

# MACHINE LEARNING FOR FLUID MECHANICS

**STEVE BRUNTON**  
**UNIVERSITY OF WASHINGTON**

(Video by Petros Vrellis)

# MACHINE LEARNING FOR FLUID MECHANICS

**Nathan Kutz**



**Bing Brunton**



**Josh Proctor**



**Beverley McKeon**



**Georgios Rigas**



**Bernd Noack**



**JC Loiseau**



**Eurika  
Kaiser**



**Bethany  
Lusch**



**Alan  
Kaptanoglu**



**Isabel  
Scherl**



**Sam  
Rudy**



**Jared  
Callaham**



**Benjamin  
Herrmann**

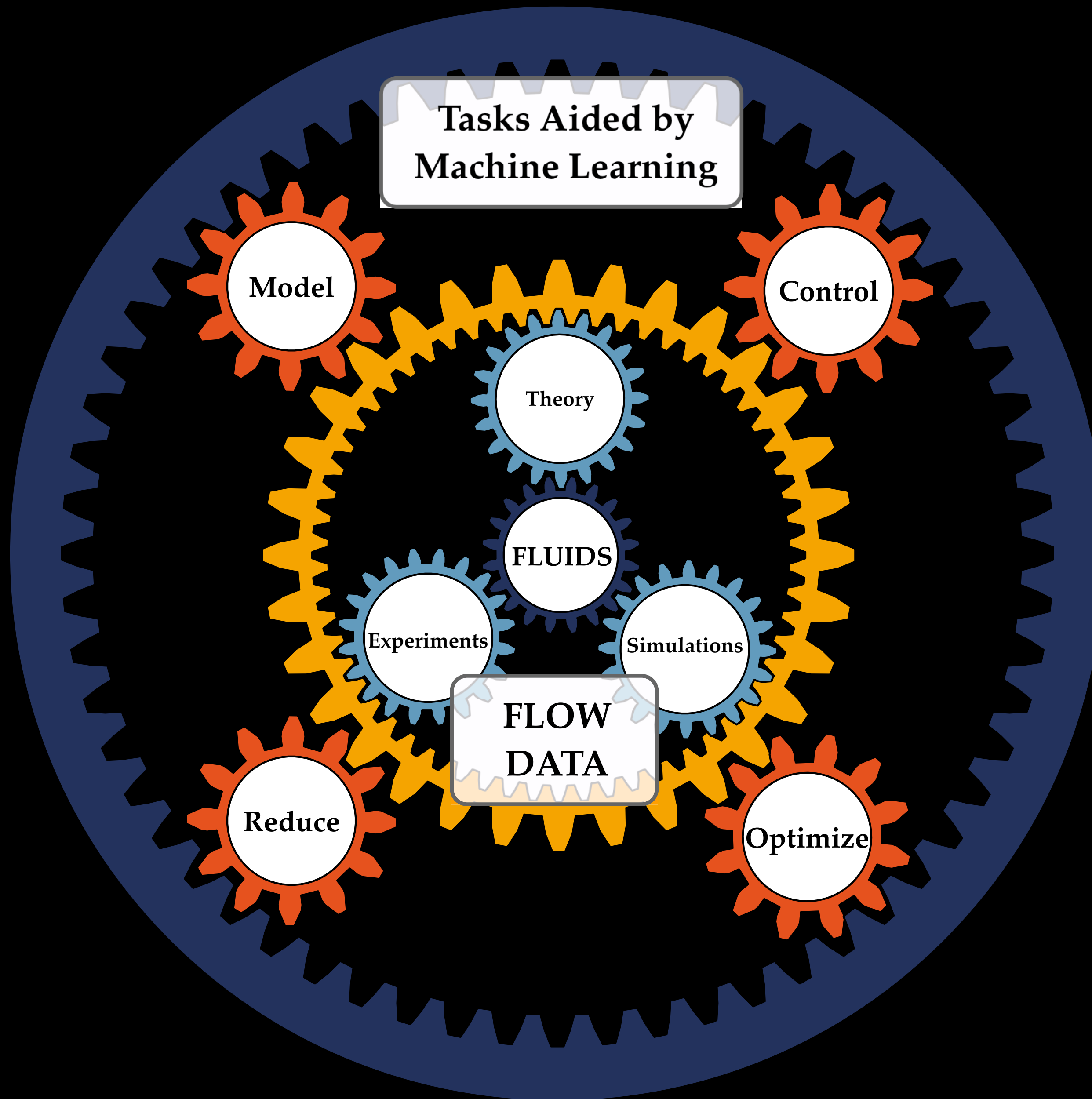


**Kathleen  
Champion**



# Machine Learning for Fluid Mechanics

Steven L. Brunton,<sup>1</sup> Bernd R. Noack,<sup>2</sup> and Petros Koumoutsakos<sup>3,4</sup>



## Keywords

machine learning, data-driven modeling, optimization, control

## Abstract

The field of fluid mechanics is rapidly advancing, driven by unprecedented volumes of data from experiments, field measurements, and large-scale simulations at multiple spatiotemporal scales. Machine learning presents us with a wealth of techniques to extract information from data that can be translated into knowledge about the underlying fluid mechanics. Moreover, machine learning algorithms can augment domain knowledge and automate tasks related to flow control and optimization. This article presents an overview of past history, current developments, and emerging opportunities of machine learning for fluid mechanics. We outline fundamental machine learning methodologies and discuss their uses for understanding, modeling, optimizing, and controlling fluid flows. The strengths and limitations of these methods are addressed from the perspective of scientific inquiry that links data with modeling, experiments, and simulations. Machine learning provides a powerful information processing framework that can augment, and possibly even transform, current lines of fluid mechanics research and industrial applications.

# MACHINE LEARNING: MODELS FROM DATA VIA OPTIMIZATION

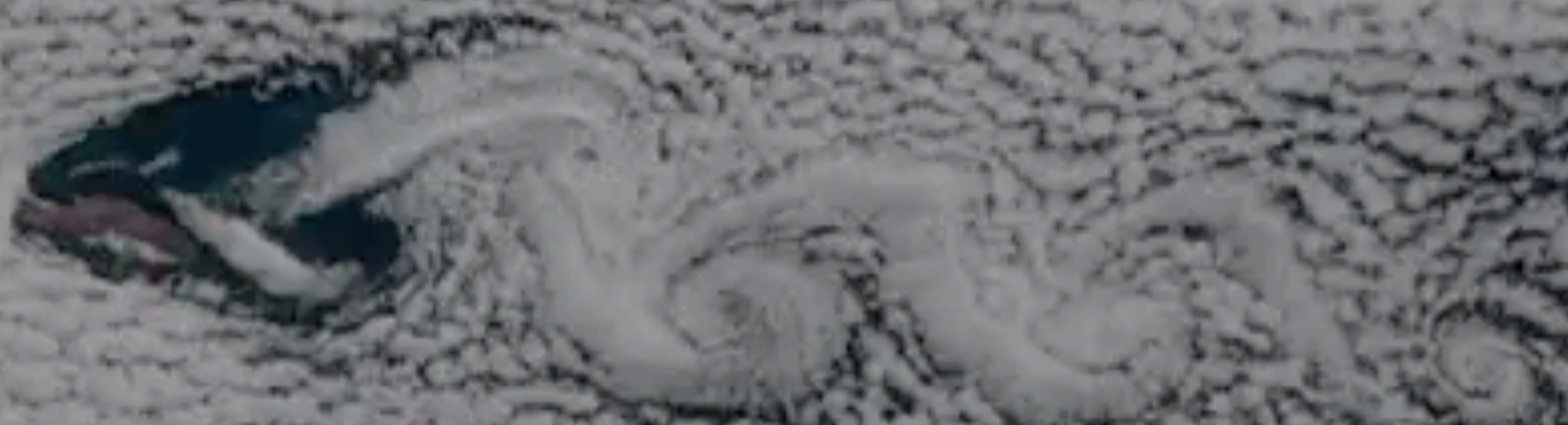
## Optimization Problems:

- ▶ High-dimensional
- ▶ Nonlinear
- ▶ Non-convex
- ▶ Multiscale

## Fluid Dynamics Tasks:

- ▶ Dimension Reduction
- ▶ Reduced Order Modeling
- ▶ Sparse Sensing
- ▶ Control

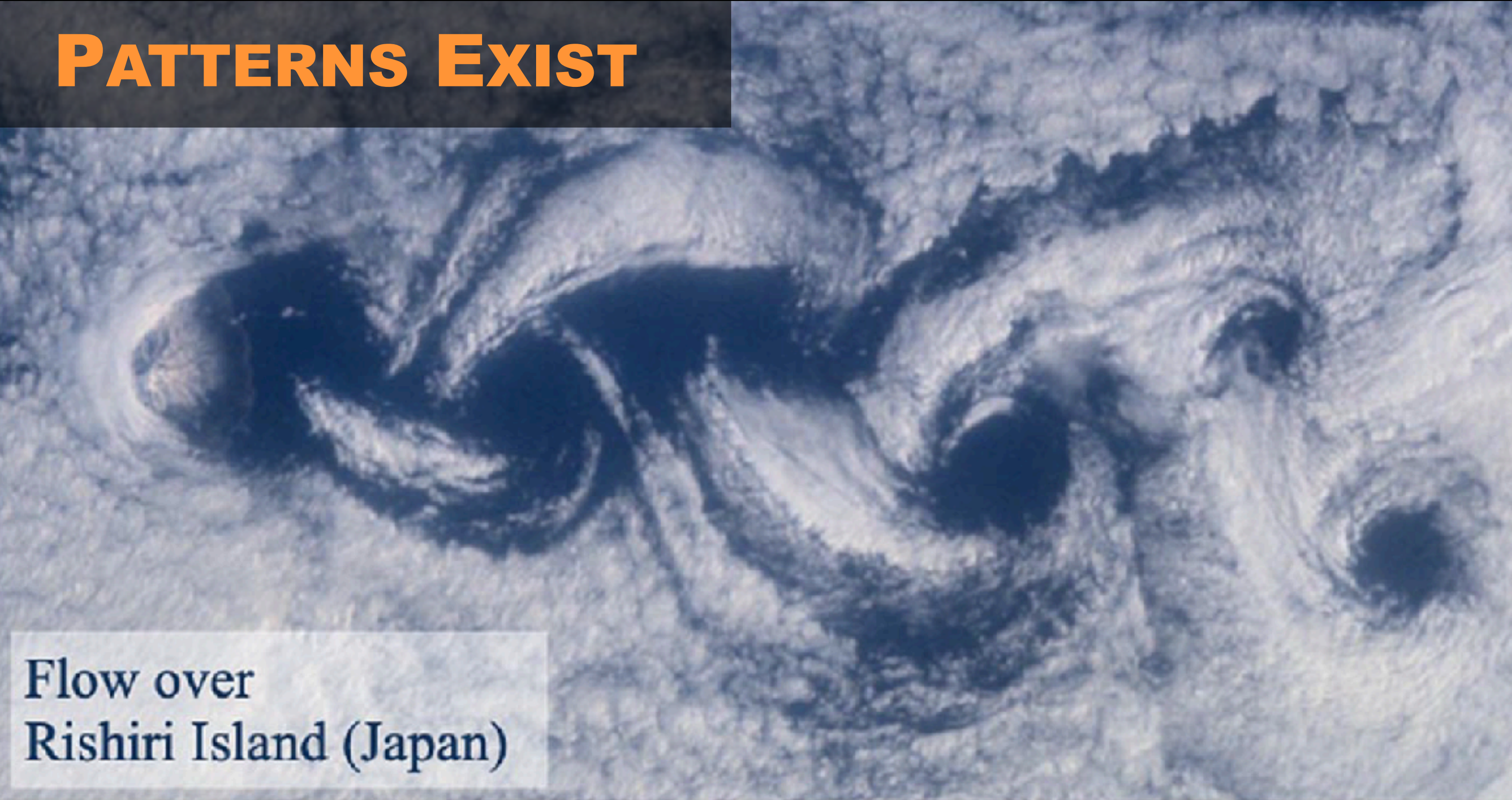
**PATTERNS EXIST**



**@CollinGrossWx**  
**Guadalupe Island**



# PATTERNS EXIST



Flow over  
Rishiri Island (Japan)

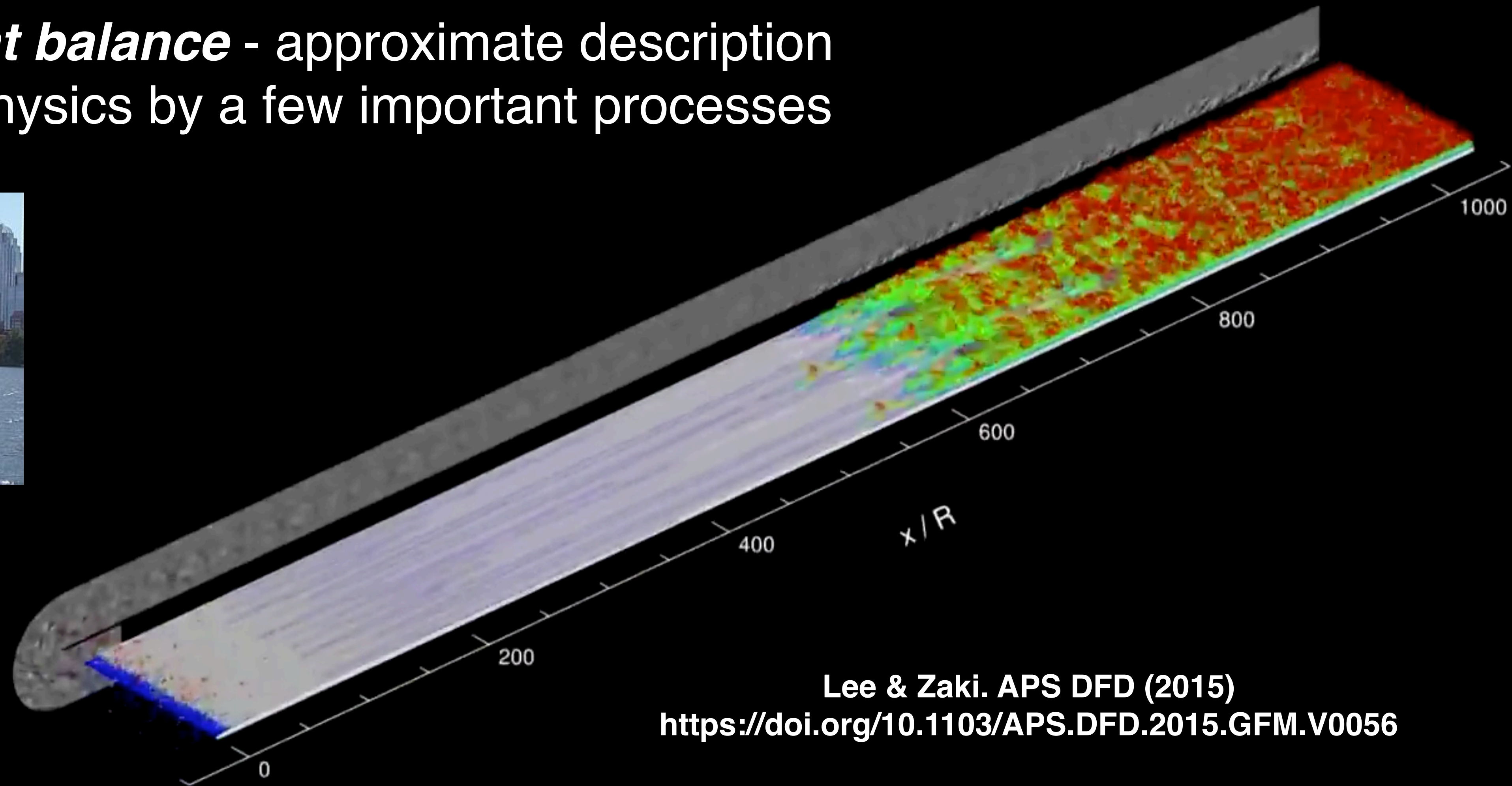


Flow over a cylinder  
( $Re = 100$ )

**Taira et al., AIAA J. 2017**

# DOMINANT BALANCE

*Dominant balance* - approximate description of local physics by a few important processes

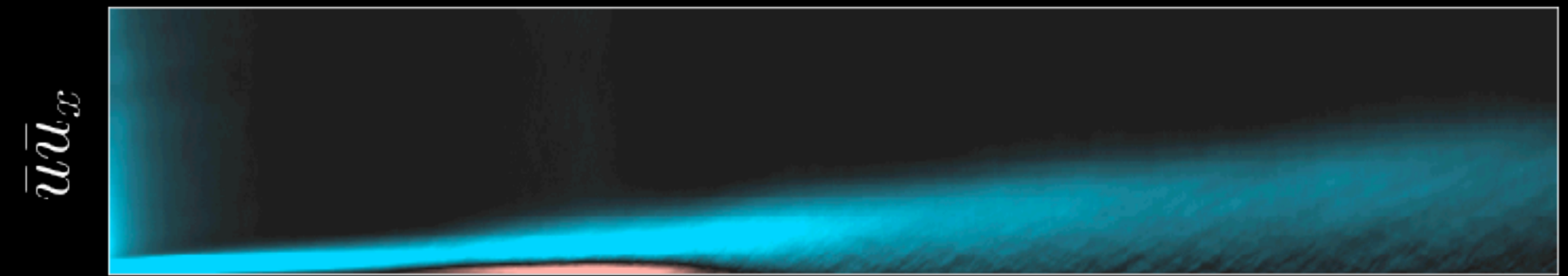


Lee & Zaki. APS DFD (2015)  
<https://doi.org/10.1103/APS.DFD.2015.GFM.V0056>

# Reynolds-averaged Navier-Stokes equations

$$\bar{u}\bar{u}_x + \bar{v}\bar{u}_y + \overline{(u'^2)}_x + \overline{(u'v')} _y = -\rho^{-1}\bar{p}_x + \nu\nabla^2\bar{u}$$

$$u(x, t) = \bar{u}(x) + u'(x, t)$$

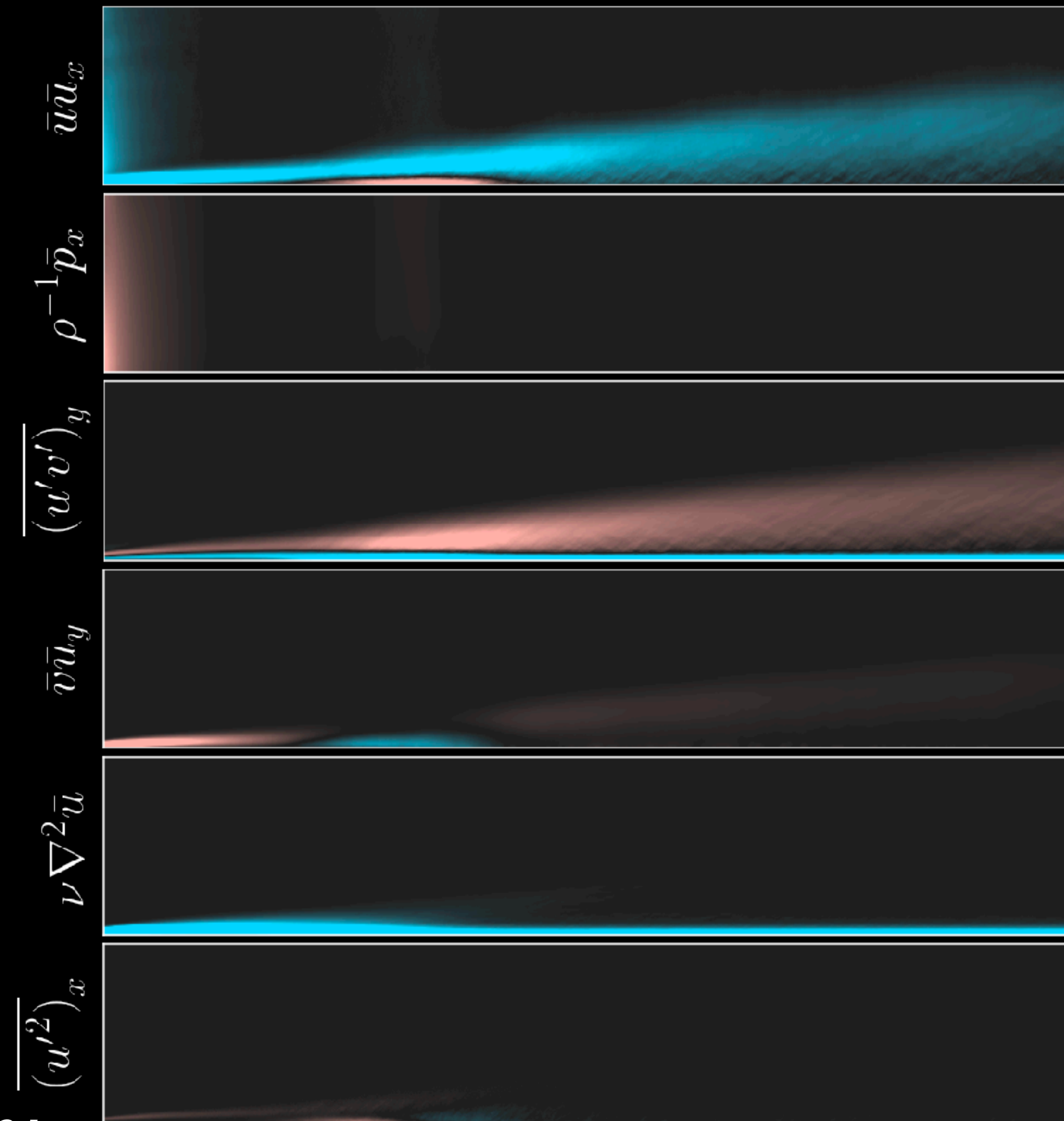




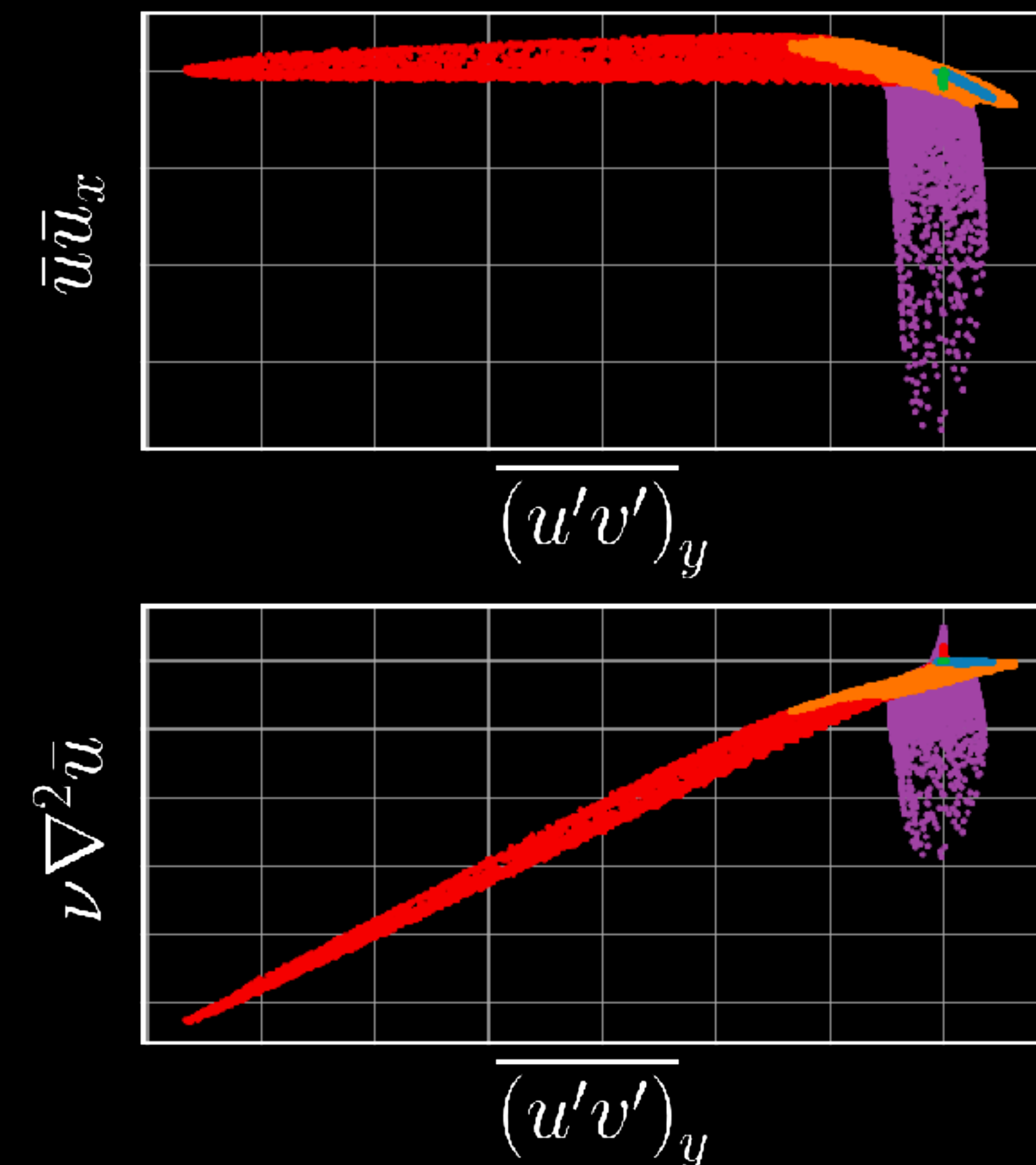
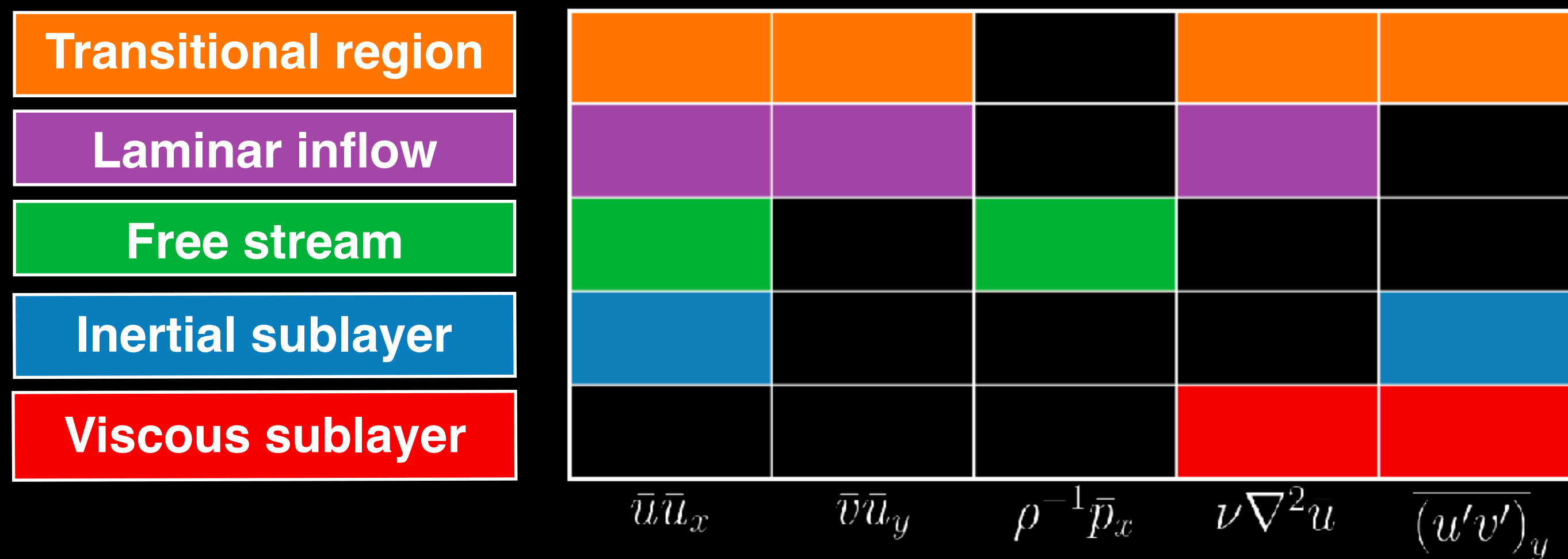
# Reynolds-averaged Navier-Stokes equations

$$\bar{u}\bar{u}_x + \bar{v}\bar{u}_y + \overline{(u'^2)}_x + \overline{(u'v')} _y = -\rho^{-1}\bar{p}_x + \nu\nabla^2\bar{u}$$

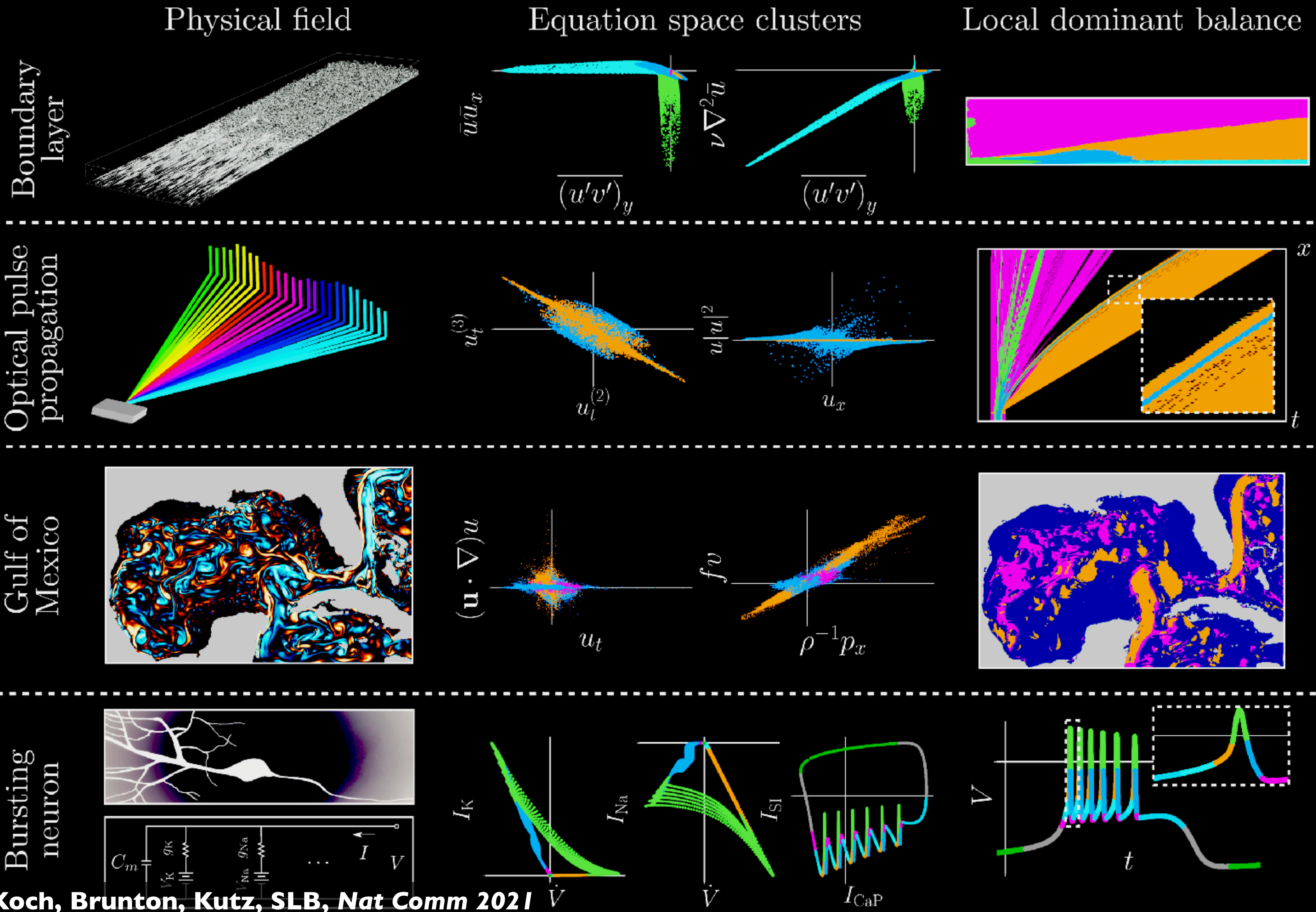
$$u(x, t) = \bar{u}(x) + u'(x, t)$$



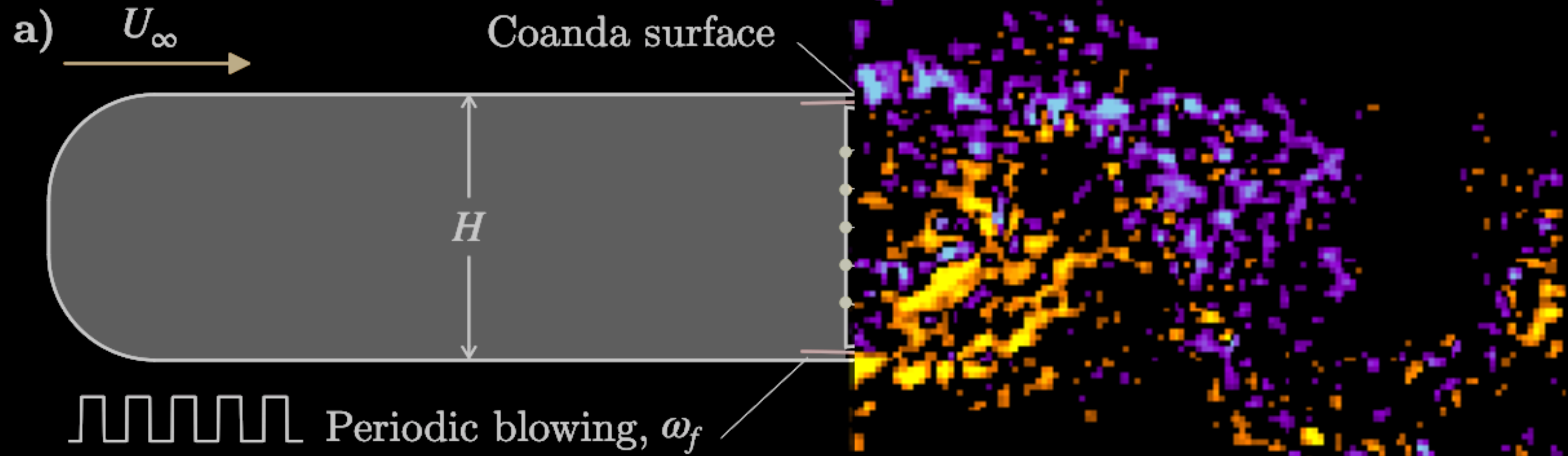
# Equation space representation



- Clustering (GMM)
- Subspace identification (Sparse PCA)
- Interpretable balance laws



# REDUCED ORDER MODELS



$$\frac{d}{dt}\mathbf{x} = \mathbf{f}(\mathbf{x})$$



**There is a need for  
INTERPRETABLE and GENERALIZABLE  
Machine Learning**

© 2017 Google

$$F = ma$$



**There is a need for  
INTERPRETABLE and GENERALIZABLE  
Machine Learning**

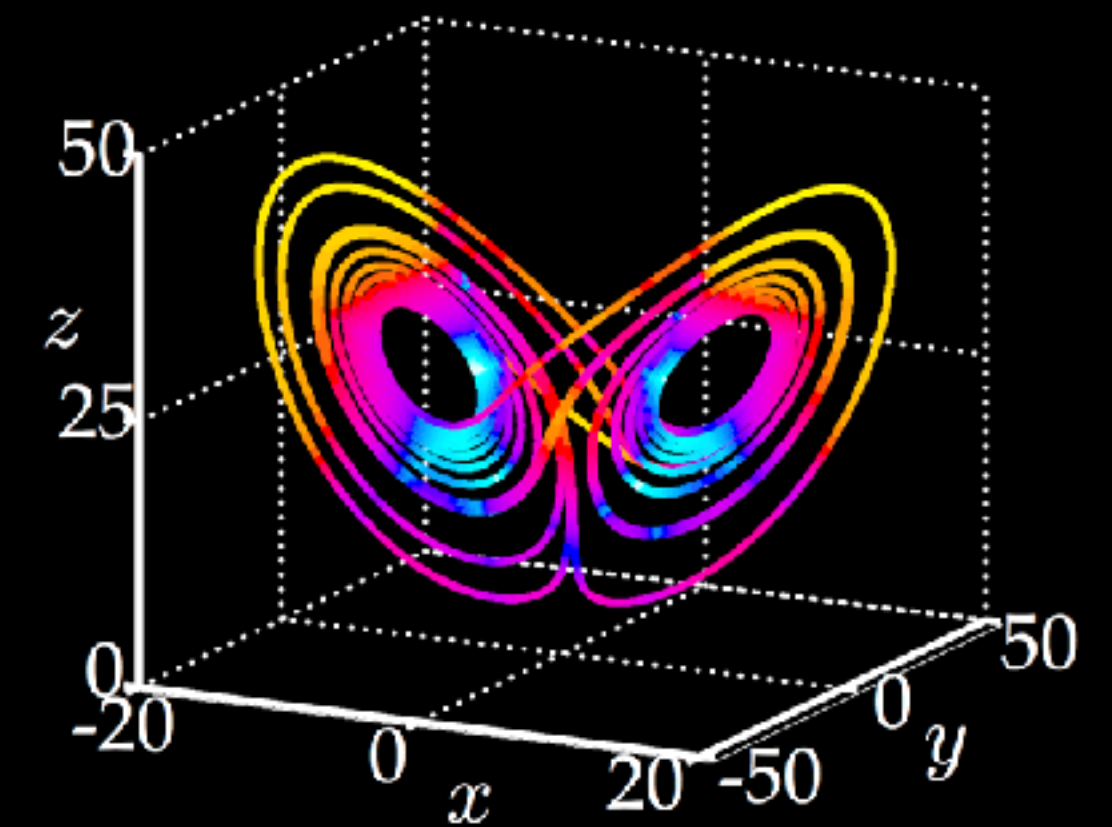
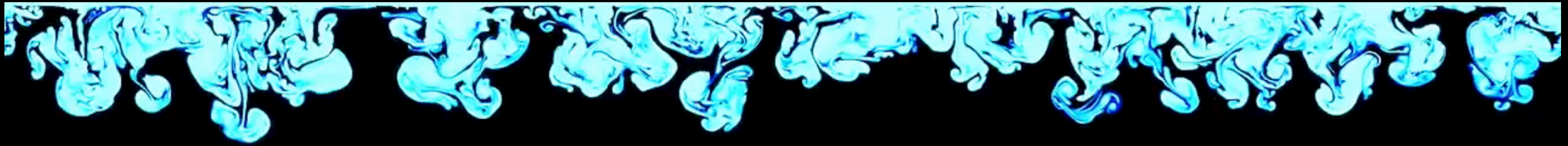
**EVERYTHING SHOULD BE MADE  
AS SIMPLE AS POSSIBLE,  
BUT NOT SIMPLER.**

**Albert Einstein**

**There is a need for**  
**INTERPRETABLE and GENERALIZABLE**  
**Machine Learning**

- **LOW-DIMENSIONAL**
- **SPARSE**

# CHAOTIC THERMAL CONVECTION



$$\dot{x} = \sigma(y - x)$$

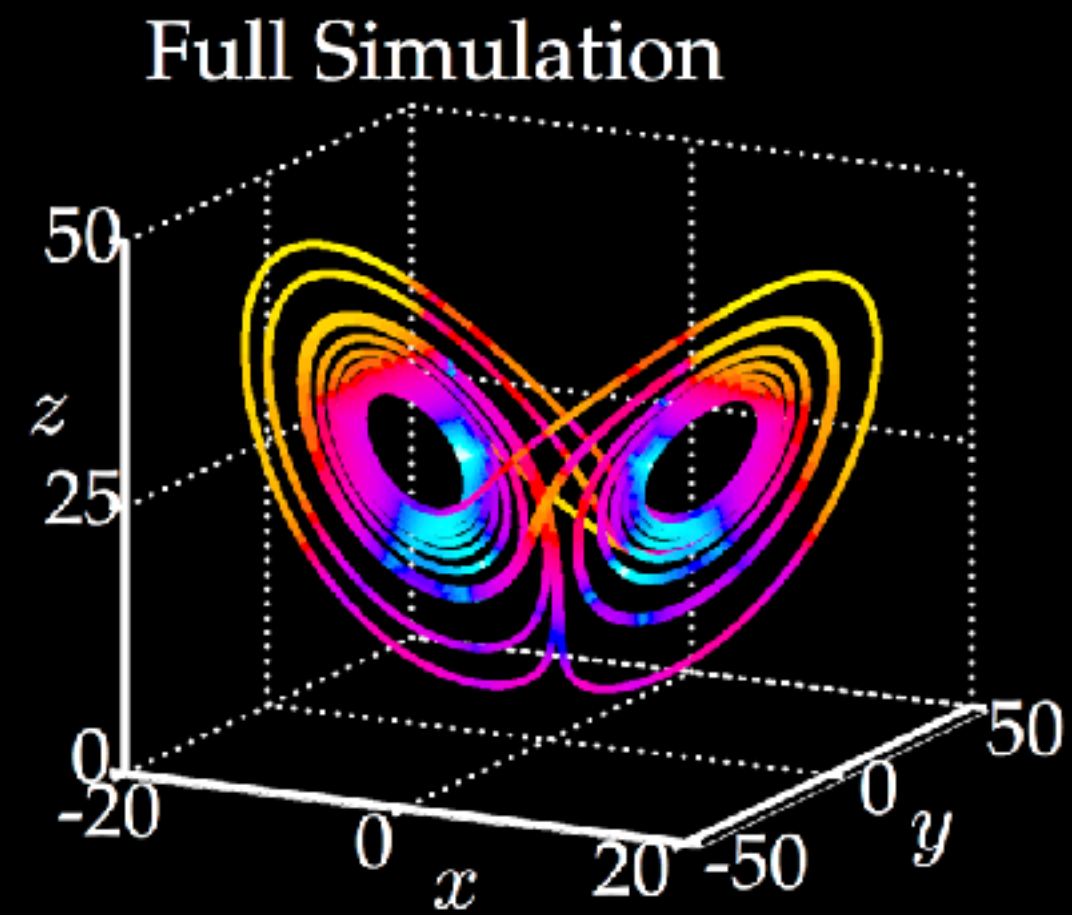
$$\dot{y} = x(\rho - z) - y$$

$$\dot{z} = xy - \beta z.$$



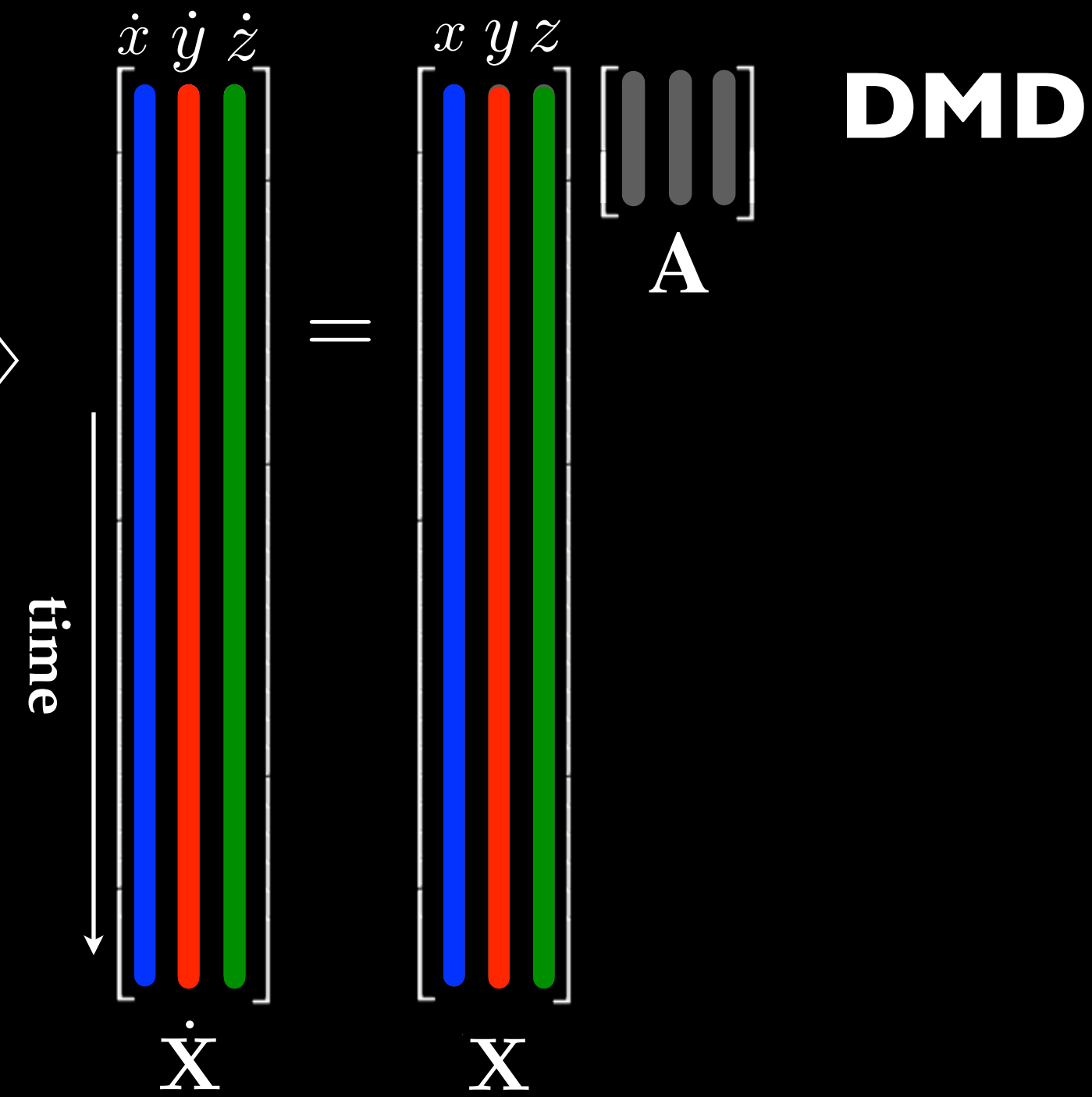


# Sparse Identification of Nonlinear Dynamics (SINDy)

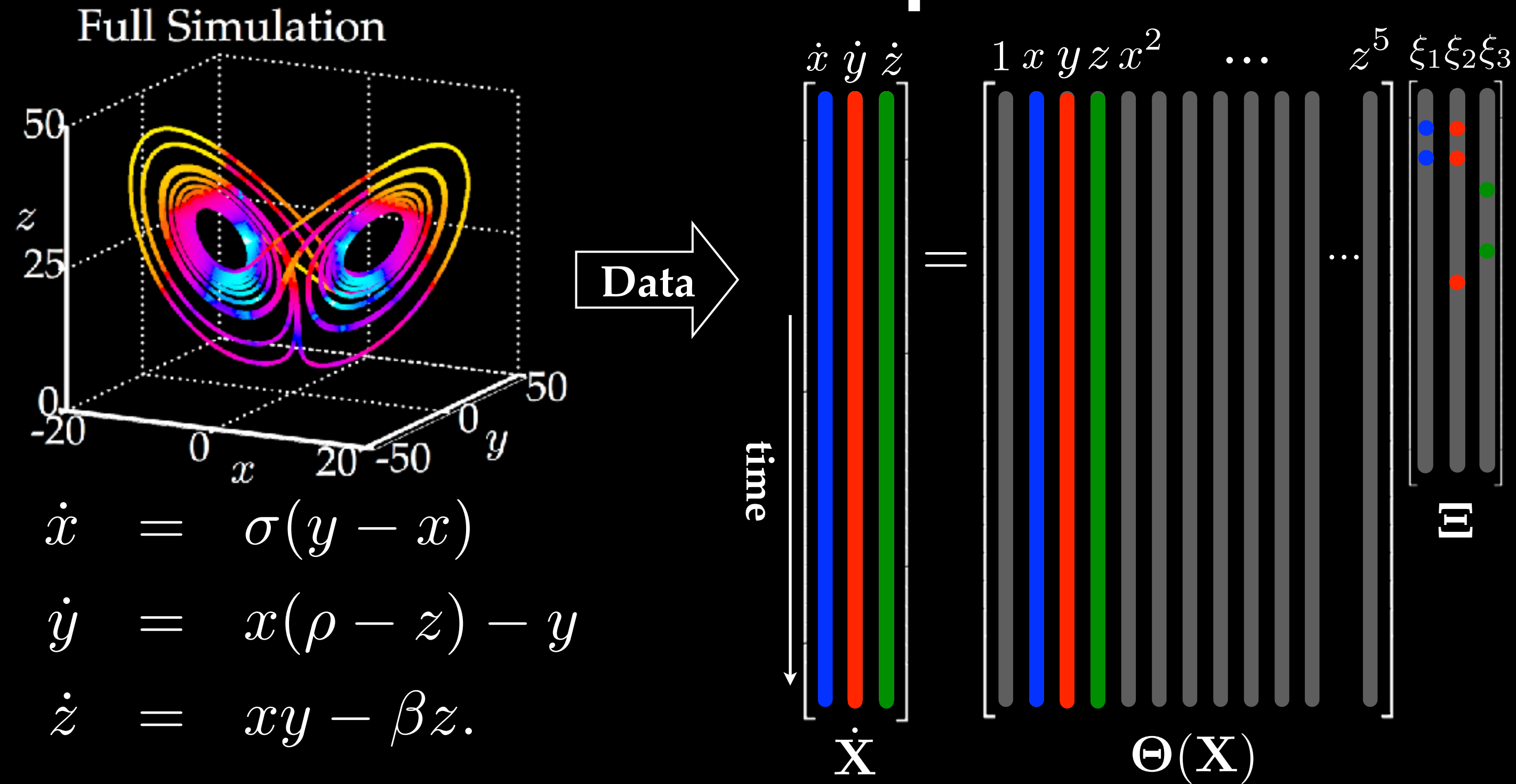


Data

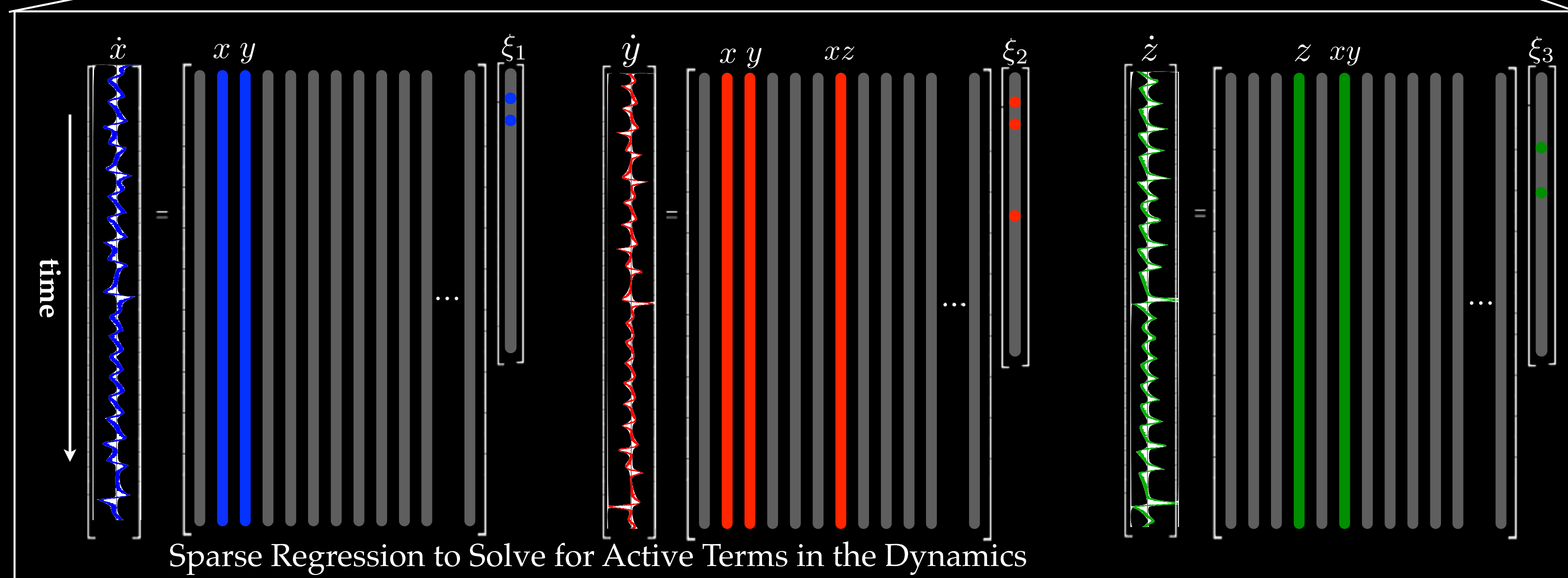
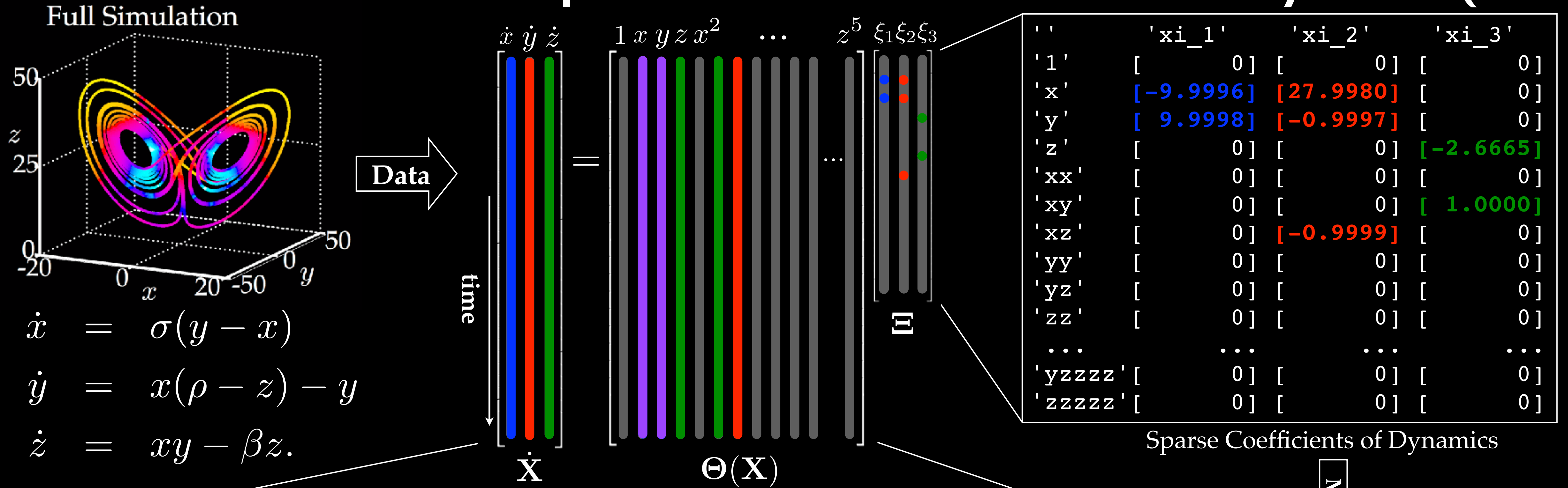
$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= x(\rho - z) - y \\ \dot{z} &= xy - \beta z.\end{aligned}$$



# Sparse Identification of Nonlinear Dynamics (SINDy)

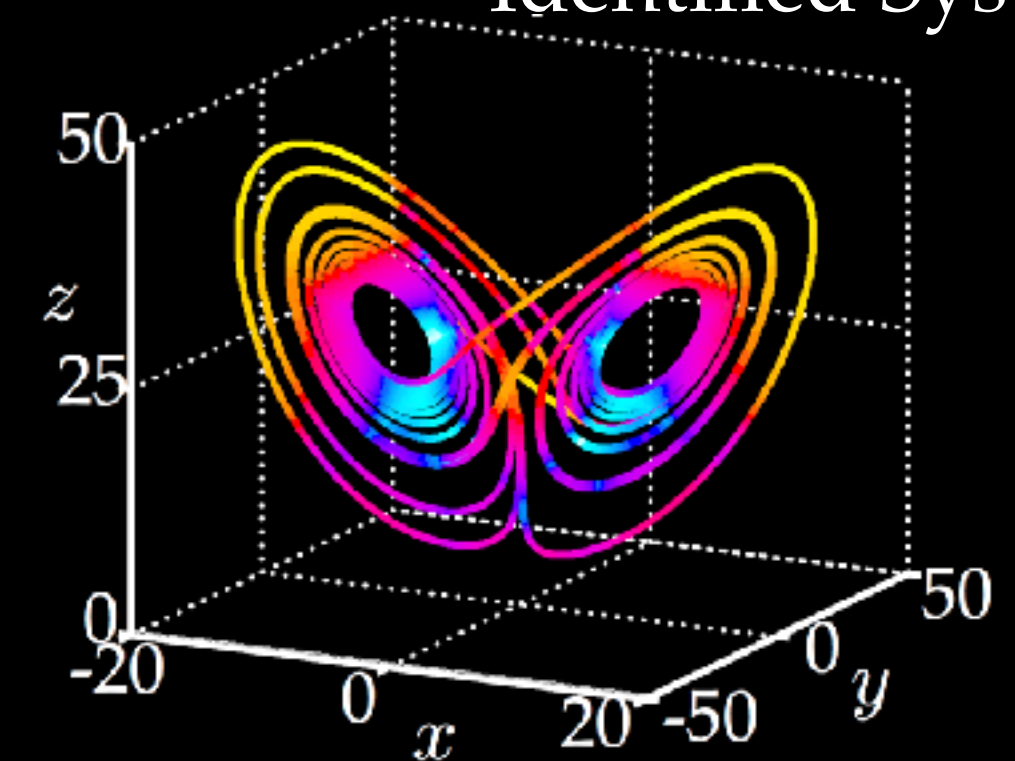


# Sparse Identification of Nonlinear Dynamics (SINDy)

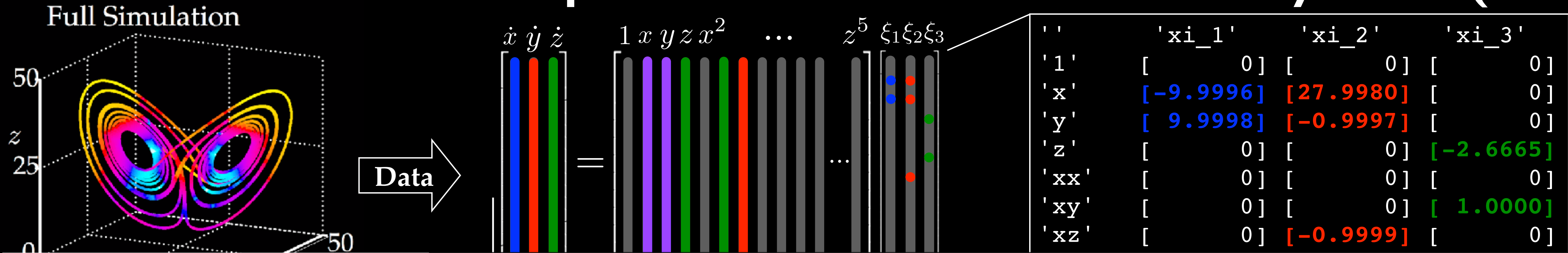


Model

Identified System



# Sparse Identification of Nonlinear Dynamics (SINDy)

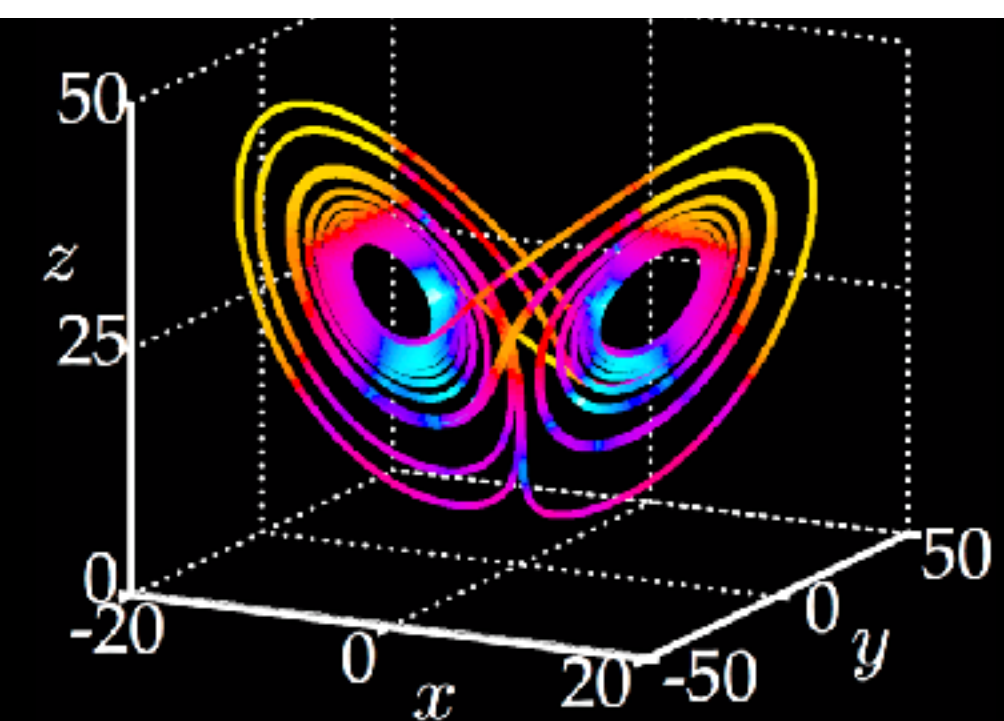
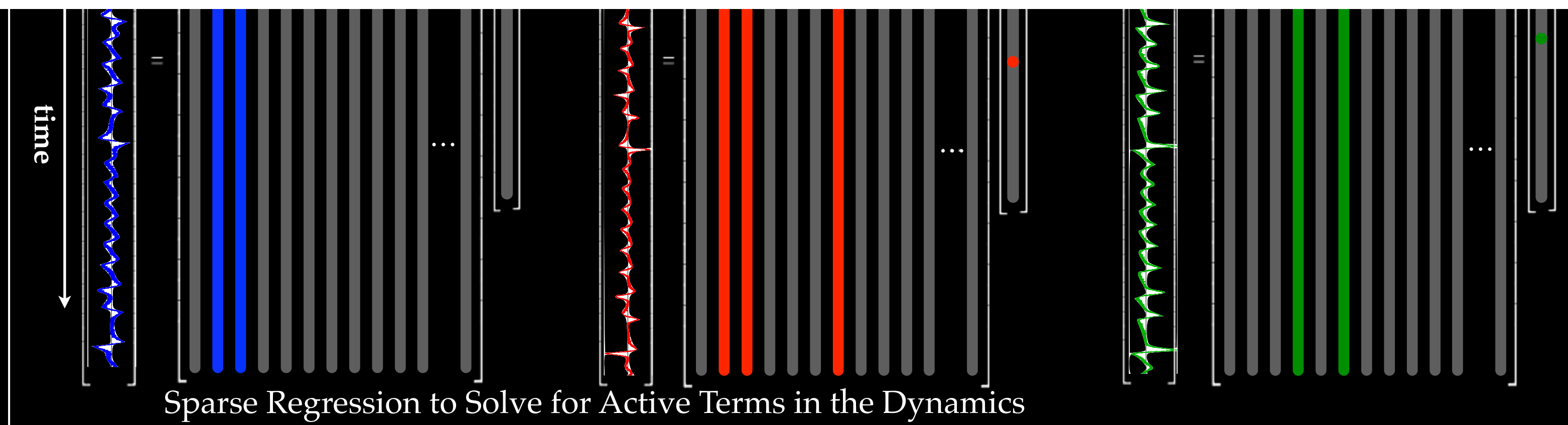


PySINDy

OPEN-SOURCE SOFTWARE

Build CI passing docs passing pypi package 1.0.0 codecov 95% JOSS 10.21105/joss.02104 DOI 10.5281/zenodo.3832319

PySINDy is a sparse regression package with several implementations for the Sparse Identification of Nonlinear Dynamical systems (SINDy) method introduced in Brunton et al. (2016a), including the unified optimization approach of Champion et al. (2019) and SINDy with control from Brunton et al. (2016b). A comprehensive literature review is given in de Silva et al. (2020).



SLB, Proctor, Kutz, PNAS 2016.

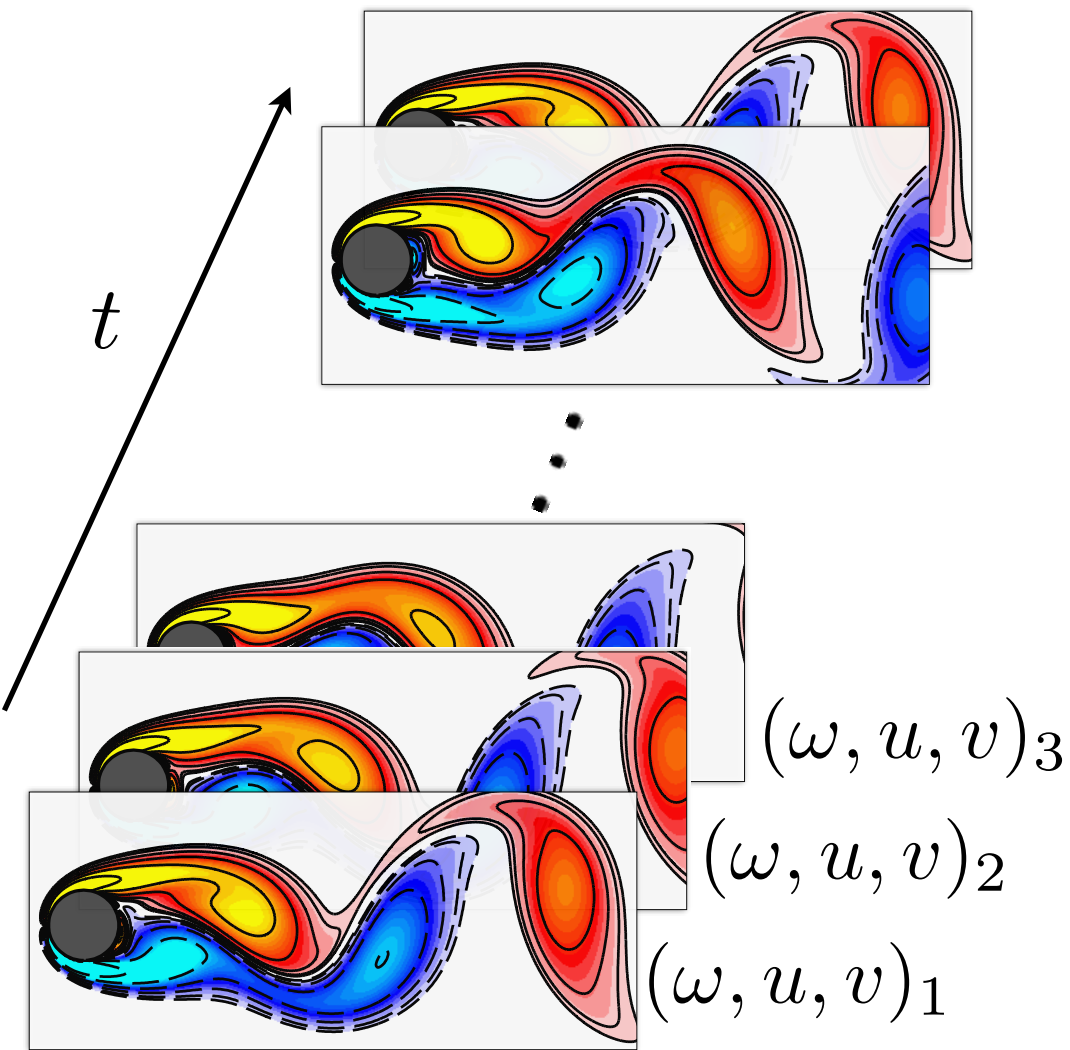
# PDEs

Rudy, SLB, Proctor, Kutz  
*Science Advances*, 2017



Full Data

## 1a. Data Collection



$$\omega_t = \Theta(\omega, u, v)\xi$$

1b. Build Nonlinear Library of Data and Derivatives

## 1c. Solve Sparse Regression

$$\arg \min_{\xi} \|\Theta\xi - \omega_t\|_2^2 + \lambda\|\xi\|_0$$

## d. Identified Dynamics

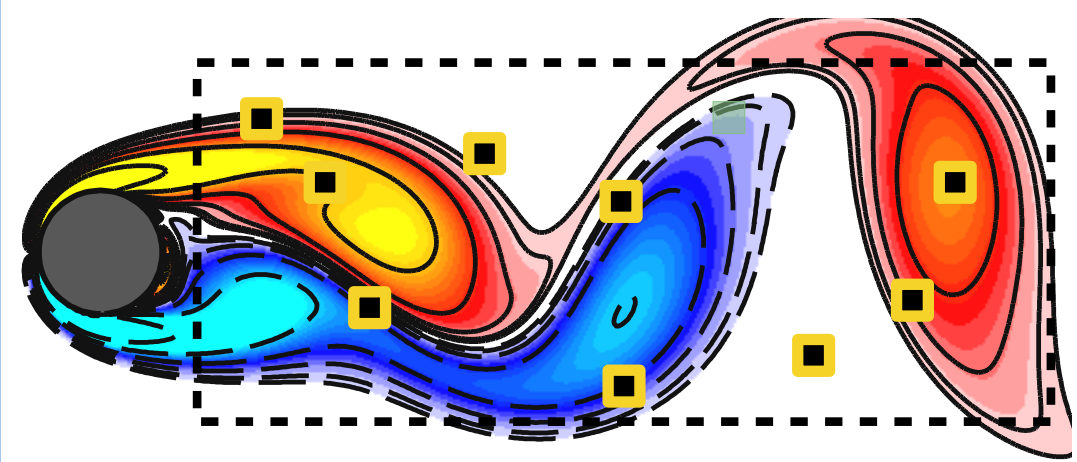
$$\omega_t + 0.9931u\omega_x + 0.9910v\omega_y = 0.0099\omega_{xx} + 0.0099\omega_{yy}$$

Compare to True Navier Stokes ( $Re = 100$ )

$$\omega_t + (\mathbf{u} \cdot \nabla)\omega = \frac{1}{Re}\nabla^2\omega$$

Compressed Data

## 2a. Subsample Data



$$\omega_t = \Theta(\omega, u, v)\xi$$

2b. Compressed library

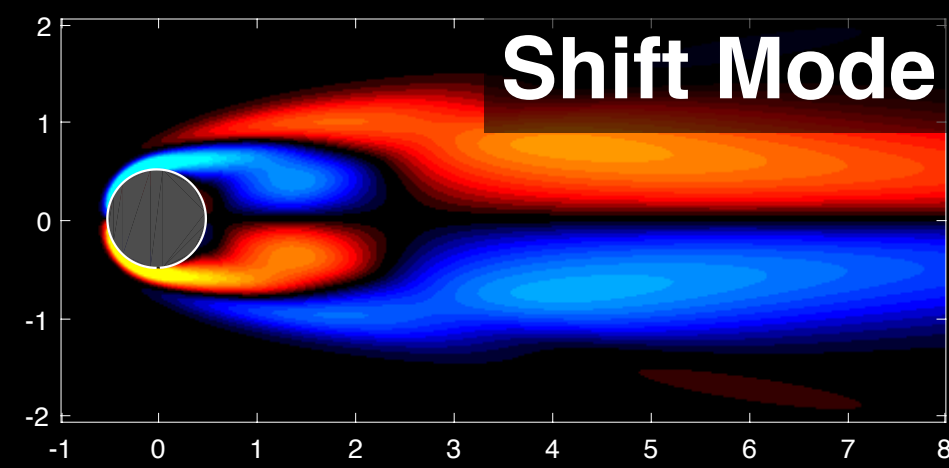
$$C\omega_t = C\Theta(\omega, u, v)\xi$$

Sampling  $C$

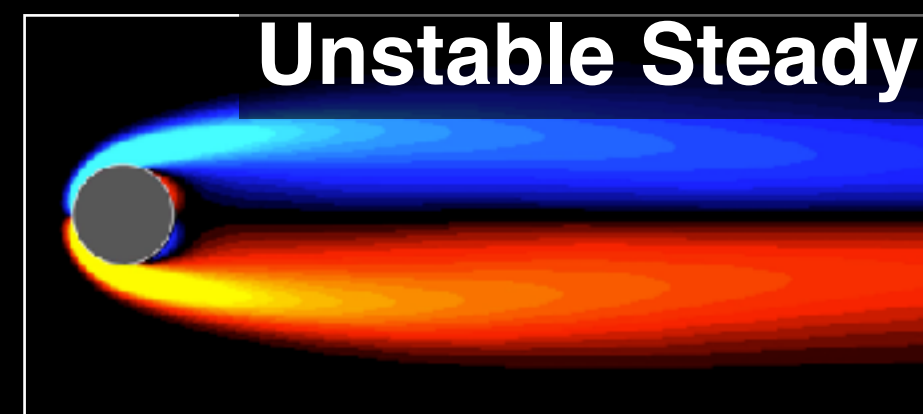
## 2c. Solve Compressed Sparse Regression

$$\arg \min_{\xi} \|C\Theta\xi - C\omega_t\|_2^2 + \lambda\|\xi\|_0$$

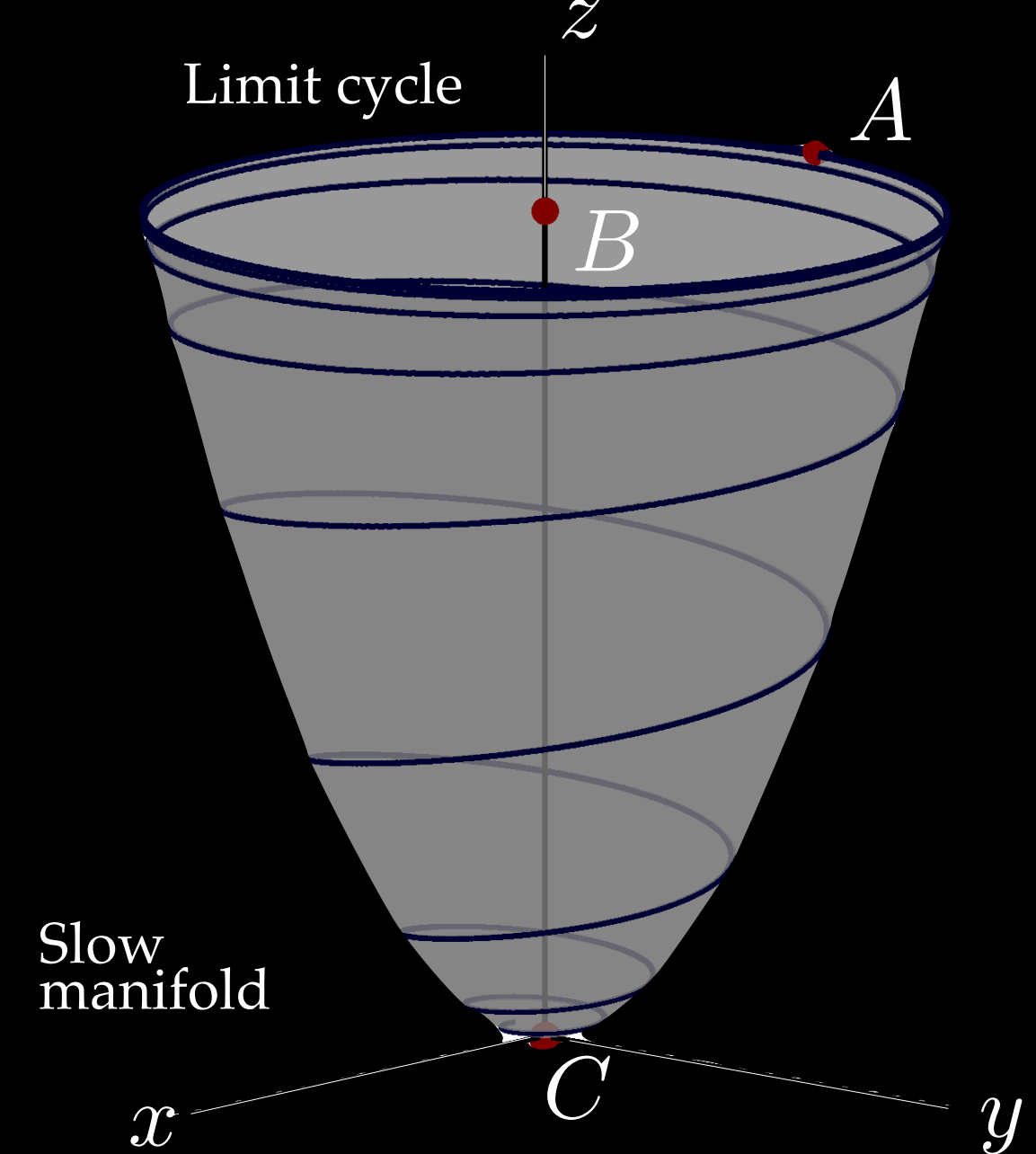
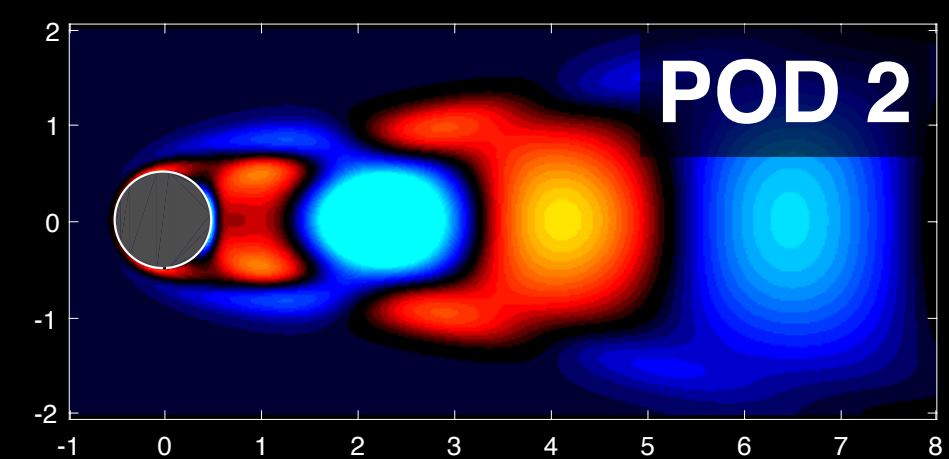
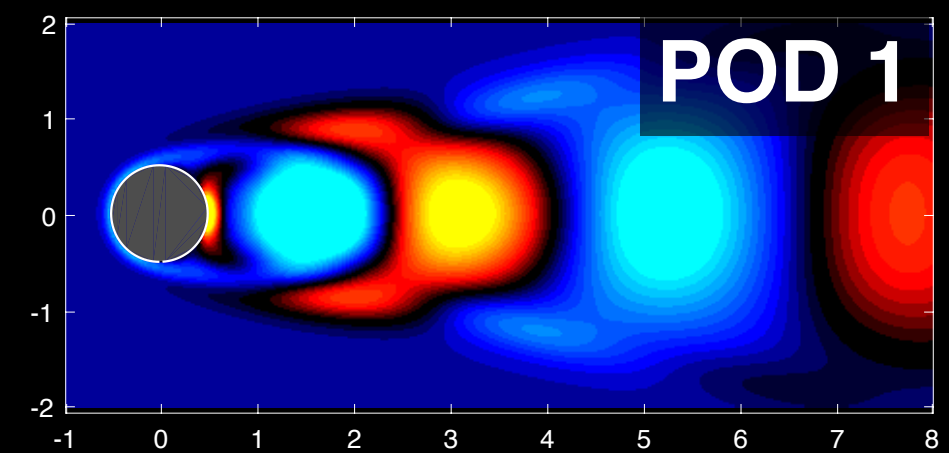
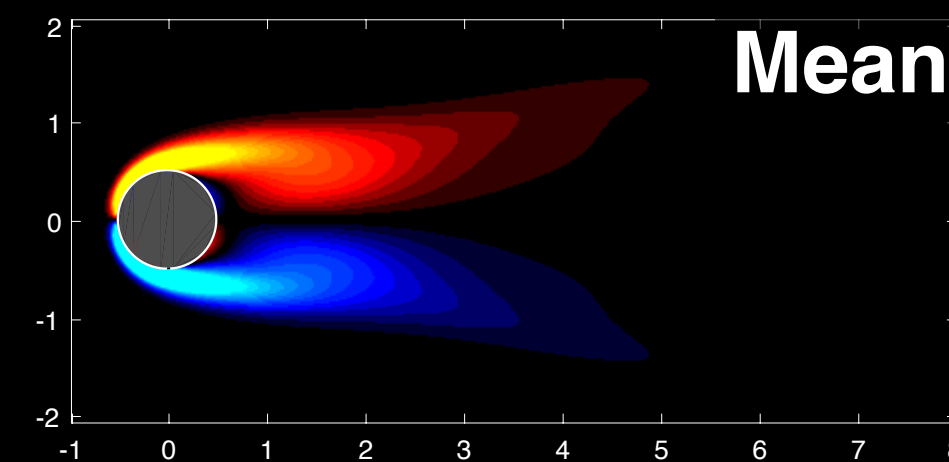
# REDUCED ORDER MODELS



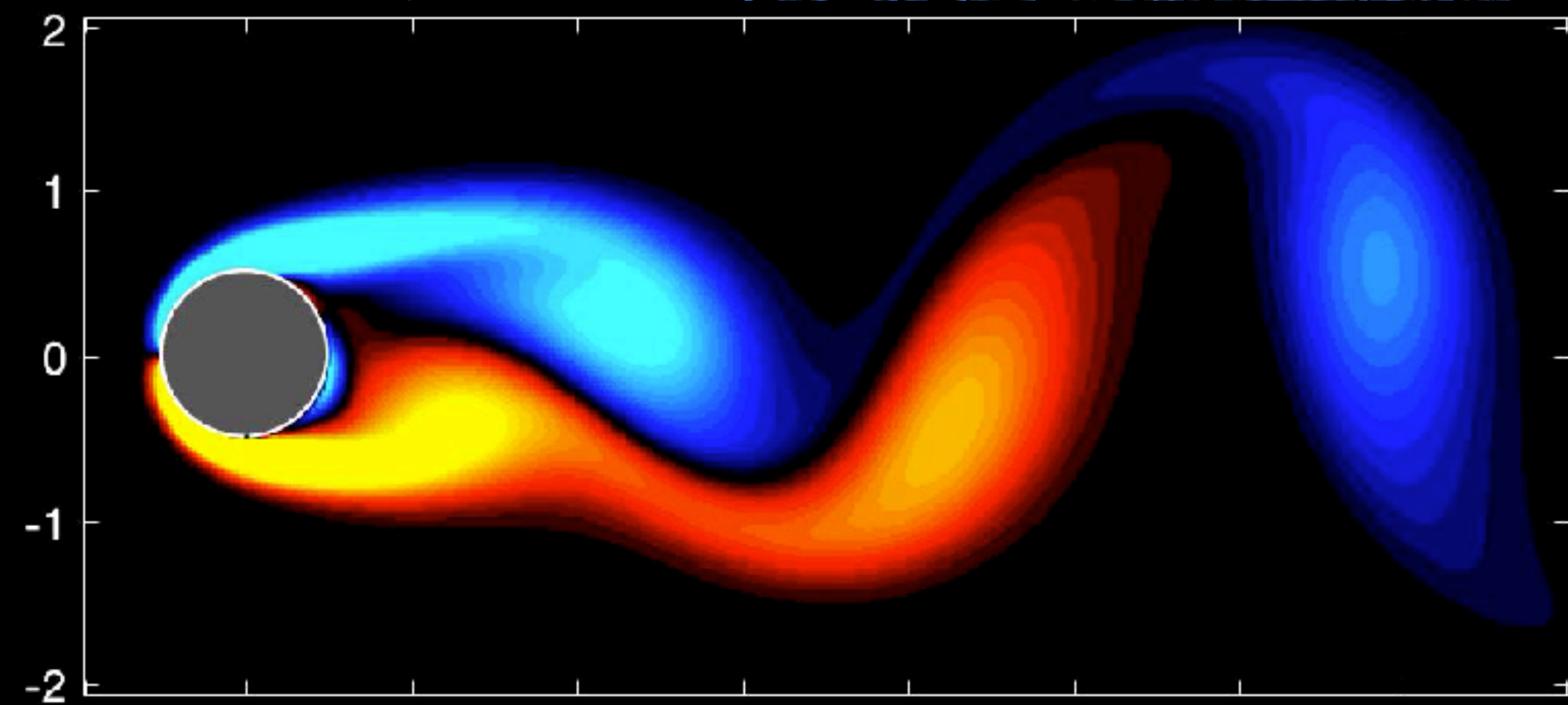
=



-

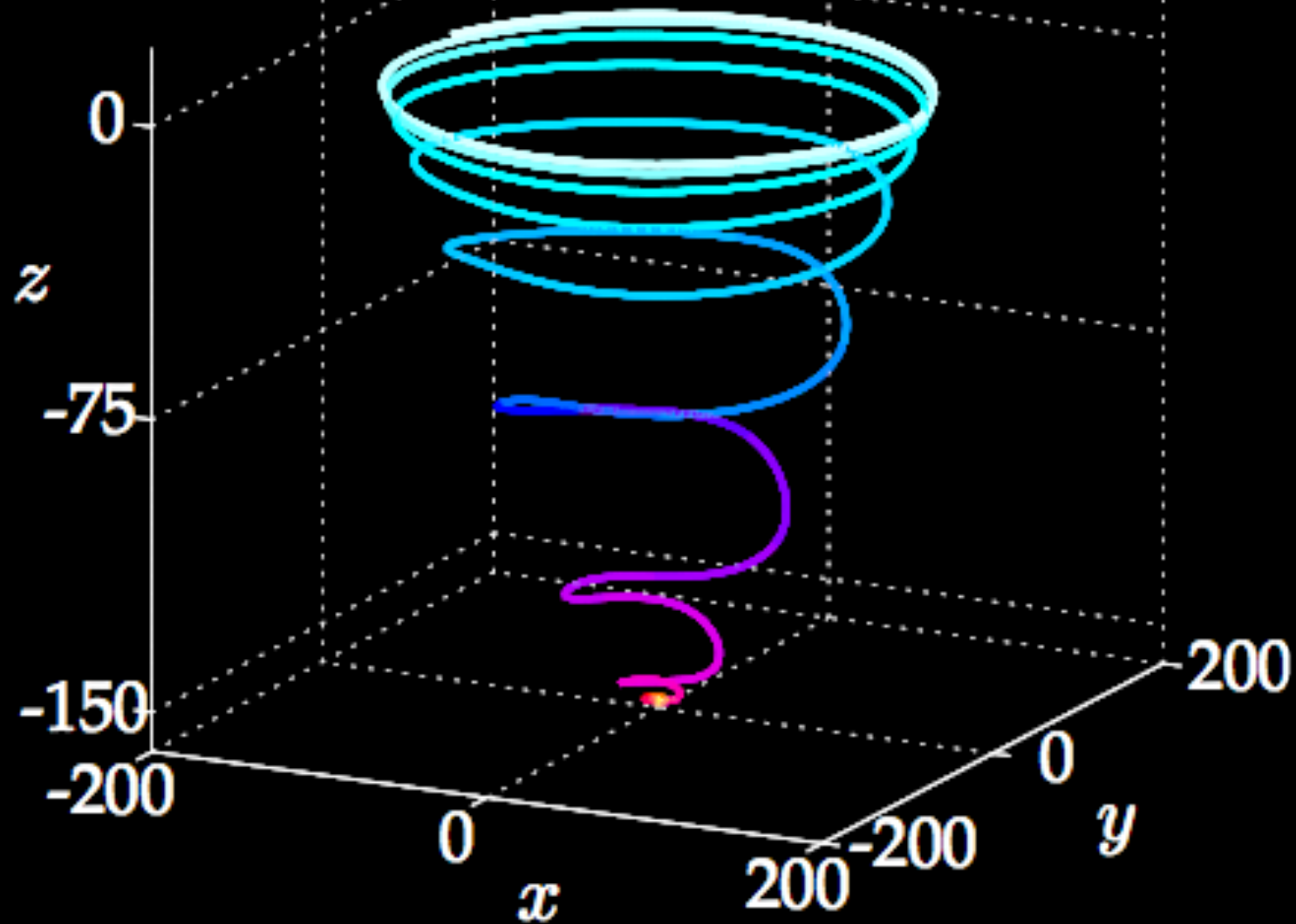


$$\begin{aligned} \dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2). \end{aligned}$$

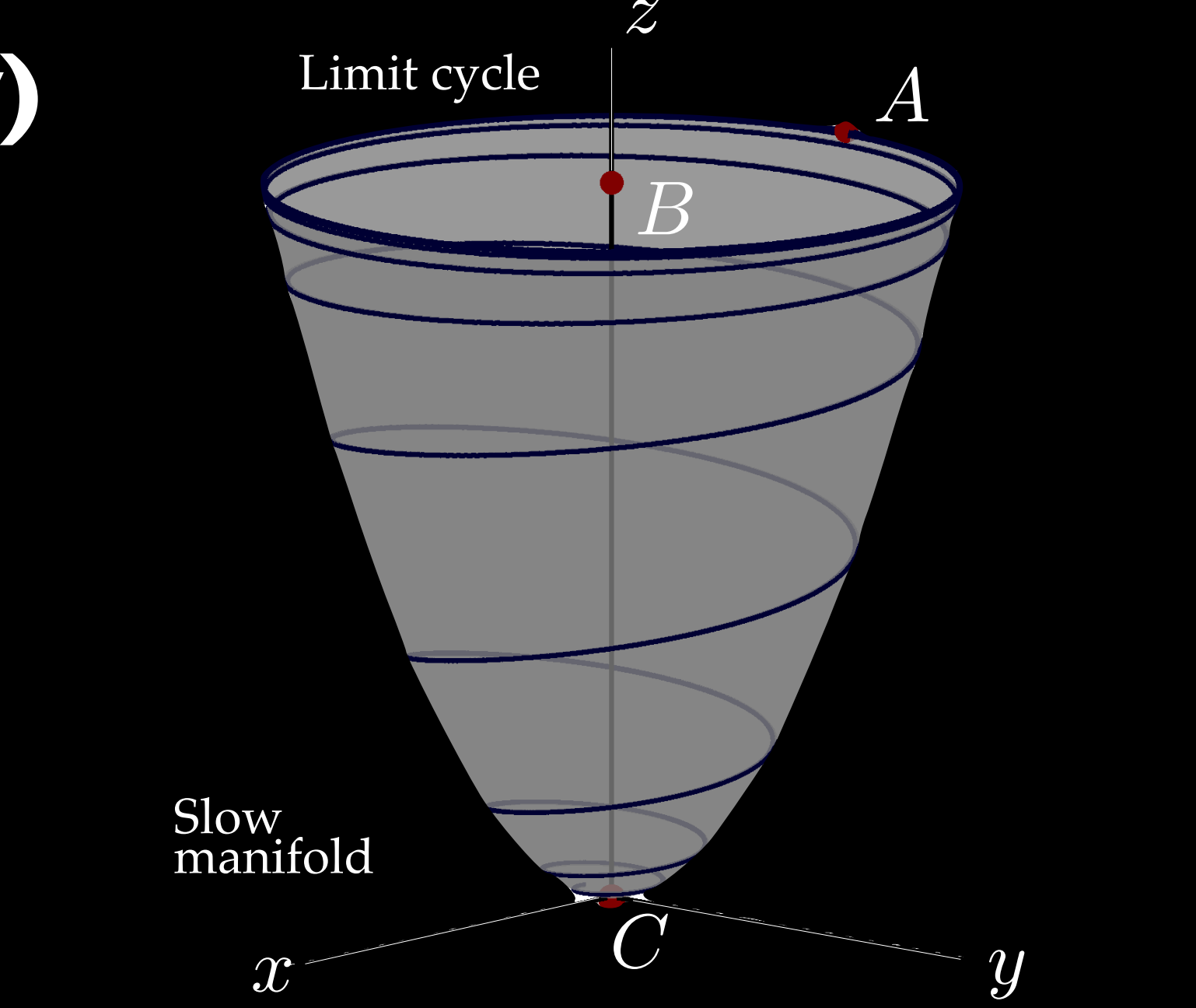
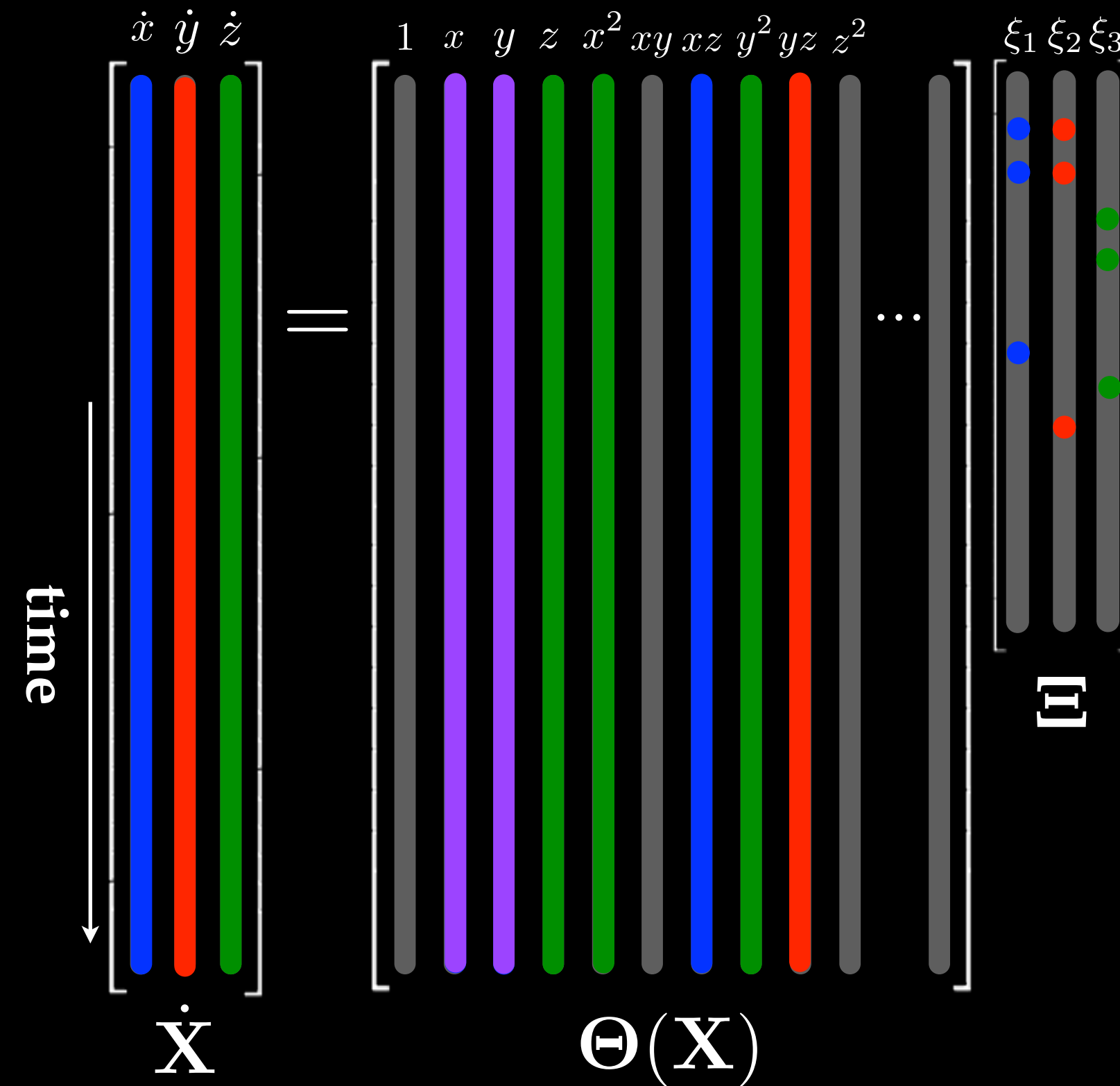
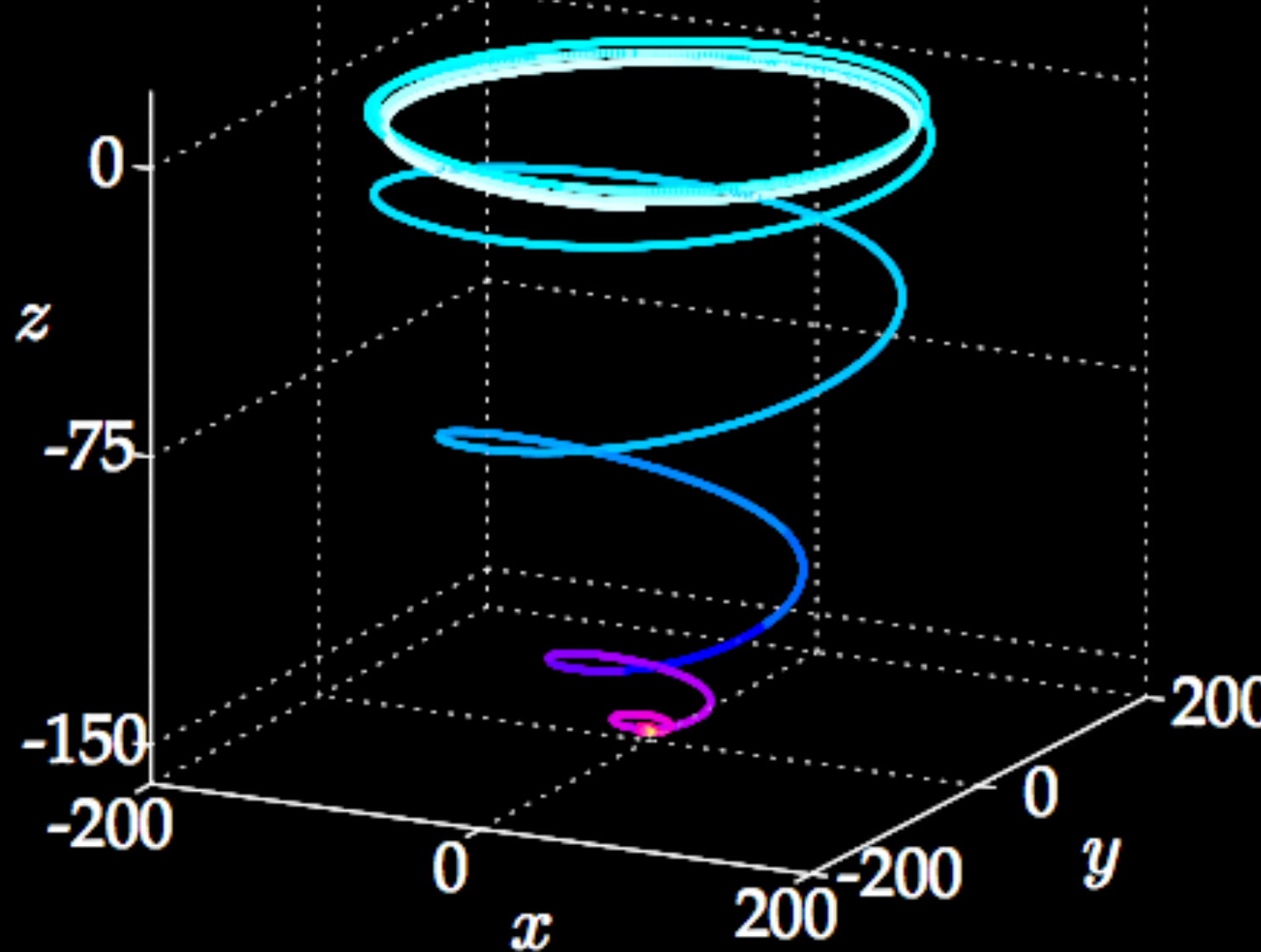


# Sparse Identification of Nonlinear Dynamics (SINDy)

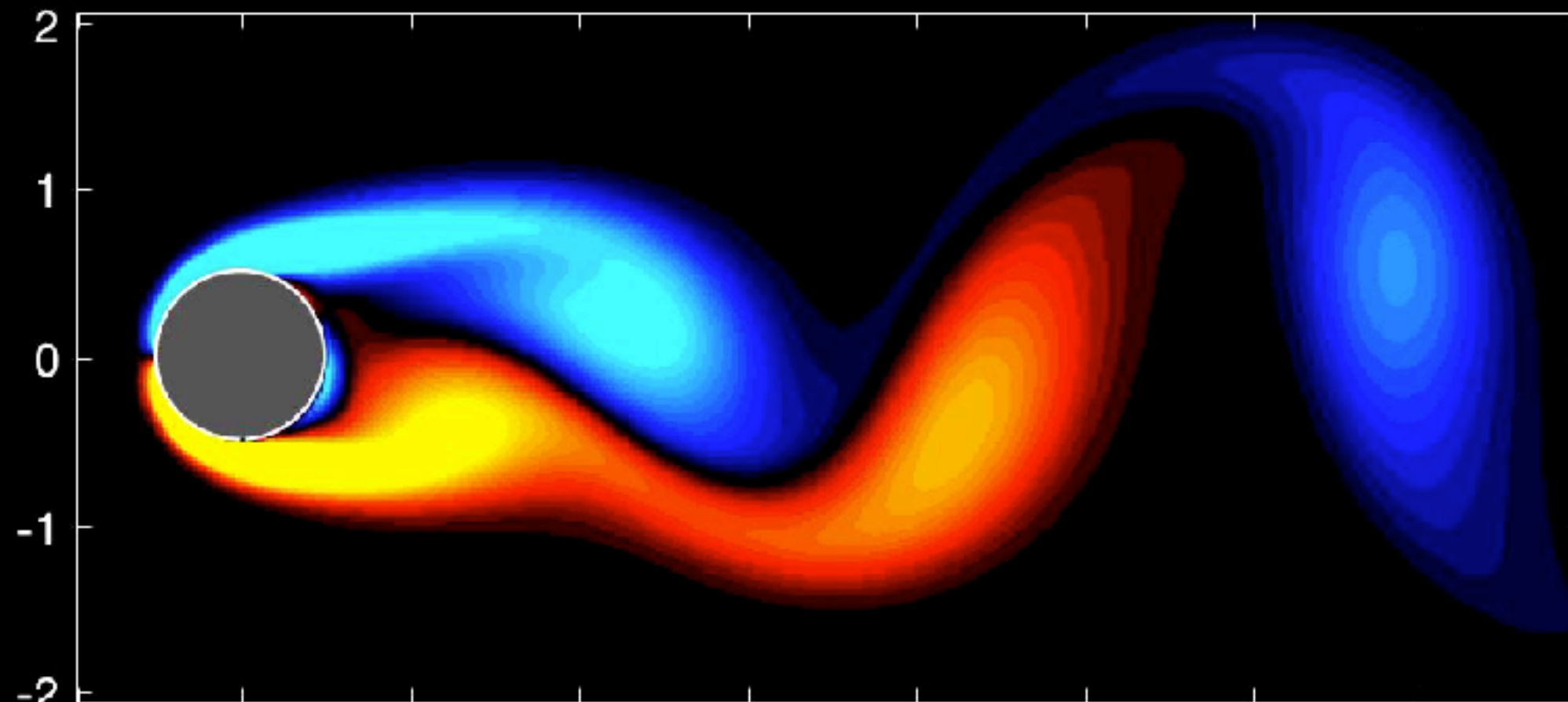
## Full System



## Identified System

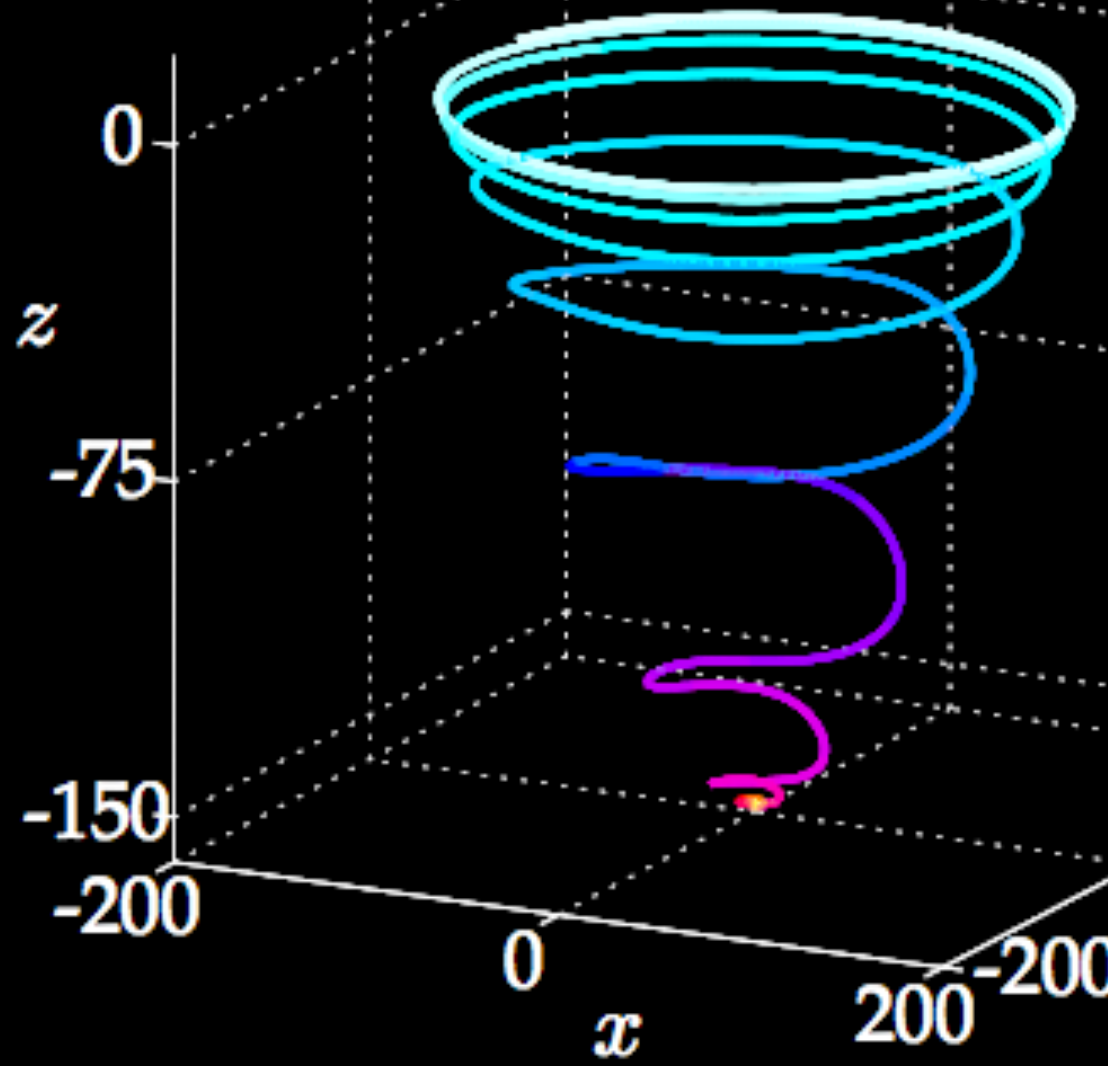


$$\begin{aligned} \dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2). \end{aligned}$$



# Sparse Identification of Nonlinear Dynamics (SINDy)

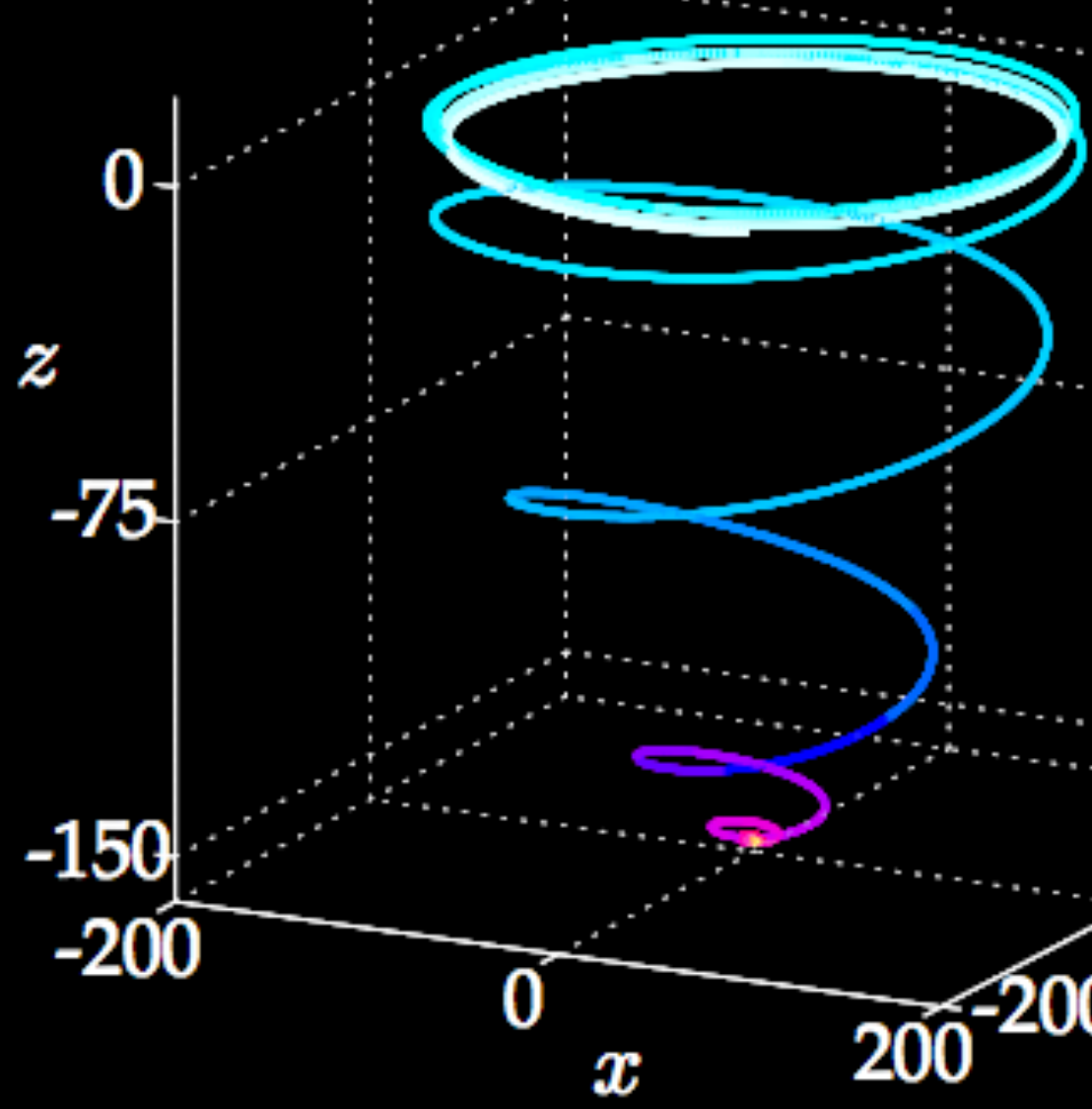
## Full System



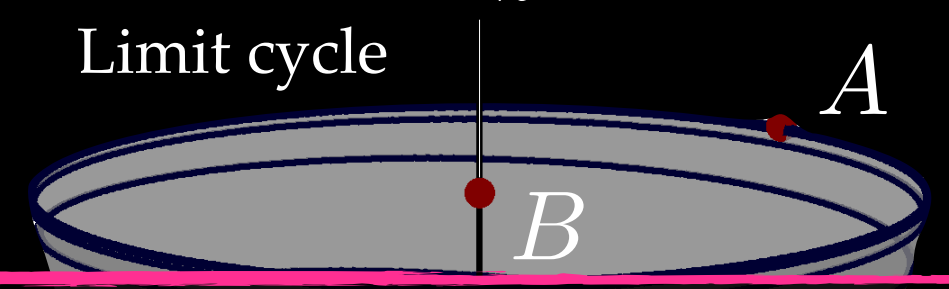
**Innovation 1: Enforcing known constraints**

- ▶ Skew-symmetric quadratic nonlinearities to enforce energy conservation
- ▶ Improved stability

## Identified System



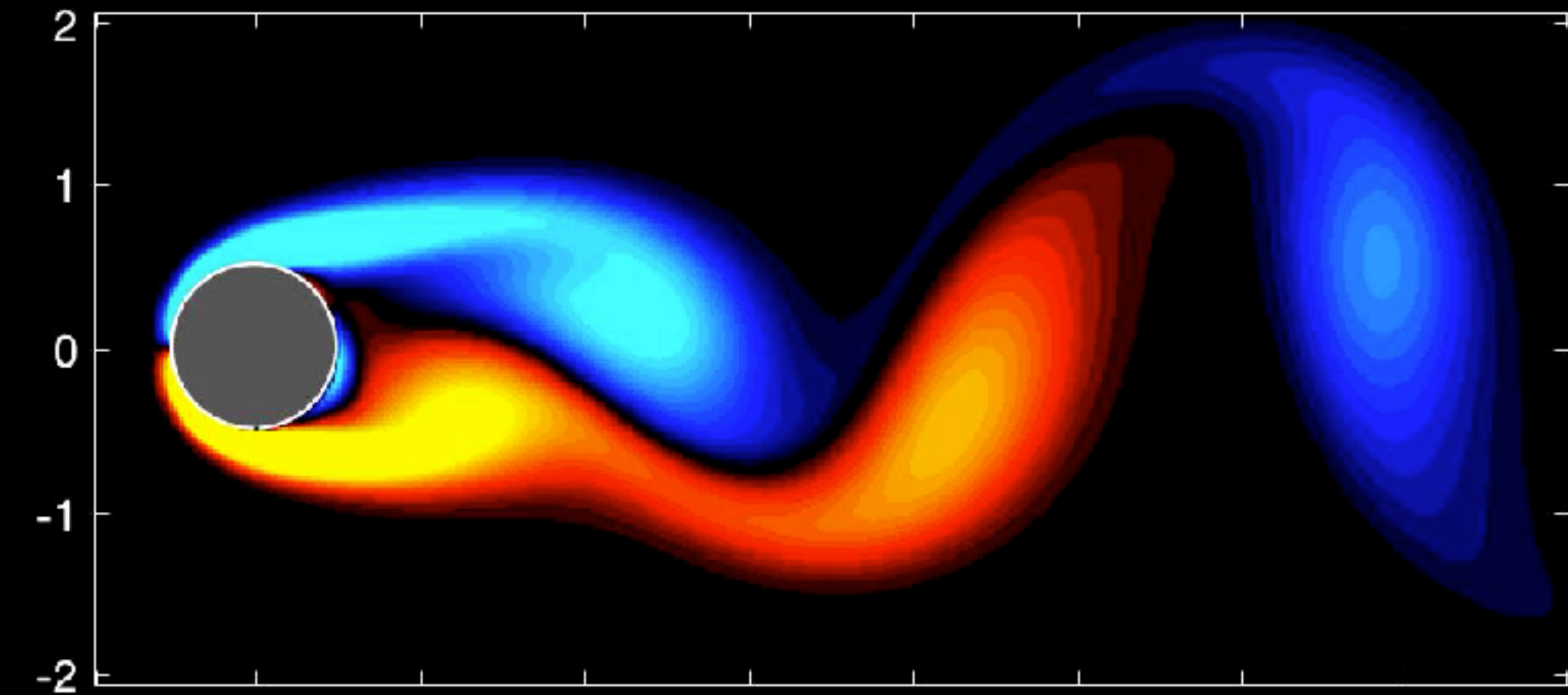
$$\min_{\xi, z} \|\Theta(X)E - \dot{X}\|_2^2 + z^T(C\xi - d)$$



**Innovation 2: Higher-order Nonlinearities**

- ▶ Cubic, Quintic, Septic terms approximate truncated terms in Galerkin expansion

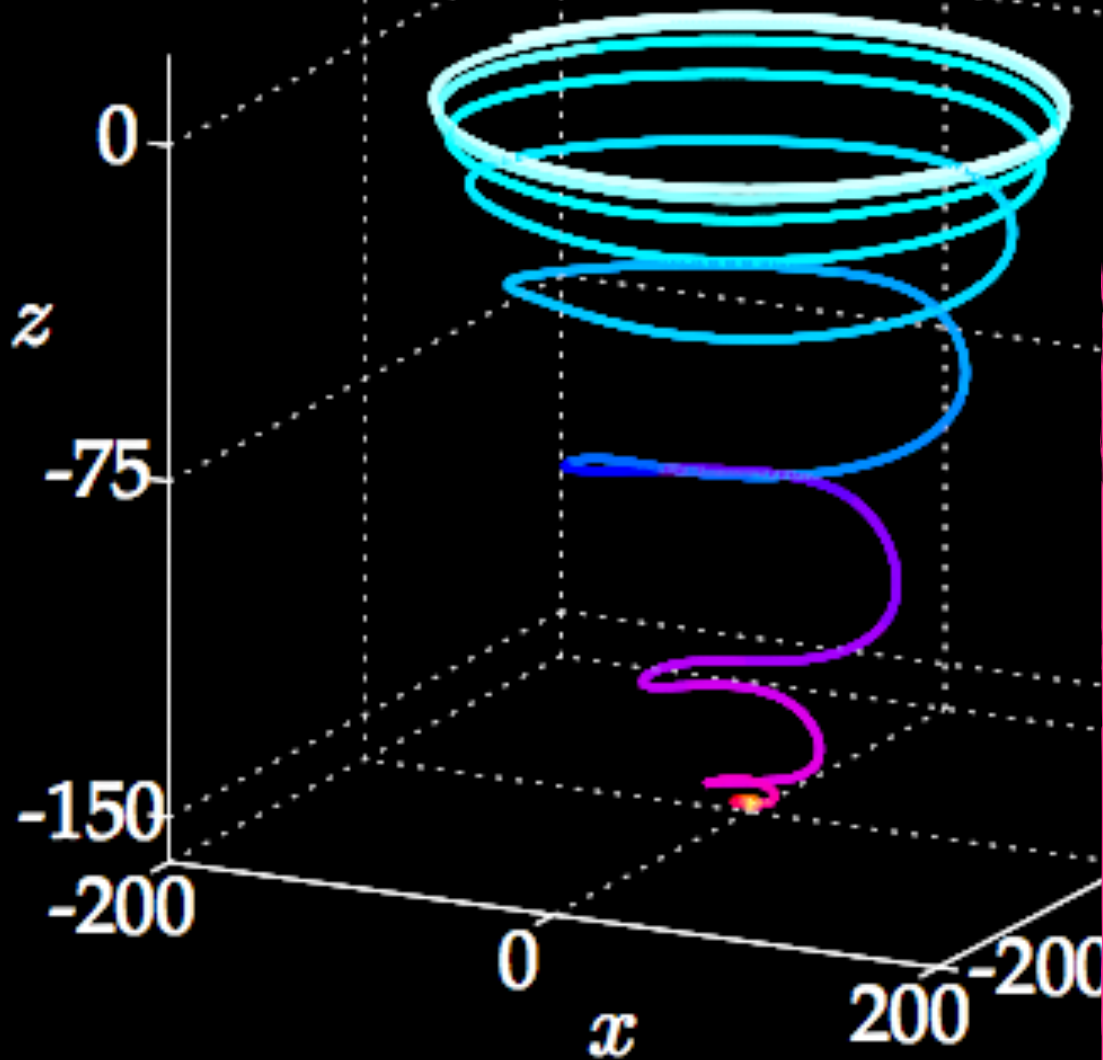
$$\begin{aligned} \dot{x} &= \mu x - \omega y + Axz \\ \dot{y} &= \omega x + \mu y + Ayz \\ \dot{z} &= -\lambda(z - x^2 - y^2). \end{aligned}$$



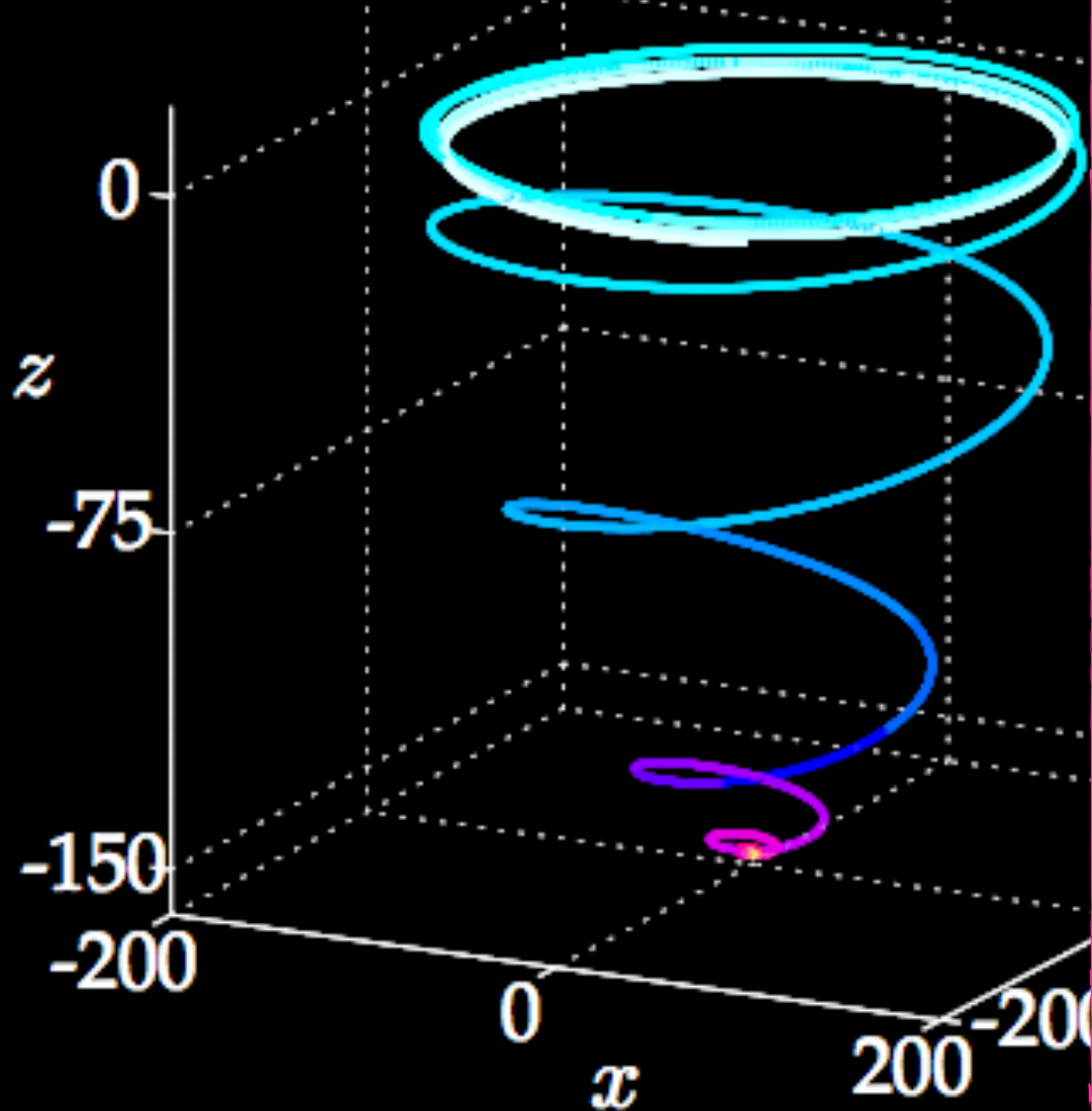


# Sparse Identification of Nonlinear Dynamics (SINDy)

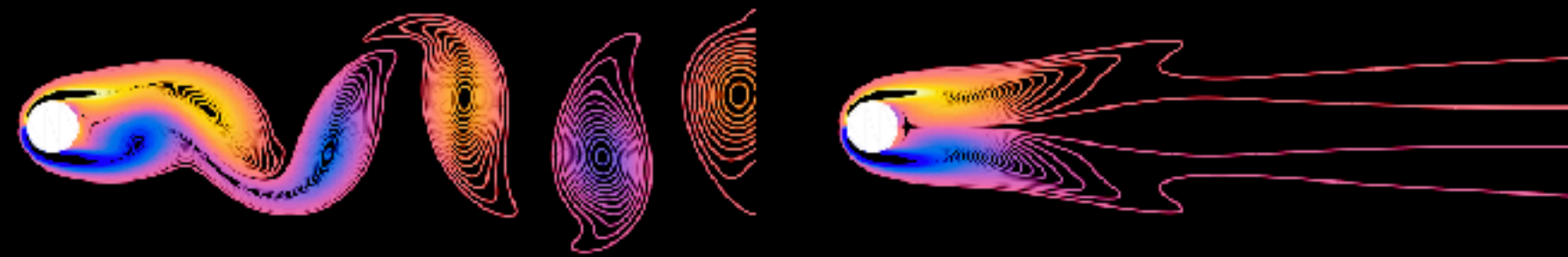
## Full System



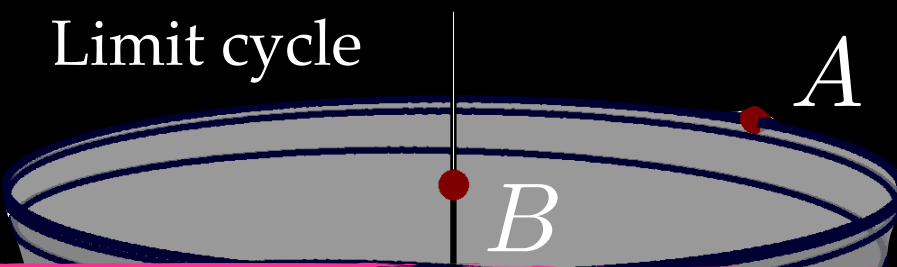
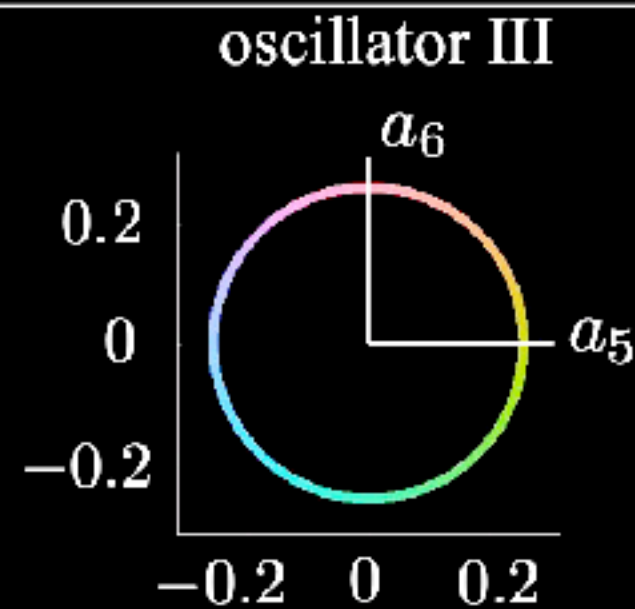
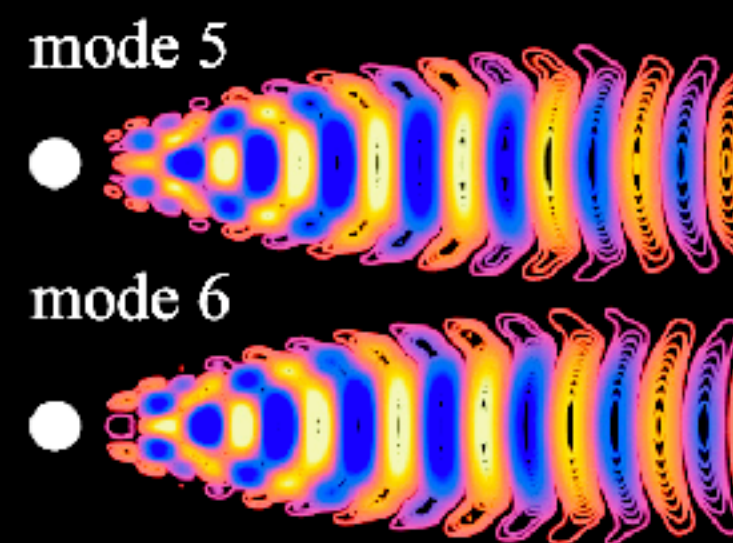
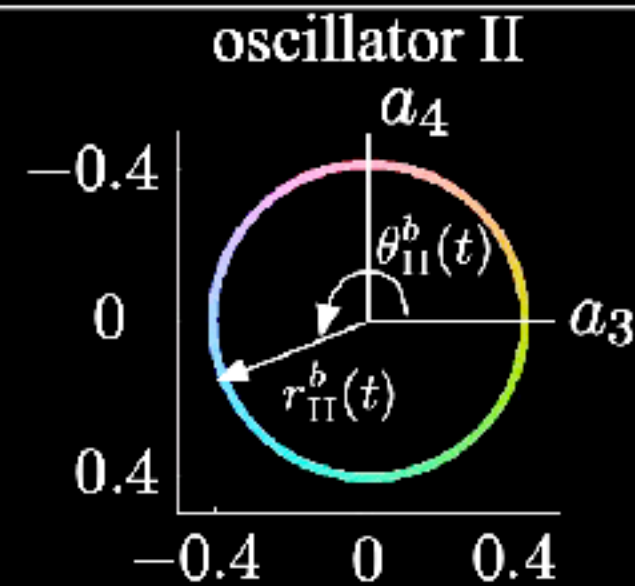
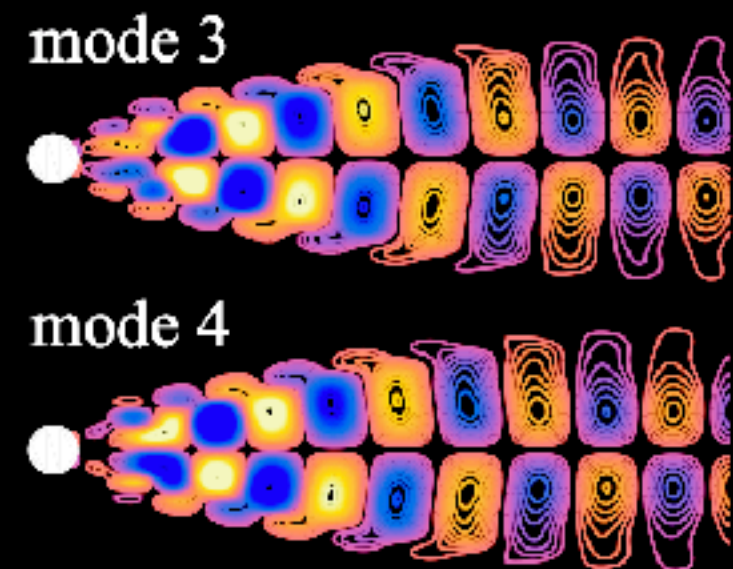
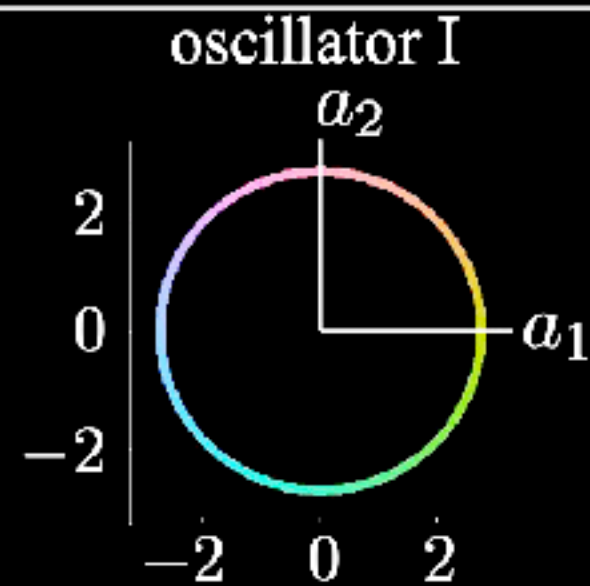
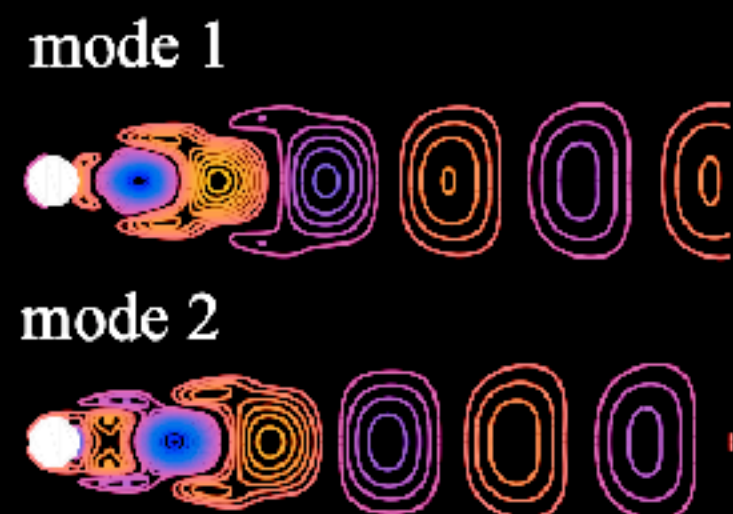
## Identified System



(a) Instantaneous snapshot ( $\omega$ ) (b) Mean flow ( $\bar{\omega}$ )



(c) Spatial modes ( $\phi_{2j-1}^\omega, \phi_{2j}^\omega$ ) (d) Oscillators ( $z_m^b$ )



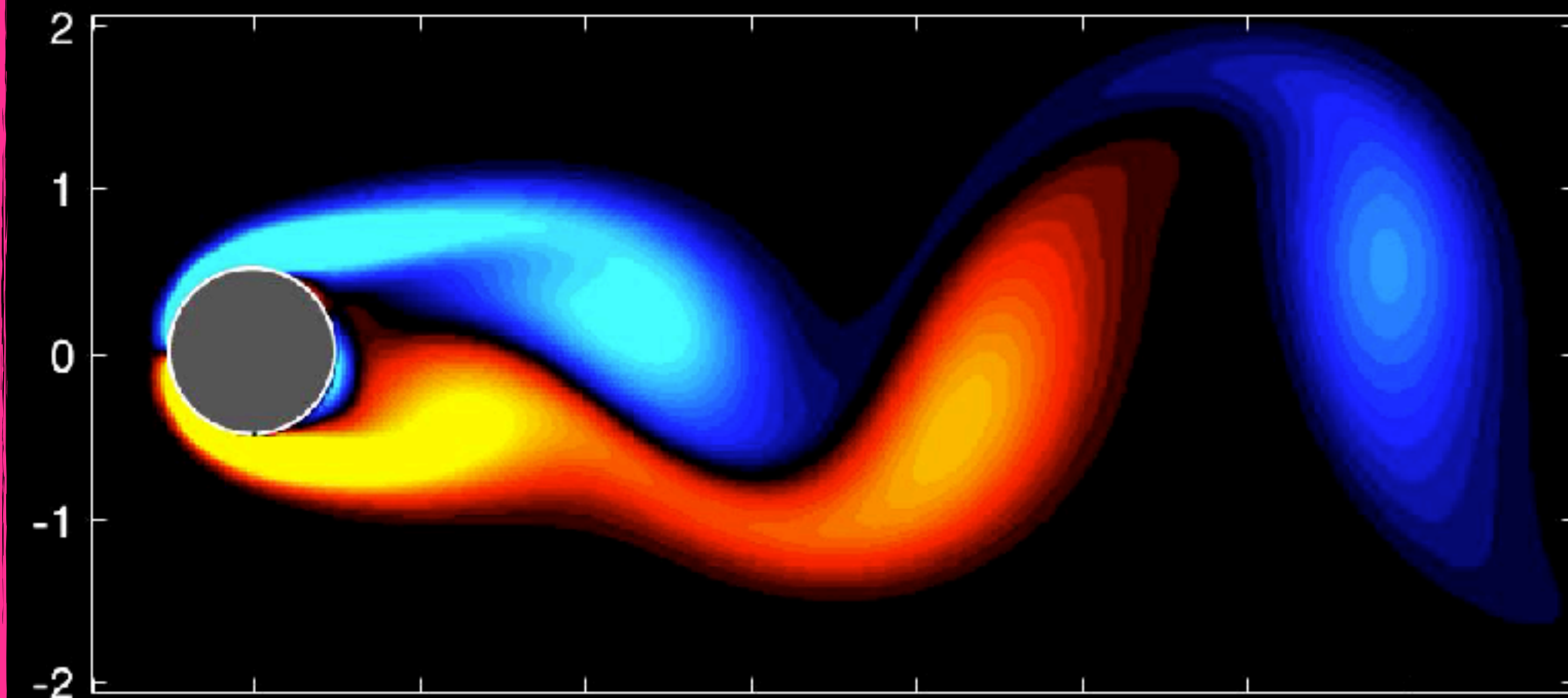
## Innovation 2: Higher-order Nonlinearities

- Cubic, Quintic, Septic terms approximate truncated terms in Galerkin expansion

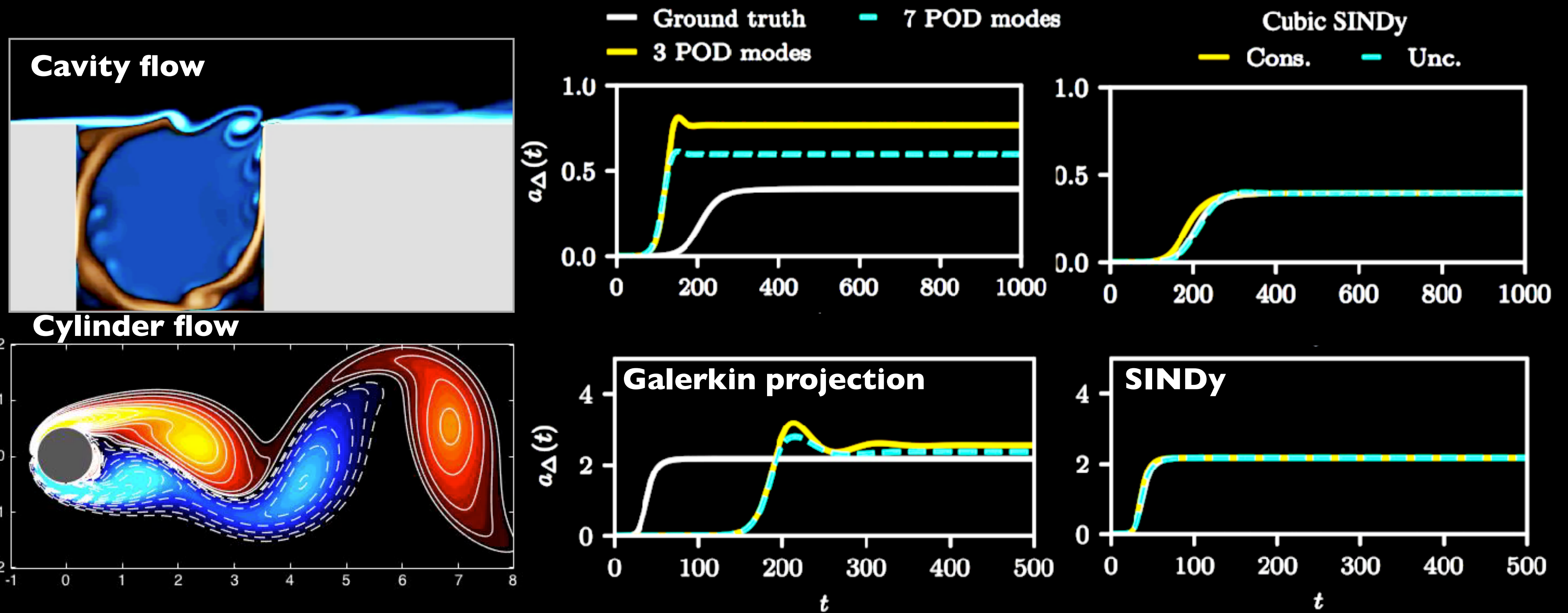
$$\dot{x} = \mu x - \omega y + Axz$$

$$\dot{y} = \omega x + \mu y + Ayz$$

$$\dot{z} = -\lambda(z - x^2 - y^2).$$



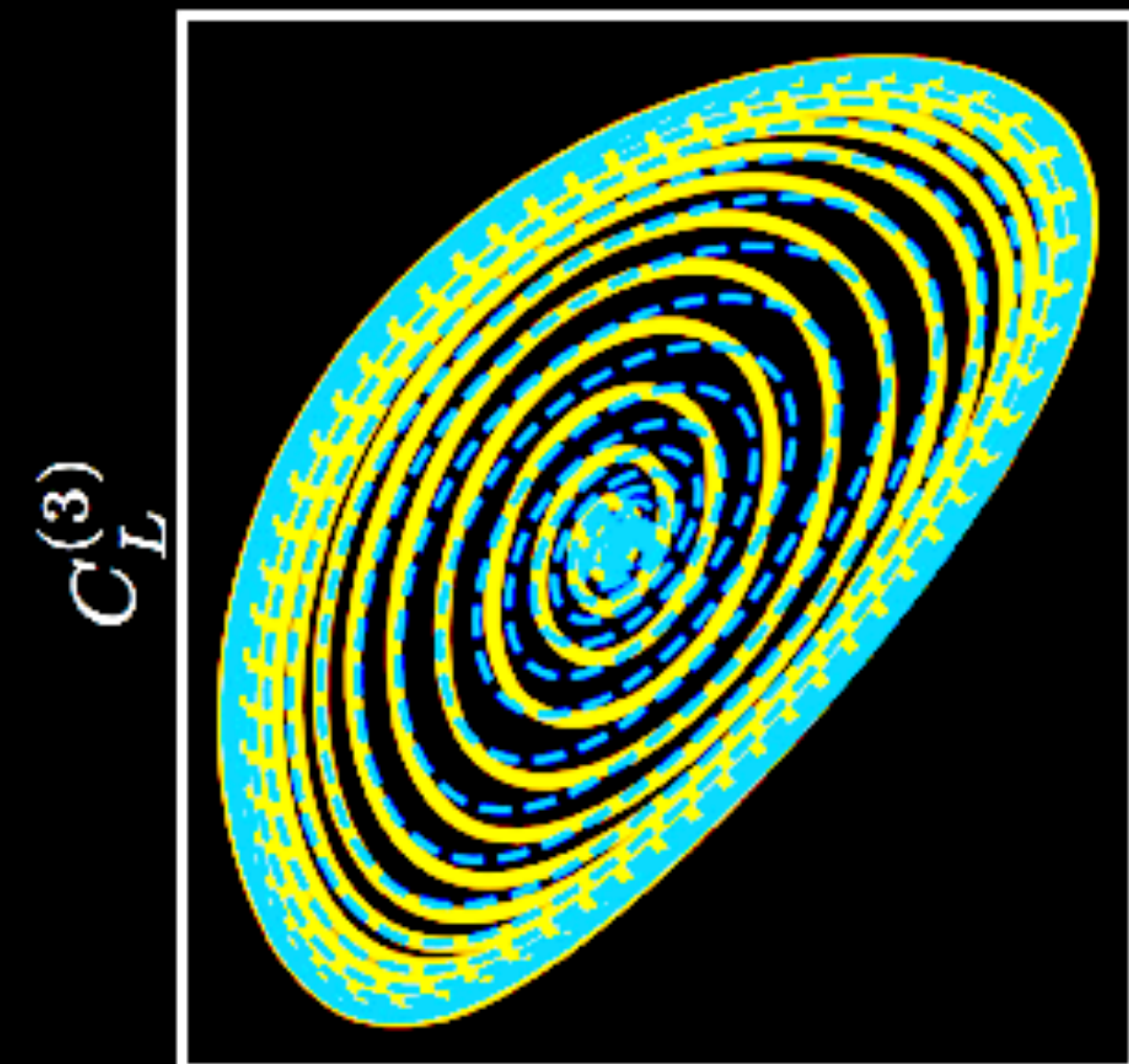
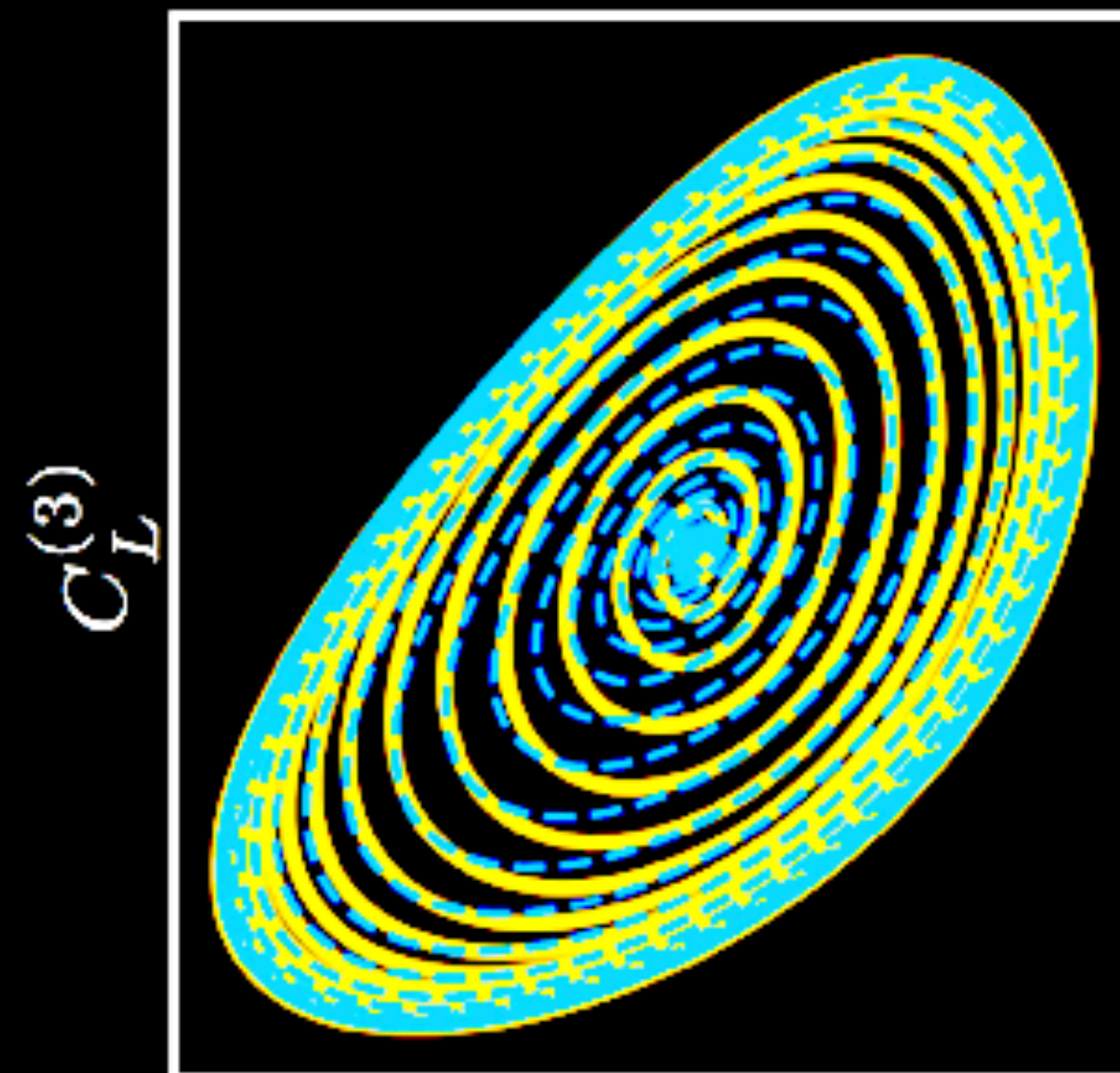
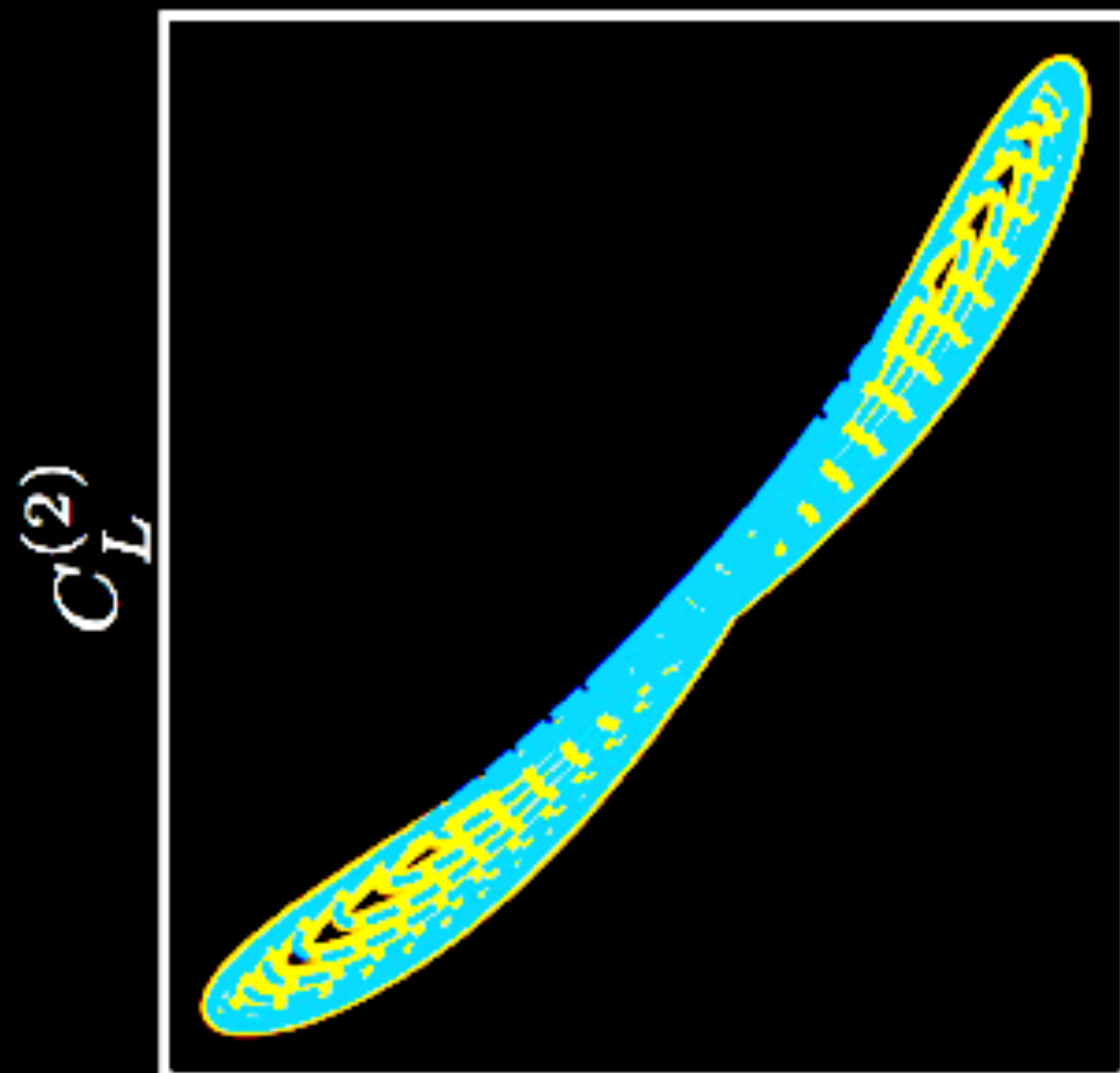
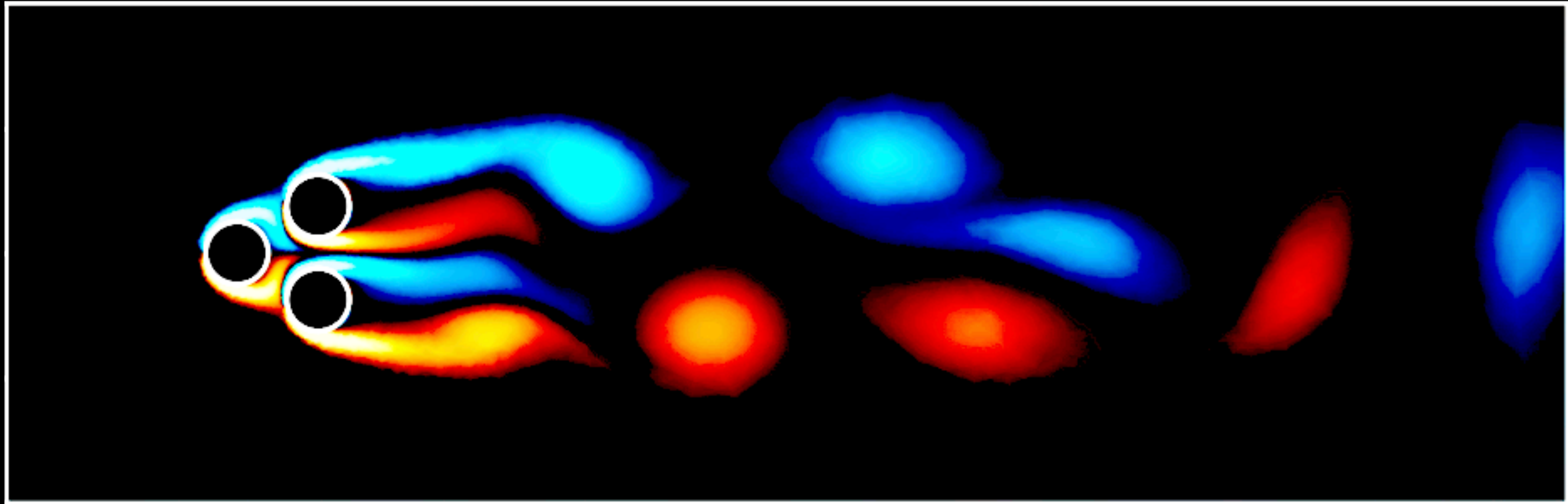
# Constrained Sparse Galerkin Regression



$$\ddot{x} - \underbrace{(0.2 - 0.24x^2 - 0.15\dot{x}^2)}_{k(x, \dot{x})} \dot{x} + 1.26x = 0$$

**Spring-Mass Damper with Nonlinear Damping!**

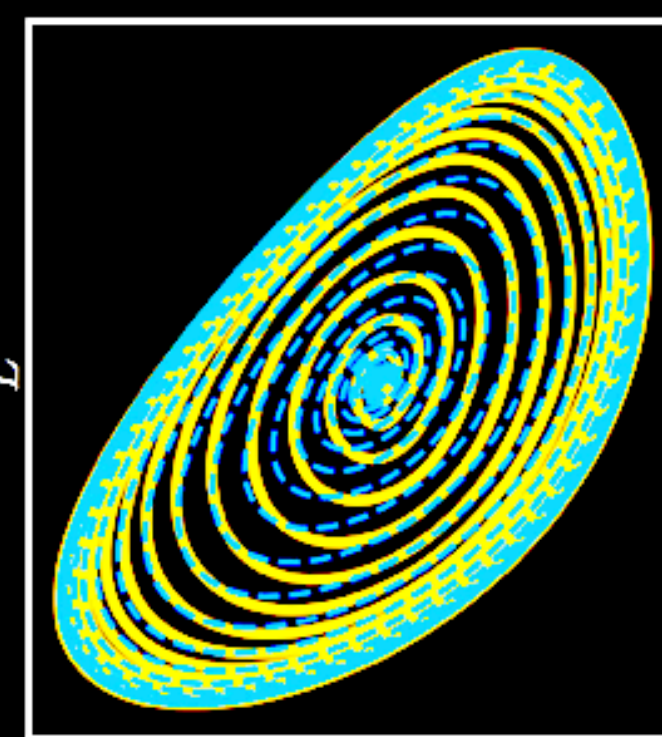
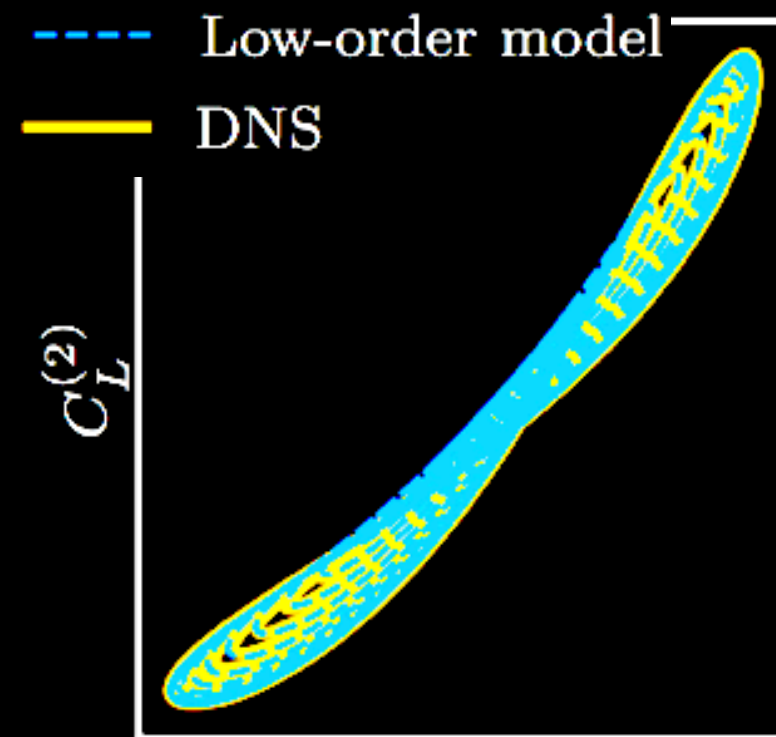
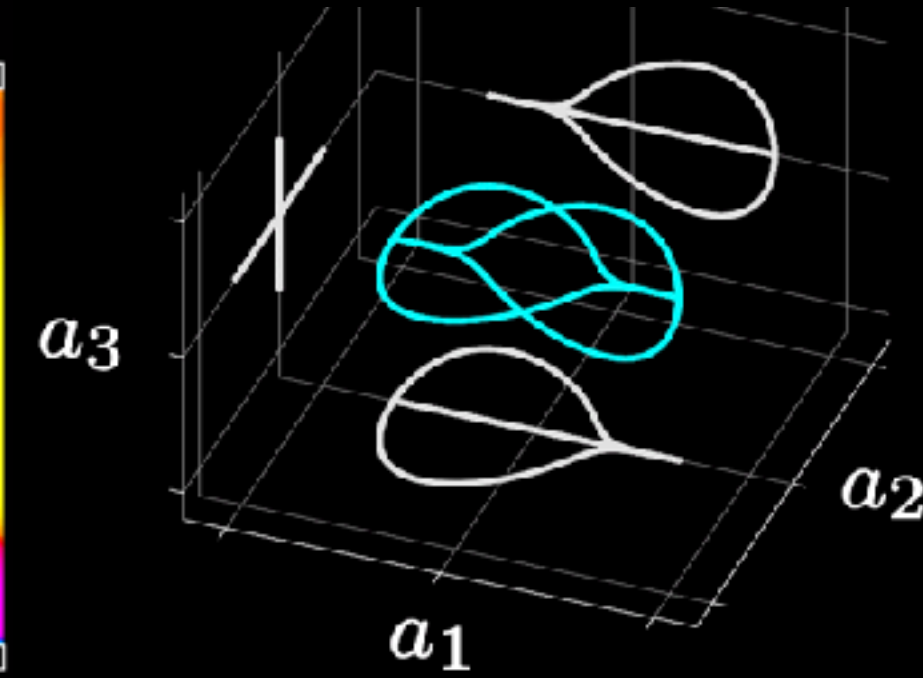
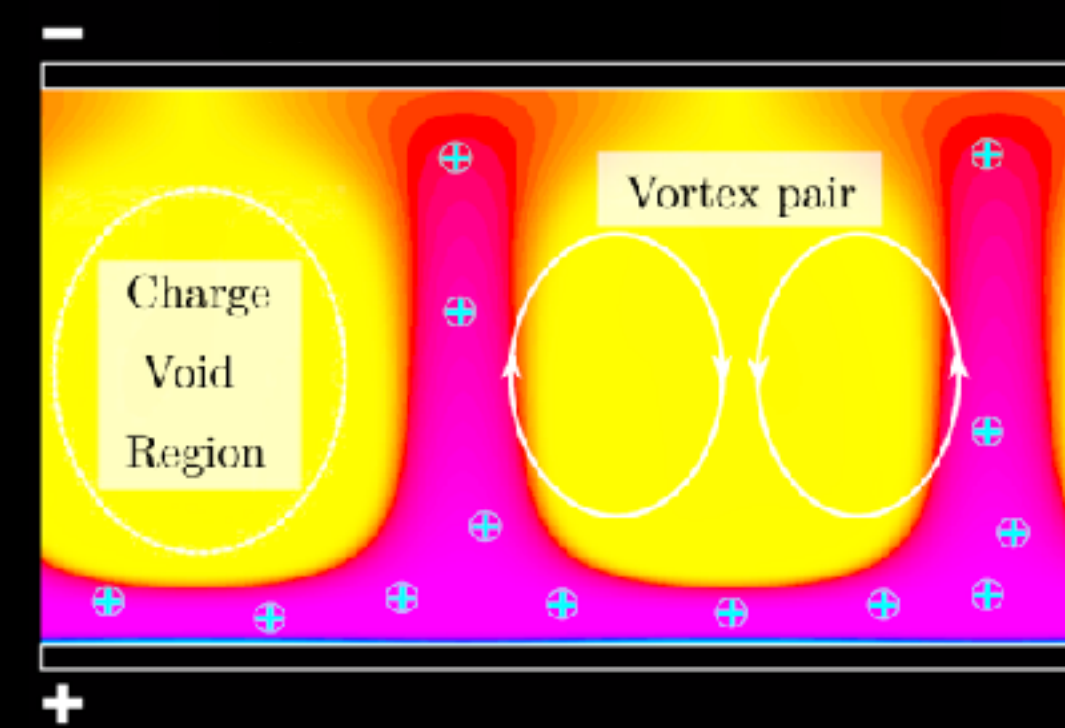
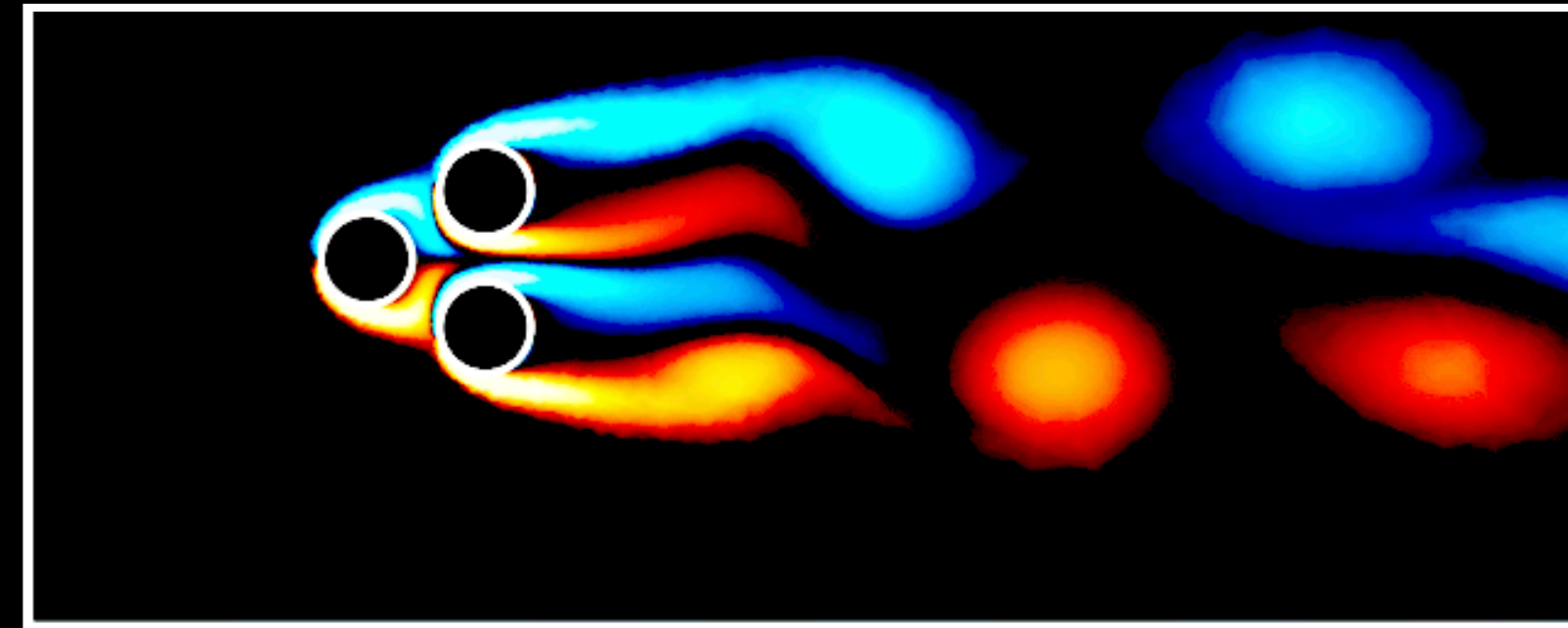
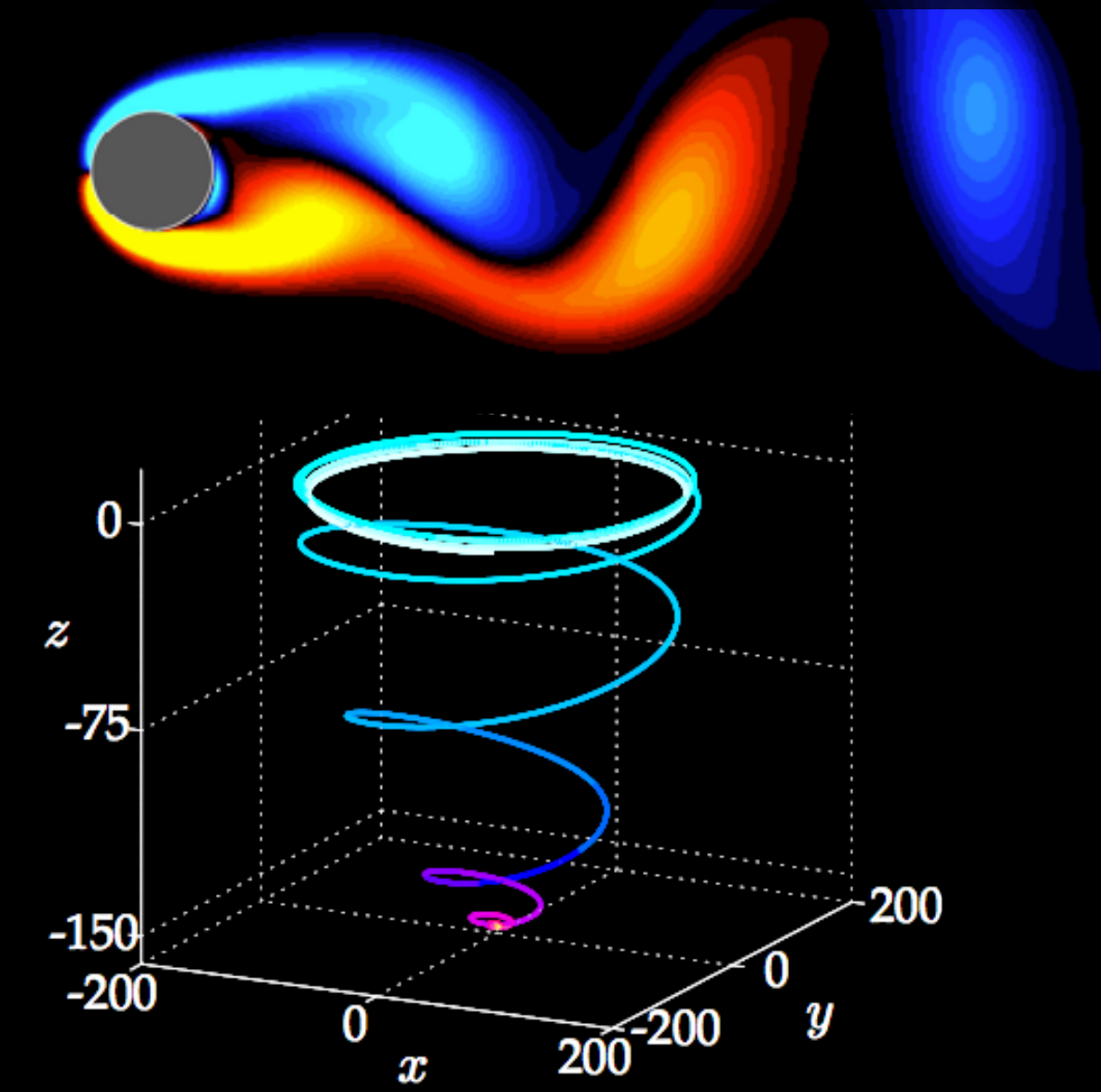
# More Complex Flow: Fluidic Pinball



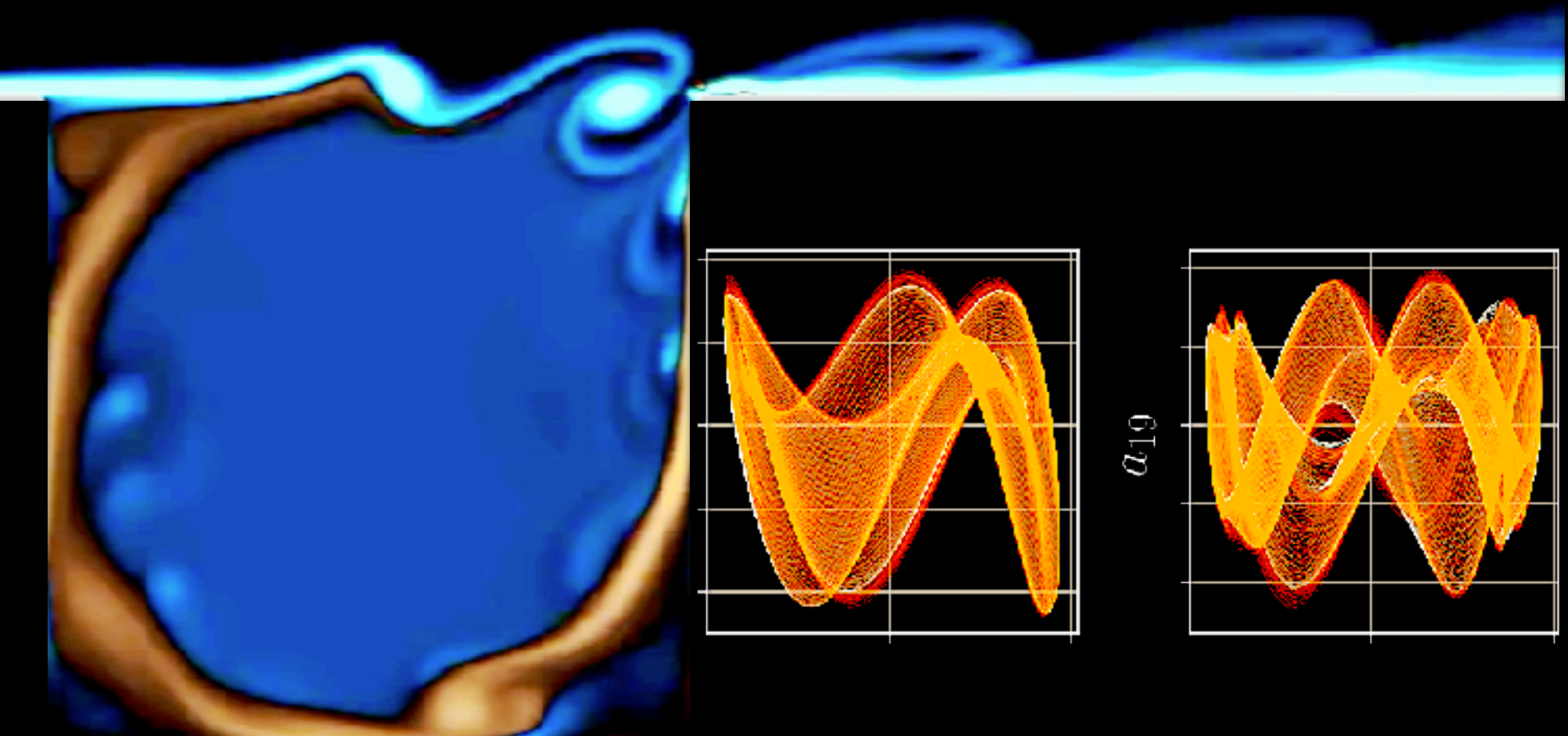
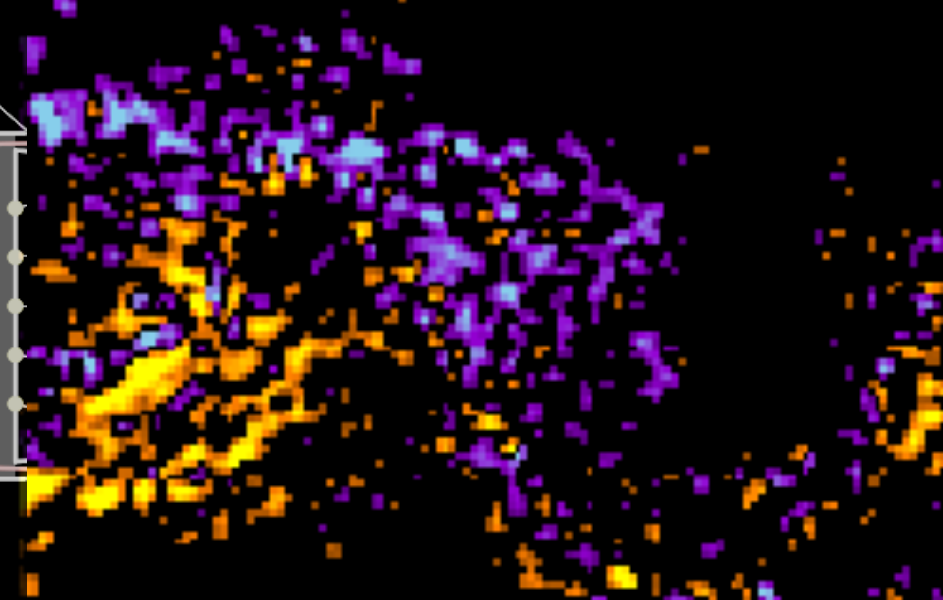
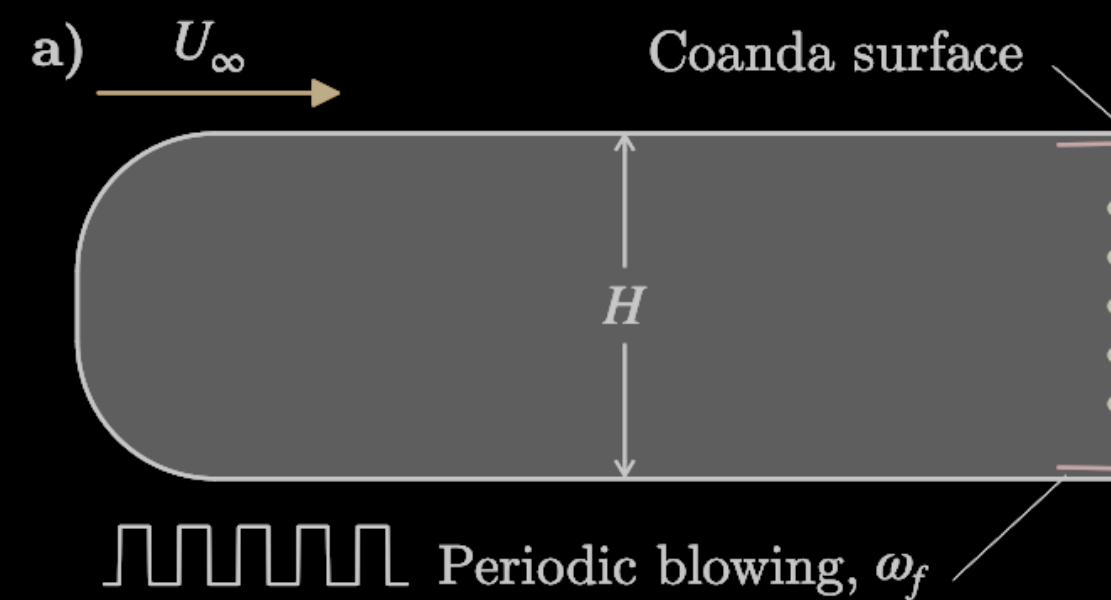
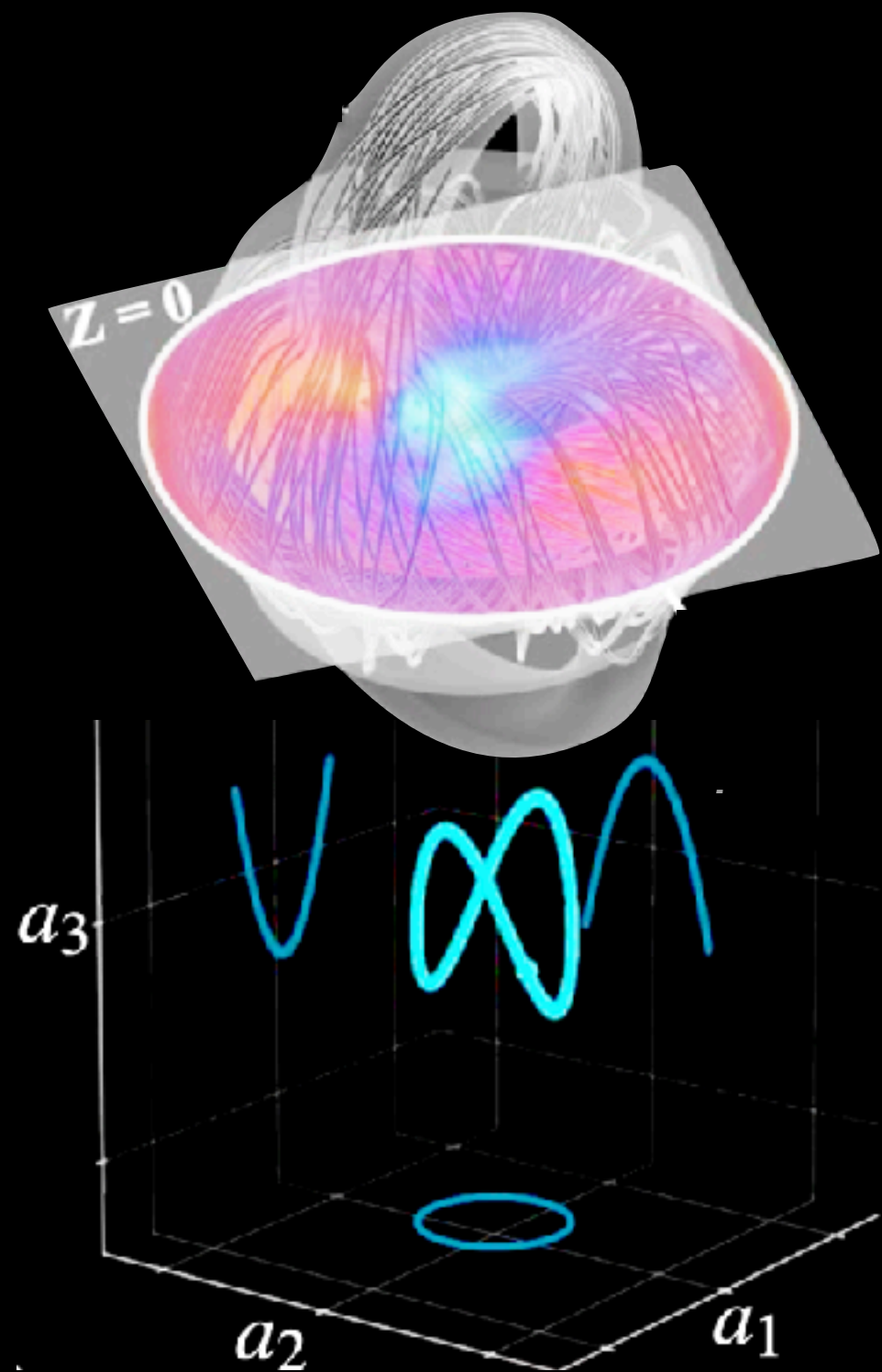
— DNS

- - - Low-order model

Brunton et al. *PNAS* 2016 **SPARSE NONLINEAR MODELS OF FLUID DYNAMICS**



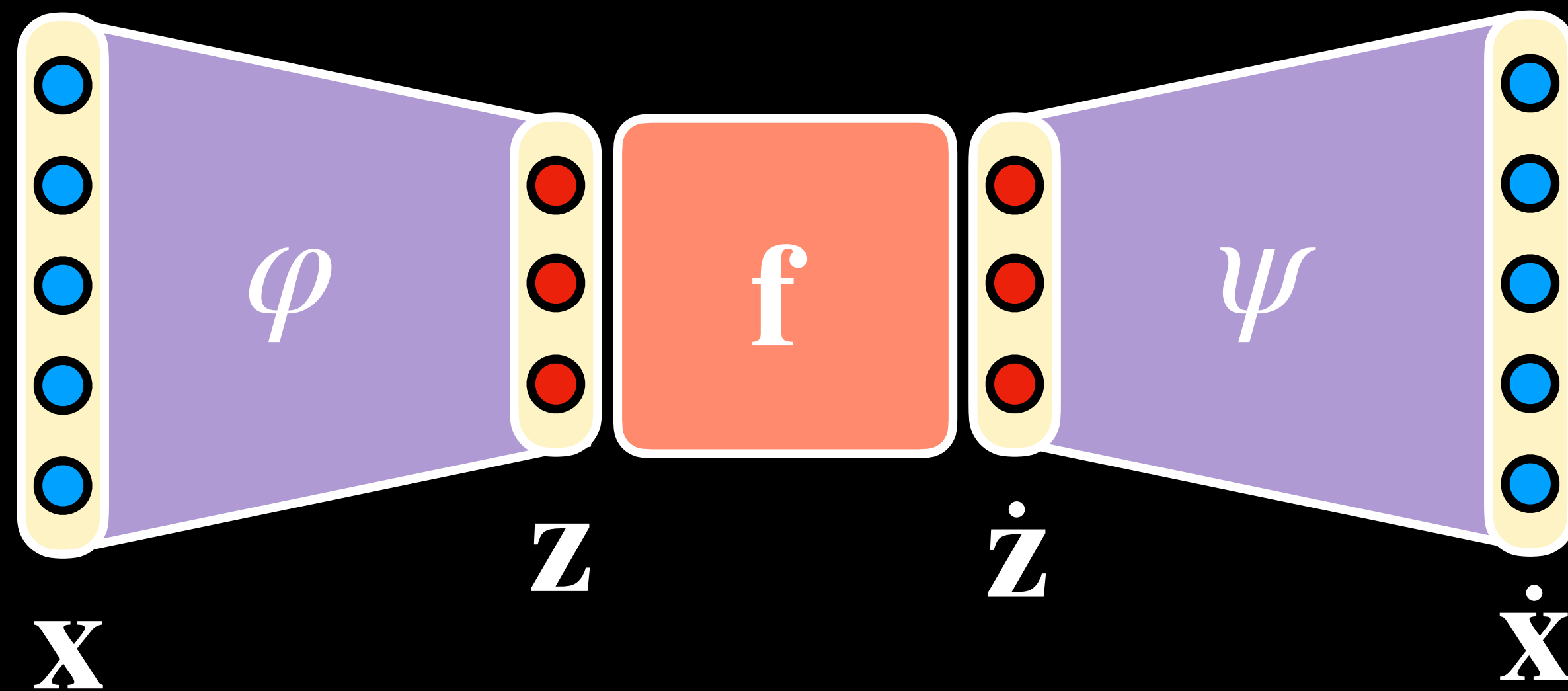
$$\frac{d}{dt} \mathbf{x} = \mathbf{f}(\mathbf{x})$$



**There is a need for**  
**INTERPRETABLE and GENERALIZABLE**  
**Machine Learning**

- **LOW-DIMENSIONAL**
- **SPARSE**

**There is a need for  
INTERPRETABLE and GENERALIZABLE  
Machine Learning**



$$\frac{d}{dt}\mathbf{z} = \mathbf{f}(\mathbf{z})$$

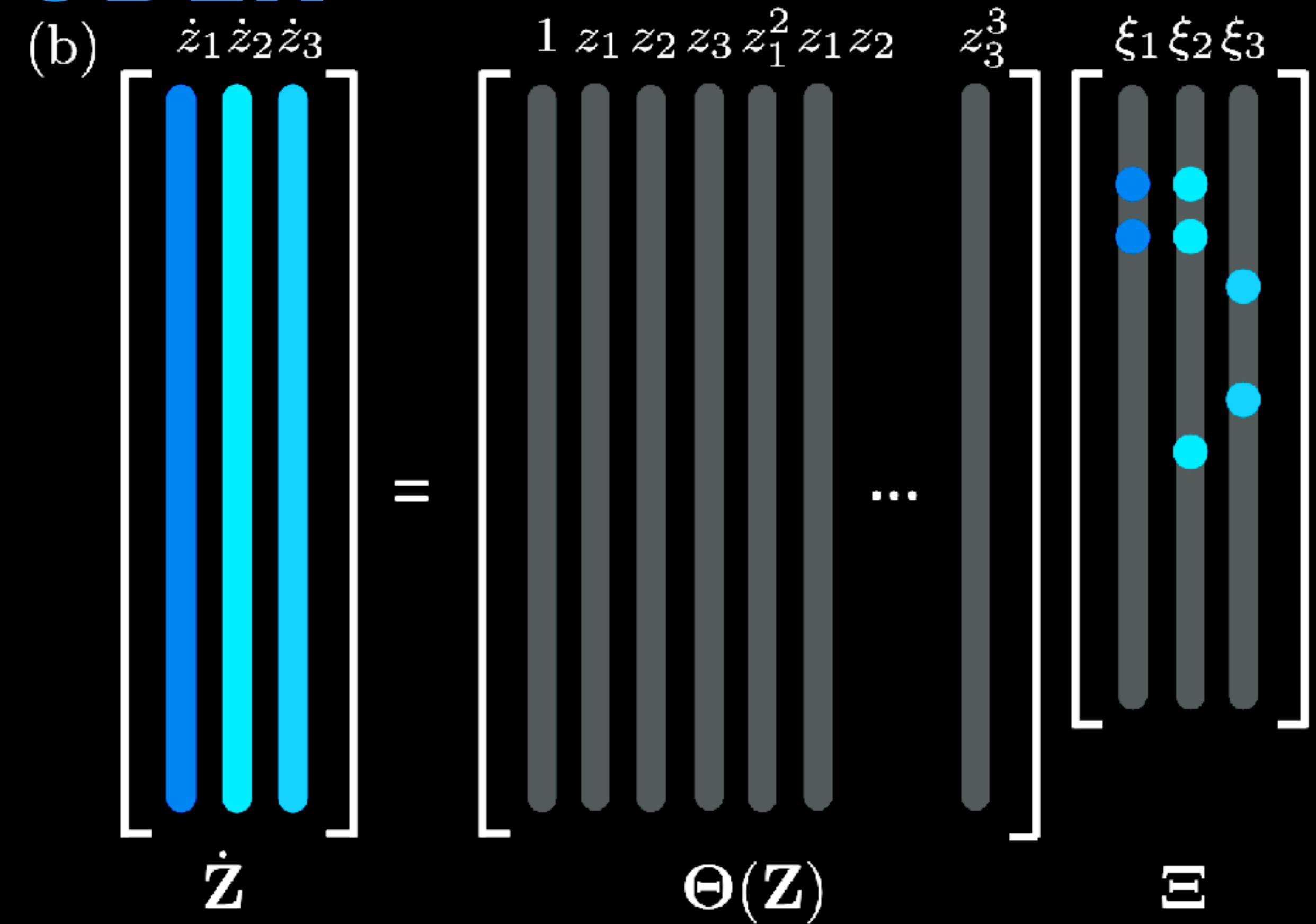
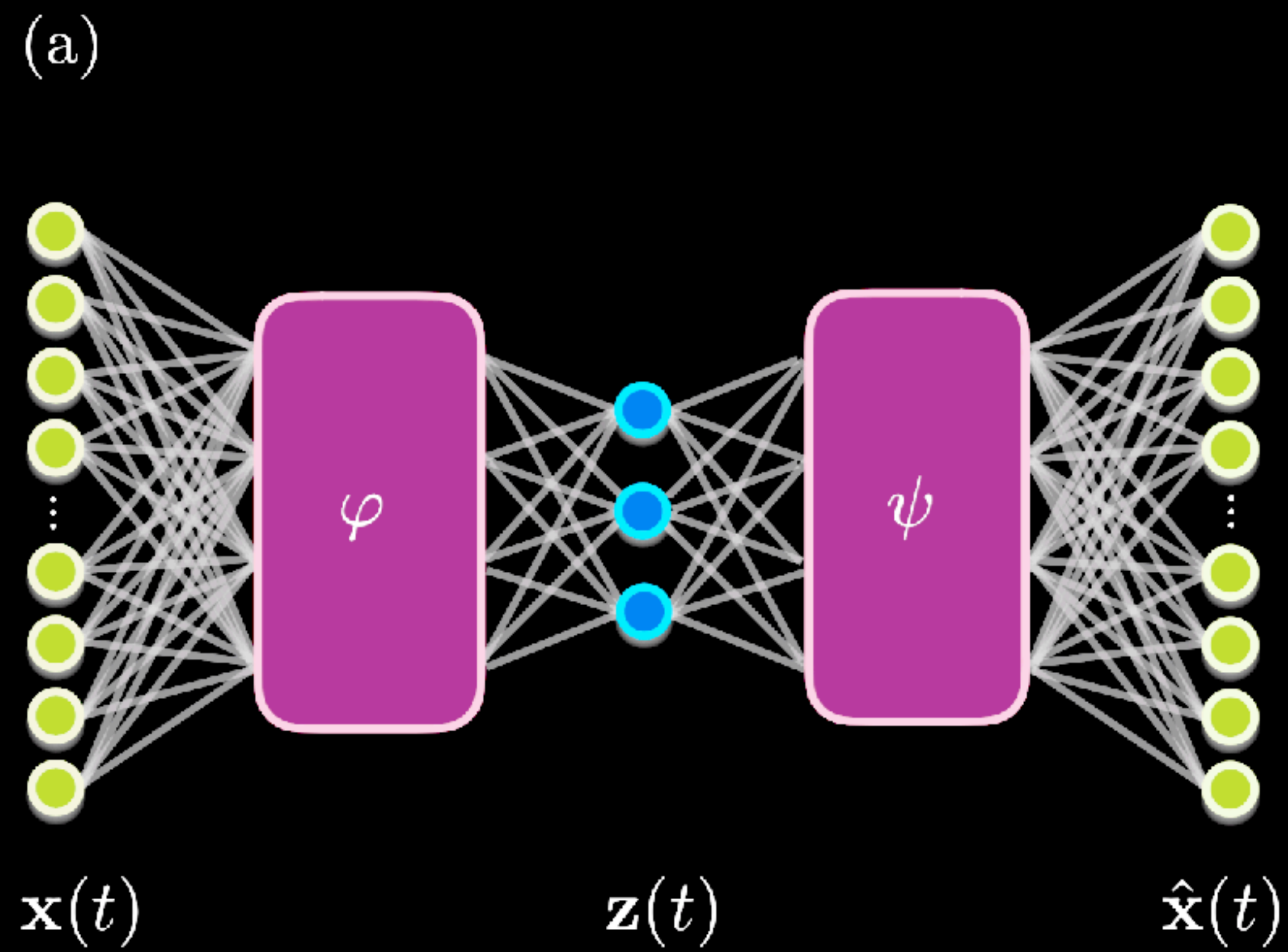
# Heliocentrism



# Geocentrism



# SINDY + AUTOENCODER



$$\dot{\mathbf{z}}_i = \nabla_{\mathbf{x}} \varphi(\mathbf{x}_i) \dot{\mathbf{x}}_i \quad \Theta(\mathbf{z}_i^T) = \Theta(\varphi(\mathbf{x}_i)^T)$$

$$\underbrace{\|\mathbf{x} - \psi(\mathbf{z})\|_2^2}_{\text{reconstruction loss}} + \underbrace{\lambda_1 \|\dot{\mathbf{x}} - (\nabla_{\mathbf{z}} \psi(\mathbf{z})) (\Theta(\mathbf{z}^T) \Xi)\|_2^2}_{\text{SINDy loss in } \dot{\mathbf{x}}} + \underbrace{\lambda_2 \|(\nabla_{\mathbf{x}} \mathbf{z}) \dot{\mathbf{x}} - \Theta(\mathbf{z}^T) \Xi\|_2^2}_{\text{SINDy loss in } \dot{\mathbf{z}}} + \underbrace{\lambda_3 \|\Xi\|_1}_{\text{SINDy regularization}}$$







**QUESTIONS**