

Calculation method of coefficients of bending energy and non-uniqueness of local stress field

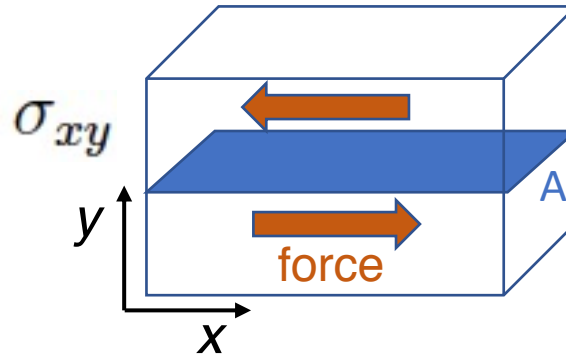
1. Non-uniqueness of local stress field
2. Virtual bending method to calculate coefficients of bending energy



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Calculation of global stress in molecular simulation

Stress: force per area



area average

Kinetic component:

Momentum transport via molecular motion

$$\sigma_{xy}^K = \frac{m}{A\Delta t} \left\langle \sum_{\substack{y_i(t) > 0, v_{i,y} < -\frac{y_i(t)}{\Delta t} \\ \text{up-to-down}}} v_{i,x} - \sum_{\substack{y_i(t) < 0, v_{i,y} > -\frac{y_i(t)}{\Delta t} \\ \text{down-to-up}}} v_{i,x} \right\rangle$$

Potential component:

forces crossing the surface

$$\sigma_{xy}^U = \frac{1}{A} \left\langle \sum_{y_i > 0, y_j < 0} f_{i,x}(\mathbf{r}_i, \mathbf{r}_j, \dots, \mathbf{r}_k) \right\rangle$$

averaging
surfaces

volume average

Virial theorem:

$$\boldsymbol{\sigma} = \boldsymbol{\sigma}_K + \boldsymbol{\sigma}_U,$$

$$\boldsymbol{\sigma}_K = -\frac{1}{V} \sum_i \langle m_i \mathbf{v}_i \otimes \mathbf{v}_i \rangle,$$

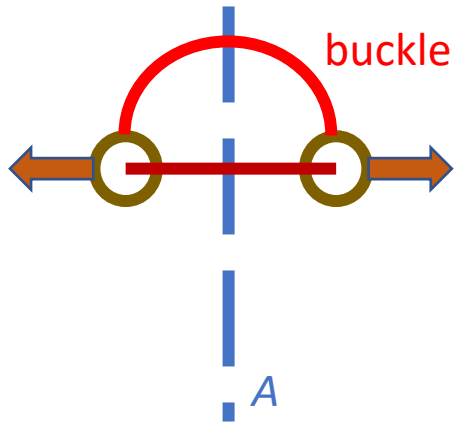
$$\boldsymbol{\sigma}_U = -\frac{1}{V} \sum_i \langle \mathbf{f}_i \otimes \mathbf{r}_i \rangle,$$

Pressure tensor

$$P_{\alpha\beta} = -\sigma_{\alpha\beta}$$

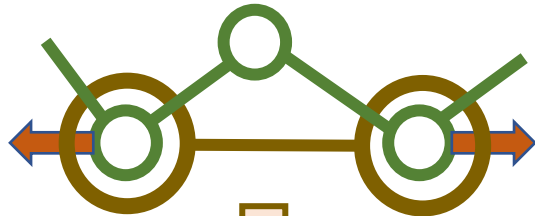
Clear definition. Stress is uniquely determined.

Local stress for pairwise potentials



Force propagating through the surface, but lateral position can be different.

Coarse-graining from  to 



 average

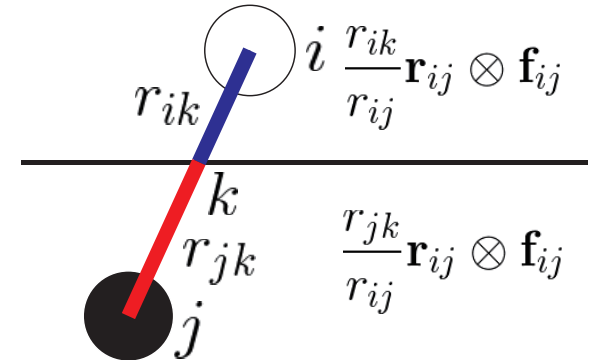


Propagating along cones?

Propagating pathway is not uniquely determined.



Let's use the straight line for simplicity!
Irving-Kirkwood-Noll (IKN) procedure



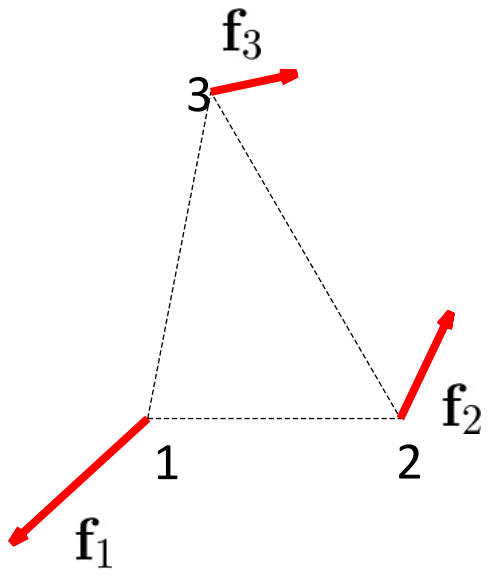
Minimizing sum of length, etc.

Admal and Tadmor, J. Elast. 100, 63-143 (2010).

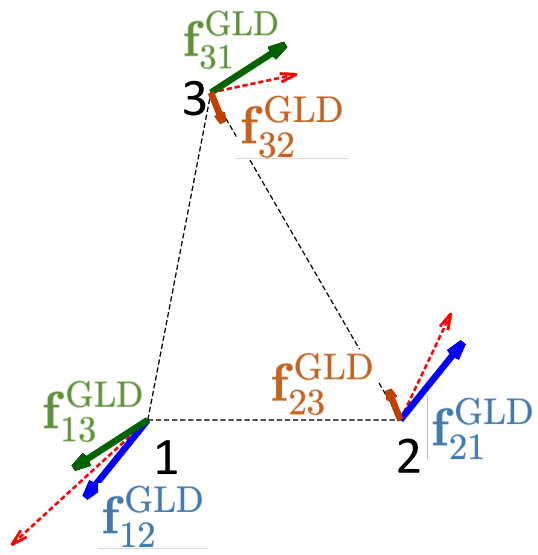
Local stress for multi-body potentials

decomposition to pairwise forces

three-body forces

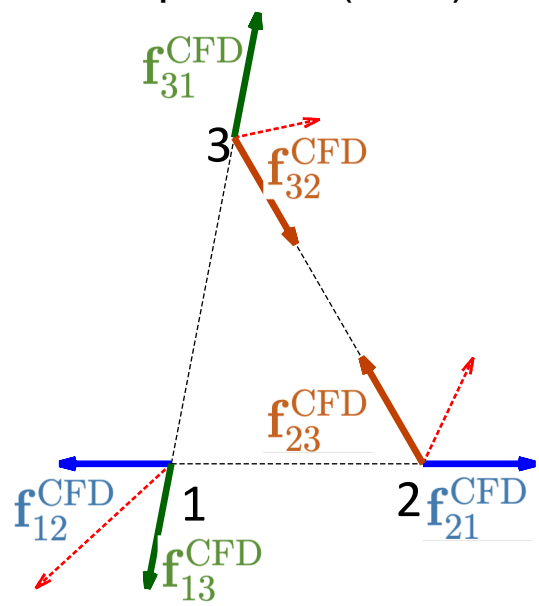


Goetz Lipowsky Decomposition



$$\mathbf{f}_{ij}^{\text{GLD}} = (\mathbf{f}_i - \mathbf{f}_j) / n$$

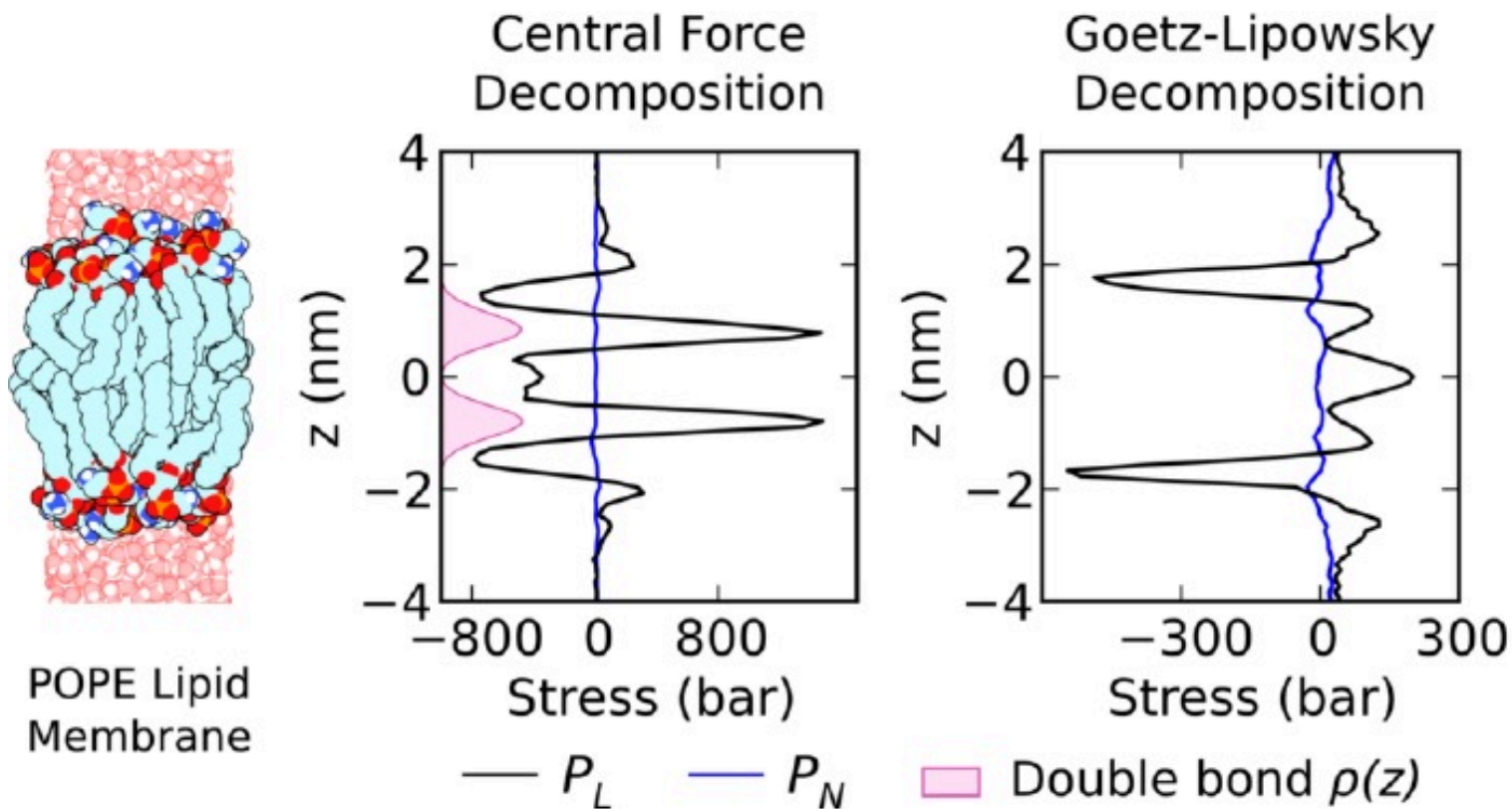
Central Force Decomposition (CFD)



$$\mathbf{f}_{ij}^{\text{CFD}} = f_{ij} \hat{\mathbf{r}}_{ij}$$

$\mathbf{r}_{ij} \nparallel \mathbf{f}_{ij}$ $\sigma_{\alpha\beta} \neq \sigma_{\beta\alpha}$	$\mathbf{r}_{ij} \parallel \mathbf{f}_{ij}$ $\sigma_{\alpha\beta} = \sigma_{\beta\alpha}$
Angular momentum not conserved	conserved

Pressure profile of membrane ($P = -\sigma$)



Stress profile strongly depends on force decomposition!

Central Force Decomposition (CFD) for n -body potentials

CFD is not unique at $n > 4$ in 3D ($n > 3$ in 2D).

More degrees of freedom
 $n(n-1)/2 > 3n - 6$ in 3D
 $2n - 3$ in 2D

For large n , CFD force pairs are give by

$$\Psi = (f_{12}, \dots, f_{ij}, \dots)$$

$$\Psi = \Psi_0 + \sum_{\ell}^{n_{\text{rest}}} a_{\ell} \Psi_{\ell}$$

$$\Psi_0 \cdot \Psi_{\ell} = 0.$$

a_{ℓ} is an arbitrary real number.

Ψ_0 is called covariant or irrotational component.

(Arroyo)

(Admal)

Admal and Tadmor, J. Mech. Phys. Solids 93, 72 (2016).

Torres-Sánchez, Vanegas, and Arroyo, J. Mech. Phys. Solids 93, 224 (2016).

In covariant CFD, Ψ_0 is used as a unique decomposition.

$$\text{minimization of } \Psi^2 = \sum_{ij} f_{ij}^2$$

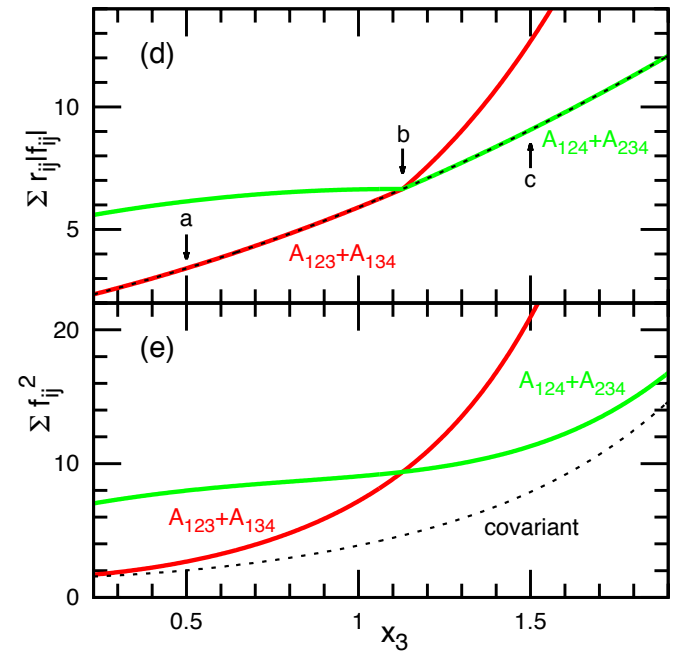
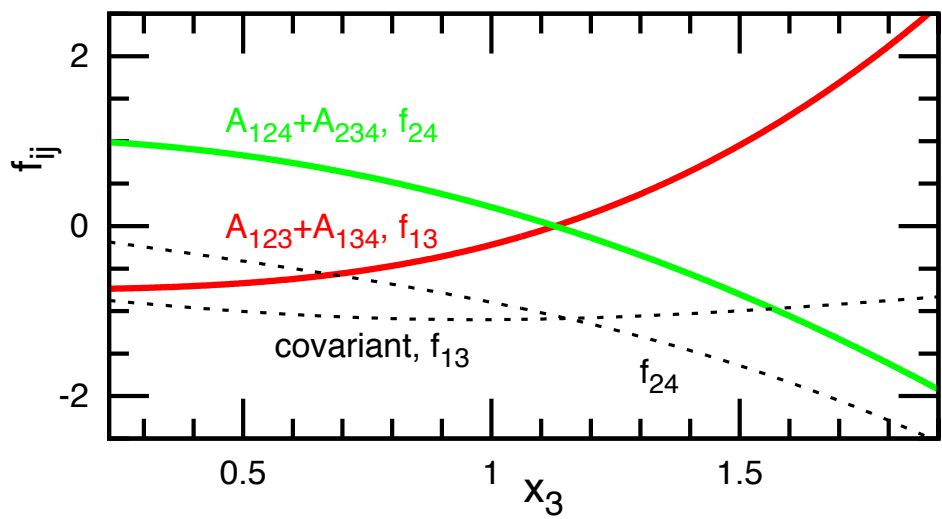
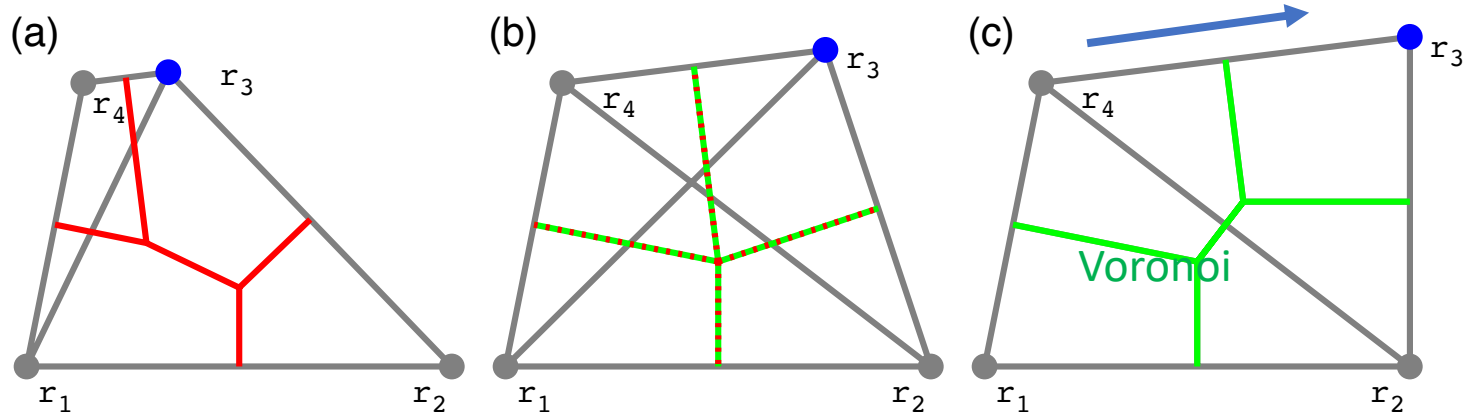
Torres-Sánchez, **Vanegas**, and **Arroyo**, J. Mech. Phys. Solids 93, 224 (2016).

Example of the force decomposition (area of tetragon in 2D)

Potential A_{1234}^2

$$A_{1234} = A_{123} + A_{134} = A_{124} + A_{134}$$

$$\Psi_1 = \Psi(A_{123} + A_{134}) - \Psi(A_{124} + A_{134})$$



Q: Which do you choose, covariant CFD or Voronoi?

Force decomposition of pairwise potentials

Case: a multibody potential expresses a sum of pairwise potentials in some limit.

$$U_{\text{ps}} = \sum_k U_{\text{pair},k}(r_{ij})$$

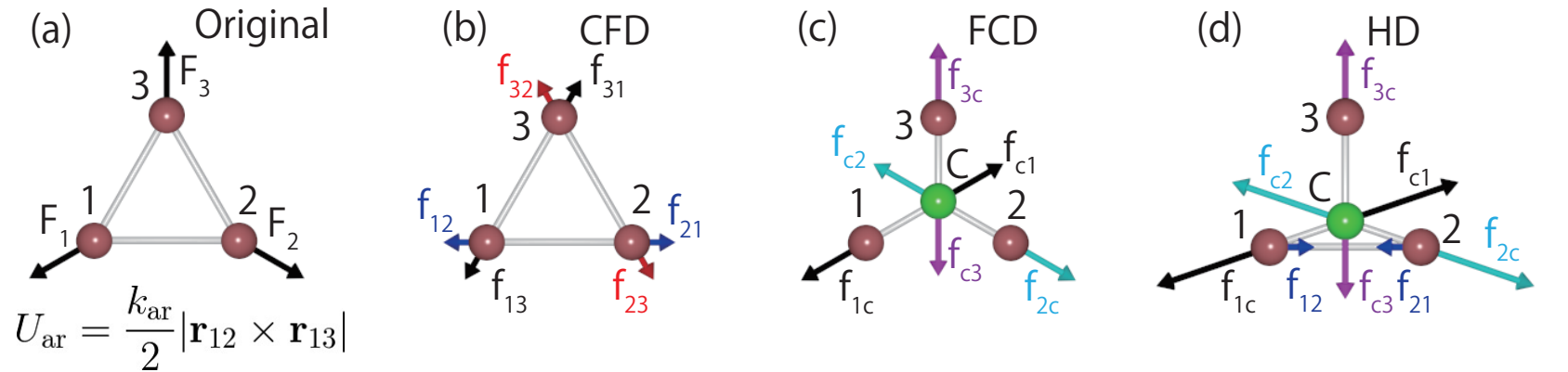
Force decomposition should be

$$f_{ij} = -\frac{\partial U_{\text{pair},k}}{\partial r_{ij}}$$

But

covariant CFD and any other methods only based on f_i cannot give this decomposition.

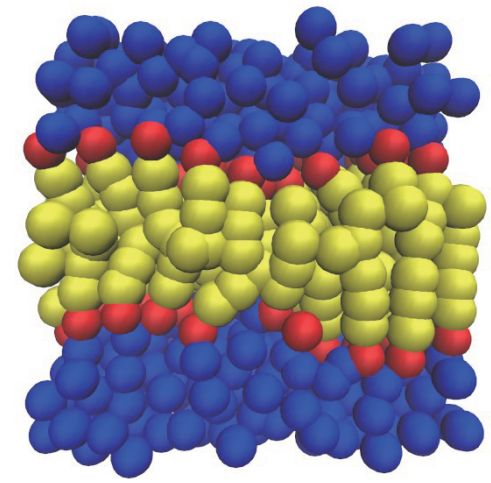
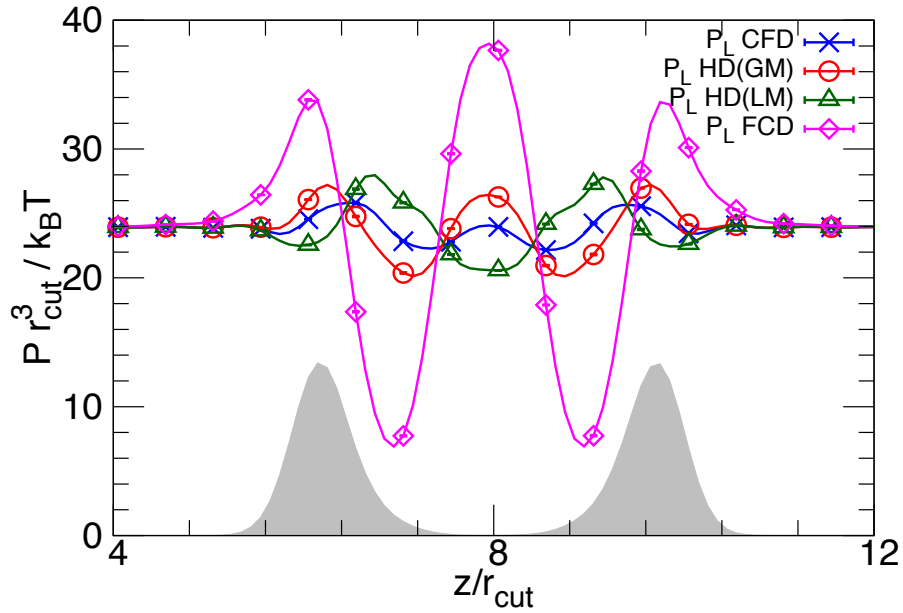
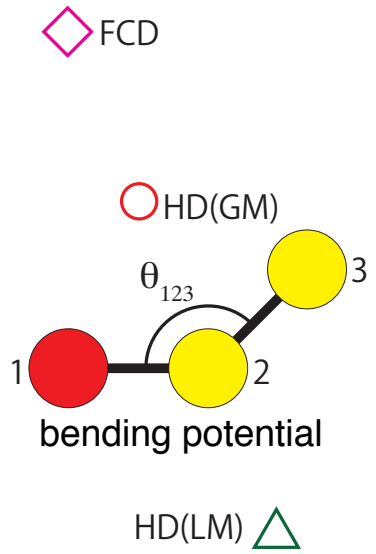
Force Center Decomposition (FCD) for three-body potentials



Another decomposition conserving angular momentum

Force Center Decomposition (FCD):
 Forces of a three-body potential always meet at one point.
 These force pairs can be used for decomposition.

Pressure profile of membrane, again



DPD membrane

Stress profile strongly depends on force decomposition even under the angular-momentum conservation!

But profile is always **mirror-symmetric**.

Summary 1

Local stress field is not uniquely determined on molecular scale.

K. M. Nakagawa and HN, Phys. Rev. E **94**, 053304 (2016).

HN, Phys. Rev. E **102**, 053315 (2020).

Questions:

Q1: Is molecular-scale local stress a meaningful quantity?

If yes:

Q2: How do you calculate local stress?

a. From higher resolution data

(quantum calculation for all-atom MD, All-atom for CG)

b. Following some manner (covariant CFD or others)

Q3: Do macroscopic properties depend on the decomposition?

2. Virtual bending method to calculate coefficients of bending energy

Bending energy

$$F = \int \left[\frac{\kappa}{2} (C_1 + C_2 - C_0)^2 + \bar{\kappa} C_1 C_2 \right] dA$$

- Bending rigidity κ
- Saddle-splay modulus (Gaussian modulus) $\bar{\kappa}$
- Spontaneous curvature C_0

Estimation of saddle-splay modulus from stress profile

moments of stress profile

$$-\kappa C_0 = \int (\sigma_{\parallel}(z) - \sigma_{zz}(z))z dz,$$

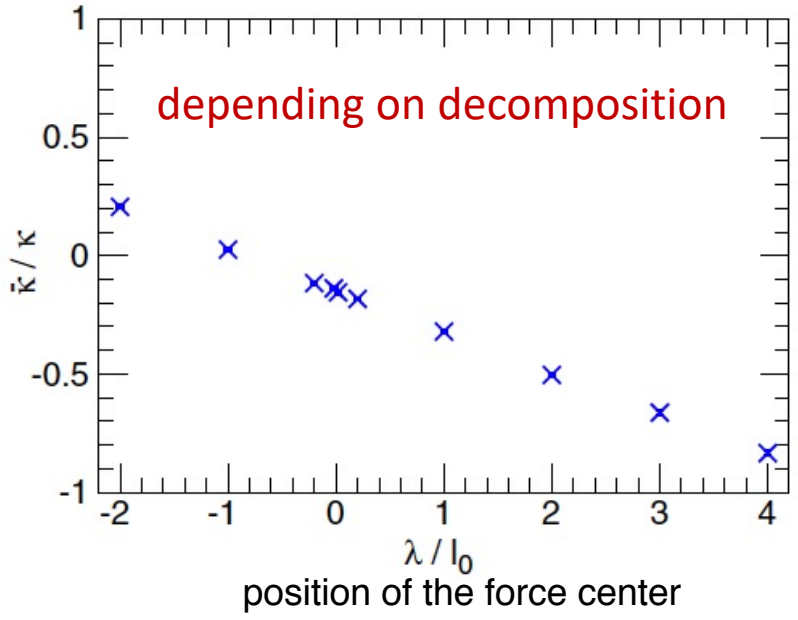
first moment

$$\boxed{\bar{\kappa}} = \int (\sigma_{\parallel}(z) - \sigma_{zz}(z))z^2 dz,$$

second moment

lateral vertical

W. Helfrich, Physics of Defects (1981).
 I. Szleifer, D. Kramer, A. Ben-Shaul, W. M. Gelbart,
 and S. A. Safran, J. Chem. Phys. 92, 6800 (2016).



Q: What's wrong?

K. M. Nakagawa and HN, Phys. Rev. E 94, 053304 (2016).

?

$$\bar{\kappa}/\kappa \simeq -1$$

for lipid membrane

Hu, Briguglio, and Deserno, Biophys. J. 102, 1403 (2012).

Aim:

Calculating $\kappa, \bar{\kappa}, C_0$

directly from mechanical response

without using force decomposition

Free energy change by virtual deformation (parameter λ)

$$F = -k_B T \ln \left(\int e^{-E/k_B T} d\Omega \right),$$

$$\left. \frac{\partial F}{\partial \lambda} \right|_{V,T} = \frac{\int \frac{\partial E}{\partial \lambda} e^{-E/k_B T} d\Omega}{\int e^{-E/k_B T} d\Omega} = \left\langle \frac{\partial E}{\partial \lambda} \right\rangle_{V,T},$$

$$\left. \frac{\partial^2 F}{\partial \lambda^2} \right|_{V,T} = \left\langle \frac{\partial^2 E}{\partial \lambda^2} \right\rangle_{V,T} - \frac{1}{k_B T} \left(\left\langle \left(\frac{\partial E}{\partial \lambda} \right)^2 \right\rangle_{V,T} - \left\langle \frac{\partial E}{\partial \lambda} \right\rangle_{V,T}^2 \right),$$

thermal-fluctuation term



**This is not considered in stress profile method.
A: Second moment $\neq \bar{\kappa}$**

Example of virtual deformation (calculation of surface tension γ)

affine deformation (constant volume, lateral extension)

$$\mathbf{r}'_i = \begin{pmatrix} 1 + \varepsilon/2 & 0 & 0 \\ 0 & 1 + \varepsilon/2 & 0 \\ 0 & 0 & 1 - \varepsilon \end{pmatrix} \mathbf{r}_i$$

virtual work

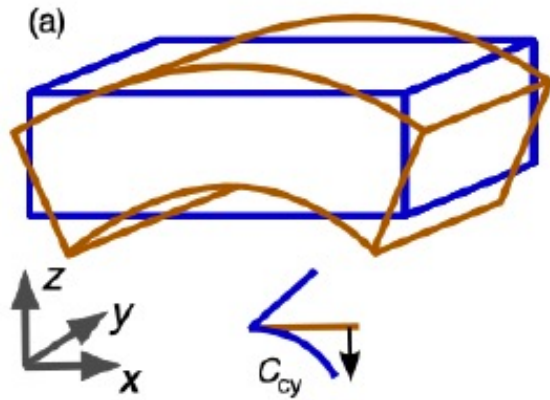
$$\Delta F = \gamma \Delta A_{xy} \quad \Delta A_{xy} = \varepsilon A_{xy}$$

$$\begin{aligned} \gamma &= \frac{1}{A_{xy}} \sum_i \left\langle \frac{1}{2} \left(x_i \frac{\partial U}{\partial x_i} + y_i \frac{\partial U}{\partial y_i} \right) - z_i \frac{\partial U}{\partial z_i} \right\rangle \\ &= [(\sigma_{xx} + \sigma_{yy})/2 - \sigma_{zz}]/A_{xy} \end{aligned}$$

same form as in usual method of stress difference

Virtual bending deformation

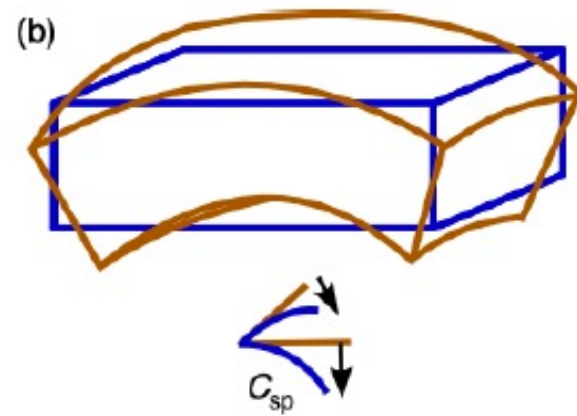
Cylindrical deformation



$$F = \frac{\kappa}{2} (C_{cy} - C_0)^2 A_{xy}$$

κ and C_0

Spherical deformation



$$F = \left[\frac{\kappa}{2} (2C_{sp} - C_0)^2 + \bar{\kappa} C_{sp}^2 \right] A_{xy}$$

also, $\bar{\kappa}$

Local deformation with constant curvature is available under periodic boundary condition.

(not for longer-range interactions than length of simulation box)

$$\left. \frac{\partial F}{\partial C_{cy}} \right|_{V,T,C_{cy}=0} = -\kappa C_0 A_{xy} = \left\langle \frac{\partial U}{\partial C_{cy}} \right\rangle, \quad (16)$$

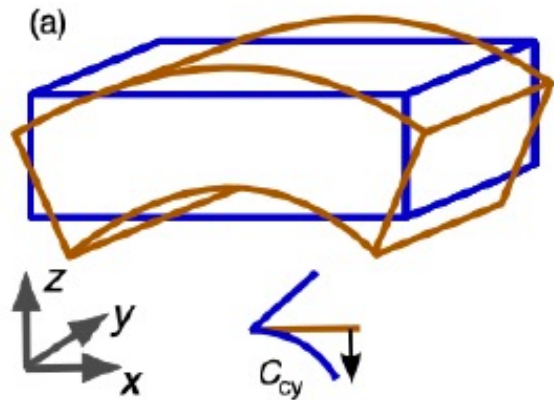
$$\left. \frac{\partial^2 F}{\partial C_{cy}^2} \right|_{V,T,C_{cy}=0} = \kappa A_{xy} = \left\langle \frac{\partial^2 U}{\partial C_{cy}^2} \right\rangle \quad (17)$$

$$-\frac{1}{k_B T} \left(\left\langle \left(\frac{\partial U}{\partial C_{cy}} \right)^2 \right\rangle - \left\langle \frac{\partial U}{\partial C_{cy}} \right\rangle^2 \right),$$

$$\left. \frac{\partial^2 F}{\partial C_{sp}^2} \right|_{V,T,C_{sp}=0} = (4\kappa + 2\bar{\kappa}) A_{xy} = \left\langle \frac{\partial^2 U}{\partial C_{sp}^2} \right\rangle \quad (18)$$

$$-\frac{1}{k_B T} \left(\left\langle \left(\frac{\partial U}{\partial C_{sp}} \right)^2 \right\rangle - \left\langle \frac{\partial U}{\partial C_{sp}} \right\rangle^2 \right),$$

Cylindrical deformation



$$\theta_{c,i} = C_{cy} x_i,$$

$$r'_{c,i} = \frac{1}{C_{cy}} + z_i - \frac{1}{2} z_i^2 C_{cy} + \frac{\alpha_1}{2} z_i^3 C_{cy}^2.$$

constant volume: $\alpha_1 = 1$
 variable α_1 to check
 volume fluctuation effects

$$x'_i = r'_i \sin \theta_{c,i},$$

$$y'_i = y_i,$$

$$z'_i = r'_i \cos \theta_{c,i} - \frac{1}{C_{cy}},$$

$$x'_i = x_i \left[1 + z_i C_{cy} - \left(\frac{z_i^2}{2} + \frac{x_i^2}{6} \right) C_{cy}^2 \right] + O(C_{cy}^3),$$

$$z'_i = z_i - \frac{1}{2} (z_i^2 + x_i^2) C_{cy} + \frac{z_i}{2} (\alpha_1 z_i^2 - x_i^2) C_{cy}^2 + O(C_{cy}^3).$$

$$U(\mathbf{r}_1, \dots, \mathbf{r}_N) = \sum_{n=2}^N \sum_{k_n} U_{k_n}(\mathbf{r}_{k_n,1}, \dots, \mathbf{r}_{k_n,n}),$$

$$\delta U_{k_n} \simeq \sum_j^n \left(\delta x_j \frac{\partial U_{k_n}}{\partial x_j} + \delta y_j \frac{\partial U_{k_n}}{\partial y_j} + \delta z_j \frac{\partial U_{k_n}}{\partial z_j} \right) \quad (26)$$

$$+ \frac{1}{2} \left(\sum_j^n \delta x_j \frac{\partial}{\partial x_j} + \delta y_j \frac{\partial}{\partial y_j} + \delta z_j \frac{\partial}{\partial z_j} \right)^2 U_{k_n}.$$

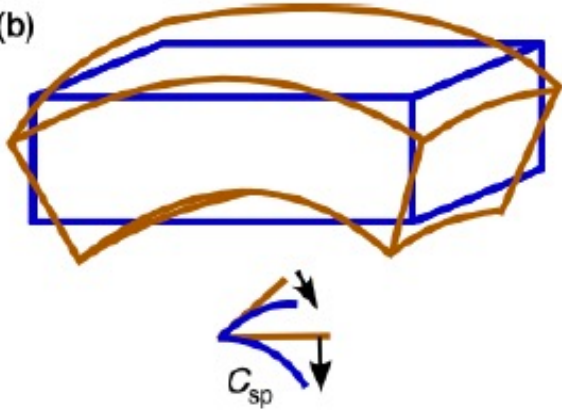
$$\left\langle \frac{\partial U_{k_n}}{\partial C_{cy}} \right\rangle = \sum_j^n \left\langle \frac{z_j}{2} \left(x_j \frac{\partial U_{k_n}}{\partial x_j} + y_j \frac{\partial U_{k_n}}{\partial y_j} \right) - \left(\frac{z_j^2}{2} + \frac{x_j^2 + y_j^2}{4} \right) \frac{\partial U_{k_n}}{\partial z_j} \right\rangle, \quad (27)$$

$$\left\langle \frac{\partial^2 U_{k_n}}{\partial C_{cy}^2} \right\rangle = \sum_j^n \left\langle -x_j \left(\frac{z_j^2}{2} + \frac{x_j^2}{6} \right) \frac{\partial U_{k_n}}{\partial x_j} - y_j \left(\frac{z_j^2}{2} + \frac{y_j^2}{6} \right) \frac{\partial U_{k_n}}{\partial y_j} + z_j \left(\alpha_1 z_j^2 - \frac{x_j^2 + y_j^2}{2} \right) \frac{\partial U_{k_n}}{\partial z_j} \right\rangle$$

$$+ \frac{1}{2} \left\langle \left(\sum_j^n x_j z_j \frac{\partial}{\partial x_j} - \frac{z_j^2 + x_j^2}{2} \frac{\partial}{\partial z_j} \right)^2 U_{k_n} + \left(\sum_j^n y_j z_j \frac{\partial}{\partial y_j} - \frac{z_j^2 + y_j^2}{2} \frac{\partial}{\partial z_j} \right)^2 U_{k_n} \right\rangle. \quad (28)$$

Spherical deformation

(b)



$$\rho_i = \sqrt{x_i^2 + y_i^2}$$

$$\rho'_i = r'_{s,i} \sin \theta_{s,i} \quad (23)$$

$$= \rho_i \left[1 + z_i C_{sp} - \left(z_i^2 + \frac{\rho_i^2}{6} \right) C_{sp}^2 \right] + O(C_{sp}^3),$$

$$z'_i = r'_{s,i} \cos \theta_{s,i} - \frac{1}{C_{sp}} \quad (24)$$

$$= z_i - \left(z_i^2 + \frac{\rho_i^2}{2} \right) C_{sp} + z_i \left(\frac{5\alpha_2}{3} z_i^2 - \frac{\rho_i^2}{2} \right) C_{sp}^2 + O(C_{sp}^3).$$

constant volume: $\alpha_2 = 1$

$$\begin{aligned} \left\langle \frac{\partial^2 U_{k_n}}{\partial C_{sp}^2} \right\rangle &= \sum_j \left\langle - \left(2z_j^2 + \frac{x_j^2 + y_j^2}{3} \right) \left(x_j \frac{\partial U_{k_n}}{\partial x_j} + y_j \frac{\partial U_{k_n}}{\partial y_j} \right) \right. \\ &\quad \left. + z_j \left[\frac{10}{3} \alpha_2 z_j^2 - (x_j^2 + y_j^2) \right] \frac{\partial U_{k_n}}{\partial z_j} \right\rangle \\ &\quad + \left\langle \left[\sum_j \left(x_j z_j \frac{\partial}{\partial x_j} + y_j z_j \frac{\partial}{\partial y_j} \right) \right. \right. \\ &\quad \left. \left. - \left(z_j^2 + \frac{x_j^2 + y_j^2}{2} \right) \frac{\partial}{\partial z_j} \right]^2 U_{k_n} \right\rangle. \quad (29) \end{aligned}$$

Pairwise potential

$$\begin{aligned}
 \left\langle \frac{\partial U_{\text{pair}}}{\partial C_{\text{cy}}} \right\rangle &= \left\langle \left(\frac{\rho_{ij}^2}{2} - z_{ij}^2 \right) \frac{z_{\text{G}}}{r_{ij}} \frac{\partial U_{\text{pair}}}{\partial r_{ij}} \right\rangle, & \left\langle \frac{\partial^2 U_{\text{pair}}}{\partial C_{\text{sp}}^2} \right\rangle &= \left\langle \left[(10\alpha_2 + 4) z_{ij}^2 z_{\text{G}}^2 - \rho_{ij}^2 z_{\text{G}}^2 \right. \right. & (32) \\
 \left. \left. \frac{3\rho_{ij}^2 z_{ij}^2}{4} - \frac{\rho_{ij}^4}{12} + \frac{5\alpha_2 z_{ij}^4}{6} \right] \frac{1}{r_{ij}} \frac{\partial U_{\text{pair}}}{\partial r_{ij}} \right. & \\
 \left. + (\rho_{ij}^4 + 4z_{ij}^4 - 4\rho_{ij}^2 z_{ij}^2) z_{\text{G}}^2 \right. & \\
 \left. \left(\frac{1}{r_{ij}^2} \frac{\partial^2 U_{\text{pair}}}{\partial r_{ij}^2} - \frac{1}{r_{ij}^3} \frac{\partial U_{\text{pair}}}{\partial r_{ij}} \right) \right\rangle, & \\
 \left\langle \frac{\partial^2 U_{\text{pair}}}{\partial C_{\text{cy}}^2} \right\rangle &= \left\langle \left(\frac{3\alpha_1 + 1}{2} z_{ij}^2 z_{\text{G}}^2 + \frac{\alpha_1}{4} z_{ij}^4 \right. \right. & \\
 \left. \left. - \frac{x_{ij}^4 + y_{ij}^4}{24} - \frac{\rho_{ij}^2 z_{ij}^2}{4} \right) \frac{1}{r_{ij}} \frac{\partial U_{\text{pair}}}{\partial r_{ij}} \right. & \\
 \left. + \frac{z_{\text{G}}^2}{2} [(x_{ij}^2 - z_{ij}^2)^2 + (y_{ij}^2 - z_{ij}^2)^2] \right. & \\
 \left. \left(\frac{1}{r_{ij}^2} \frac{\partial^2 U_{\text{pair}}}{\partial r_{ij}^2} - \frac{1}{r_{ij}^3} \frac{\partial U_{\text{pair}}}{\partial r_{ij}} \right) \right\rangle, &
 \end{aligned}$$

$$\mathbf{r}_{ij} = \mathbf{r}_i - \mathbf{r}_j$$

$$\mathbf{r}_{\text{G}} = (\mathbf{r}_i + \mathbf{r}_j)/2$$

Relation between first derivative and first stress moment

$$-\kappa C_0 A_{xy} = \left\langle \frac{\partial U}{\partial C_{cy}} \right\rangle$$

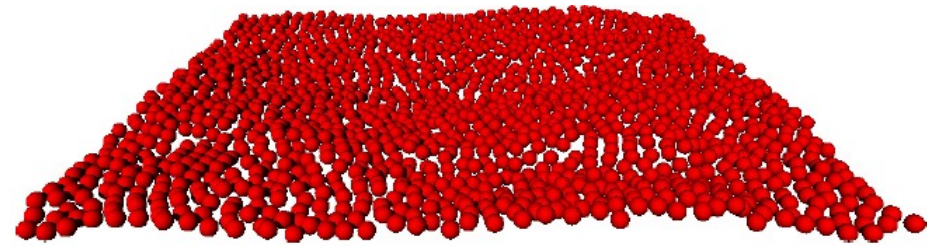
$$\begin{aligned} \frac{\partial U_{k_n}}{\partial C_{cy}} &= \sum_j^n \frac{z_j}{2} \left(x_j \frac{\partial U_{k_n}}{\partial x_j} + y_j \frac{\partial U_{k_n}}{\partial y_j} \right) - \left(\frac{z_j^2}{2} + \frac{x_j^2 + y_j^2}{4} \right) \frac{\partial U_{k_n}}{\partial z_j} \\ &= - \sum \left(\frac{\rho_{ij}^2}{2} - z_{ij}^2 \right) \frac{z_G}{r_{ij}} f_{ij} = \text{stress moment of central} \\ &\hspace{15em} \text{force decomposition} \end{aligned}$$

The first derivative coincides with first stress moment, so that it is the discretization form of stress moment without using force decomposition.

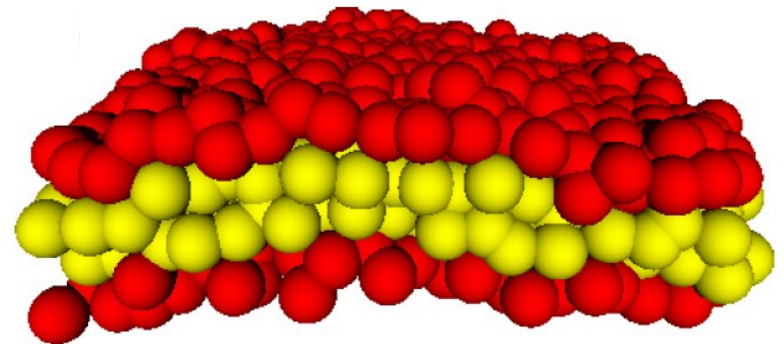
FCD gives the same moment, whereas GLD does not.
Angular-momentum-conservation is required for obtaining the right fist moment.

Calculation of κ , $\bar{\kappa}$ by virtual bending method

1. meshless membrane model
 - no solvent
 - n -body potential
 - $n \sim 20$

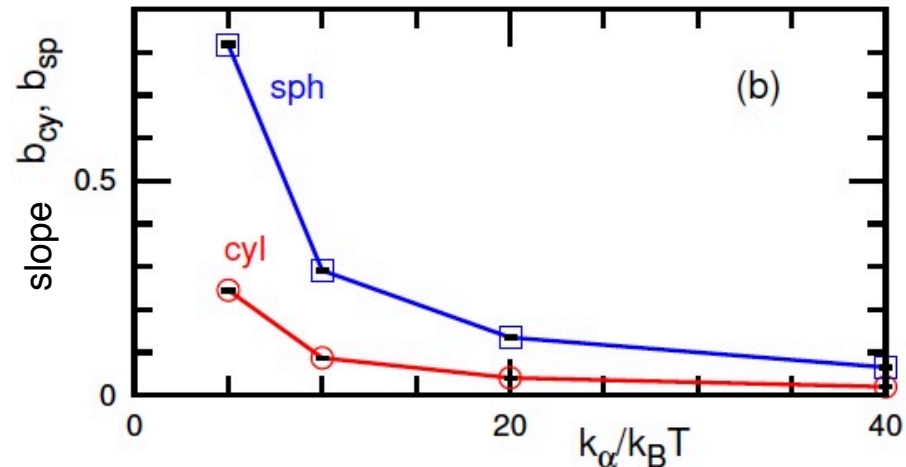
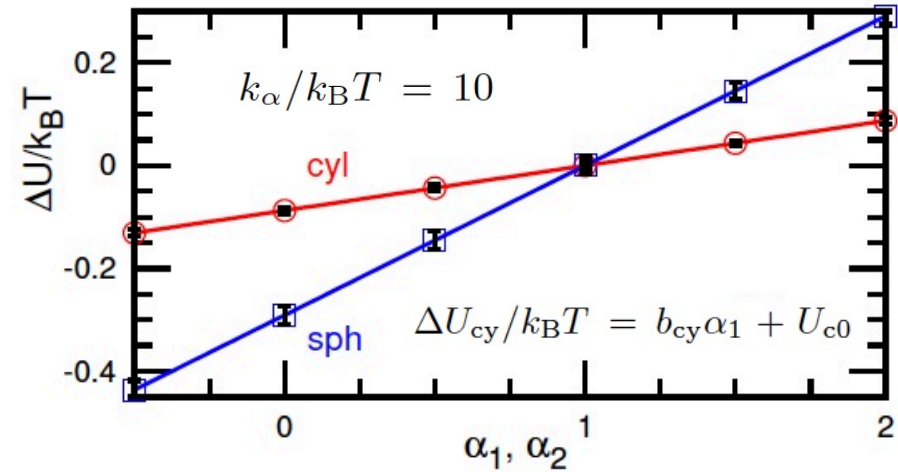
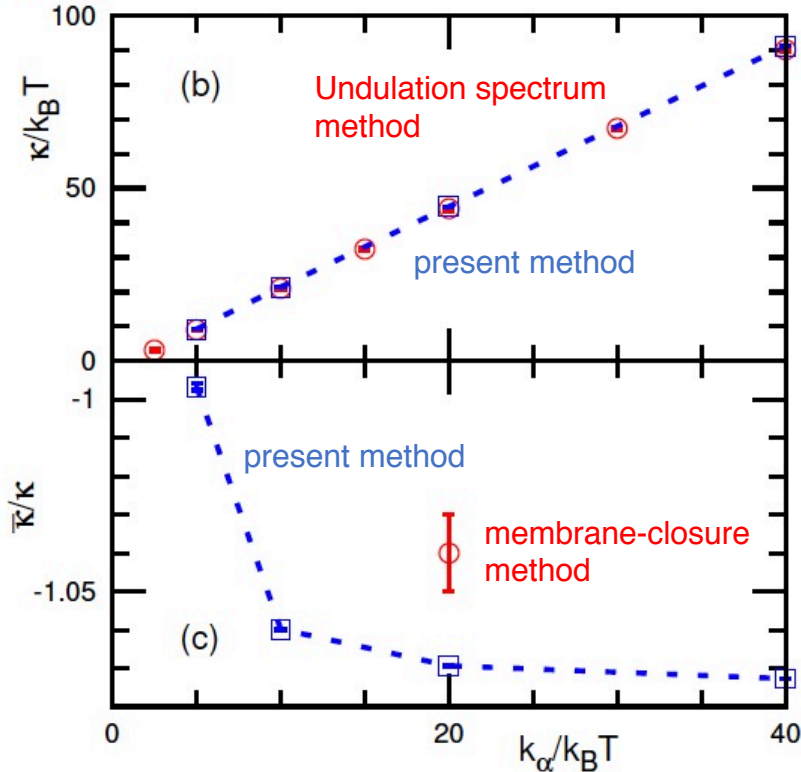
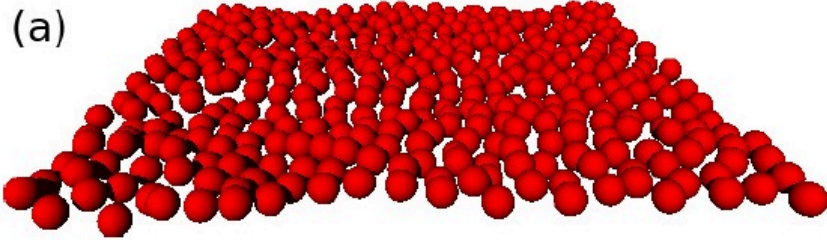


2. DPD membrane model
 - with explicit solvent
 - two-particle amphiphiles



1. meshless membrane

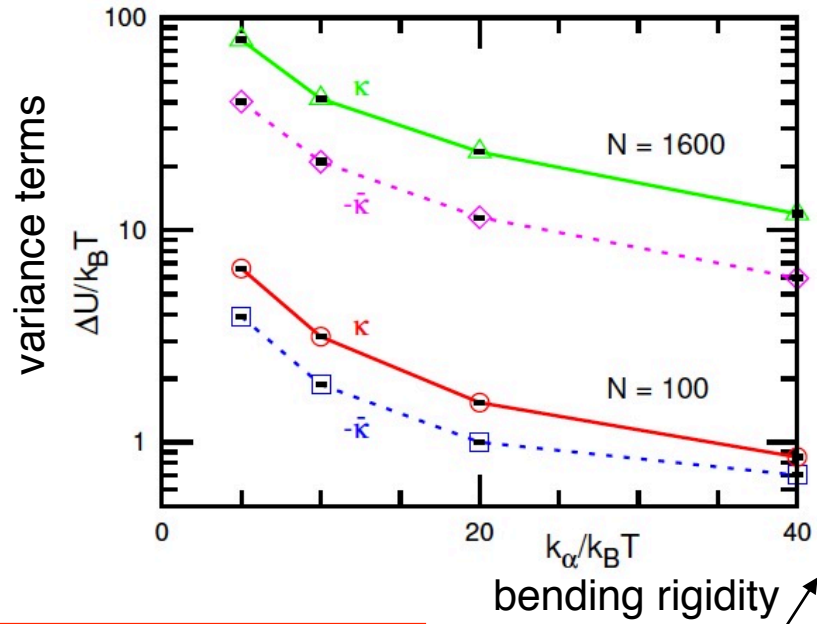
$$U = k_\alpha \sum_i \alpha_{\text{pl}}(\mathbf{r}_i) + \varepsilon \left\{ \sum_{i < j} U_{\text{rep}}(r_{i,j}) + \sum_i U_{\text{att}}(\rho_i) \right\}$$



$\kappa, \bar{\kappa}$ are accurately estimated!

α -dependence (volume-fluctuation effects) is very small.

Influence of membrane fluctuations



$$\left. \frac{\partial^2 F}{\partial C_{cy}^2} \right|_{V,T,C_{cy}=0} = \kappa A_{xy} = \left\langle \frac{\partial^2 U}{\partial C_{cy}^2} \right\rangle - \frac{1}{k_B T} \left(\left\langle \left(\frac{\partial U}{\partial C_{cy}} \right)^2 \right\rangle - \left\langle \frac{\partial U}{\partial C_{cy}} \right\rangle^2 \right),$$

$$\left. \frac{\partial^2 F}{\partial C_{sp}^2} \right|_{V,T,C_{sp}=0} = (4\kappa + 2\bar{\kappa}) A_{xy} = \left\langle \frac{\partial^2 U}{\partial C_{sp}^2} \right\rangle - \frac{1}{k_B T} \left(\left\langle \left(\frac{\partial U}{\partial C_{sp}} \right)^2 \right\rangle - \left\langle \frac{\partial U}{\partial C_{sp}} \right\rangle^2 \right)$$

Variance terms are larger at larger membrane, but the difference are cancelled with other terms so that values of κ , $\bar{\kappa}$ are unchanged.

Variance terms are far from negligible.

Simple DPD liquid (no membrane, i.e., $\kappa = \bar{\kappa} = 0$)

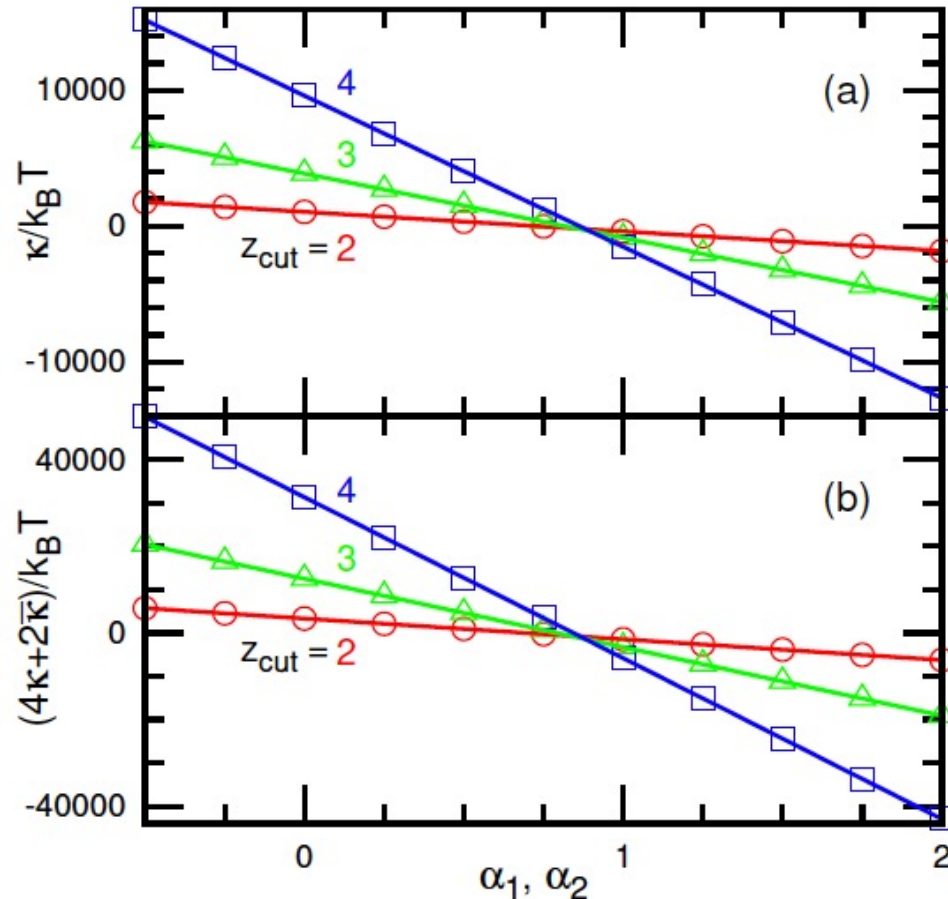
soft repulsion

$$U = \sum \frac{a}{2} \left(\frac{r_{ij}}{r_{\text{cut}}} - 1 \right)^2 \Theta(r_{\text{cut}} - r_{ij})$$

$$a = 100k_B T$$

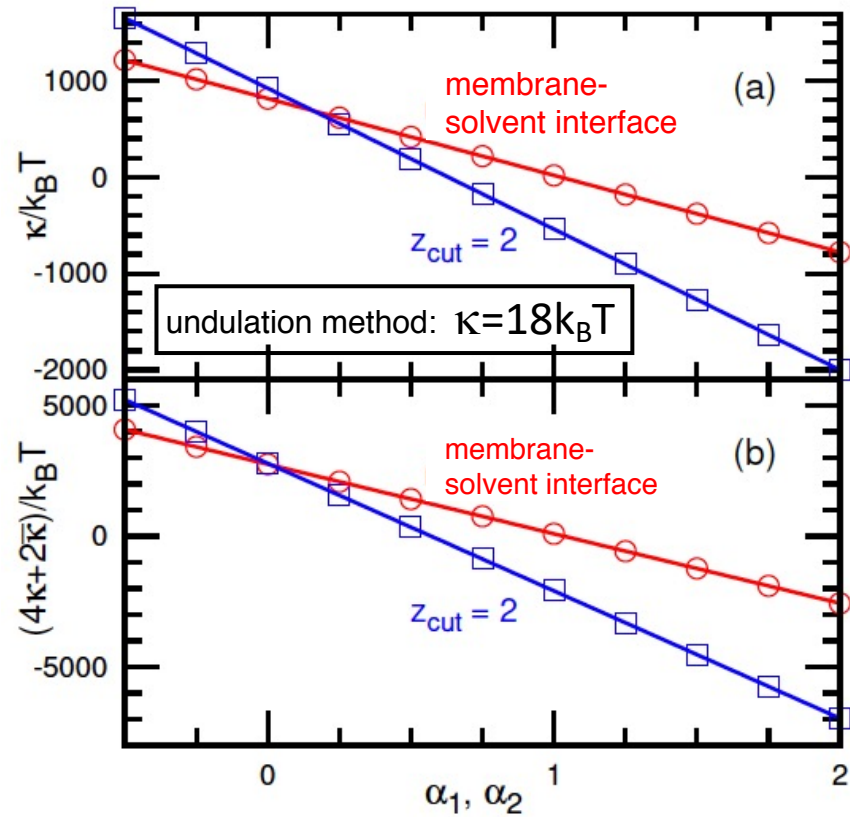
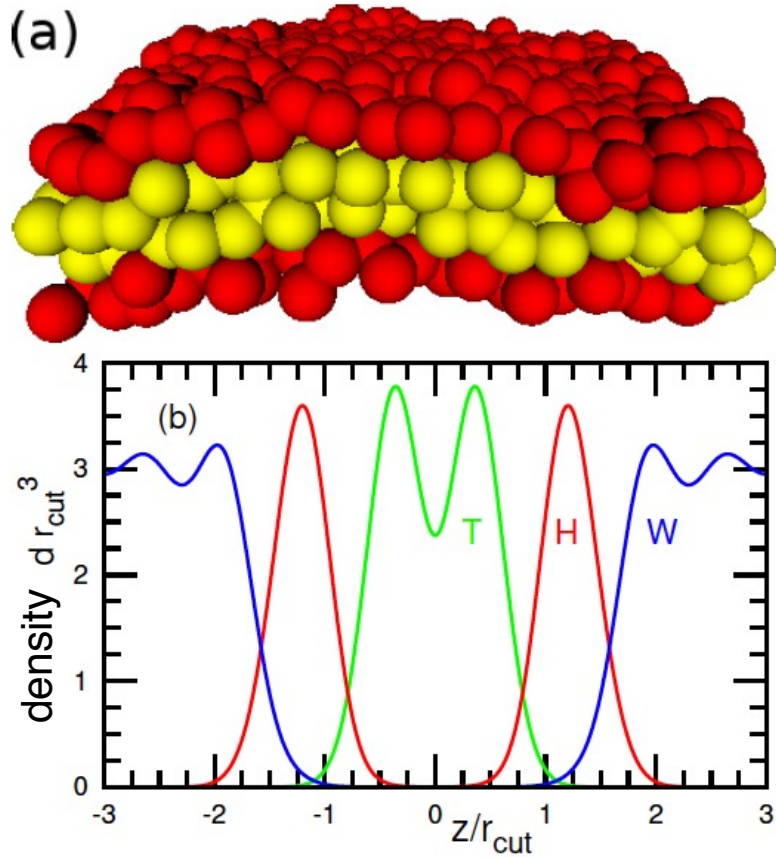
calculated for the region
 $|z| < z_{\text{cut}}$

$\kappa = 0$ or $\bar{\kappa} = 0$ is obtained
 at $\alpha_1, \alpha_2 = 0.7-0.9$.



α -dependence is huge.

2. DPD bilayer membrane



Right values are obtained at $\alpha_1 = \alpha_2 = 1.0$ for cutoff of membrane interface, but α -dependence is terrible.

The method itself looks fine but one more thing is required for accurate estimation.

Summary 2

For meshless membranes, bending rigidity and saddle-splay modulus are accurately calculated by virtual bending method.

For thick membrane with explicit solvent, further extension is required for accurate estimation.

HN, Phys. Rev. E **102**, 053315 (2020).

Questions:

Q3: Do macroscopic properties depend on the decomposition?

First stress moment: $(-\kappa C_0)$ independent of decomposition

Second moment: (not $\bar{\kappa}$) dependent on decomposition

Q4: How are the volume fluctuations included in this method?

Q5: Is the virtual deformation method applicable to other deformations such as twisting?

Summary of Questions

Q1: Is molecular-scale local stress a meaningful quantity?

If yes:

Q2: How do you calculate local stress?

a. From higher resolution data

(quantum calculation for all-atom MD, All-atom for CG)

b. Following some manner (covariant CFD or others)

Q3: Do macroscopic properties depend on the decomposition?

Q4: How are the volume fluctuations included in this method?

Q5: Is the virtual deformation method applicable to other deformations such as twisting?

**Thank you for your attention &
Looking forward for discussion!**

