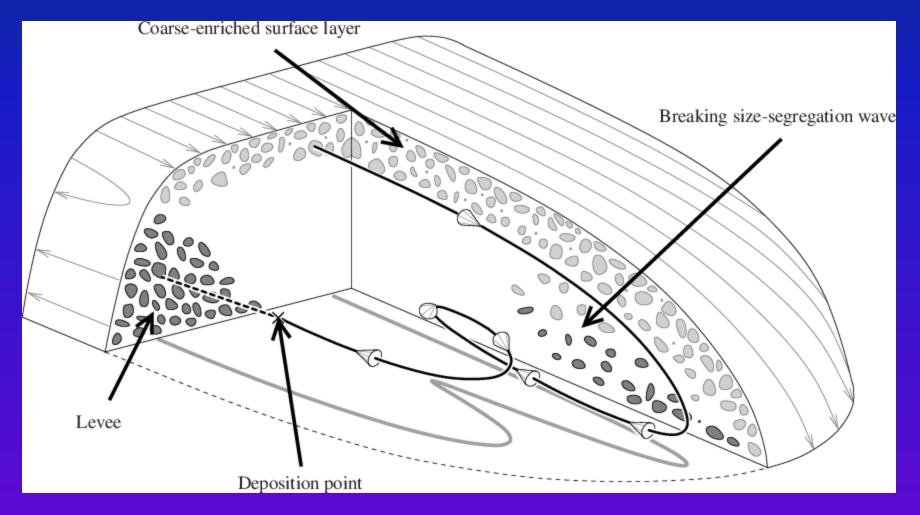


Schematic diagram of the levee formation process

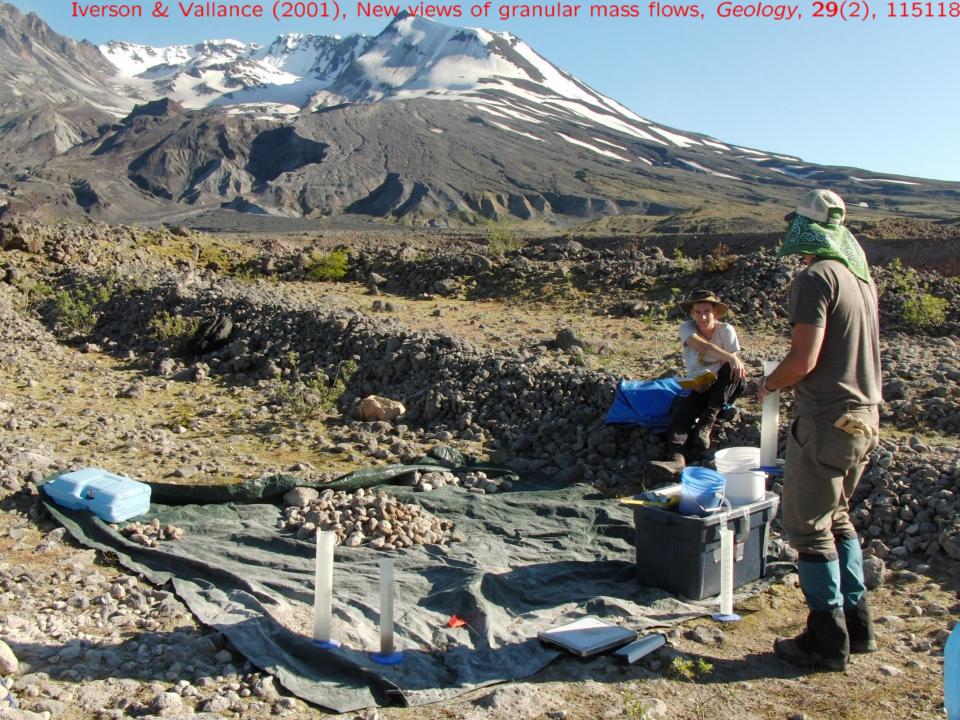


- larger particles are shouldered to the sides to create levees
- this is an example of a segregation-mobility feedback effect







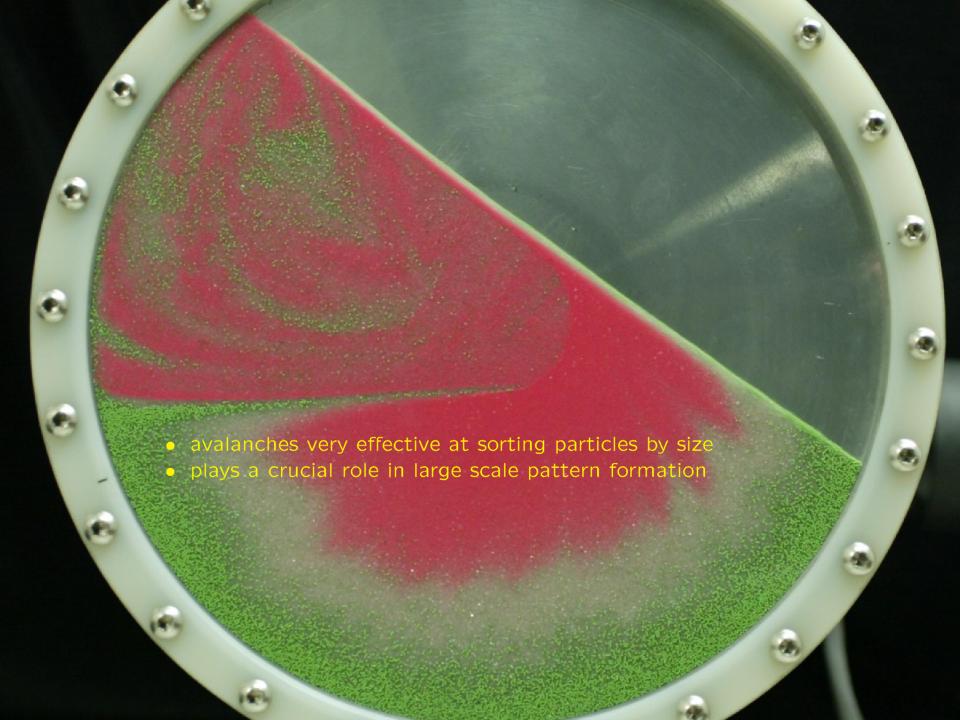


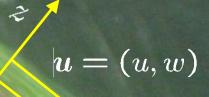
Segregation induced finger formation ...



Pouliquen, Delours & Savage (1997), Nature. **386**, 816-817. Woodhouse *et al.* (2012), J. Fluid Mech. **709**, 543-580.







- Kinetic sieving and squeeze expulsion
 - small particles fall down into gaps
 - and then force large particles up
 - to create inversely graded layers

Slowly rotating mixture

Large

Medium

Smal

Surface avalanche

Mixture framework

• the volume fraction ϕ^{ν} of constituent ν , per unit volume of mixture, lies in the range

$$0 \le \phi^{\nu} \le 1$$
.

and their sum

$$\sum_{\forall \nu} \phi^{\nu} = 1.$$

 In standard mixture theory the partial and intrinsic density, stress, pressure and velocity fields satisfy

$$\rho^{\nu} = \phi^{\nu} \rho^{\nu*}, \quad \sigma^{\nu} = \phi^{\nu} \sigma^{\nu*}, \quad p^{\nu} = \phi^{\nu} p^{\nu*}, \quad u^{\nu} = u^{\nu*}$$

The bulk density, pressure and velocity are

$$ho = \sum_{\forall
u}
ho^{
u}, \quad p = \sum_{\forall
u} p^{
u}, \quad
ho u = \sum_{\forall
u}
ho^{
u} u^{
u}$$

Mass and momentum balances for each constituent

Each constituent satisfies individual mass

$$\frac{\partial \rho^{\nu}}{\partial t} + \nabla \cdot (\rho^{\nu} \boldsymbol{u}^{\nu}) = 0,$$

and momentum balances

$$\frac{\partial}{\partial t}(\rho^{\nu}u^{\nu}) + \nabla \cdot (\rho^{\nu}u^{\nu} \otimes u^{\nu}) = \nabla \cdot \sigma^{\nu} + \rho^{\nu}g + \beta^{\nu},$$

where \otimes is the dyadic product and g is the gravitational acceleration vector.

ullet The interaction drag $eta^
u$ consists of three terms

$$\boldsymbol{\beta}^{\nu} = p \nabla f^{\nu} - \rho^{\nu} c(\boldsymbol{u}^{\nu} - \boldsymbol{u}) - \rho d \nabla \phi^{\nu},$$

c is the coefficient of inter-particle drag, d is the coefficient of diffusive remixing

- Acceleration negligible in the z direction.
- Bulk momentum balance ⇒ pressure lithostatic

$$p = \rho g(s - z) \cos \zeta.$$

If pressure is shared in proportion

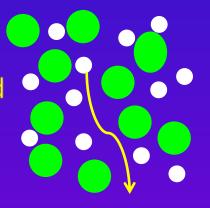
$$p^{\nu} = \phi^{\nu} p$$
, \Rightarrow NO SEGREGATION

Use non-standard partial/intrinsic pressure relation

$$p^{\nu} = f^{\nu} p,$$

where $f^{
u}$ determines the proportion load

$$0 \leq f^{
u} \leq 1, \quad \sum_{orall
u} f^{
u} = 1.$$



Assuming normal accelerations are negligible

$$\phi^{\nu}w^{\nu} = \phi^{\nu}w + (f^{\nu} - \phi^{\nu})(g/c)\cos\zeta - (d/c)\frac{\partial\phi^{\nu}}{\partial z},$$

$$f^{\nu} - \phi^{\nu} > 0 \text{ particles rise}$$

$$f^{\nu} - \phi^{\nu} = 0 \text{ no relative motion}$$

$$f^{\nu} - \phi^{\nu} < 0 \text{ particles percolate downwards}$$

Particles in a pure phase carry all of the load

$$f^{\nu}=1$$
, when $\phi^{\nu}=1$,

When no particles, they cannot carry any load

$$f^{\nu} = 0$$
, when $\phi^{\nu} = 0$.

Large particles carry more load than small

$$f^l = \phi^l + B_{ls}\phi^l\phi^s$$
 (bi-disperse)

The multi-component segregation remixing equation

- ullet $f^{
 u}$ must reduce to bidisperse case in any submixture
- suggests additive decomposition

$$f^{\nu} = \phi^{\nu} + \sum_{\forall \mu} B_{\nu\mu} \phi^{\nu} \phi^{\mu}$$
, (polydisperse case)

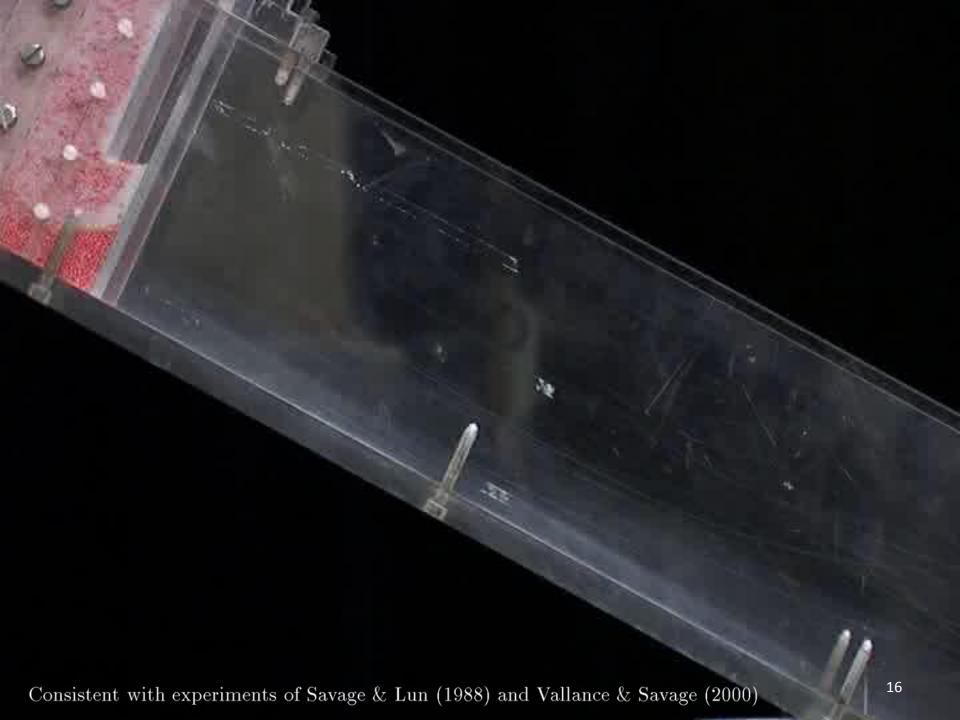
where $B_{\nu\mu} = -B_{\mu\nu}$ and $B_{(\nu\nu)} = 0$.

• Scaling on thickness H, length L and velocity U implies segregation remixing equation (phase ν) is

$$\frac{\partial \phi^{\nu}}{\partial t} + \nabla \cdot (\phi^{\nu} \boldsymbol{u}) + \frac{\partial}{\partial z} \left(\sum_{\forall \mu} S_{\nu\mu} \phi^{\nu} \phi^{\mu} \right) = \frac{\partial}{\partial z} \left(D_r \frac{\partial \phi^{\nu}}{\partial z} \right),$$

where

$$S_{\nu\mu} = \frac{Lg\cos\zeta}{HUc} B_{\nu\mu}, \quad D_r = \frac{Ld}{H^2Uc}.$$



Bi-disperse mixtures

Yields two equations for large and small particles

$$\frac{\partial \phi^{l}}{\partial t} + \nabla \cdot (\phi^{l} \boldsymbol{u}) + \frac{\partial}{\partial z} (S_{ls} \phi^{l} \phi^{s}) = \frac{\partial}{\partial z} \left(D_{r} \frac{\partial \phi^{l}}{\partial z} \right),$$

$$\frac{\partial \phi^{s}}{\partial t} + \nabla \cdot (\phi^{s} \boldsymbol{u}) - \frac{\partial}{\partial z} (S_{ls} \phi^{s} \phi^{l}) = \frac{\partial}{\partial z} \left(D_{r} \frac{\partial \phi^{s}}{\partial z} \right).$$

• The summation condition $\sum \phi^{\nu} = 1$ implies

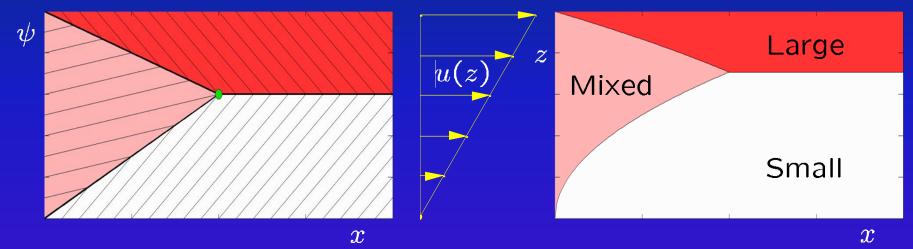
$$\phi^l + \phi^s = 1,$$

Large particle concentration can be eliminated

$$\frac{\partial \phi^s}{\partial t} + \nabla \cdot (\phi^s \boldsymbol{u}) - \frac{\partial}{\partial z} (S_{ls} \phi^s (1 - \phi^s)) = \frac{\partial}{\partial z} \left(D_r \frac{\partial \phi^s}{\partial z} \right).$$

Bridgwater, Foo & Stephens (1985), *Powder Technol.* **41**, 147-158 Savage & Lun (1988) *J. Fluid Mech.* **189**, 311-335 Dolgunin & Ukolov (1995) *Powder Technol.* **83**, 95-103 Gray & Thornton (2005) *Proc. Roy. Soc. A.* **461**, 1447-1473. Thornton, Gray & Hogg (2006) *J. Fluid Mech.* **550**, 1-25. Gray & Chugunov (2006) *J. Fluid Mech.* **569**, 365-398.

Steady-state concentration shocks in absence of diffusive-remixing



• shock height s(x) satisfies the jump condition

$$\left[\phi u \frac{ds}{dx} + S_{ls} \phi (1 - \phi) \right] = 0 \quad \Rightarrow \quad u \frac{ds}{dx} = S_{ls} (\phi^+ + \phi^- - 1) = \frac{d\psi}{dx}$$

Using depth-integrated velocity coordinates

$$\psi = \int_0^z u(z') \, dz'$$

• this can be integrated to show there are three intersecting shocks for a homogeneous inflow with $\phi = \phi_0$

$$\psi_1 = S_{ls}\phi_0 x$$
, $\psi_2 = 1 - S_{ls}(1 - \phi_0)x$, $\psi_3 = \phi_0$

A ternary mixture of large medium and small particles

Theory yields three equations, but one can be eliminated since

$$\phi^m = 1 - \phi^s - \phi^l$$

To give two equations for the large and small particles

$$\frac{\partial \phi^{l}}{\partial t} + \nabla \cdot (\phi^{l} \boldsymbol{u}) + \frac{\partial}{\partial z} \left(S_{lm} \phi^{l} (1 - \phi^{l} - \phi^{s}) + S_{ls} \phi^{l} \phi^{s} \right) = \frac{\partial}{\partial z} \left(D_{r} \frac{\partial \phi^{l}}{\partial z} \right)$$

$$\frac{\partial \phi^{s}}{\partial t} + \nabla \cdot (\phi^{s} \boldsymbol{u}) + \frac{\partial}{\partial z} \left(-S_{ls} \phi^{s} \phi^{l} - S_{ms} \phi^{s} (1 - \phi^{l} - \phi^{s}) \right) = \frac{\partial}{\partial z} \left(D_{r} \frac{\partial \phi^{s}}{\partial z} \right)$$

• A steady-state solution for a homogeneous inflow at x = 0

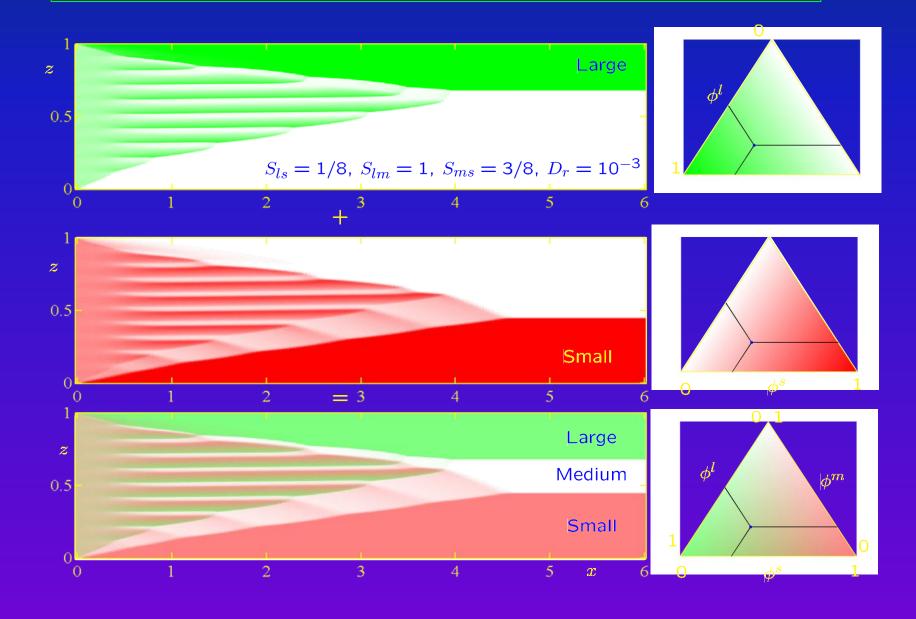
$$\phi^{\nu}(0,z) = \phi_0^{\nu}$$

and with prescribed velocity field

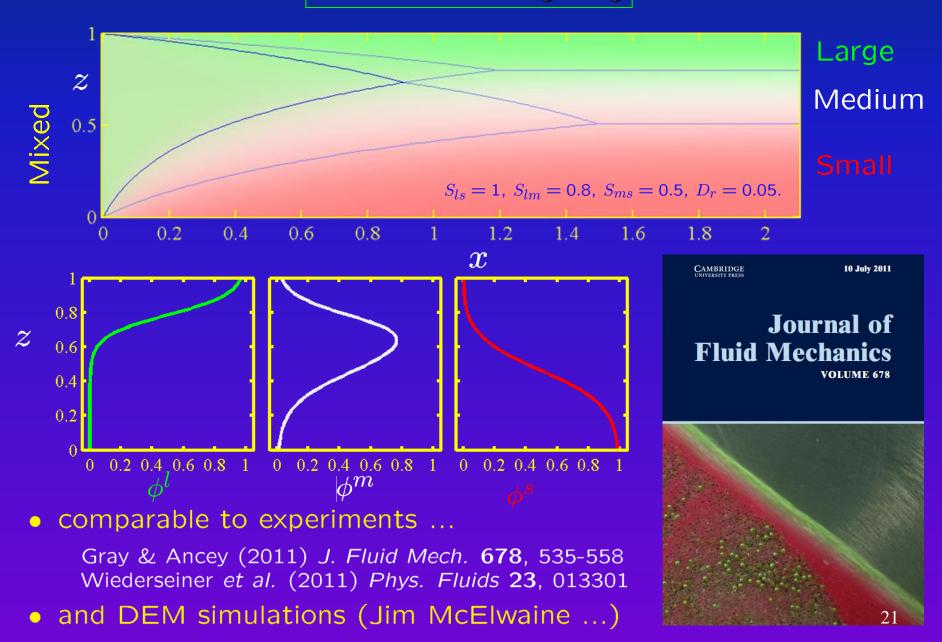
$$u = u(z), \quad w = 0$$

- subject to no-flux conditions at z = 0, 1
- can be computed using Matlab function pdepe (Galerkin Method)

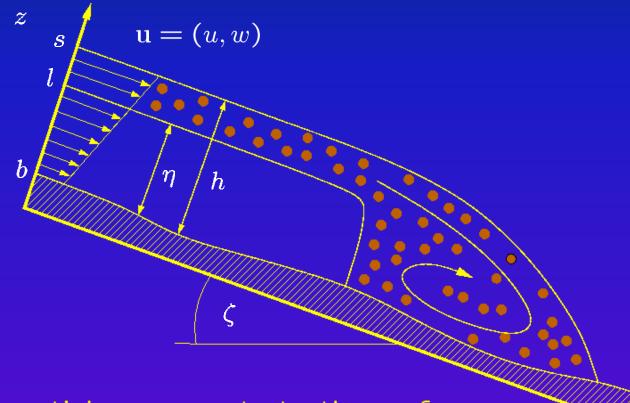
For non-monotonic segregation rates there can be linear instabilities!



Reverse distribution grading



Transport and accumulation of large particles



- large particles segregate to the surface
- where the velocity is greatest and
- are transported to the flow front where they are
- over run and recirculated by particle size segregation

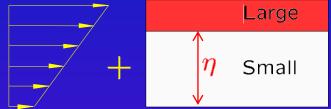
A depth averaged theory for particle size segregation

- Integrating the segregation-remixing equation w.r.t z
- subject to the no flux and kinematic boundary conditions gives

$$\frac{\partial}{\partial t}(h\overline{\phi}) + \frac{\partial}{\partial x}(h\overline{\phi}u) = 0$$

where the integrals evaluated assuming

$$h\bar{\phi} = \int_{h}^{s} \phi^{s} dz = \eta$$



i.e. linear velocity with basal slip and sharp segregation

$$h\overline{\phi u} = \int_b^s \phi^s u \, dz = \eta \overline{u} - (1 - \alpha)\overline{u}\eta \left(1 - \frac{\eta}{h}\right)$$

This yields the large particle transport equation

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x}(\eta \bar{u}) - \frac{\partial}{\partial x}\left((1-\alpha)\bar{u}\eta\left(1-\frac{\eta}{h}\right)\right) = 0.$$

for the evolution of the inversely graded shock interface η.
 Gray & Kokelaar (2010) J. Fluid Mech. 652, 105–137

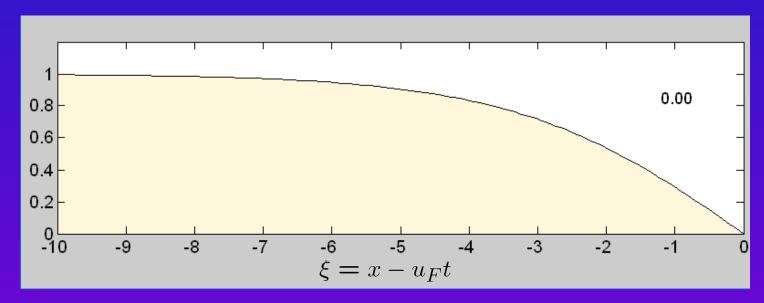
• Using $\eta = h\bar{\phi}$ this can also be rewritten as

$$\frac{\partial}{\partial t}(h\bar{\phi}) + \frac{\partial}{\partial x}(h\bar{\phi}\bar{u}) - \frac{\partial}{\partial x}((1-\alpha)h\bar{u}\bar{\phi}(1-\bar{\phi})) = 0.$$

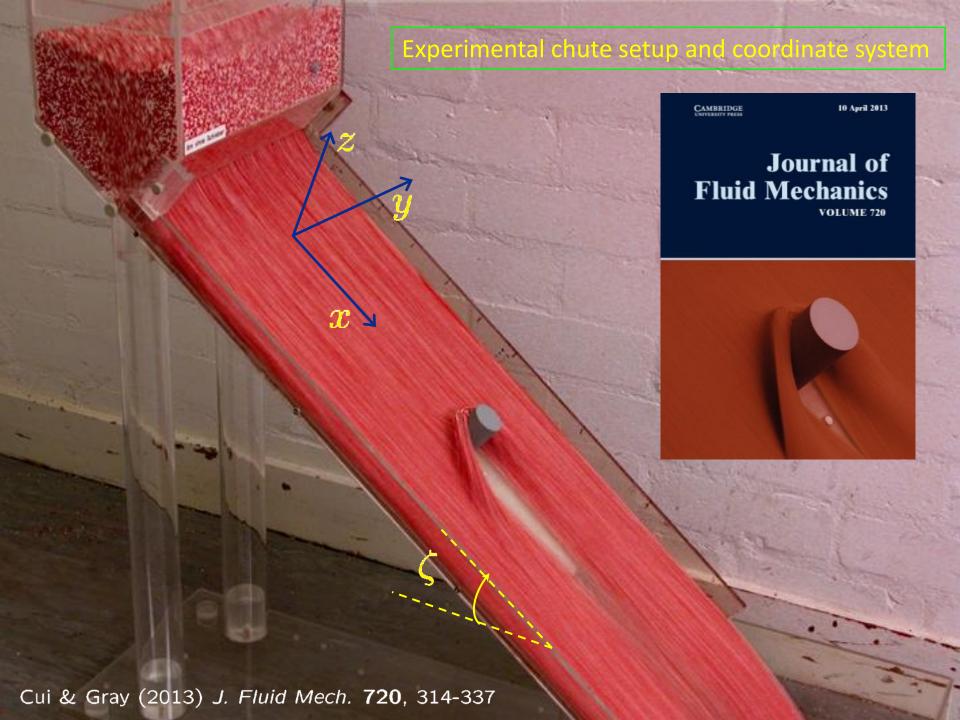
Remarkably similar to the segregation equation ...

$$\frac{\partial \phi}{\partial t} + \frac{\partial}{\partial x}(\phi u) + \frac{\partial}{\partial z}(\phi w) - S_{ls}\frac{\partial}{\partial z}(\phi (1 - \phi)) = \frac{\partial}{\partial z}\left(D_r \frac{\partial \phi}{\partial z}\right)$$

Large grains transported forwards to form bouldery flow front



more RESISTIVE larger particles ⇒ feedback on bulk flow



• For avalanche thickness h and mean velocity $\bar{u} = (\bar{u}, \bar{v})$ in the downslope x and cross-slope y directions.

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (h\bar{u}) + \frac{\partial}{\partial y} (h\bar{v}) = 0,$$

$$\frac{\partial}{\partial t} (h\bar{u}) + \frac{\partial}{\partial x} (h\bar{u}^2) + \frac{\partial}{\partial y} (h\bar{u}\bar{v}) + \frac{\partial}{\partial x} \left(\frac{1}{2}gh^2\cos\zeta \right) = hgS_{(x)},$$

$$\frac{\partial}{\partial t} (h\bar{v}) + \frac{\partial}{\partial x} (h\bar{u}\bar{v}) + \frac{\partial}{\partial y} (h\bar{v}^2) + \frac{\partial}{\partial y} \left(\frac{1}{2}gh^2\cos\zeta \right) = hgS_{(y)},$$

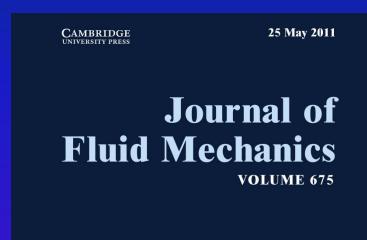
ullet source terms composed of gravity, basal friction μ and gradients of the basal topography b

$$S_{(x)} = \sin \zeta - \mu(\bar{u}/|\bar{u}|) \cos \zeta - \frac{\partial b}{\partial x} \cos \zeta,$$

$$S_{(y)} = -\mu(\bar{v}/|\bar{u}|) \cos \zeta - \frac{\partial b}{\partial y} \cos \zeta,$$

• system is hyperbolic, Froude number ${\rm Fr}=|\bar{u}|/\sqrt{gh\cos\zeta}$

Granular jets and hydraulic jumps on an inclined plane

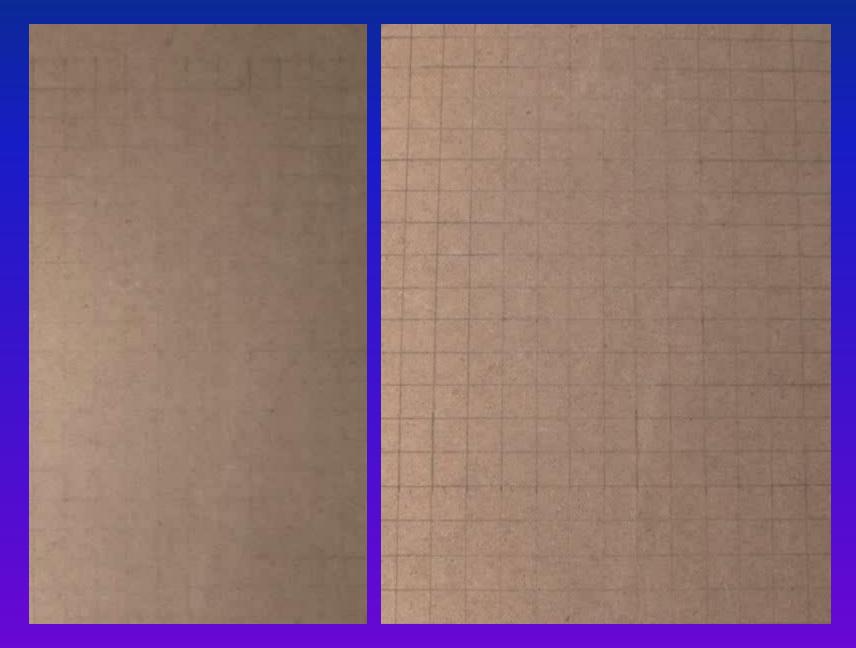


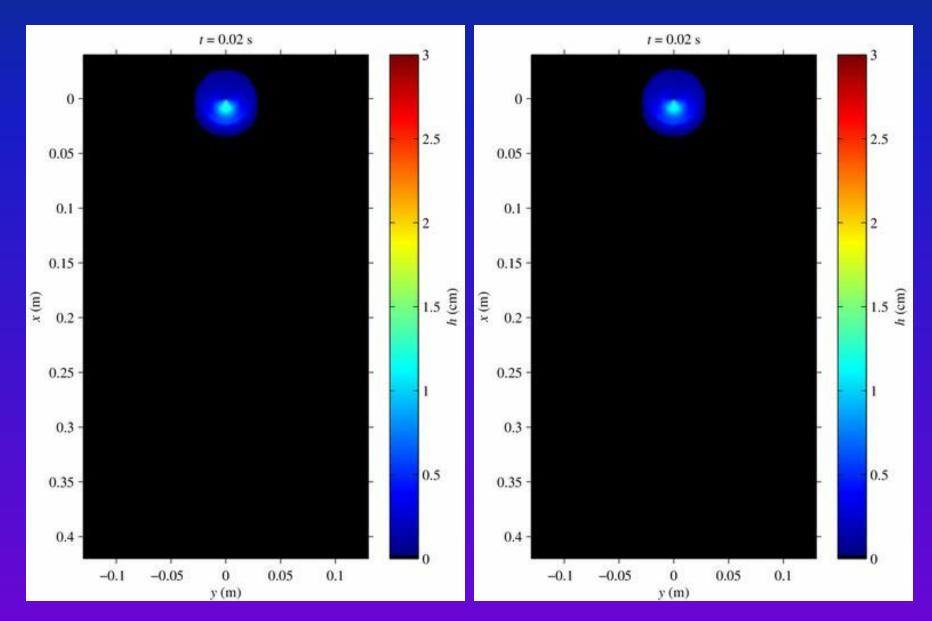


- Oblique impingement of an inviscid jet (Hasson & Peck 1964)
- Friction law for rough beds

$$\mu = \tan \zeta_1 + \frac{\tan \zeta_2 - \tan \zeta_1}{1 + \beta h/(\mathcal{L}Fr)},$$

• including treatment of static material for $0 < Fr < \beta$ (Pouliquen & Forterre 2002)





Johnson & Gray (2011) J. Fluid Mech. 675, 87-116



A simple two-dimensional fully coupled segregation model

• For avalanche thickness h, small particle thickness η and depth-averaged velocity \overline{u} the 2D coupled model is

$$\frac{\partial h}{\partial t} + \operatorname{div}(h\overline{u}) = 0,$$

$$\frac{\partial \eta}{\partial t} + \operatorname{div}\left(\eta\overline{u} - (1-\alpha)\eta\left(1 - \frac{\eta}{h}\right)\overline{u}\right) = 0,$$

$$\frac{\partial}{\partial t}(h\overline{u}) + \operatorname{div}(h\overline{u} \otimes \overline{u}) + \operatorname{grad}\left(\frac{1}{2}h^2 \cos \zeta\right) = hS,$$

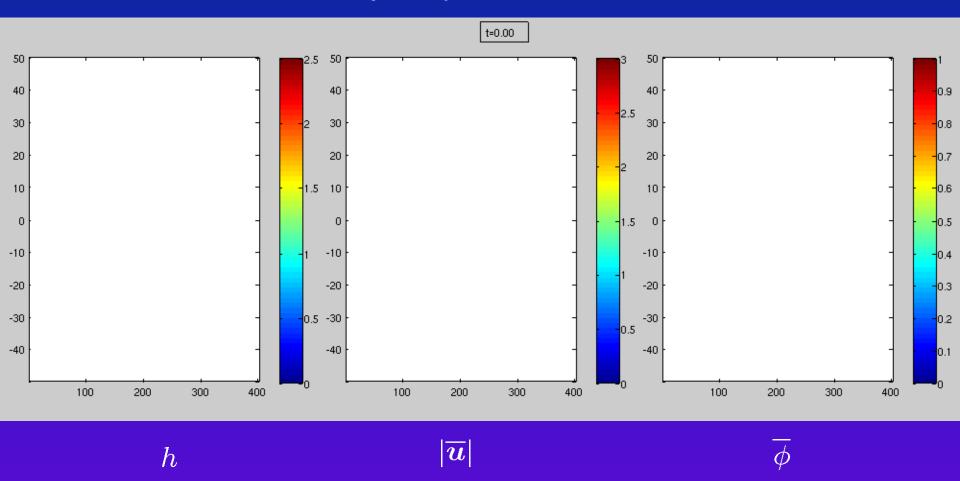
source terms composed of gravity and basal friction

$$S = \begin{pmatrix} \sin \zeta - \mu(\overline{u}/|\overline{u}|) \cos \zeta, \\ -\mu(\overline{v}/|\overline{u}|) \cos \zeta, \end{pmatrix}$$

• coupling through $\bar{\phi} = \eta/h$ dependent friction coefficient

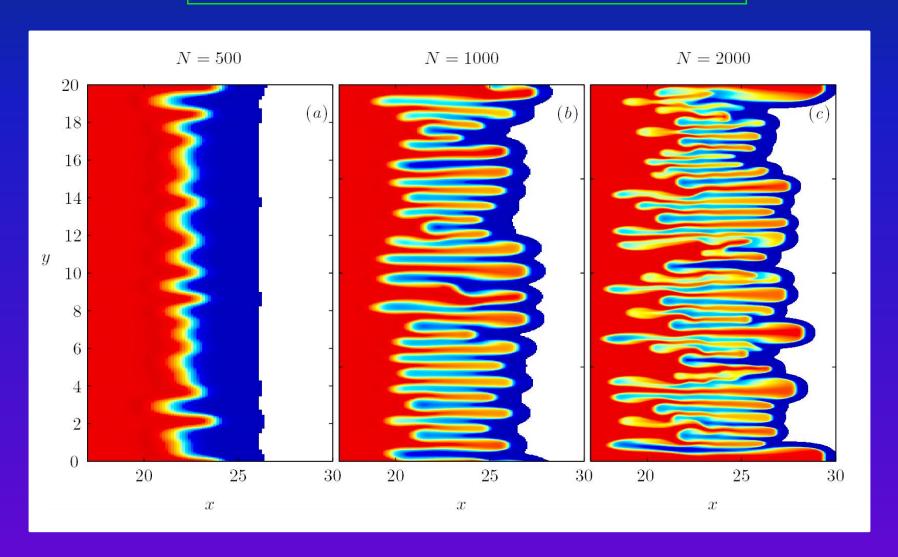
$$\mu = \left(1 - \bar{\phi}\right)\mu^L + \bar{\phi}\mu^S, \quad \mu^L > \mu^S$$

Woodhouse et al. (2012), J. Fluid Mech. 709, 543-580.



- The model is hyperbolic
- captures the instability mechanism
- and forms large rich lateral levees, BUT

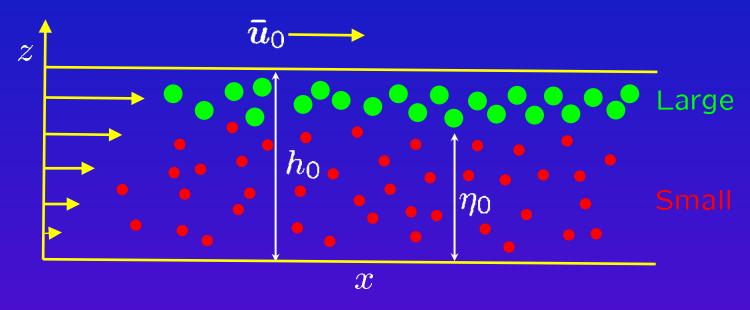
Numerical solutions are grid dependent ...!



this indicates that there is some important physics missing

Linear stability about a steady uniform base state

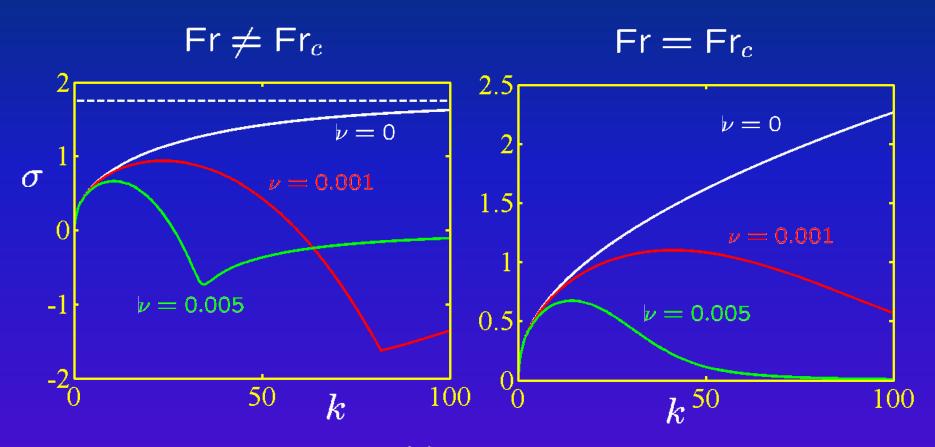
$$\bar{u} = \bar{u}_0, \ \bar{v} = 0, \ h = h_0, \ \eta = \eta_0$$



Predicts unbounded short wavelength instability when

$$\mathsf{Fr} = \mathsf{Fr}_c = \frac{1}{(1-\alpha)|2\eta_0 - 1|}$$

This is when the characteristics coincide



- Depth averaging the $\mu(I)$ rheology suggests
- adding a diffusive term to the righthand side of the form

$$\frac{\partial}{\partial x} \left(\nu h^{\frac{3}{2}} \frac{\partial \overline{u}}{\partial x} \right)$$

• which gives cut-off (Fr = Fr_c) and boundedness (Fr \neq Fr_c)

A two-dimensional fully coupled model including rheology

• When the depth-averaged $\mu(I)$ -rheology is generalized to 2D it suggests a system of conservation laws of the form

$$\frac{\partial h}{\partial t} + \operatorname{div}(h\overline{u}) = 0,$$

$$\frac{\partial \eta}{\partial t} + \operatorname{div}\left(\eta \overline{u} - (1-\alpha)\eta\left(1-\frac{\eta}{h}\right)\overline{u}\right) = 0,$$

$$\frac{\partial}{\partial t}(h\overline{u}) + \operatorname{div}(h\overline{u} \otimes \overline{u}) + \operatorname{grad}\left(\frac{1}{2}h^2\cos\zeta\right) = hS + \operatorname{div}\left(\nu h^{\frac{3}{2}}\boldsymbol{D}\right),$$

where the two-dimensional strain-rate tensor is

$$D = \frac{1}{2} \left(L + L^T \right)$$

- ullet and $L=\mathsf{grad}(ar{u})$ is the depth-averaged velocity gradient
- Numerics converges ... (Baker, Johnson & Gray in prep)

