites
- Additional sites in India and Japan give significant improvement
- Latency of minutes is possible
- Rapid follow up of observed GRBs could give localised GW sources.