

# How Discrete Element Method code can model dynamical phenomena such as saltation transport, multiple collision process and granular avalanches

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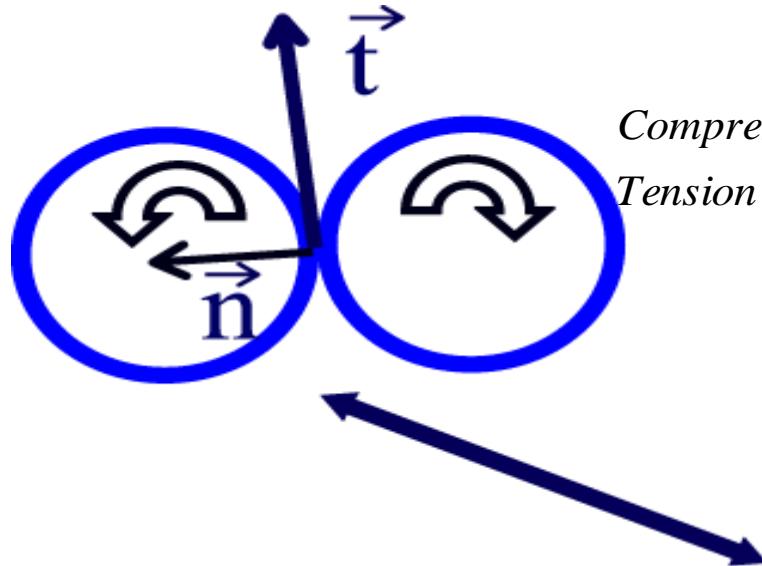
Geoflows 13, October 2013



# Schedule

1. General information for DEM
2. 3D grains interaction with humidity  
(avalanche)
3. 3D mono shot for Splash function
4. Multi shots for splash function
5. 2D saltation with wind interaction
6. Conclusion

# §1: General characteristics of DEM: Molecular Dynamics simulation (soft model)



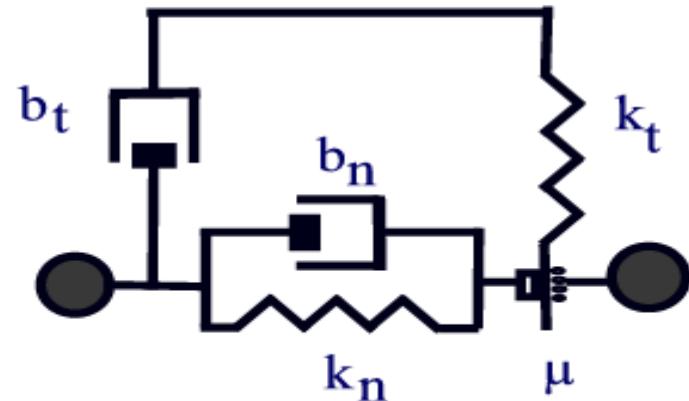
$$F_t = K_t \delta_t - b_t v_t$$

and  $F_t$  is controlled by:

$$F_t = \mu_i F_n$$

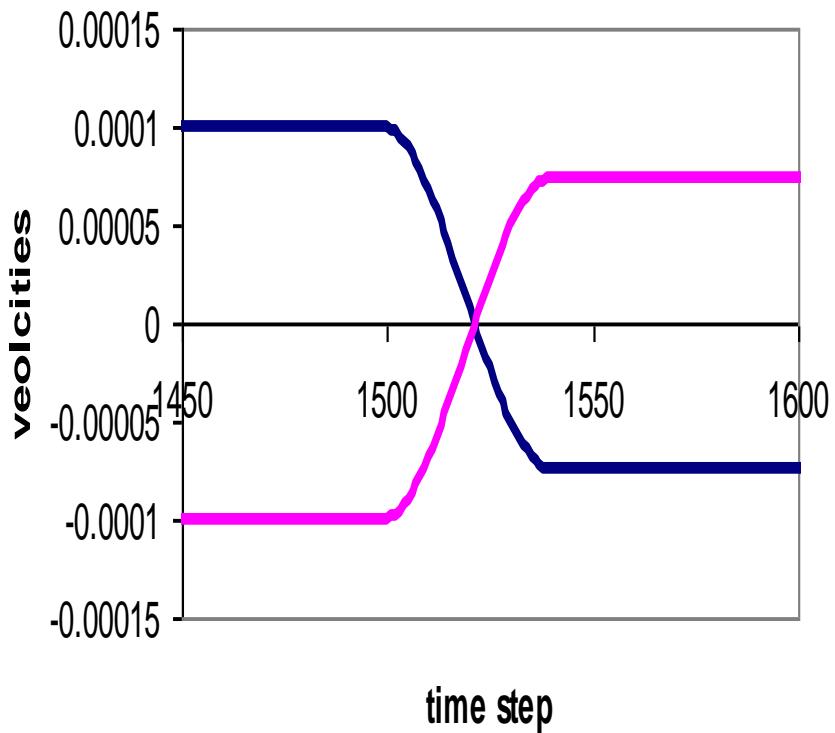
Compression :  $F_n = K_n \delta - b_n v_n$  ( $\delta$  is the positive overlap)  
Tension :  $F_n = 0$  (if  $\delta$  is negative)

+ external forces : wind, humidity, Electrostatic, ...  
+ shape factor : rolling resistance

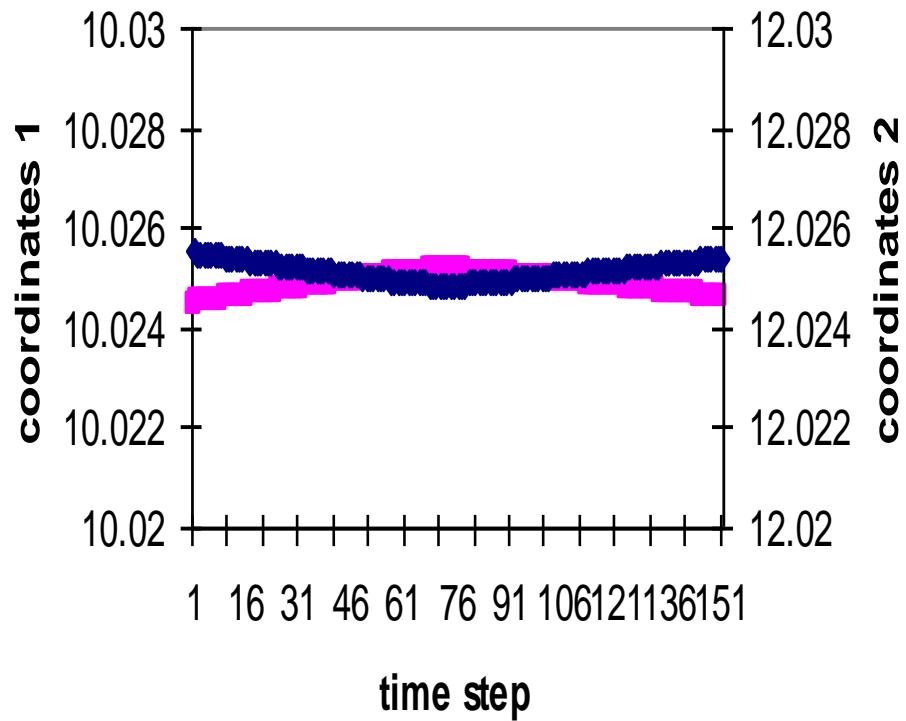


# Soft sphere interaction

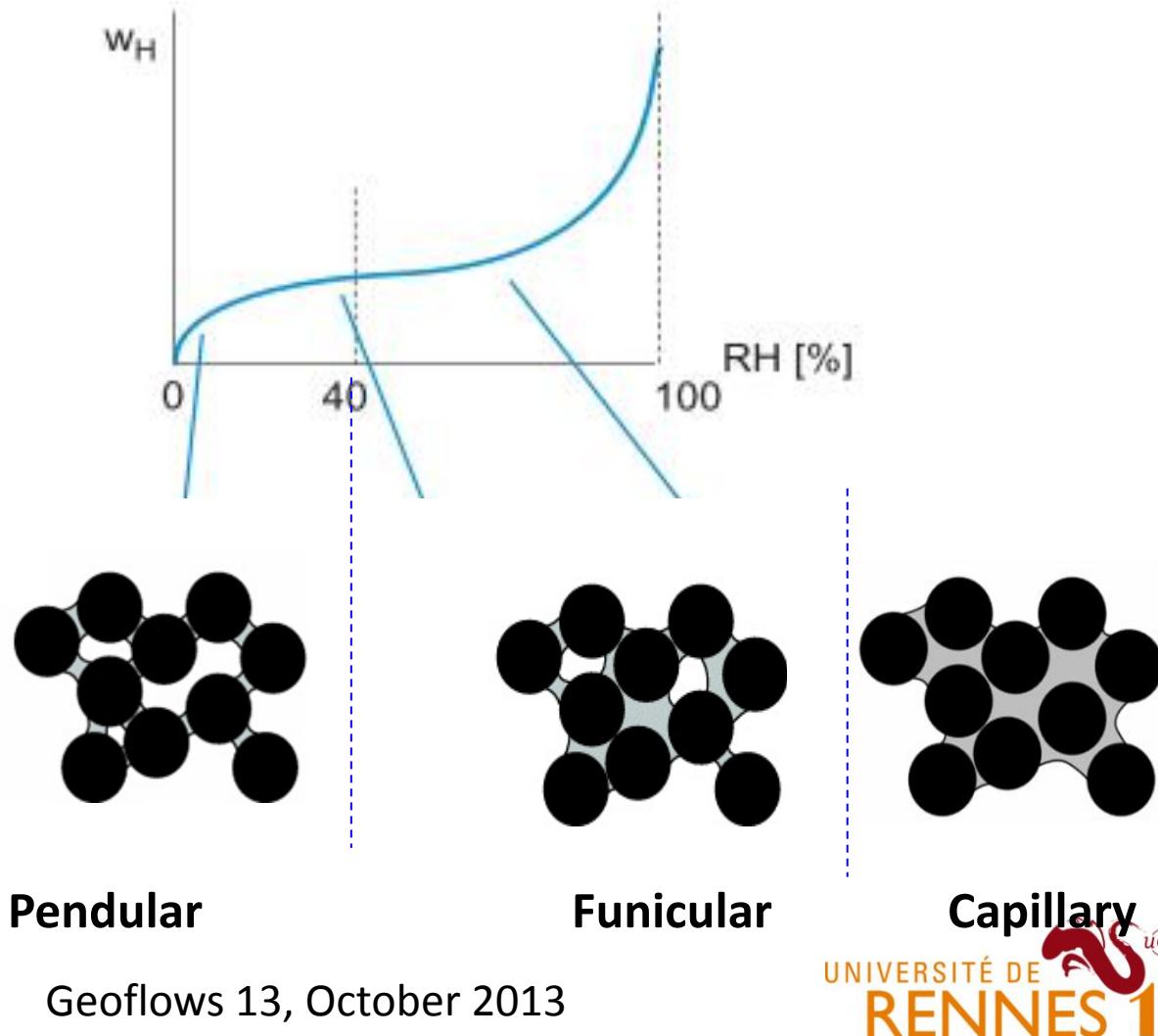
two spheres collision



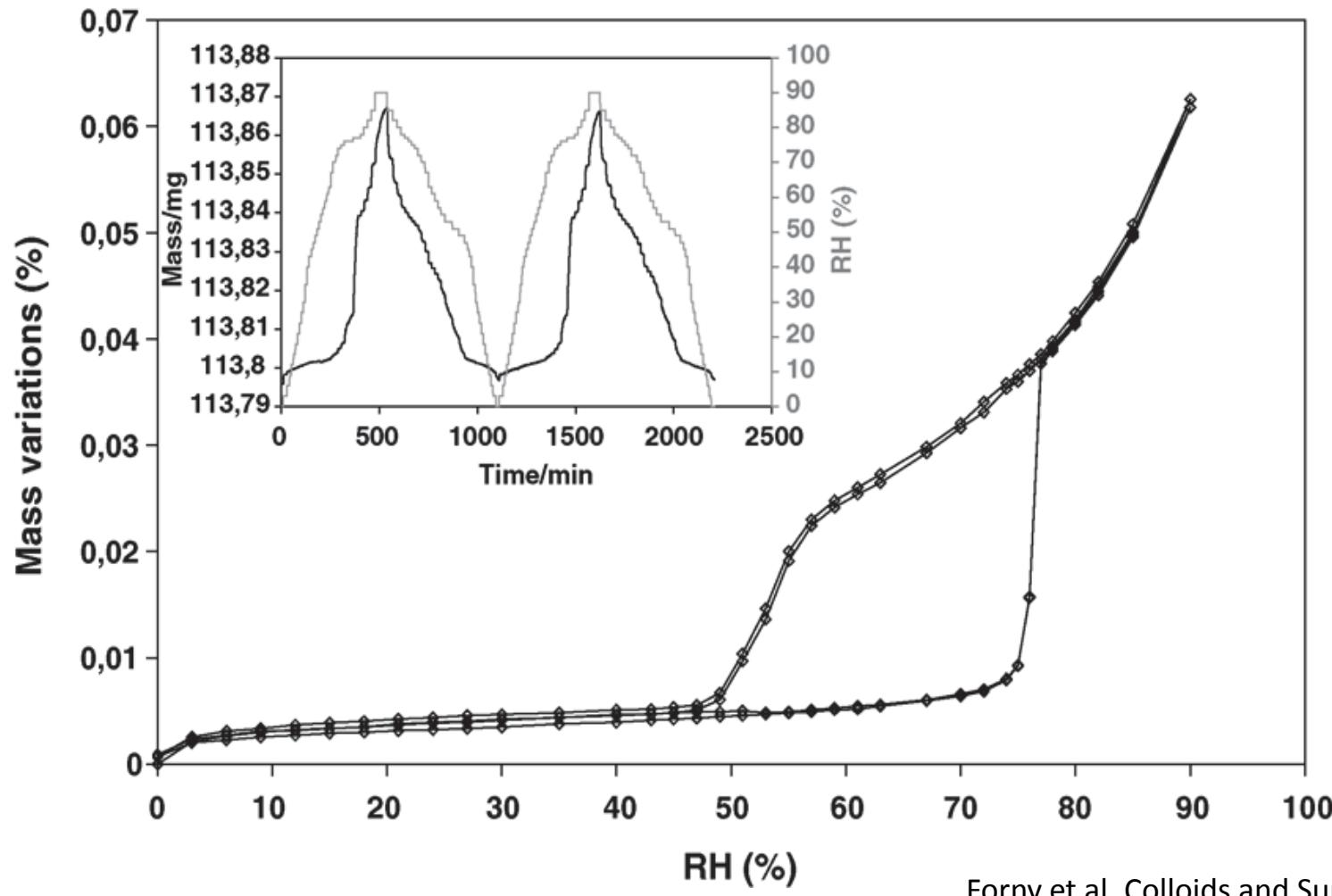
coordinates with time



# §2: 3D Avalanche with humidity (present everywhere!)

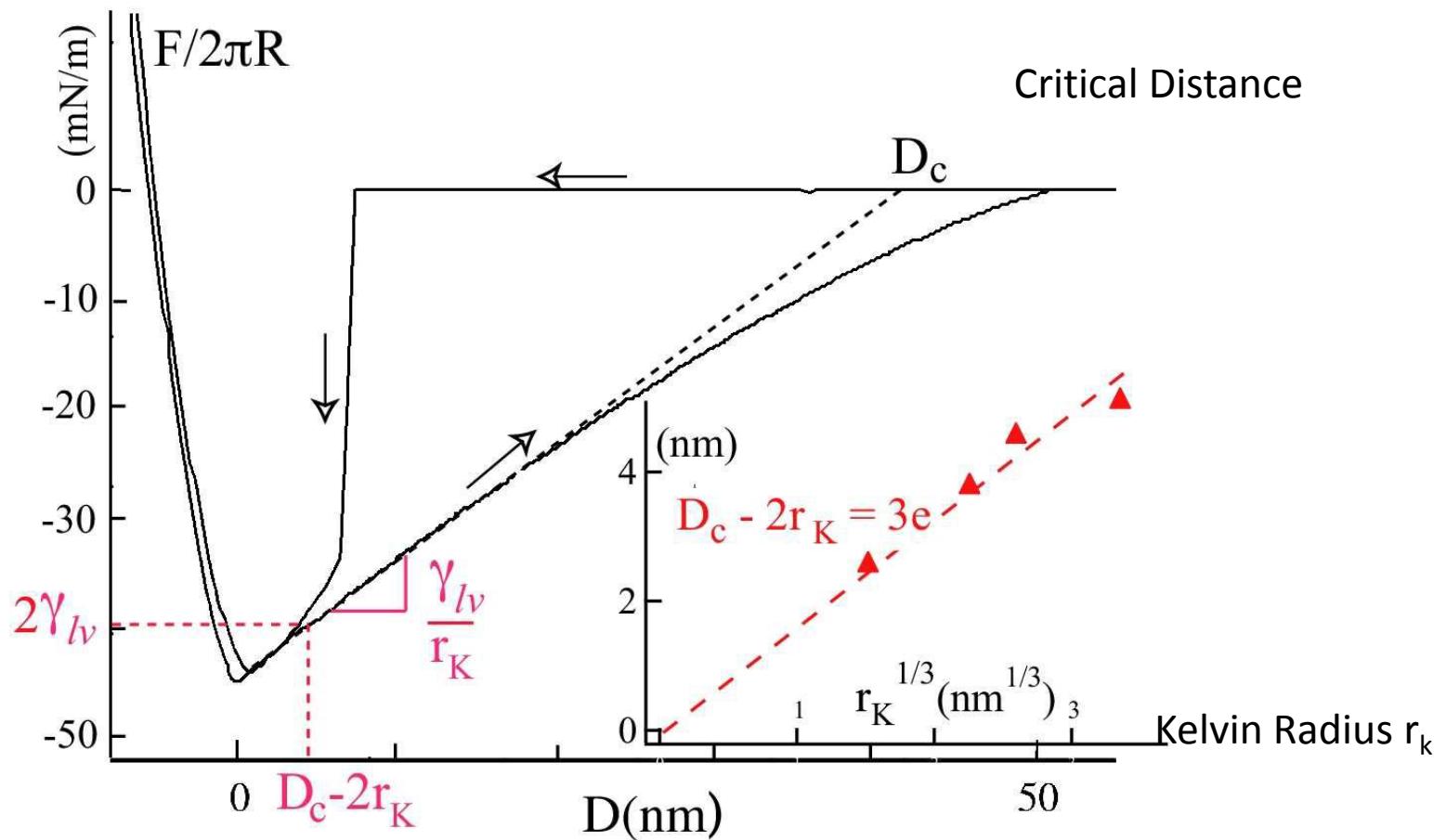


# 85 $\mu\text{m}$ glass beads



Forny et al. Colloids and Surfaces A (2005)

# Force at the contact

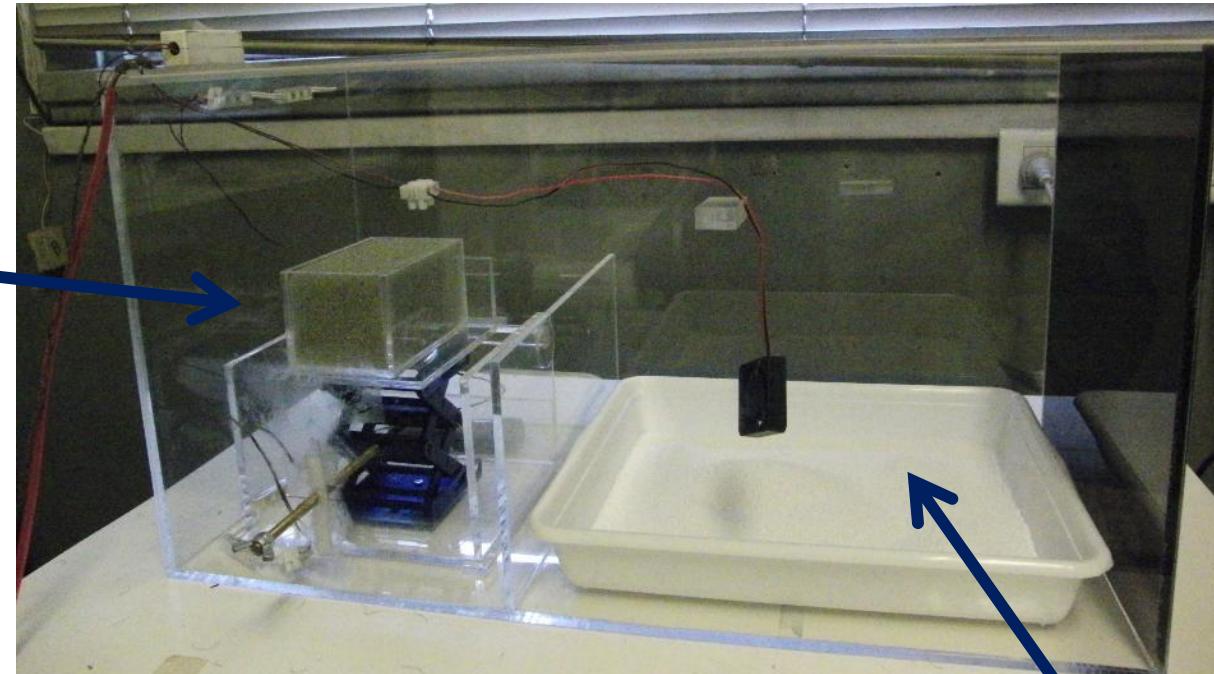


Charlaix et al. Handbook of Nanophysics (2010)

# Experimental results at FI-UBA

I. Arriarn & I. Ippolito

Tilt box



For humidity control

# 500 $\mu\text{m}$ beads

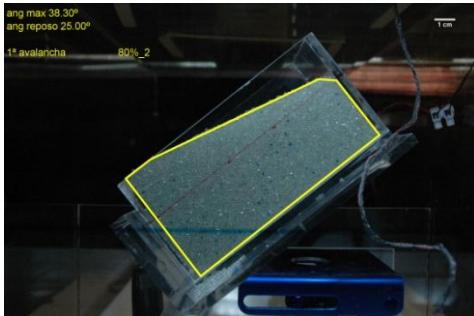


5%

37%

45%

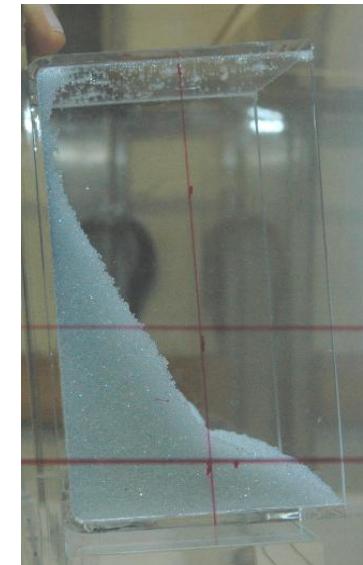
75%



80%

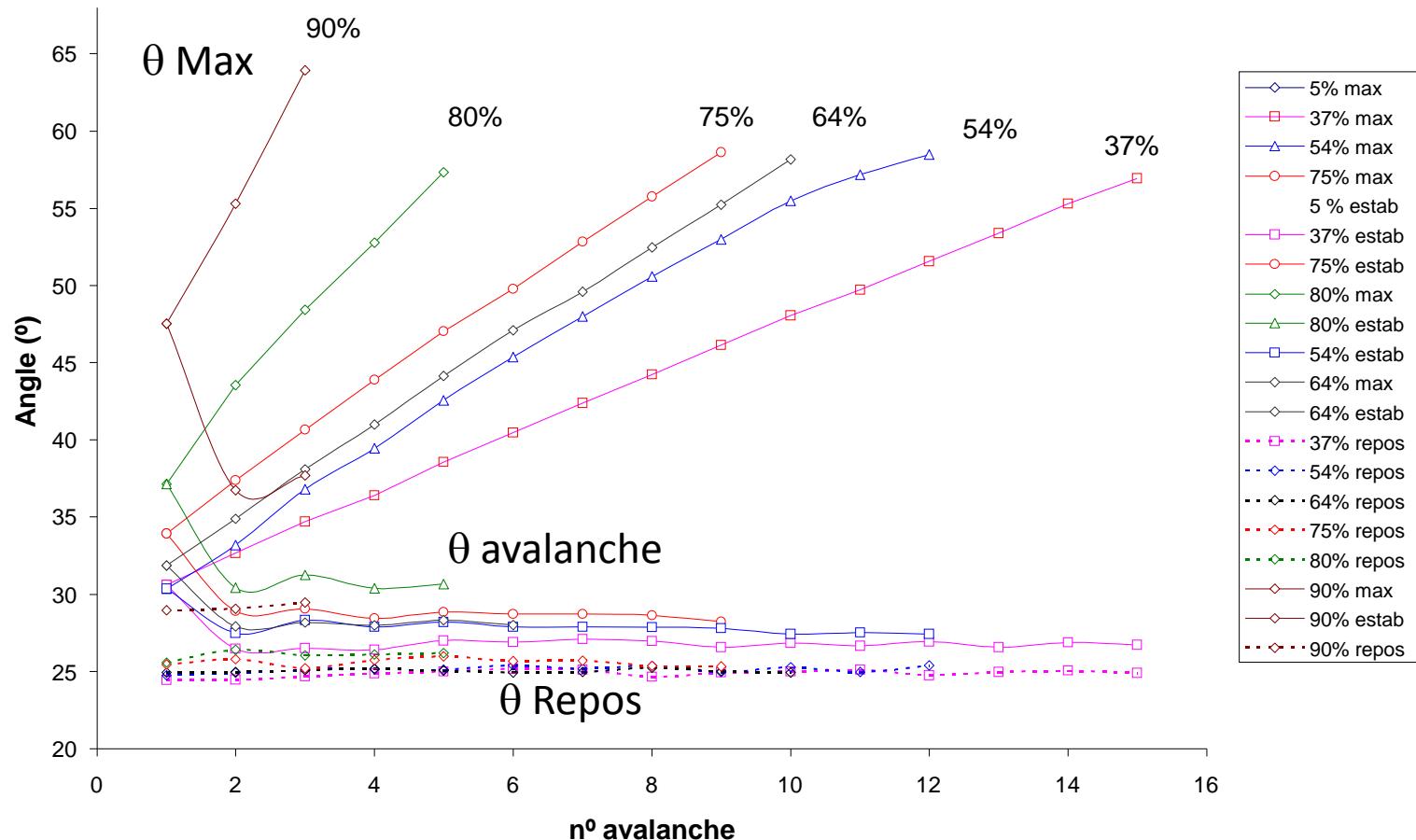


90% init

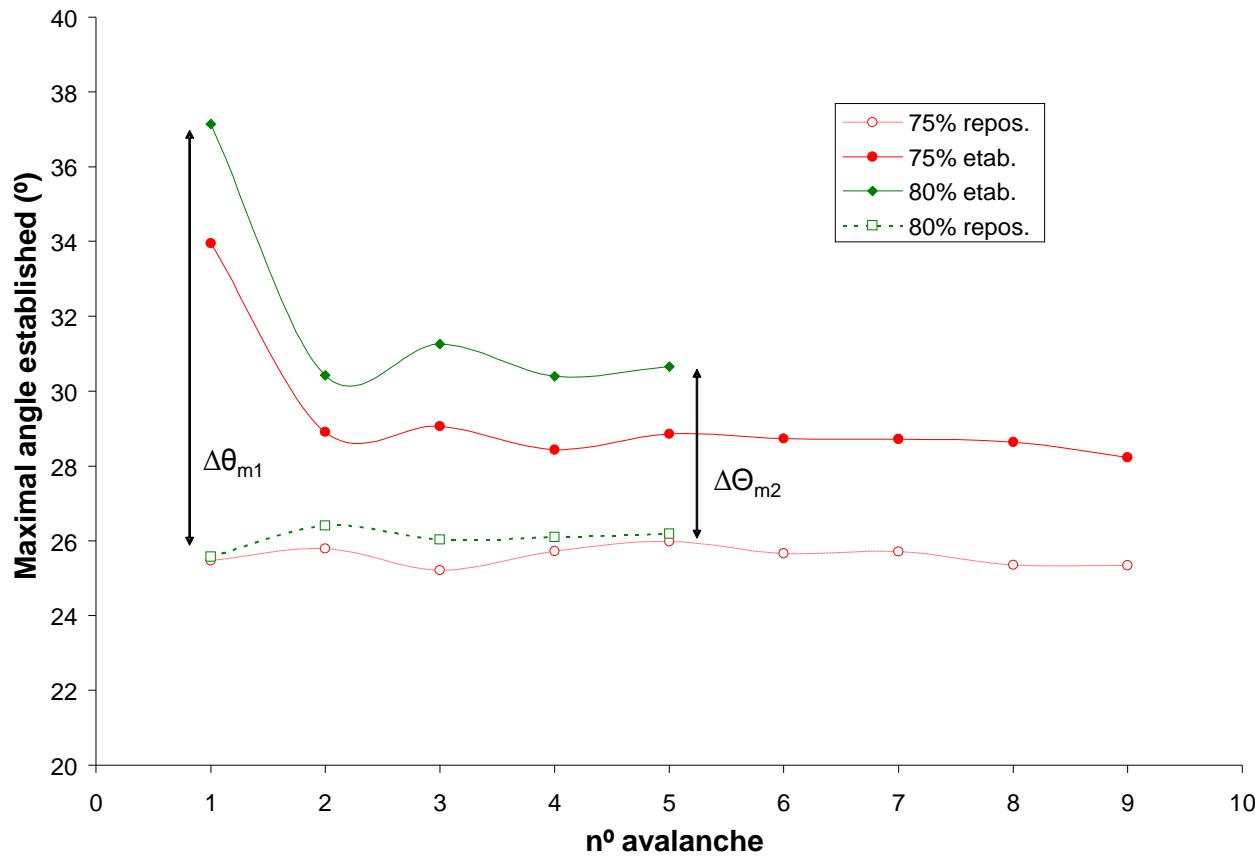


UNIVERSITÉ DE   
final

# Maximal angle and repose one (grains 1 mm)



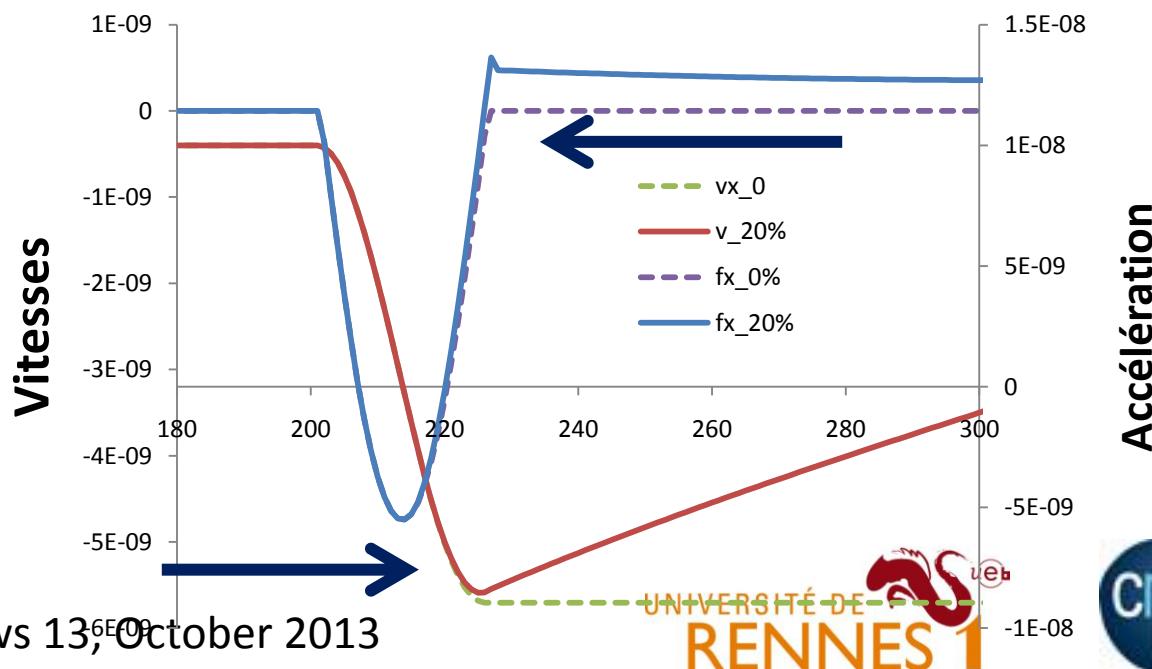
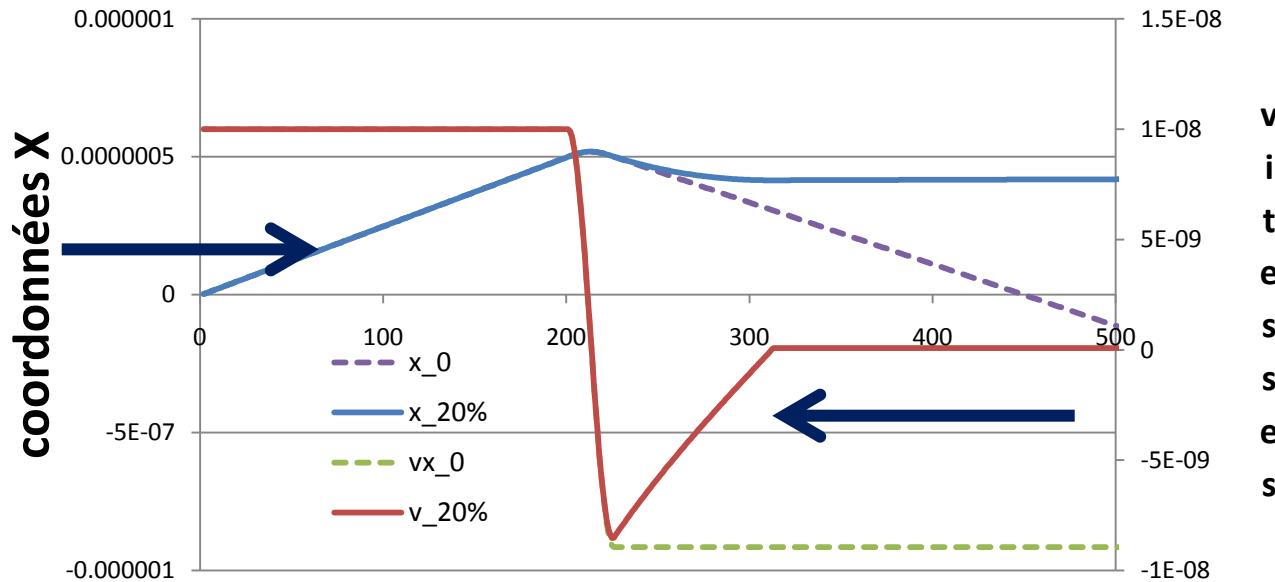
# Différence between angles 1<sup>st</sup> avalanche & following grains de 1mm



# Numerical model

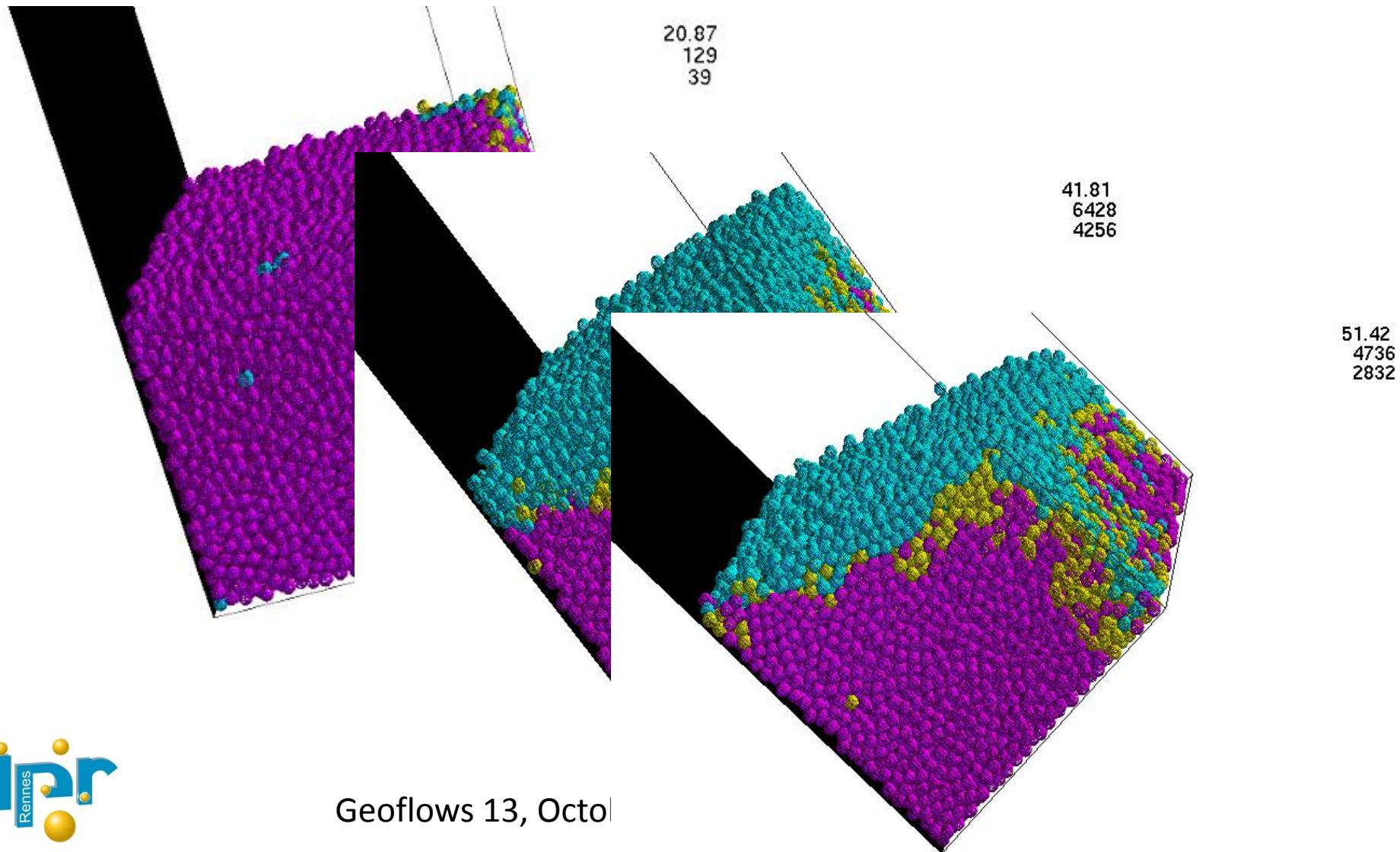
- Spring-Dashpot DEM 3D
- non periodic box
- 16000 monosize spheres
- Pré-consolidation des empilements
- Charlaix 's adhesion force
- Rotation by gravity vector
- Measures of angles in box directions

# Comparaison déplacement, vitesse, accélération avec ou sans RH

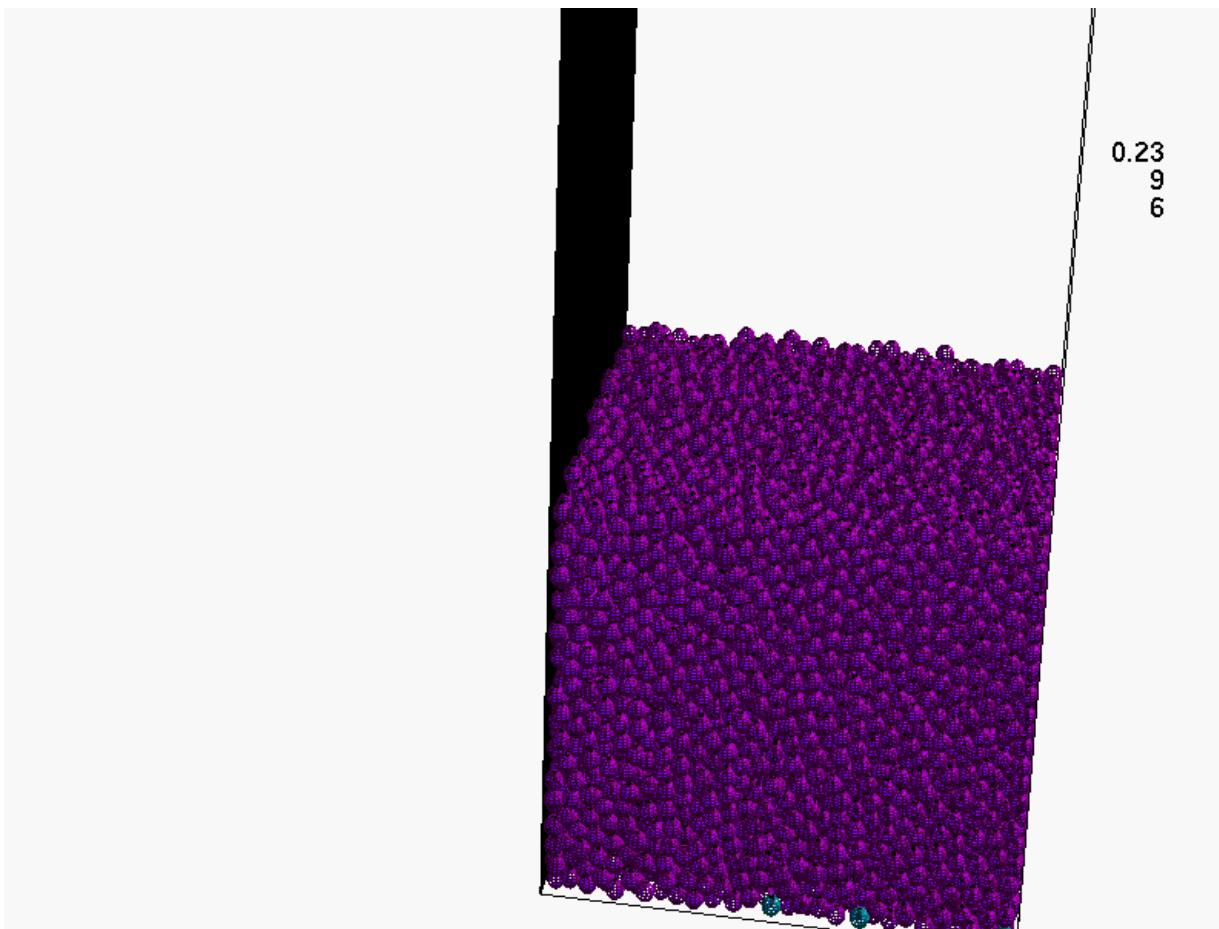


# Evolution of velocities

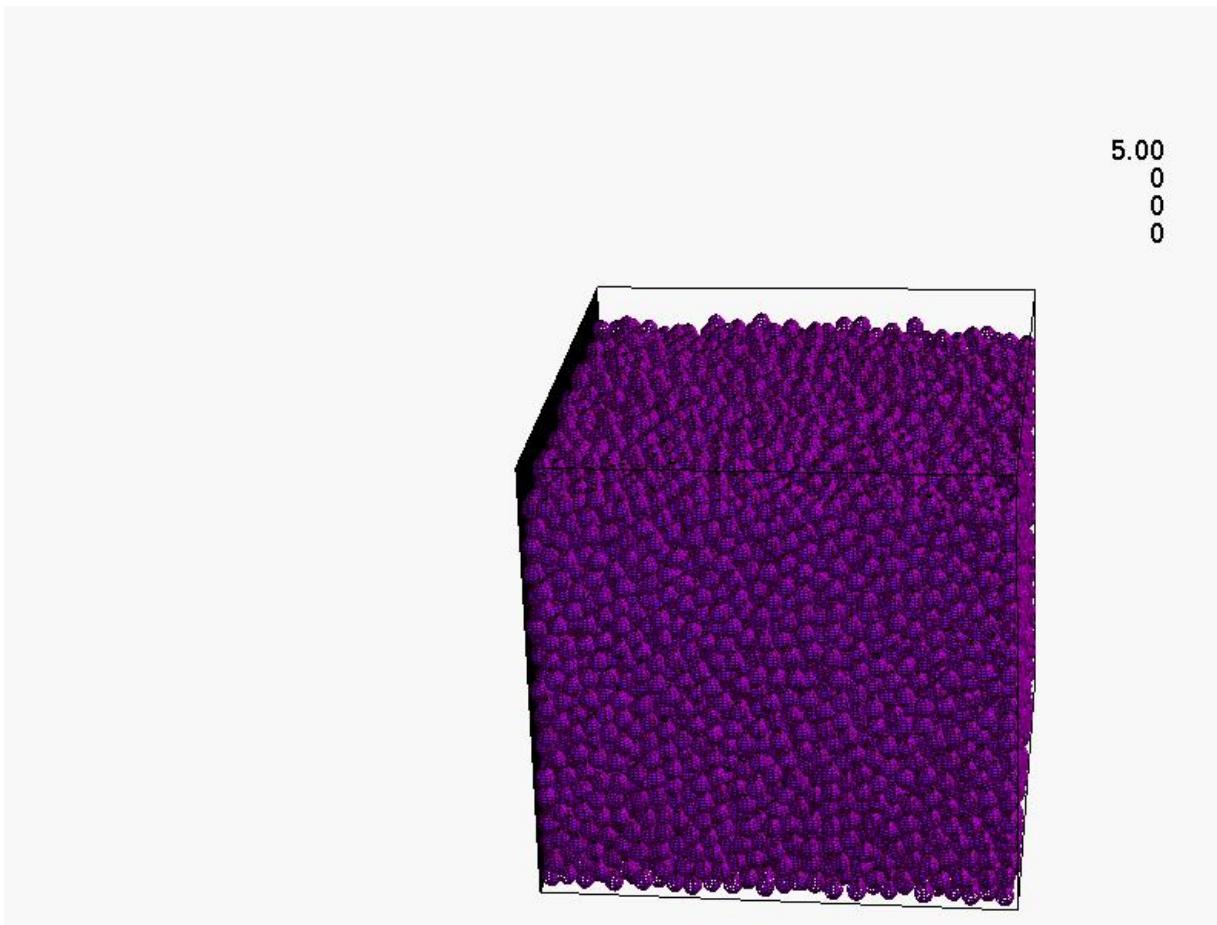
(2 vel. thresholds : 2colors :  $\theta$ +2indications)



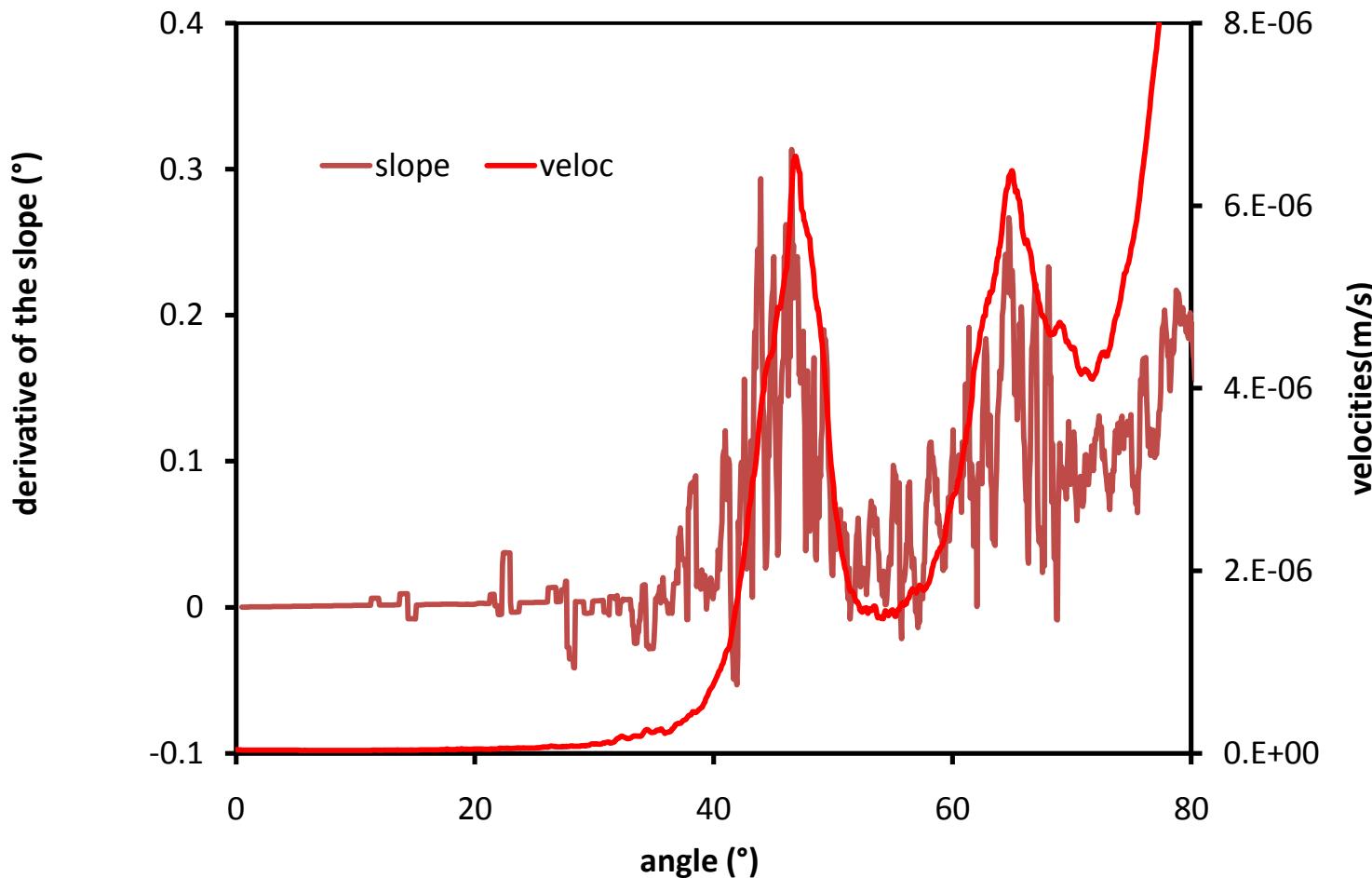
# Movie of full sequence



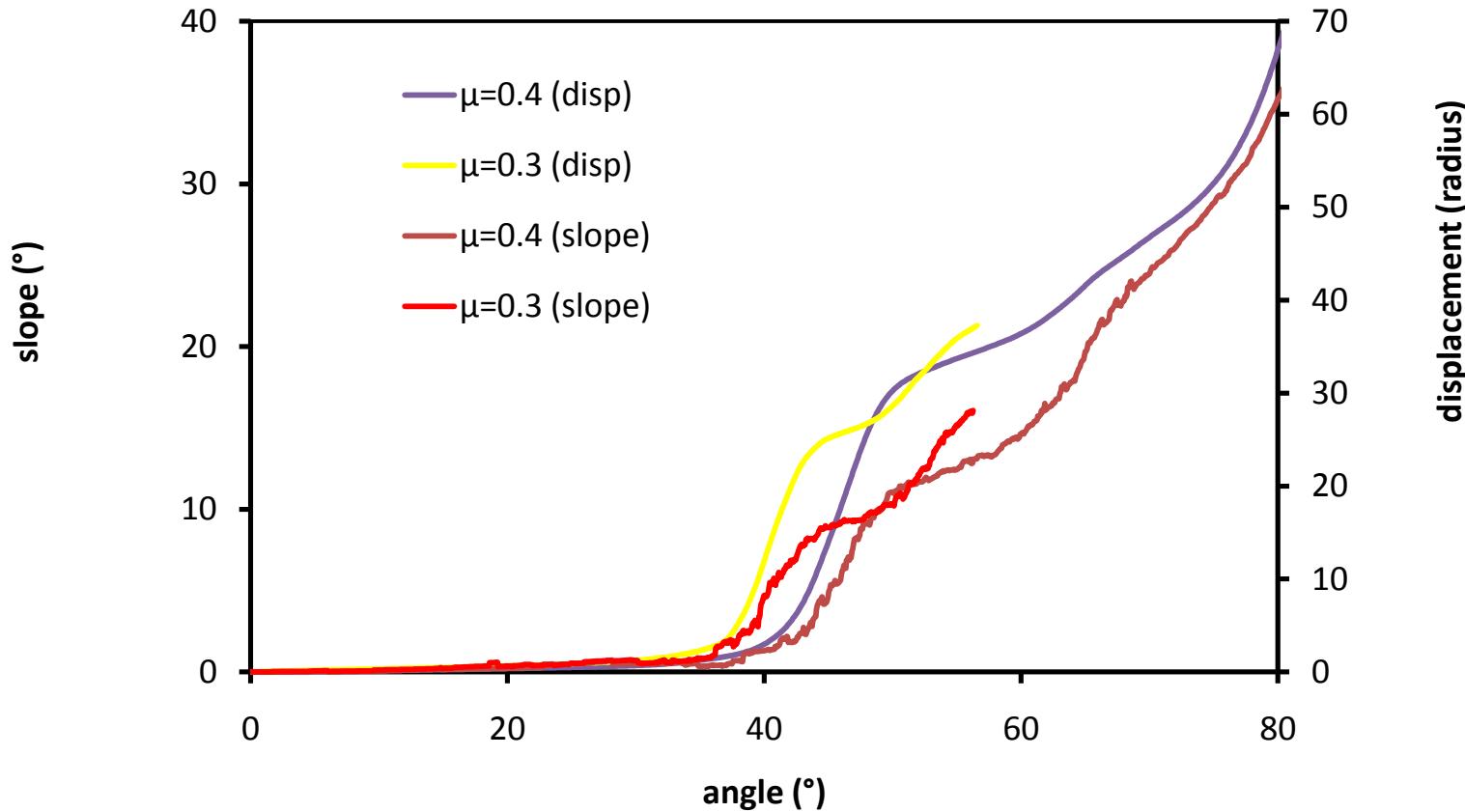
# With sphere output



# Evolution slopes velocities

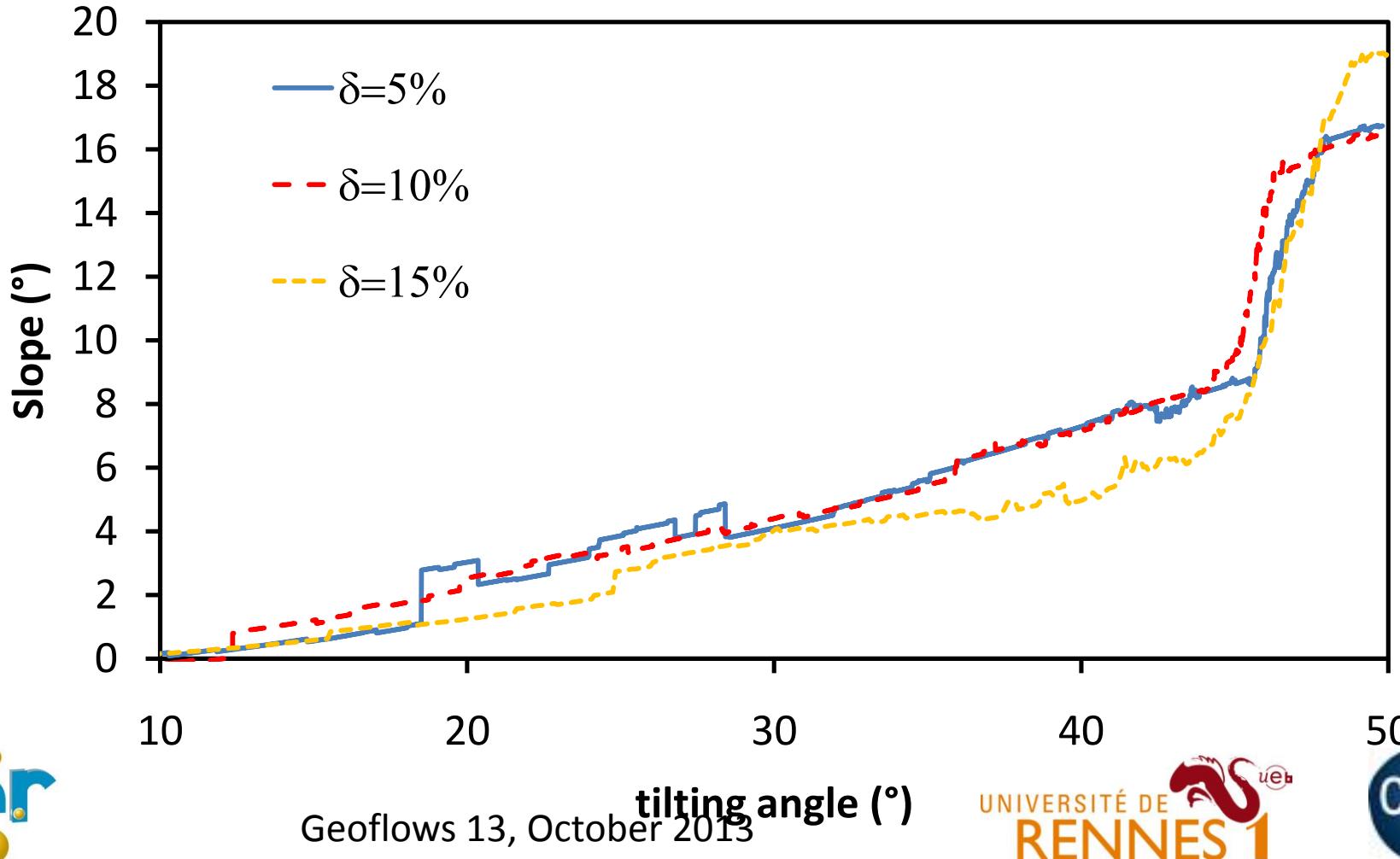


# Evolution slopes & displacement (2 friction coefficients)

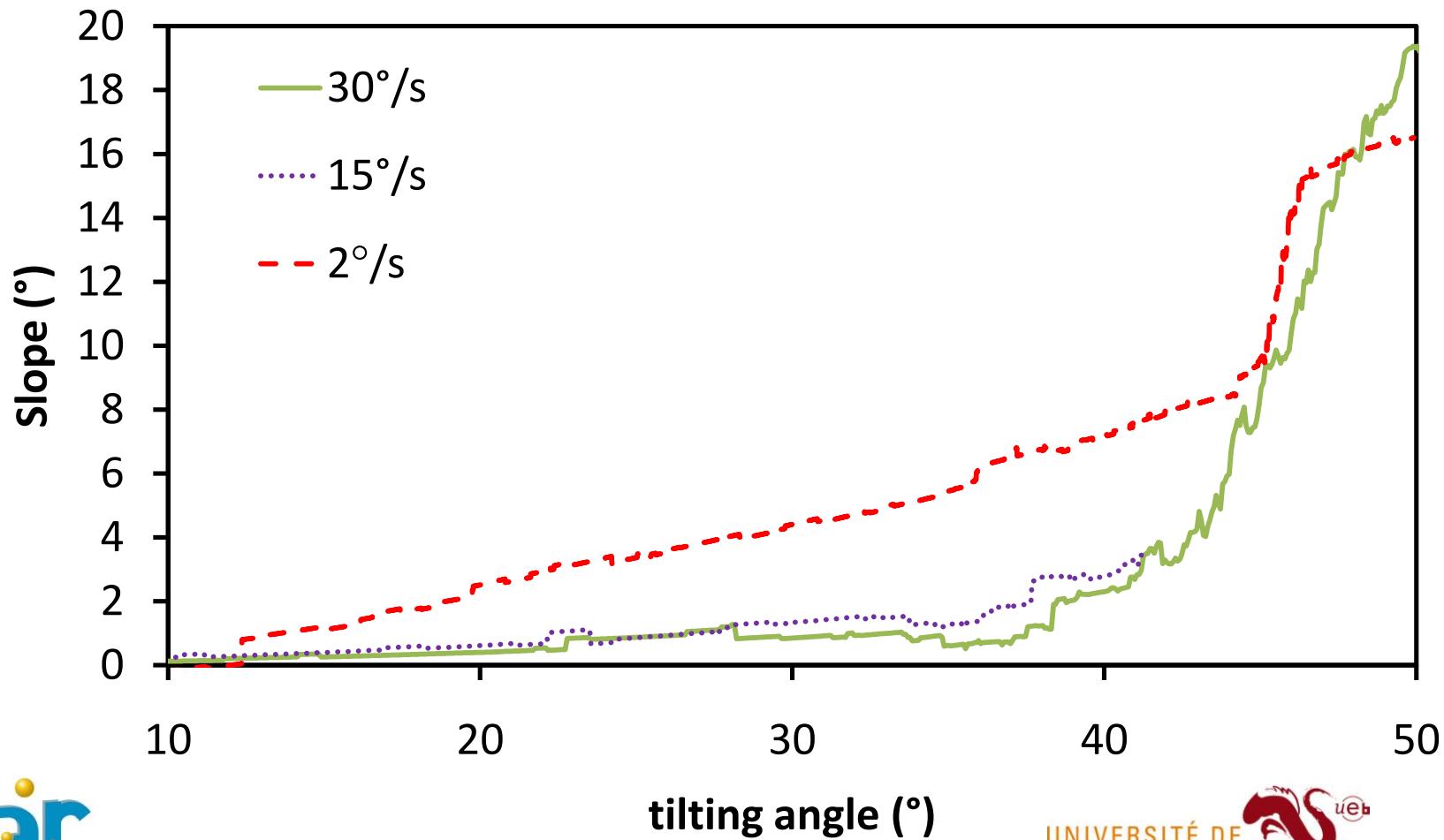


# Sphere disorder effect

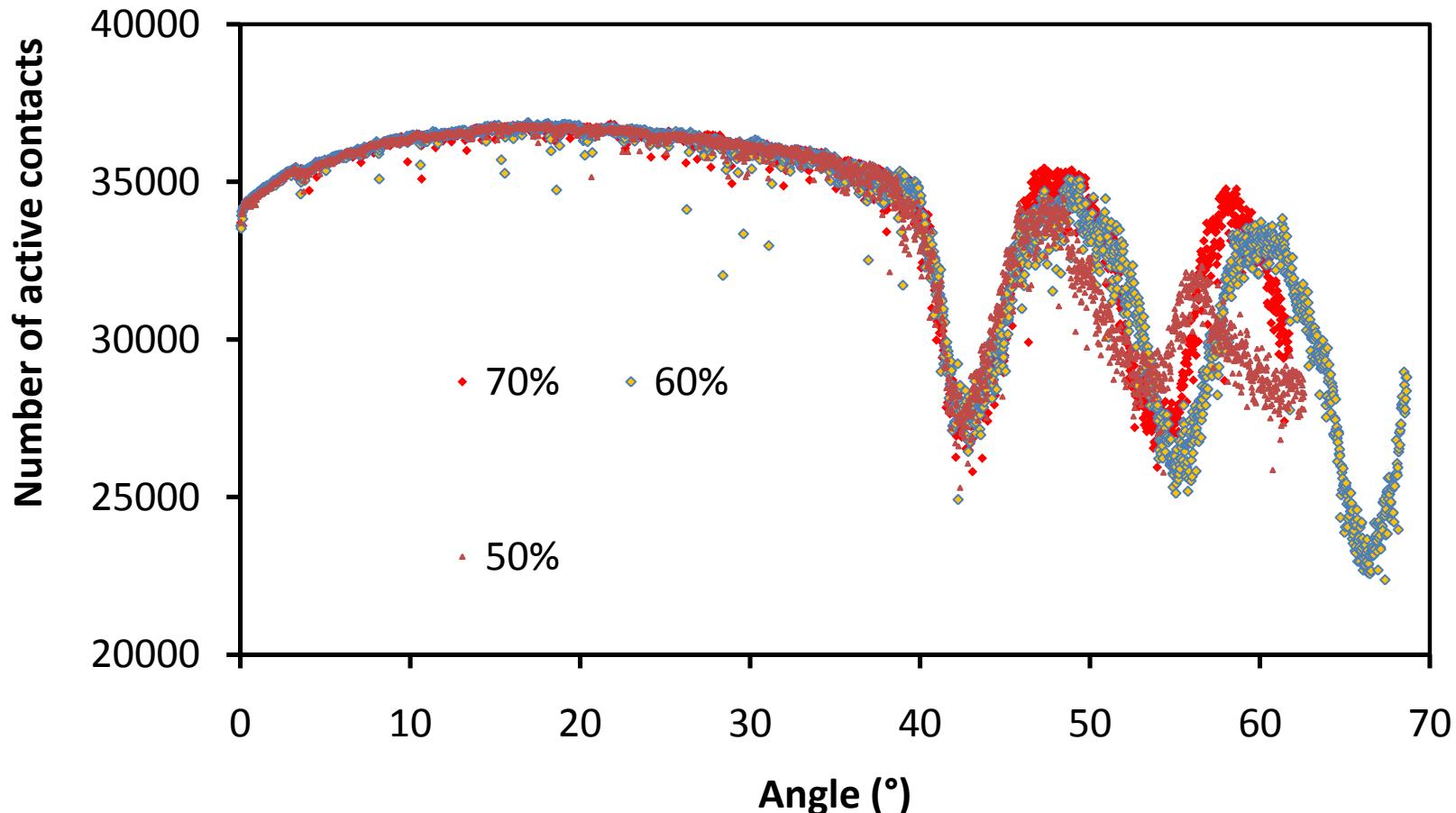
Different if higher than 10%



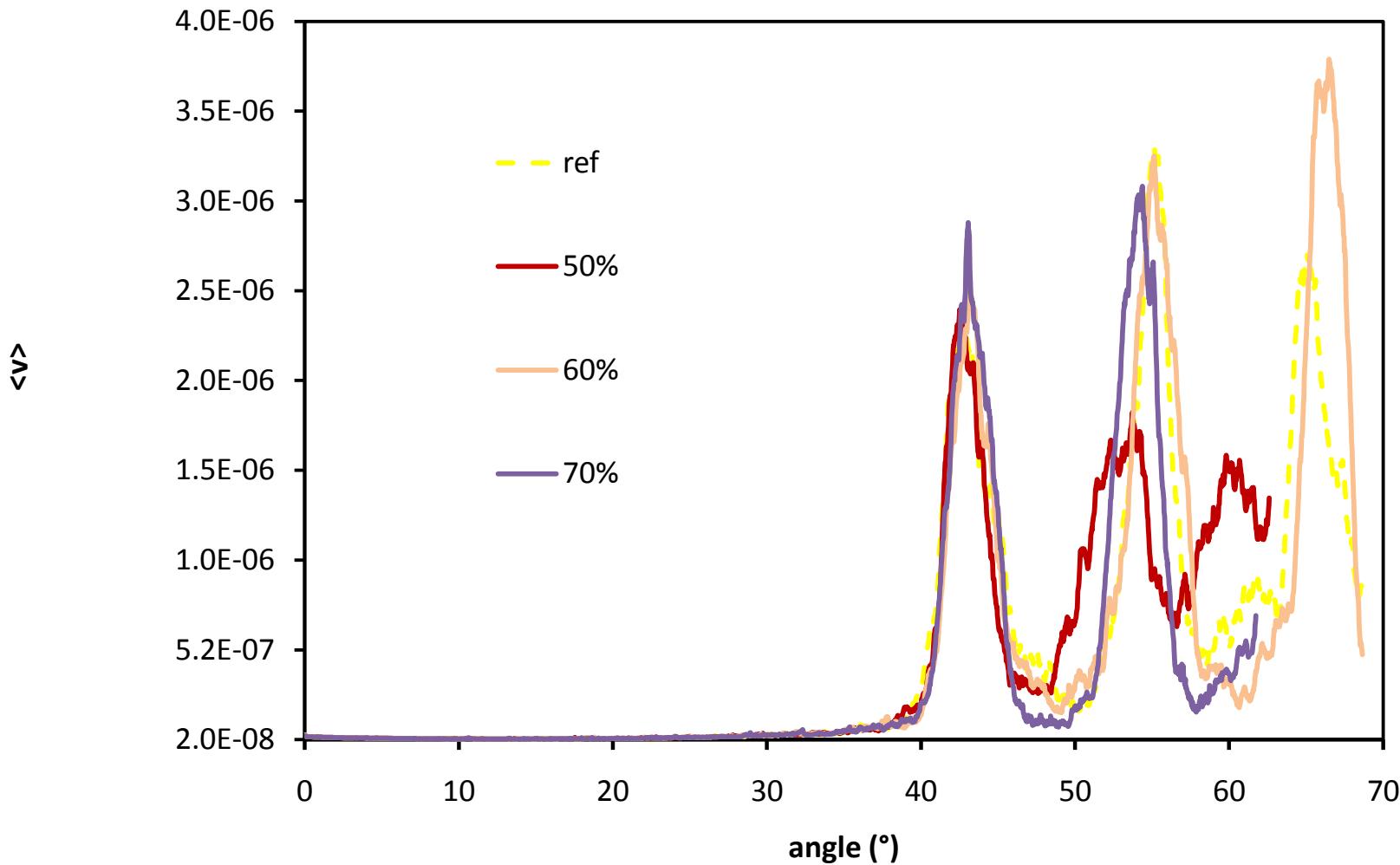
# Effects of inclination speed

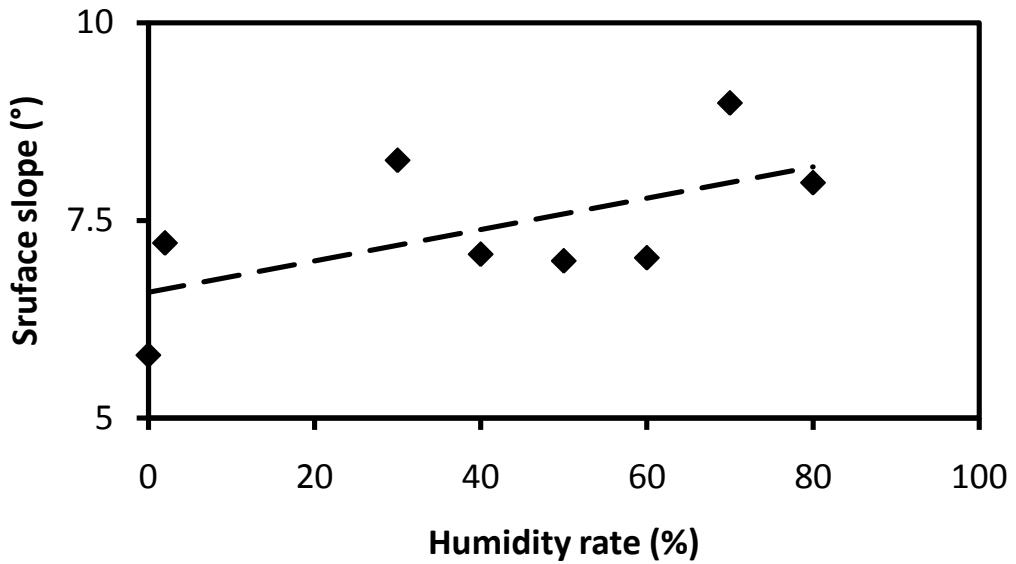


# Evolution of active contacts

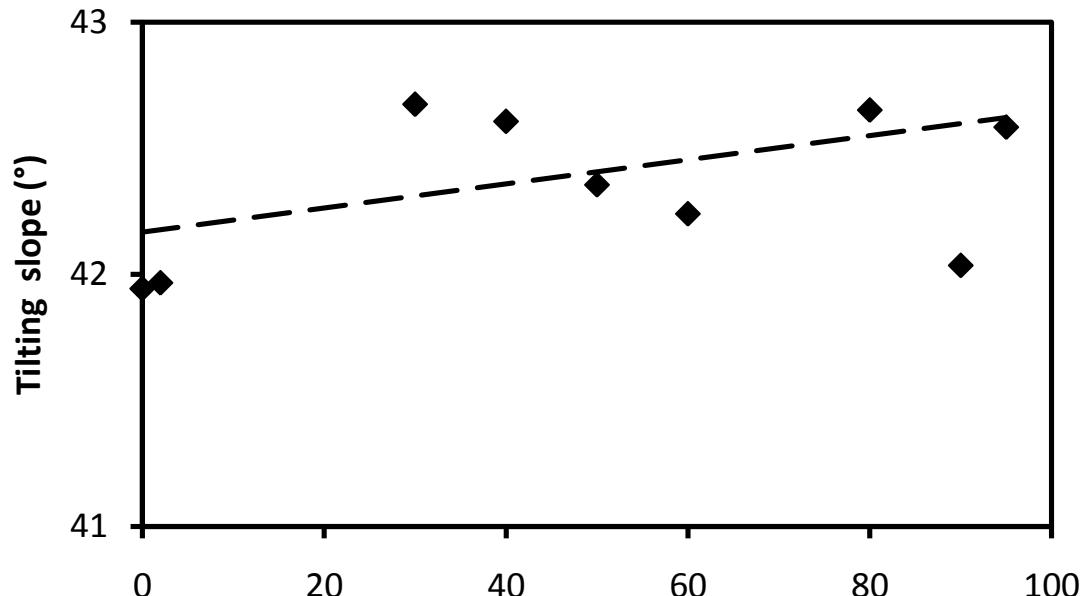


# Evolution velocities = f(RH)





# Results



# §2:Conclusions

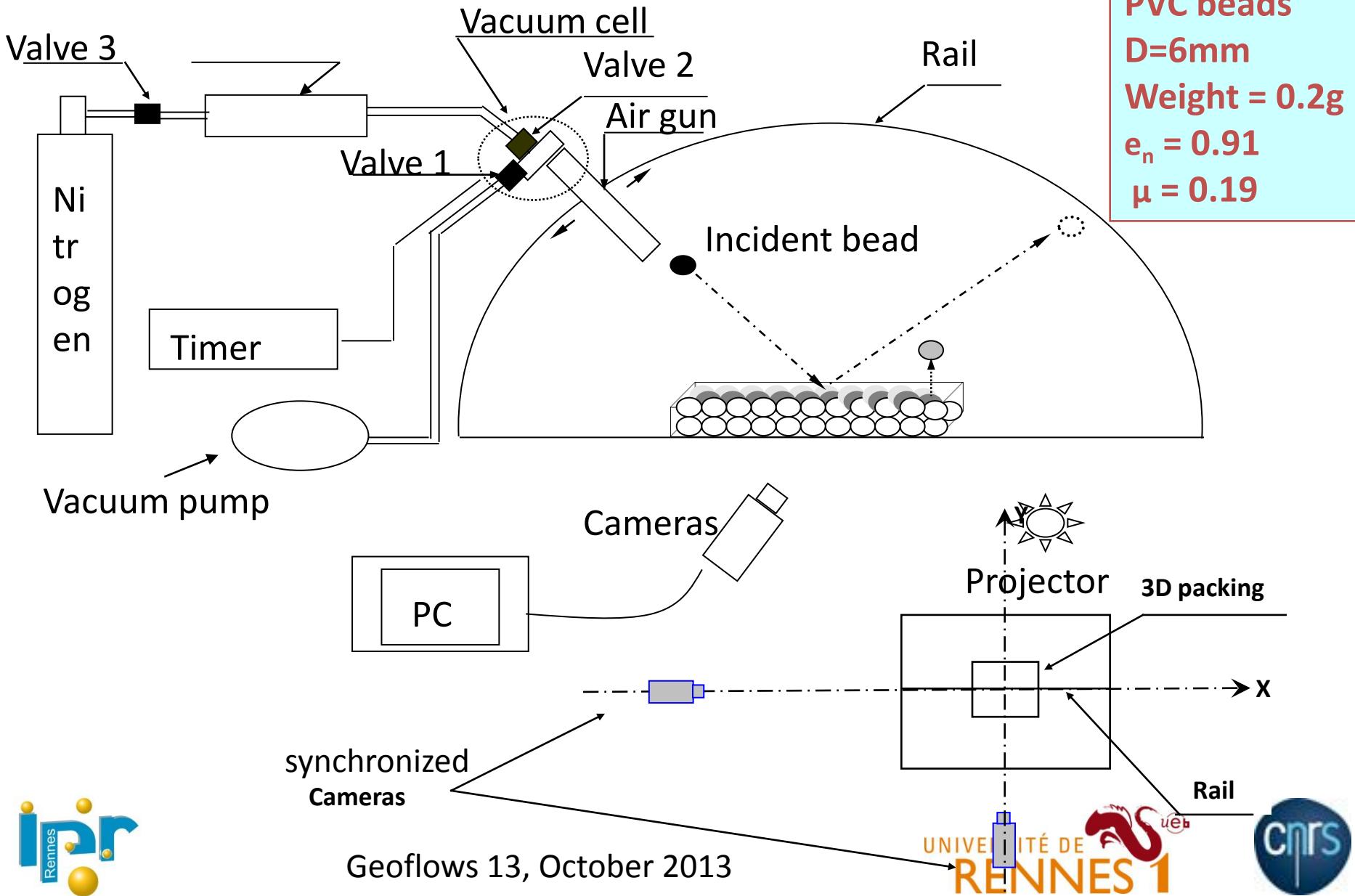
- Humidity is crucial to understand grains transport
- Humidity is difficult to model
- Correct results up to 70% RH
- Progress:
  - For high humidity rate!!!
  - Multiple capillary bridges!!

## §3-4-5 issue: sand transport by saltation

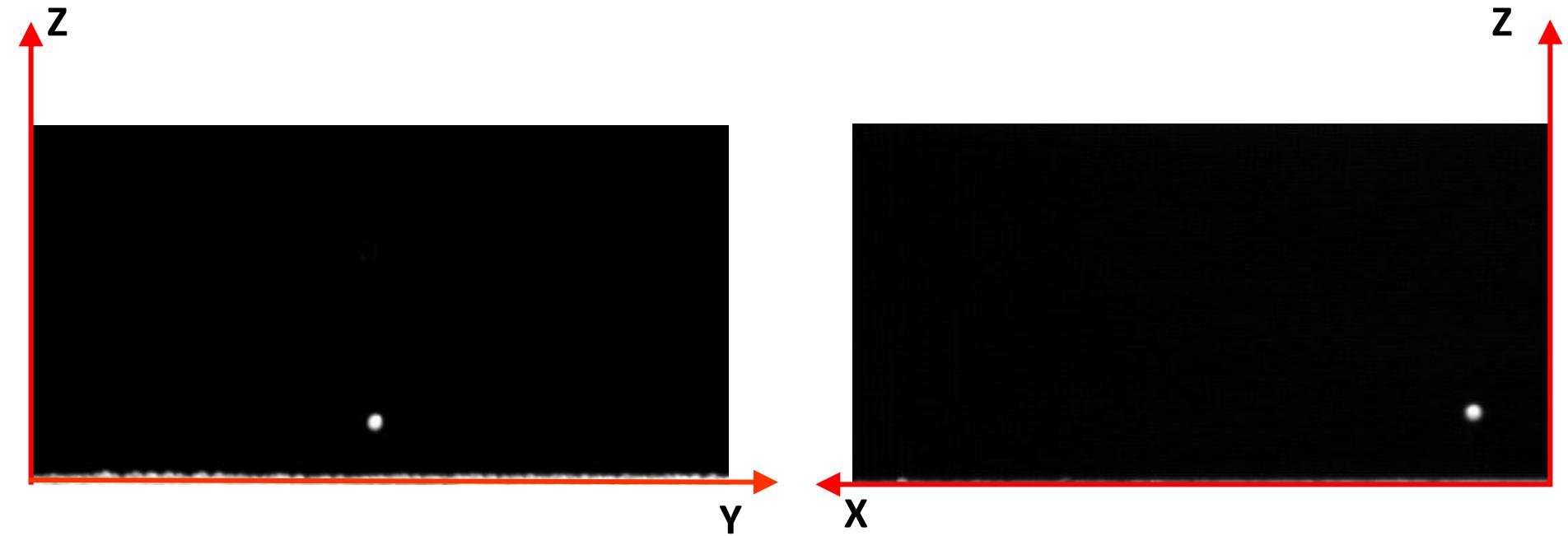


2D LASER slice of 3D sand flow inside a large wind Tunnel

# Experimental Setup



# Synchronized 3D Film



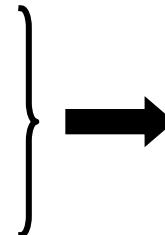
Possibility to detect the real 3D trajectories

## Control Parameters

Froude Number= 1000

Sand diameter ~ 100  $\mu\text{m}$

Impact velocities : few m/s



Impact speed ~ 10m/s

Diameter = 6mm

$$\text{Froude number} = \frac{\text{Impact kinetic energy}}{\text{Potential energy to reach One diameter high}} = \frac{V_i^2}{gd}$$

### Incident angle effect :

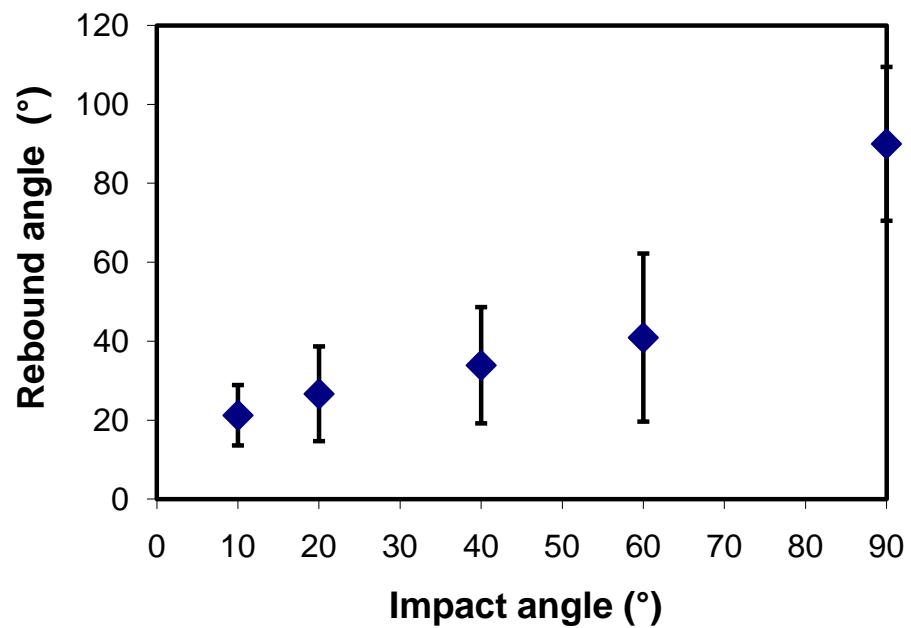
- Constant speed: 26 m/s
- Variable angle: 0° to 90°

### Incident speed effect:

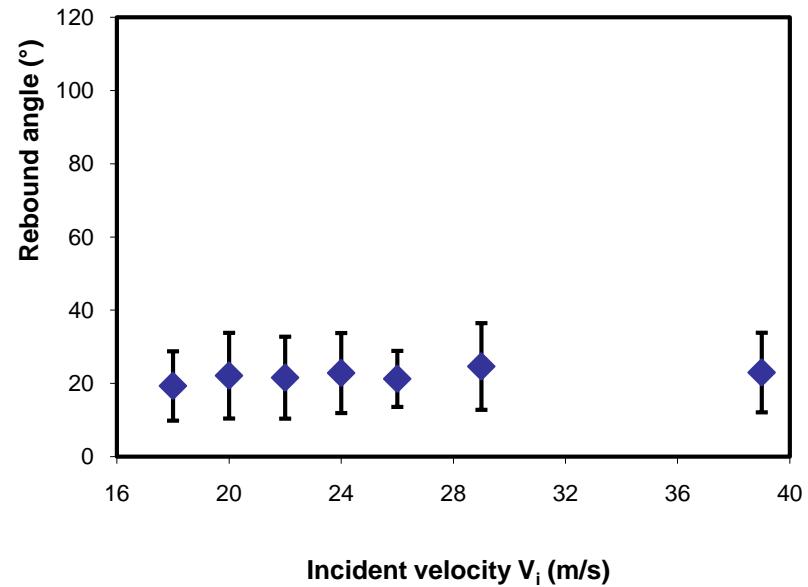
- Constant Angle: 10° ( Natural angle for saltation)
- Variable incident speed: 18 m/s et 39 m/s.

# Variation of the rebound angle

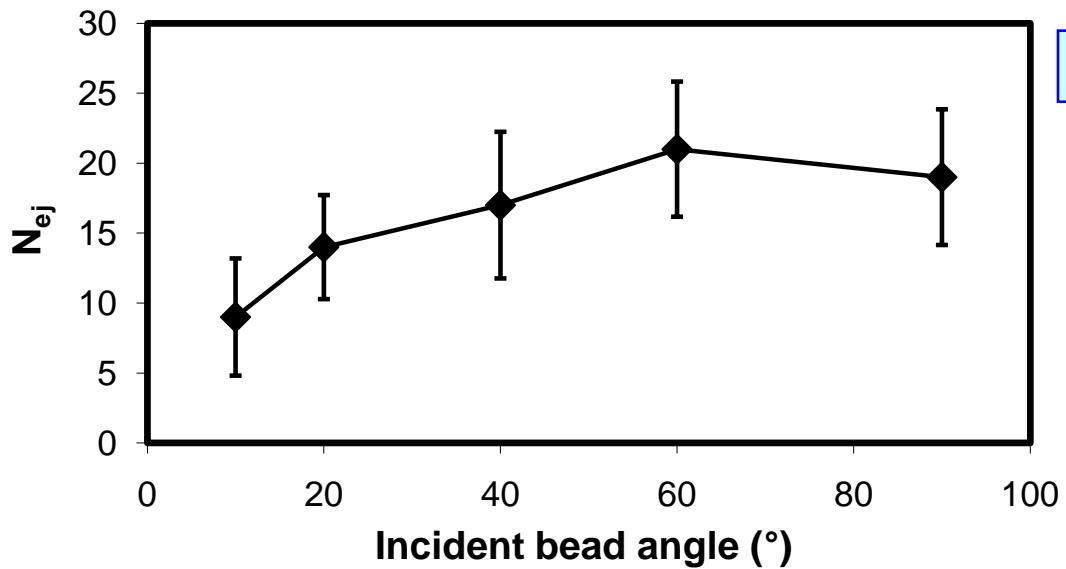
Velocity 26m/s



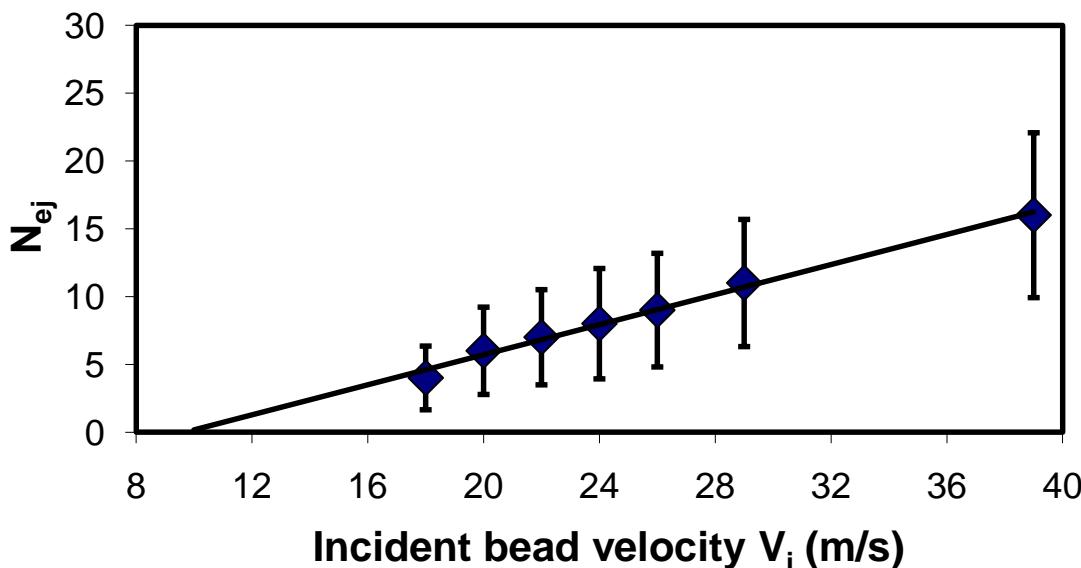
Angle 10°



## Number of ejected beads



Velocity 26m/s

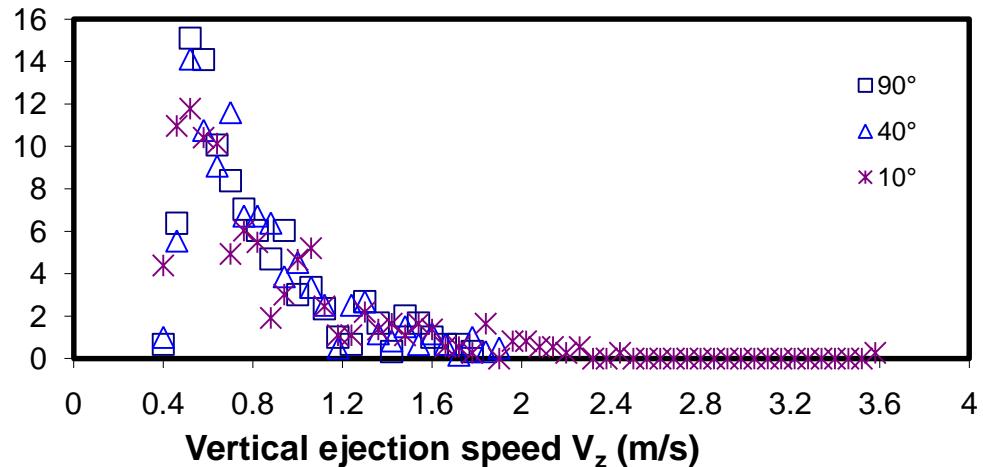


Angle 10°

$V_i^{th} = 10 \text{ m/s}$

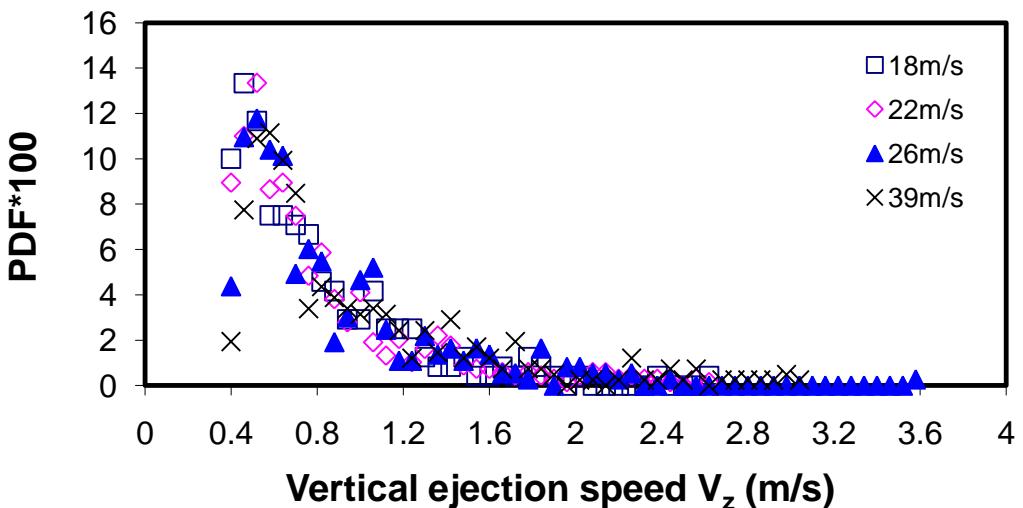
# Distribution of the vertical velocity components of ejected beads

PDF



Distribution is independent of the angle and the incident velocity

Velocity 26m/s

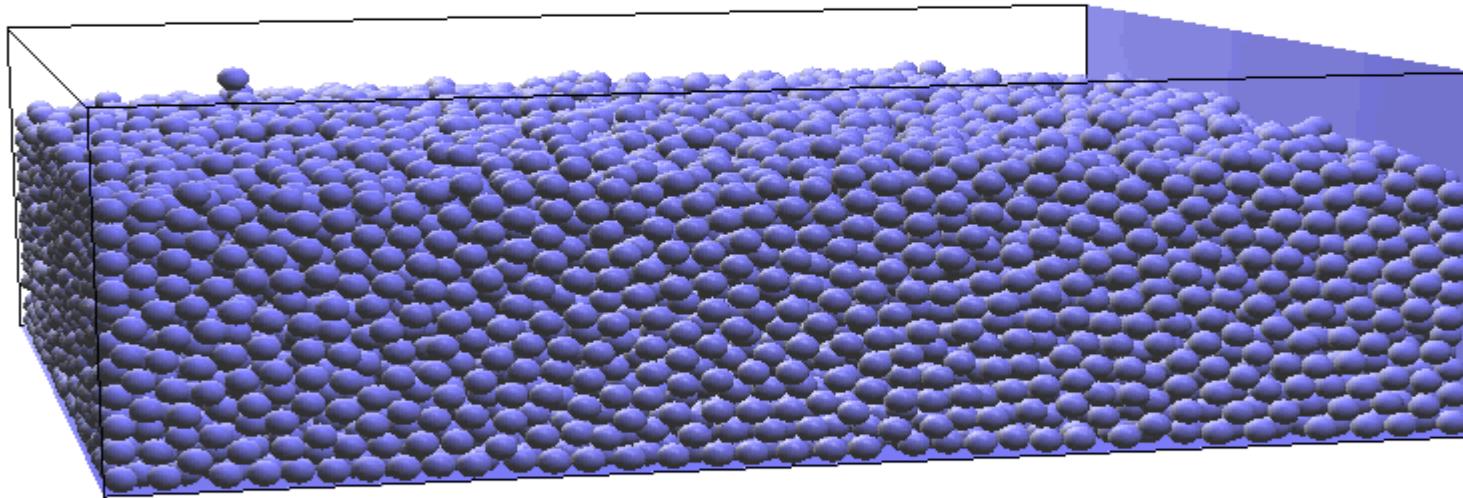


# Numerical simulation

- Discrete Element Method
  - Soft sphere model (“Spring-dashpot”)
- 30000 spheres for the packing (43x43x16)
- Same physical and mechanical parameter as the real beads :
  - Diameter = 6mm, weight= 0.2g
  - Stiffness= 1.0 E9 N/m
  - Restitution coefficient= 0.75 -0.95
  - Friction coefficient= 0.2-0.4

# Visualization of the sphere displacements

Incident bead : angle = $10^\circ$  and velocity =50 m/s

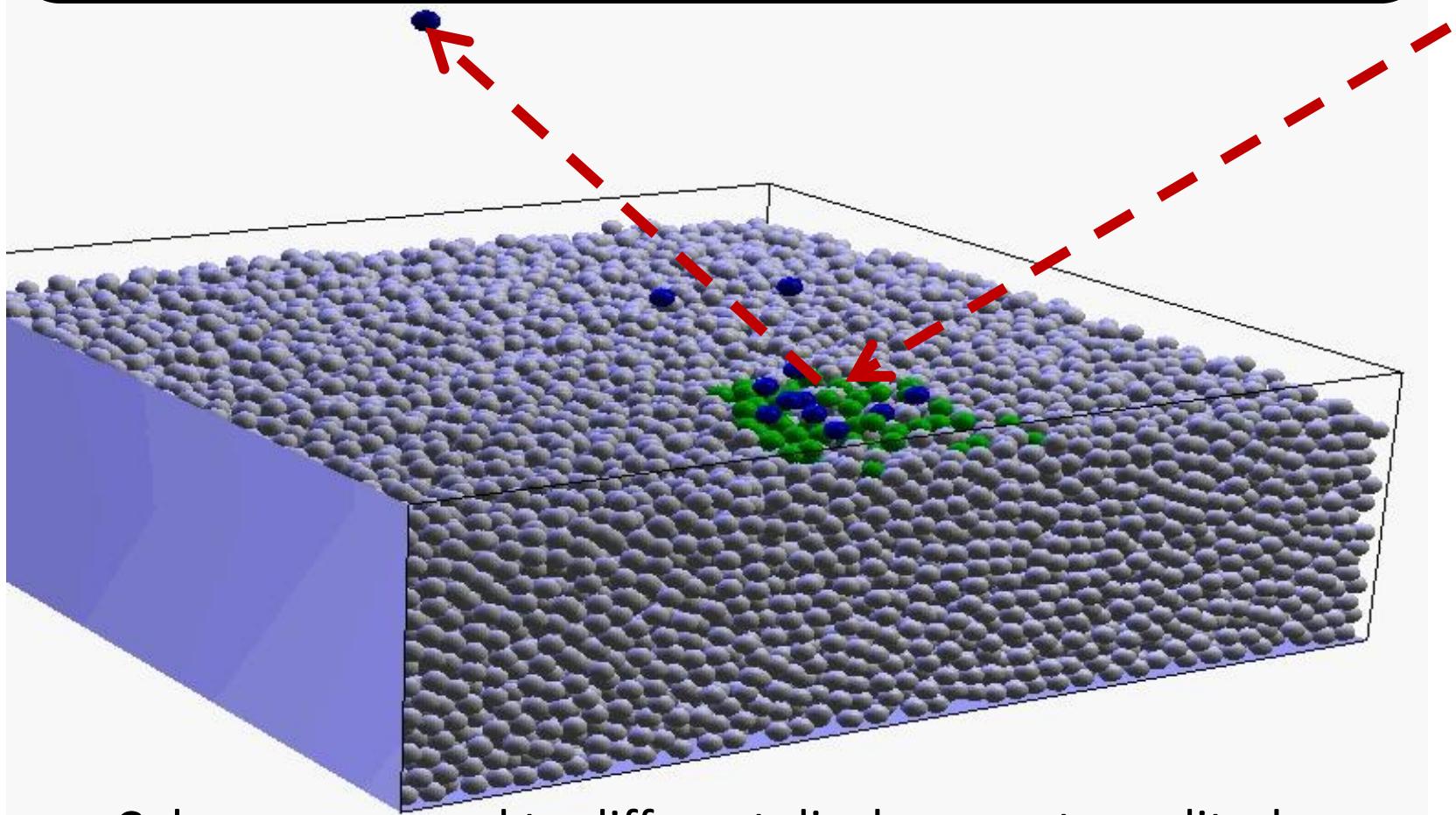


Green = displacement higher than 0.25 diameter  
Dark blue = displacement higher than 1 diameter



# DEM approach

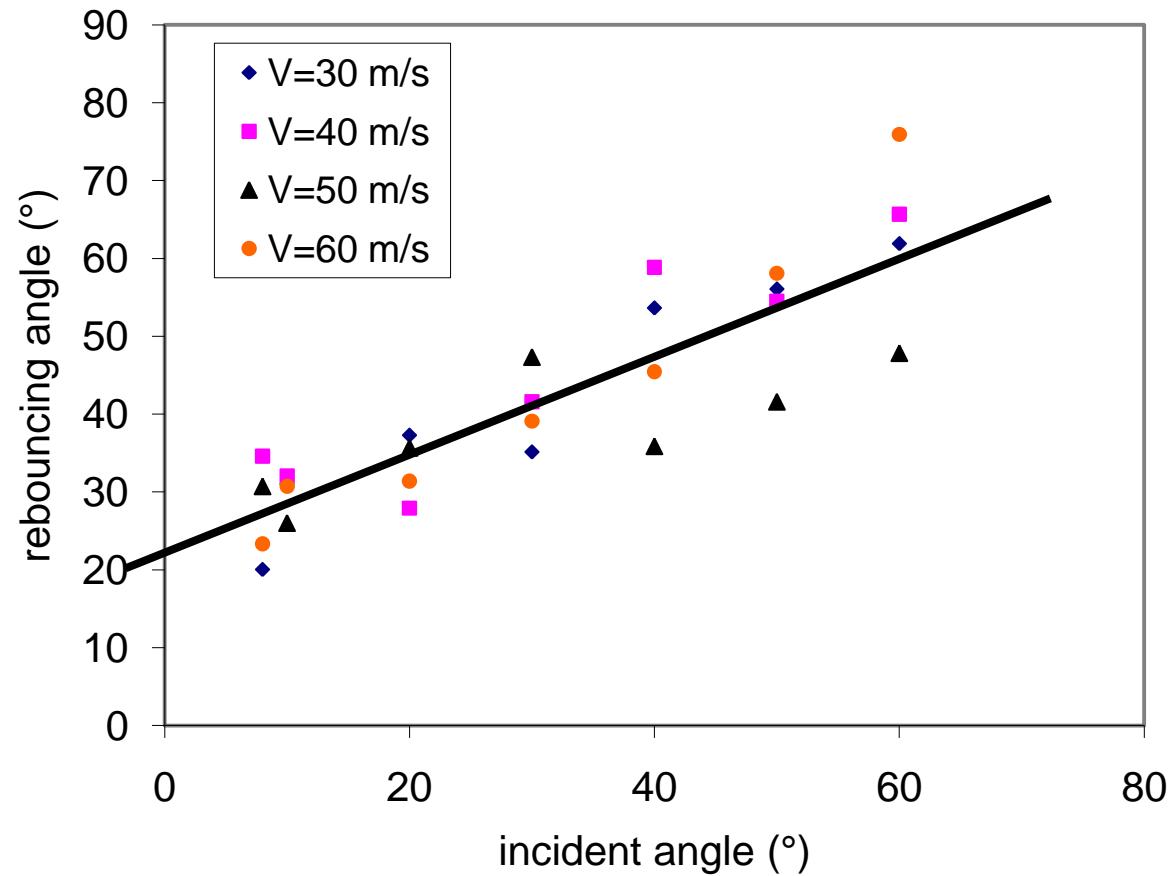
(Discrete Element Method - Soft model)



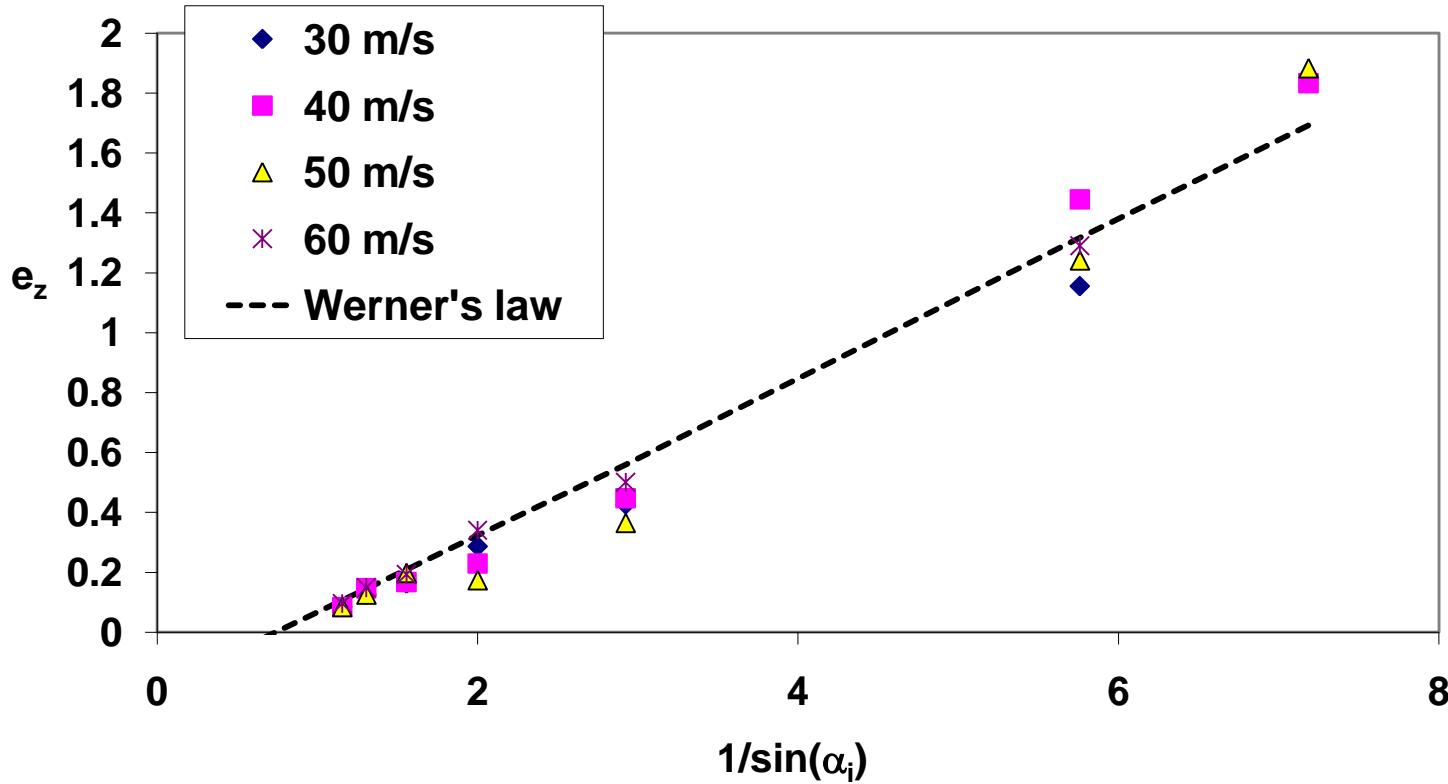
Colors correspond to different displacement amplitudes

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# Analysis of the rebound of the incident bead



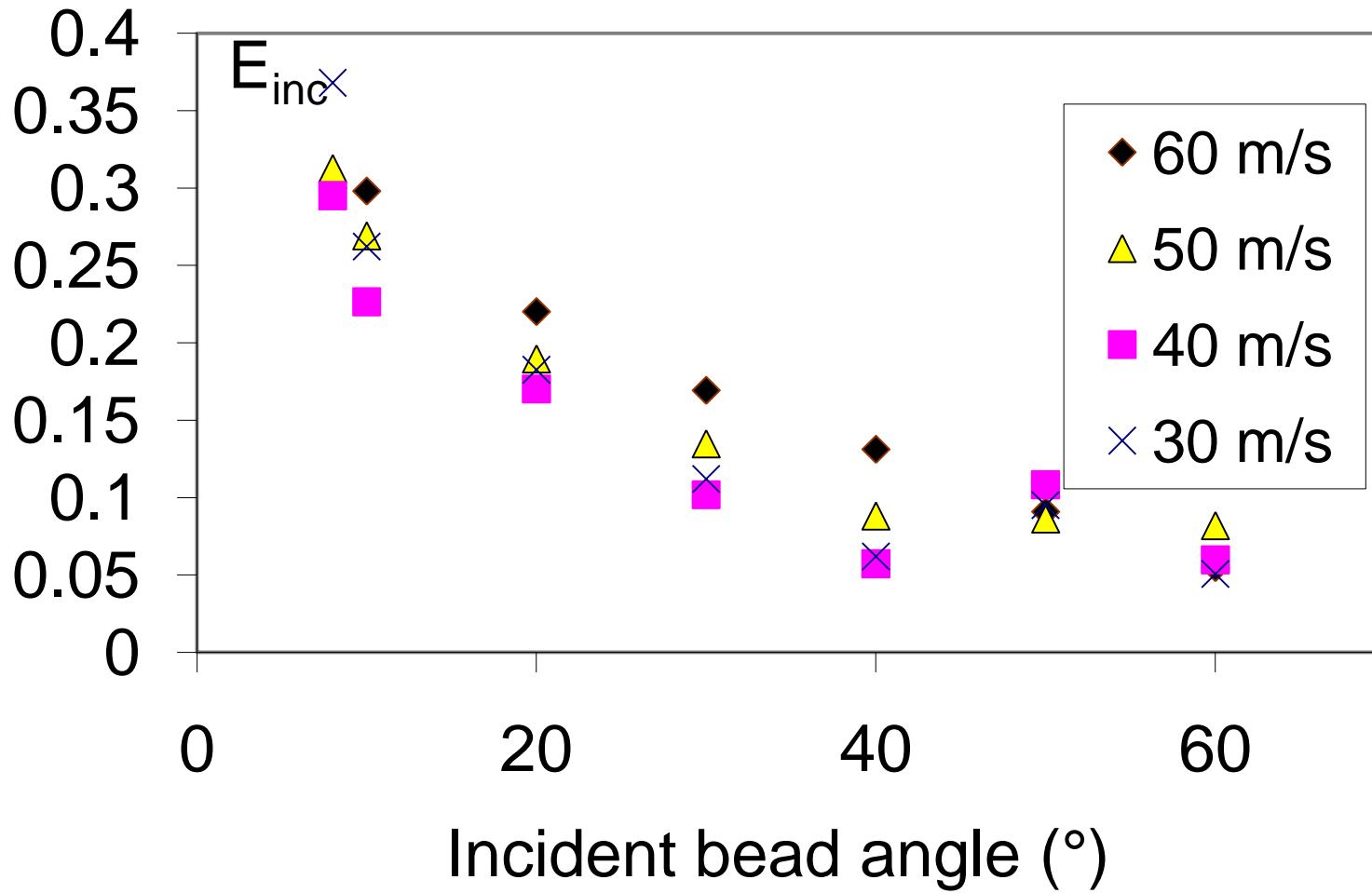
# Vertical velocity restitution



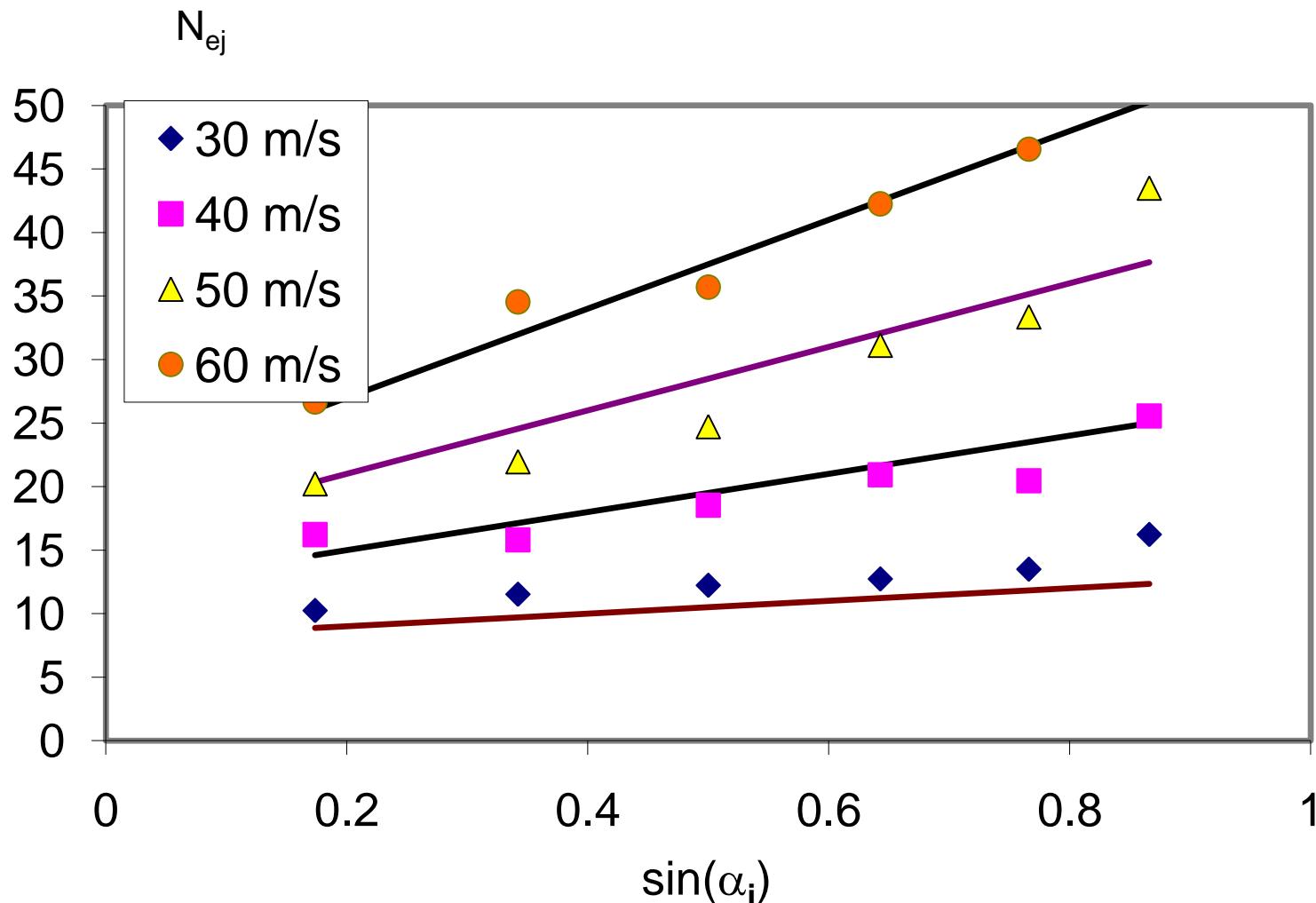
Werner's law:

$$\bar{e}_z(\alpha_i) = \left( \frac{0.320}{\sin(\alpha_i)} - 0.236 \right) \bar{e}_z(15^\circ)$$

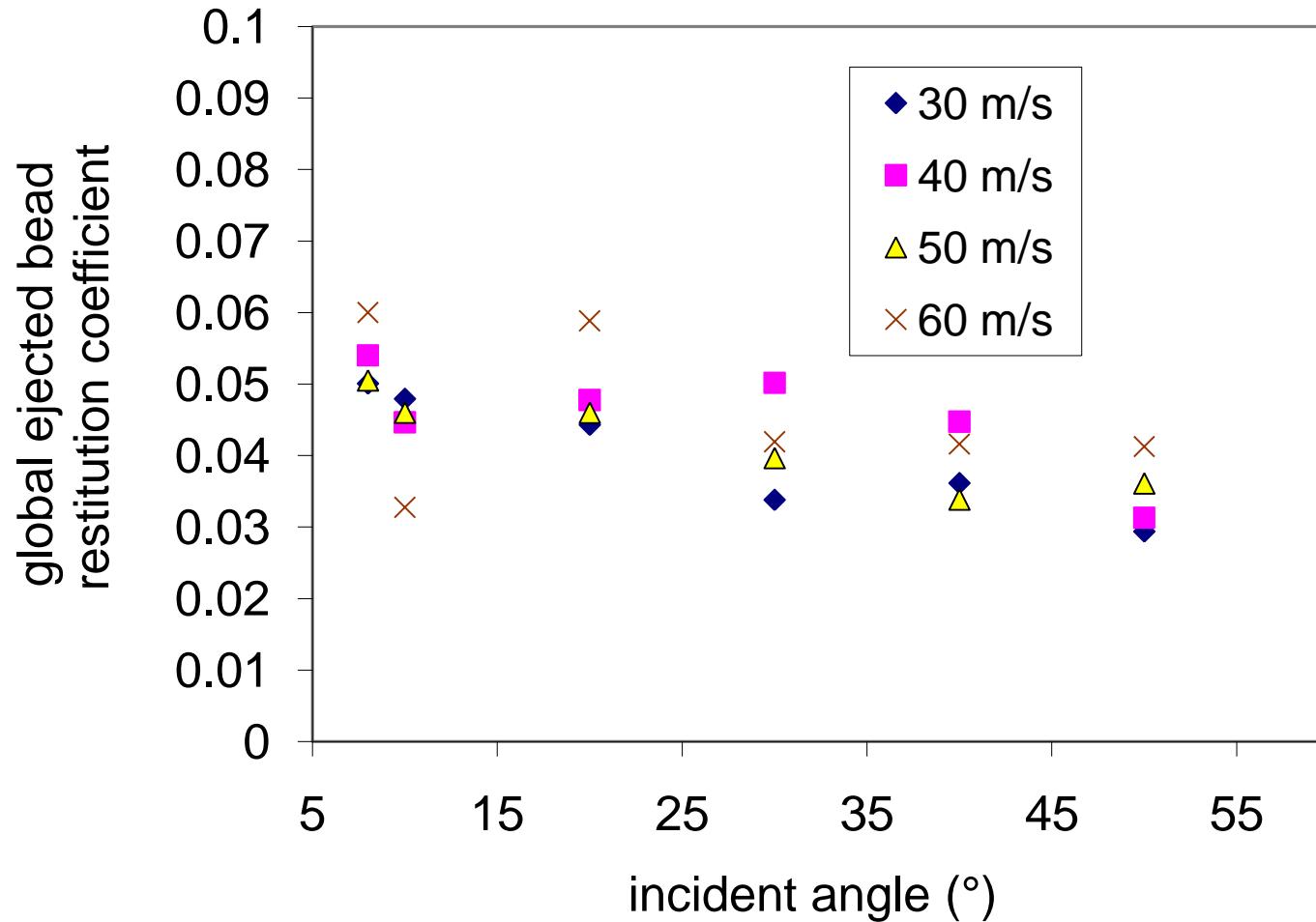
# Global energy restitution for the incident bead



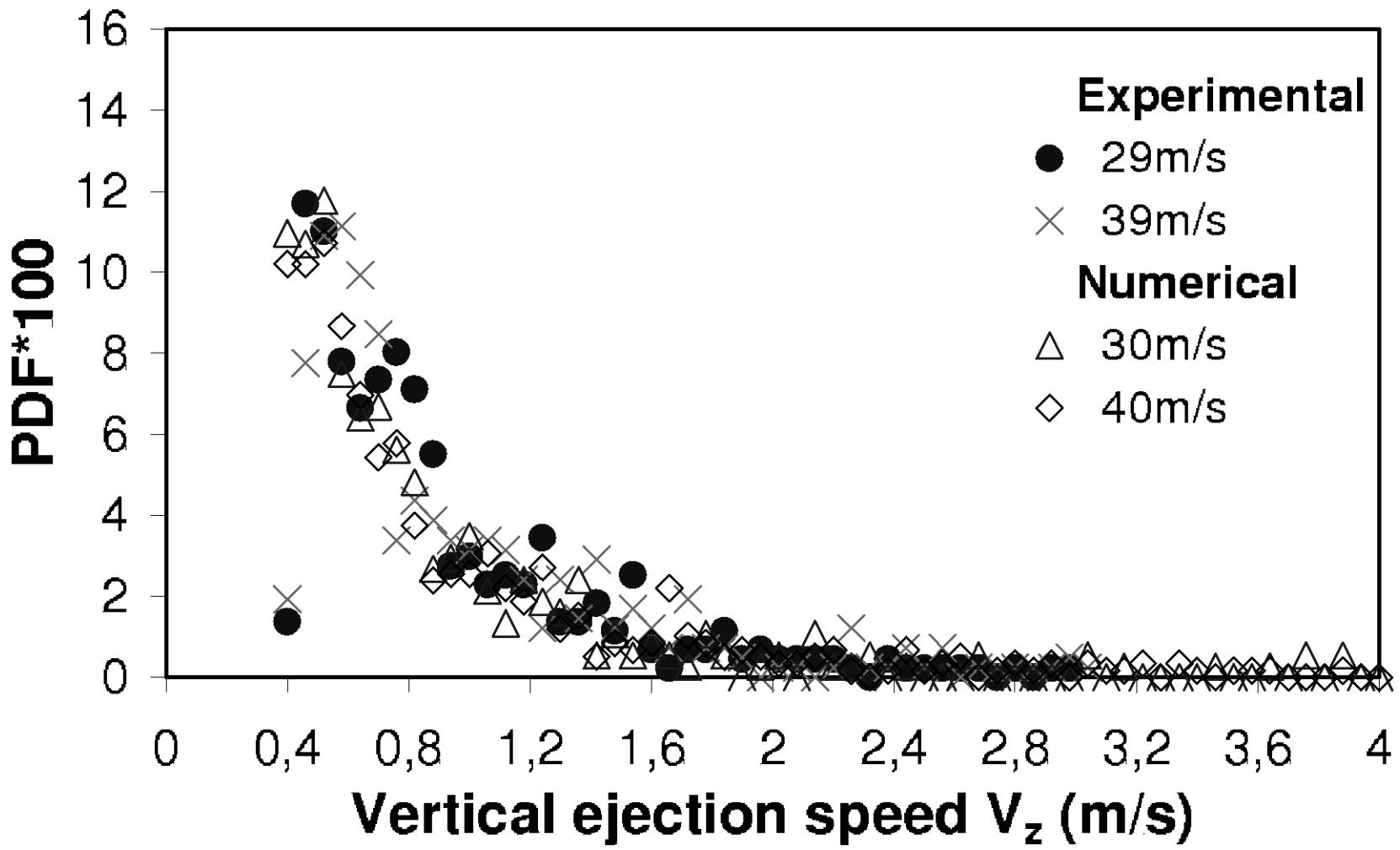
# Number of ejected beads



# Energy of the ejected beads



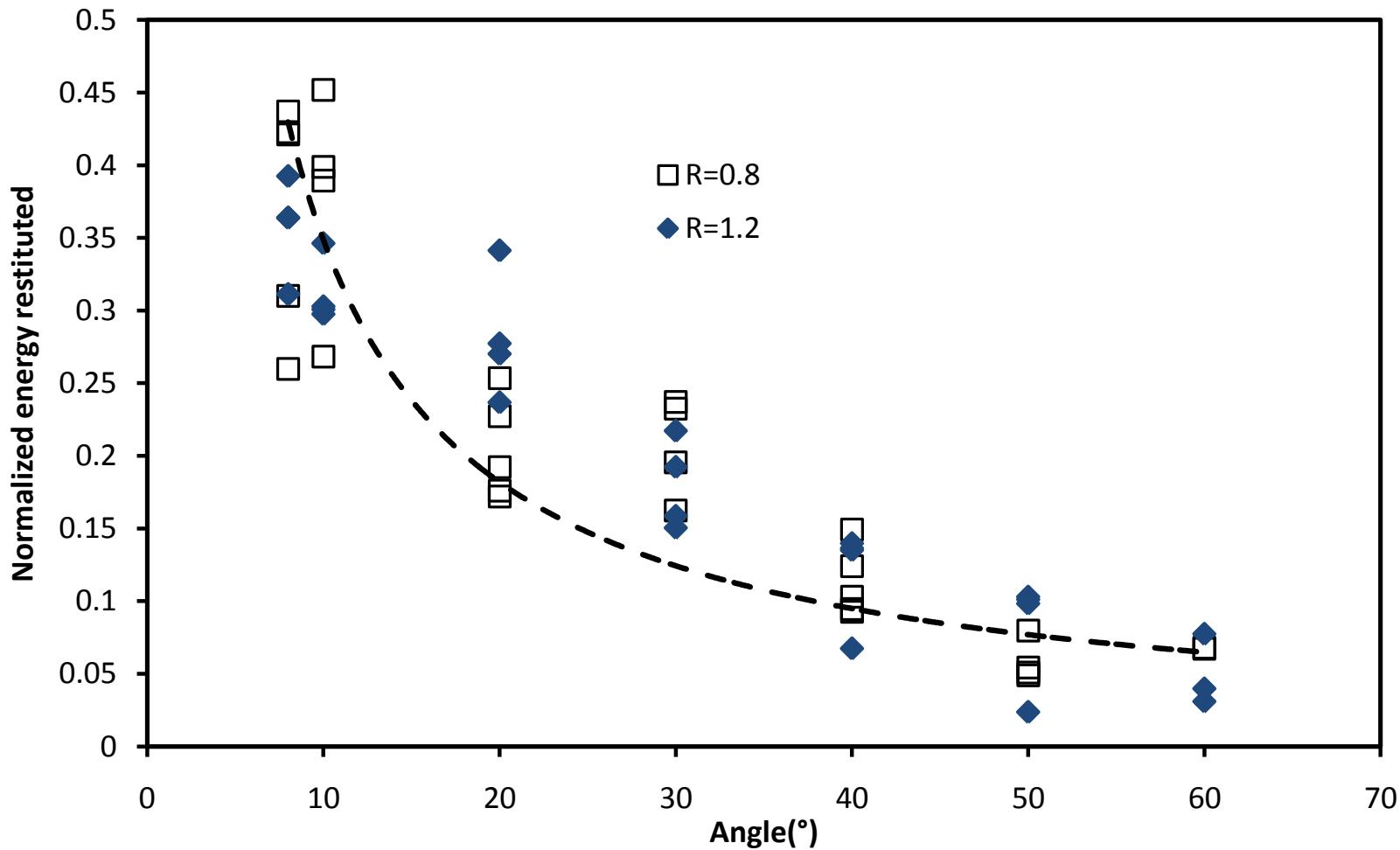
# Comparison between experimental and numerical results



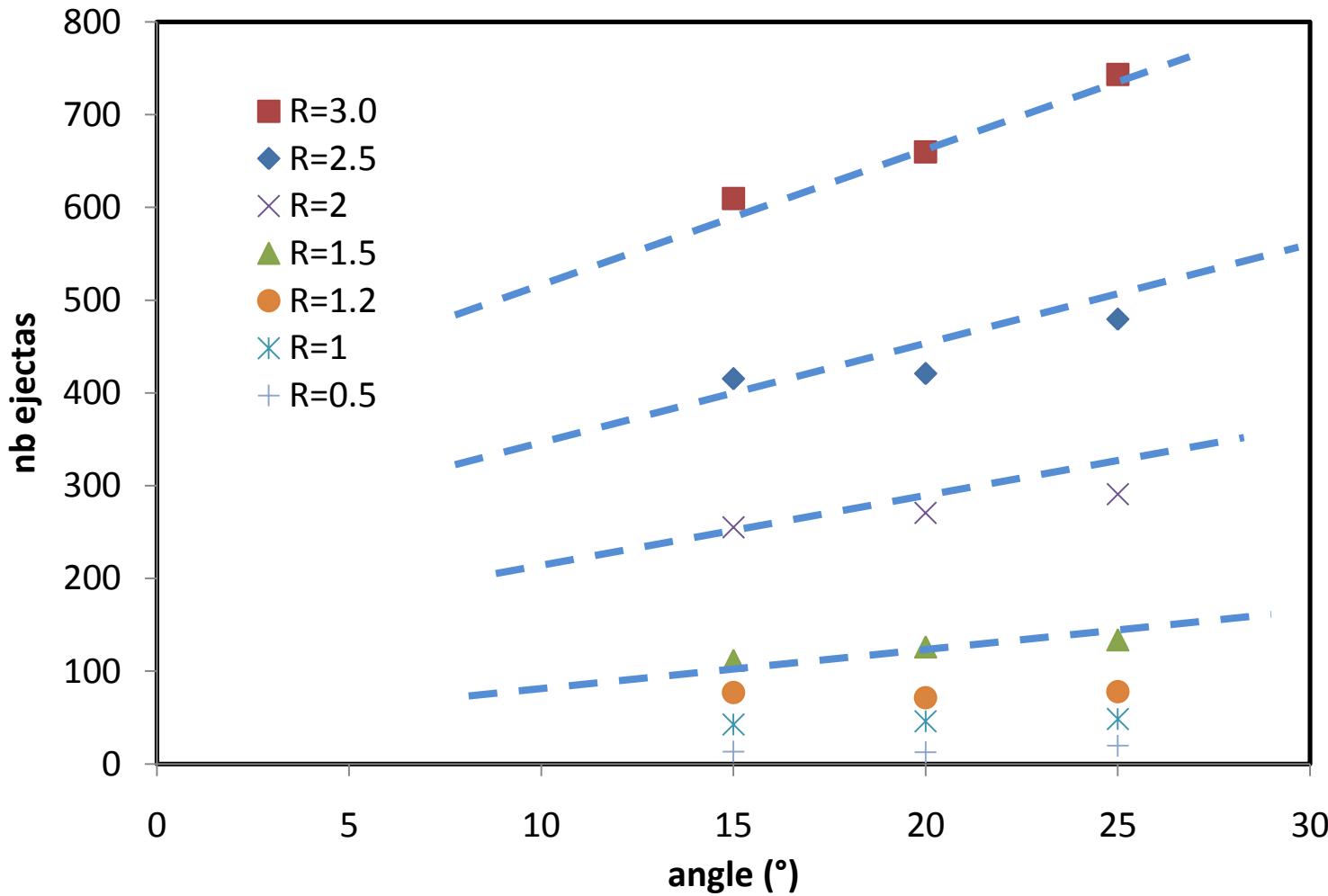
# But with different sizes!

- Monosize or binary packing of sphere
- Size of the impactant different (0.5 up to 4)
- Variable velocities and angles

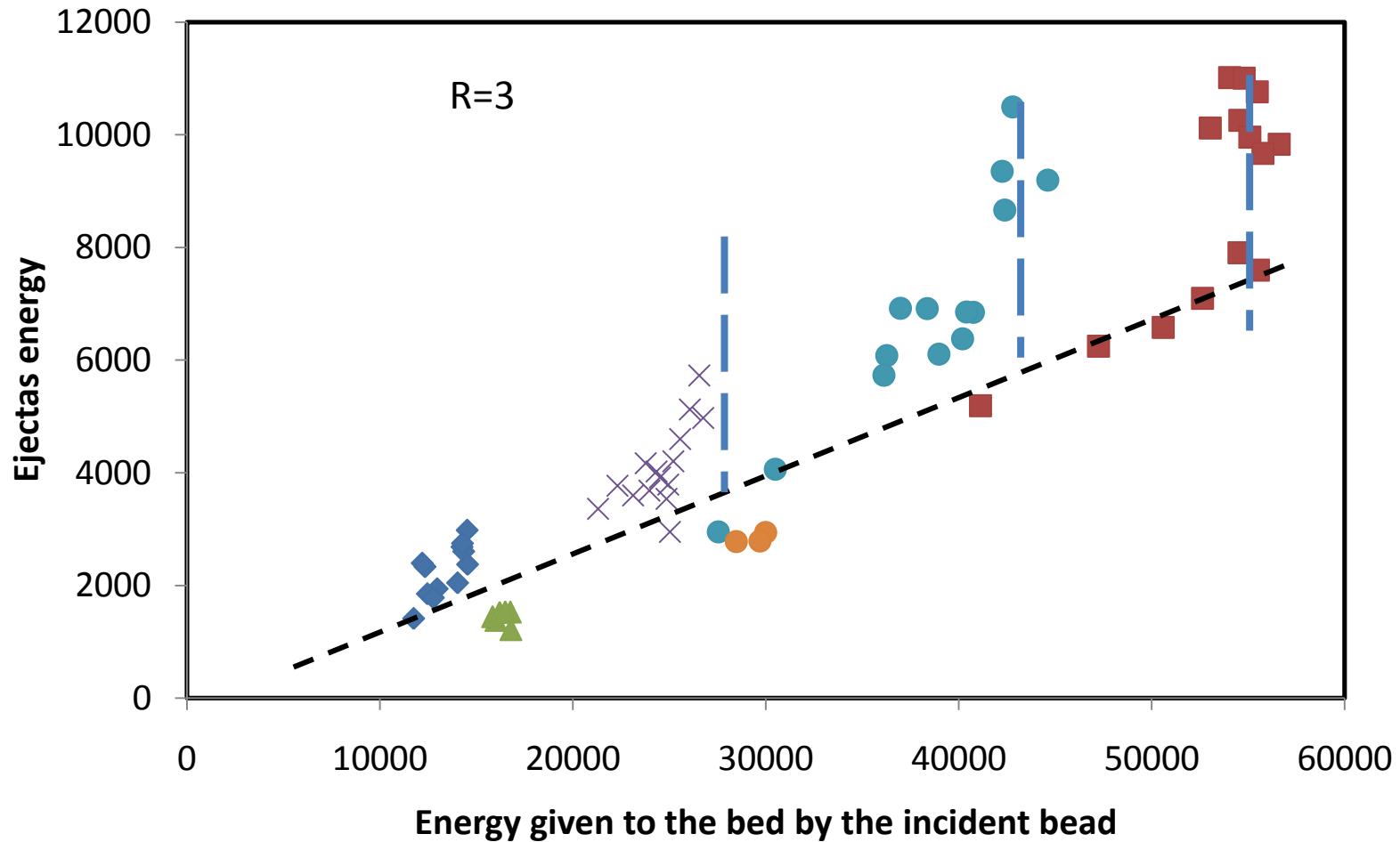
# Incident bead



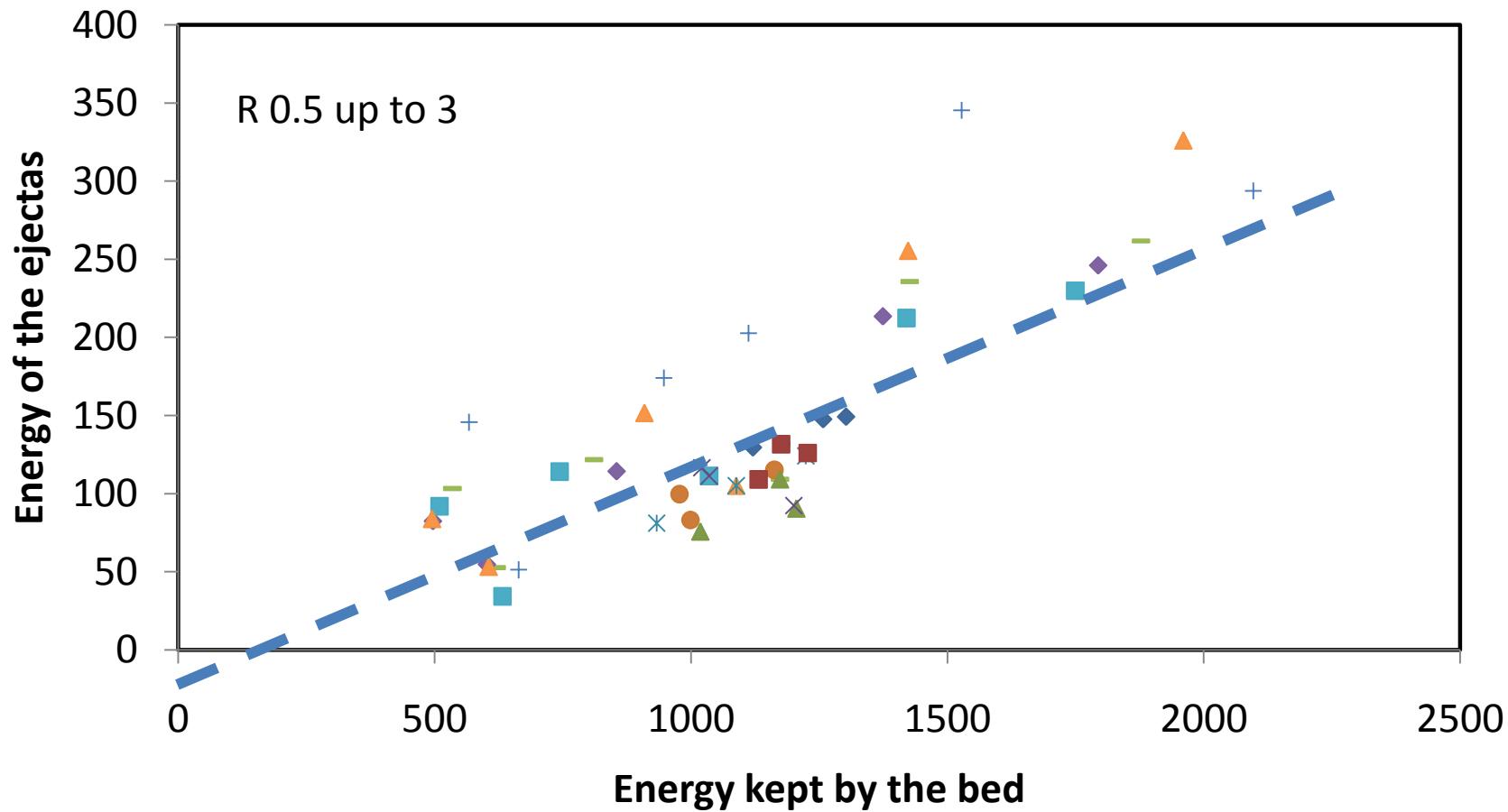
# Same impact velocities, different sizes



# 1 symbol = 1 run for 1 velocity



# For different size ratio, angle and impact velocities



## §3: Concluding results on SPLASH function

- Depends on :
  - angle
  - shot velocity
  - Coefficient of restitution of the grains
  - Coefficient of friction of the grains
  - Initial packing fraction of the grain bed
  - And so on...

**Easy to analyse on single shot**



# §4: Dry saltation problem

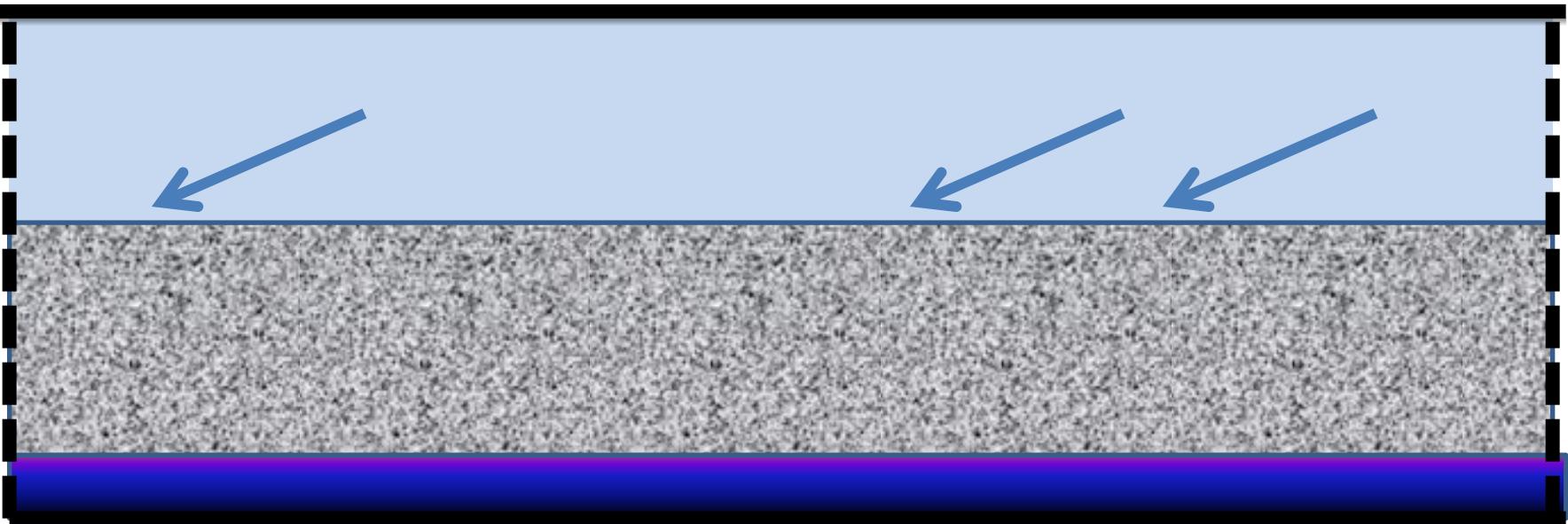
If 3D analysis:

- Too CPU consuming (i.e. too many particles)
- Problems for the periodic boundary
- Definition of the impact zone too wide

If 2D analysis:

- CPU time reasonable
- Periodic boundary on one direction
- Impact zone clear

# 2D saltation model assumptions



Horizontal boundary conditions

Full progressive dumping ( $v_x$  et  $v_y$ ) in depth on  $SP = 20 \cdot x$  Rayon)

Upper perfect mirror (at  $H = 250 \times$  Diameter)

Defined initial shot Angle (10°)

One defined shot velocity for a given run ( $E_c = \text{cste}$ )

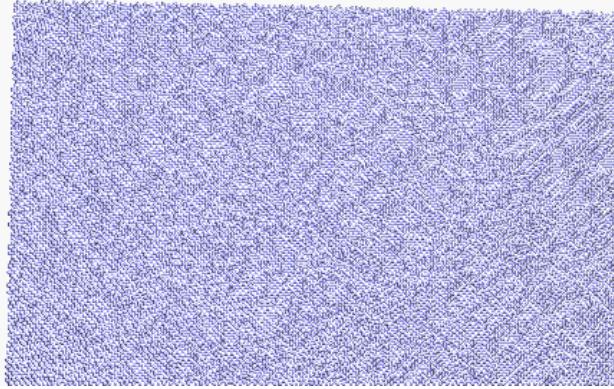
Random horizontal position for the shot ( $X = \text{random}(0, L)$ ,  $Y = \text{Cst}$ )

Interval between shots:  $T_{\text{mean}} + \text{random}(0, 1) \cdot \Delta t$

# Run Conditions

- up to 62 000 disks in 350 disks on X direction  
and 180 disks on Y direction
- Mirror at  $Y_{\max} = 250$  disks
- restitution Coefficient = 0.8
- Shot Angle =  $10^\circ$
- Disk diameter =  $250\mu\text{m}$  (sable)
- Shot velocities between 10 and 25 m/s
- Time interval between shots :  $25 \mu\text{s}$  to  $200 \mu\text{s}$
- Dumping-factor( $a=0,4$  &  $\text{SP}=25\times R$ )  
$$\text{DF} = 1 - \{a(1-y/\text{SP})^3 + (1-a)(1-y/\text{SP})^6\}$$

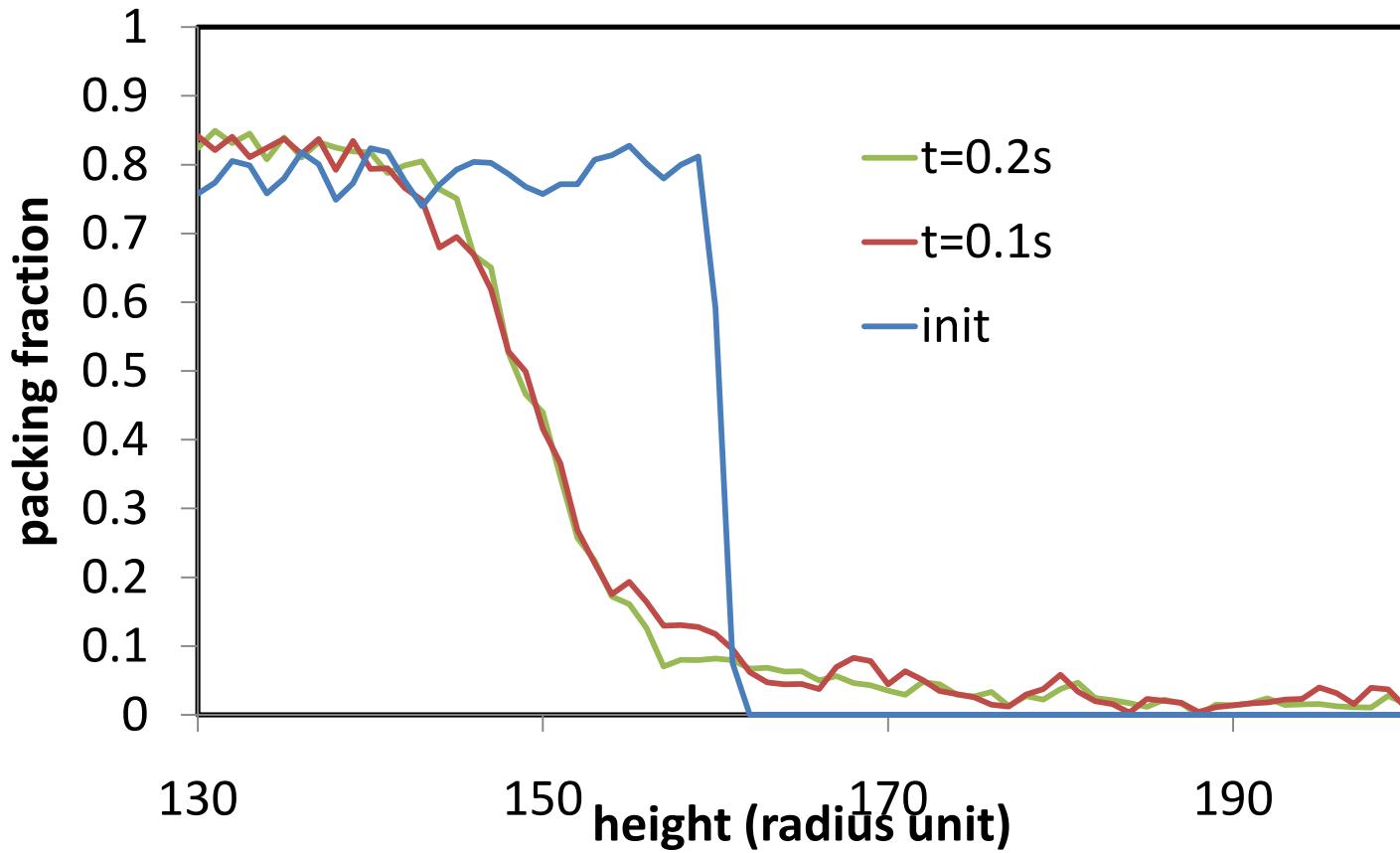
# Continuous movie of sequential shots



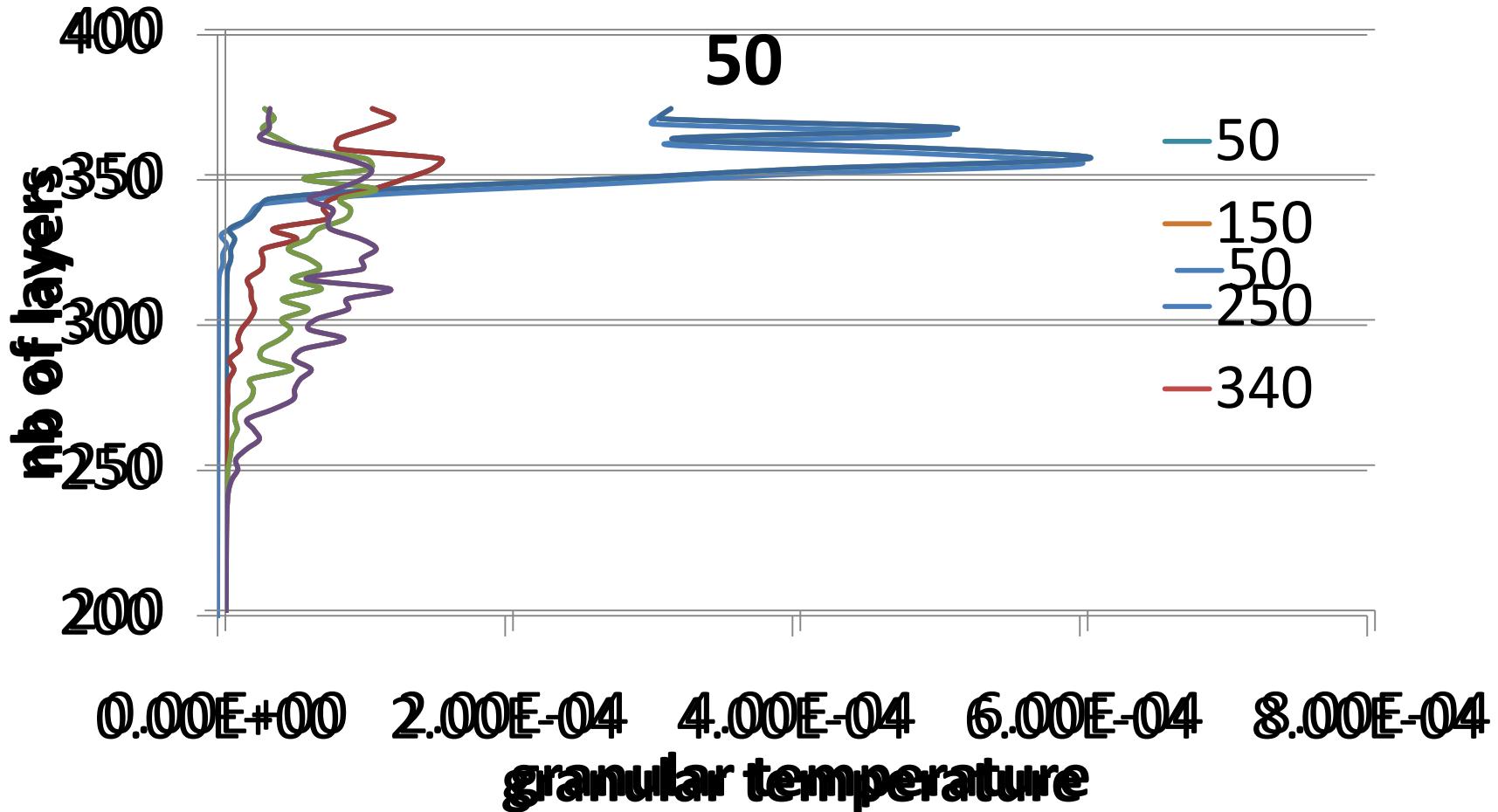
# Force network inside the bead bed



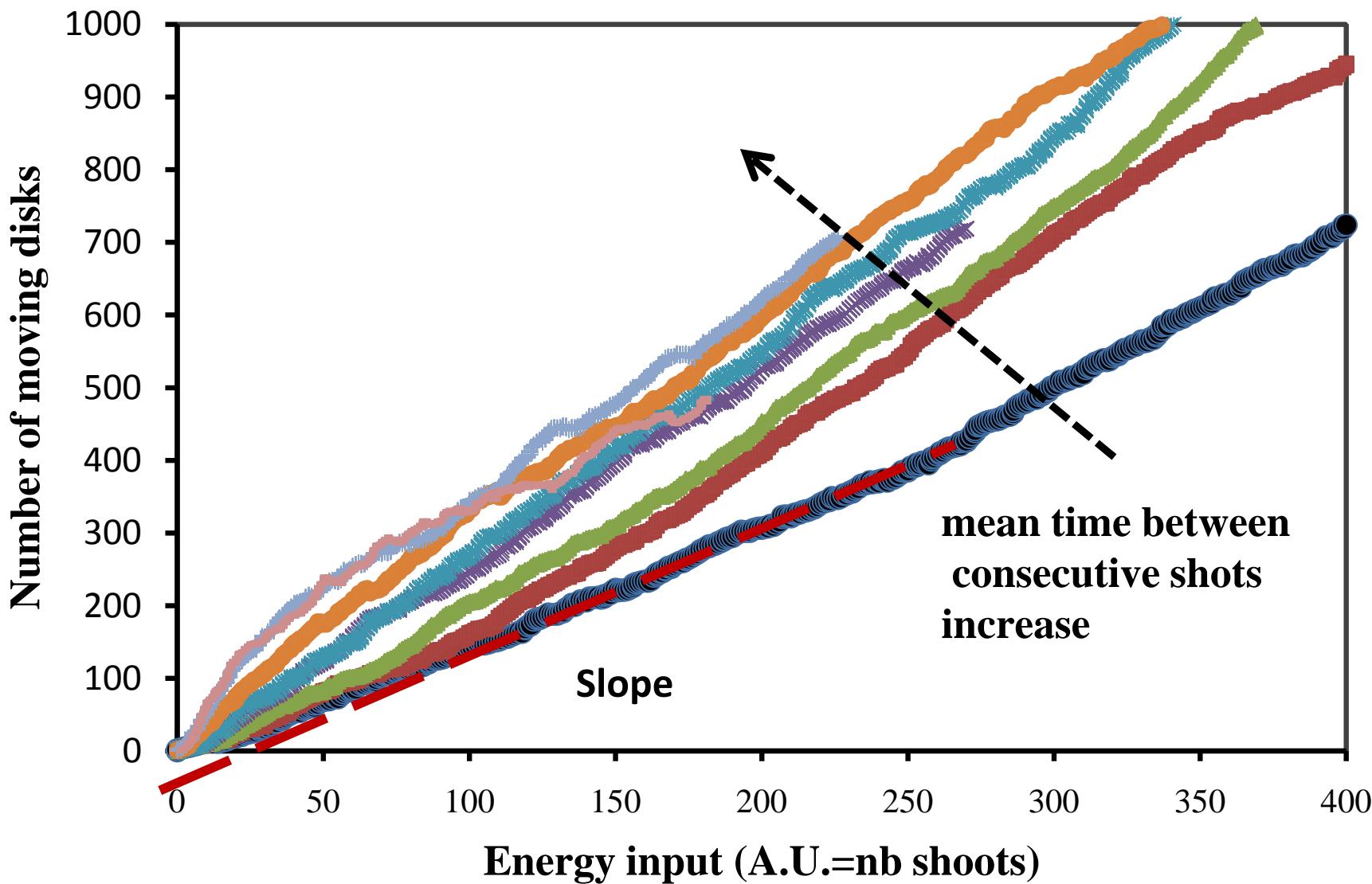
# Packing fraction



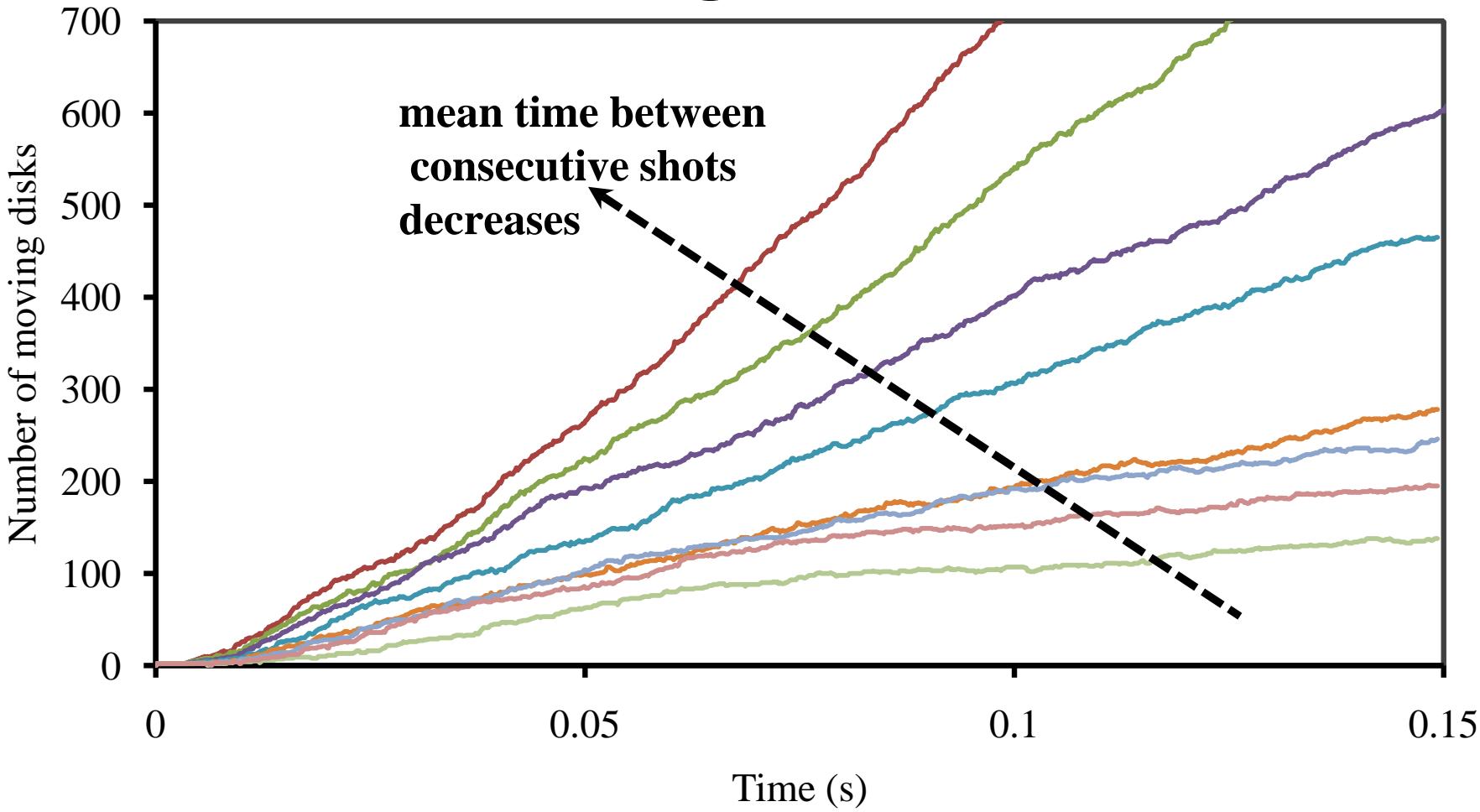
# Perturbated Layers



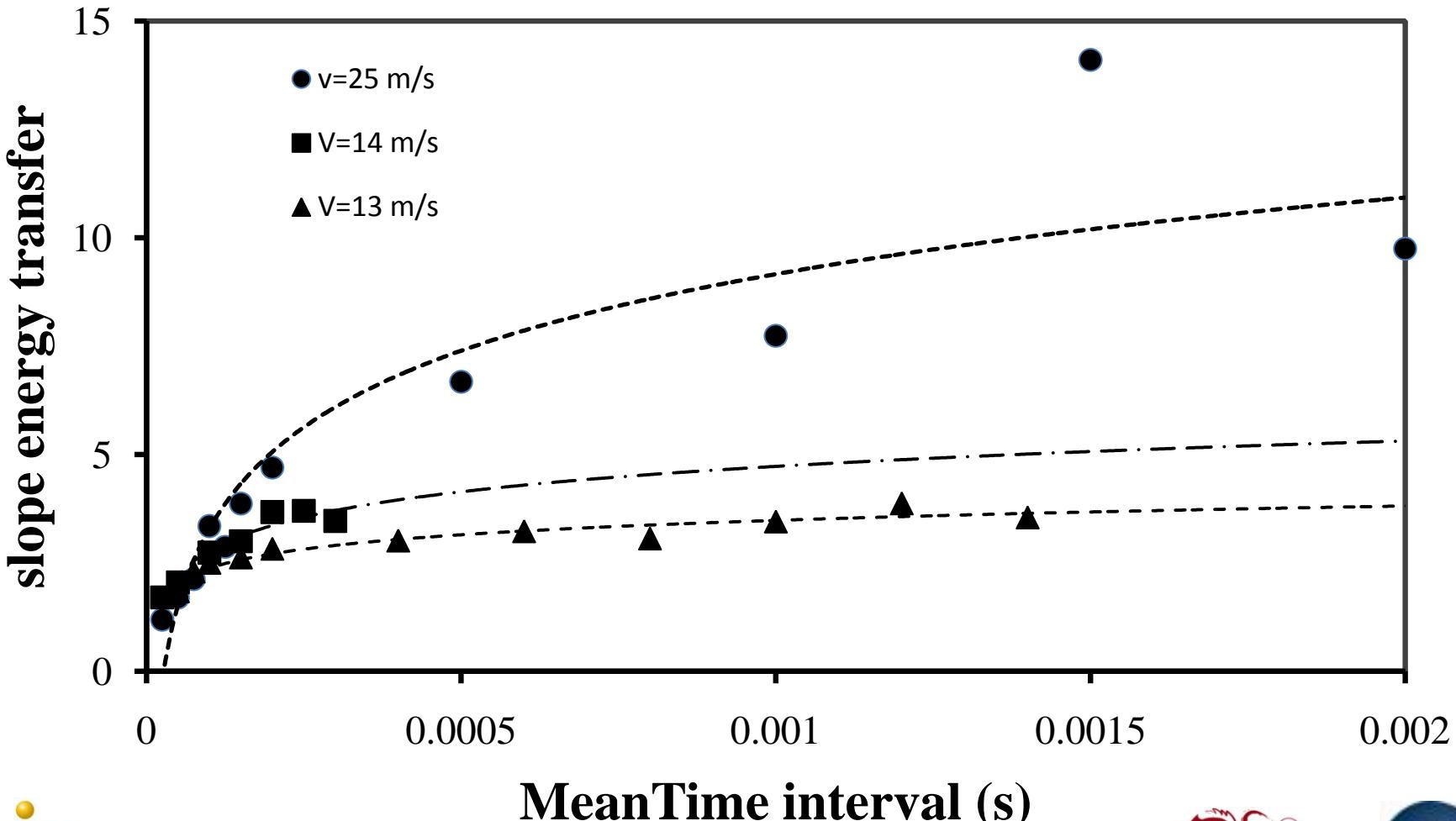
# Evolution of the moving disk amount



# Moving disks



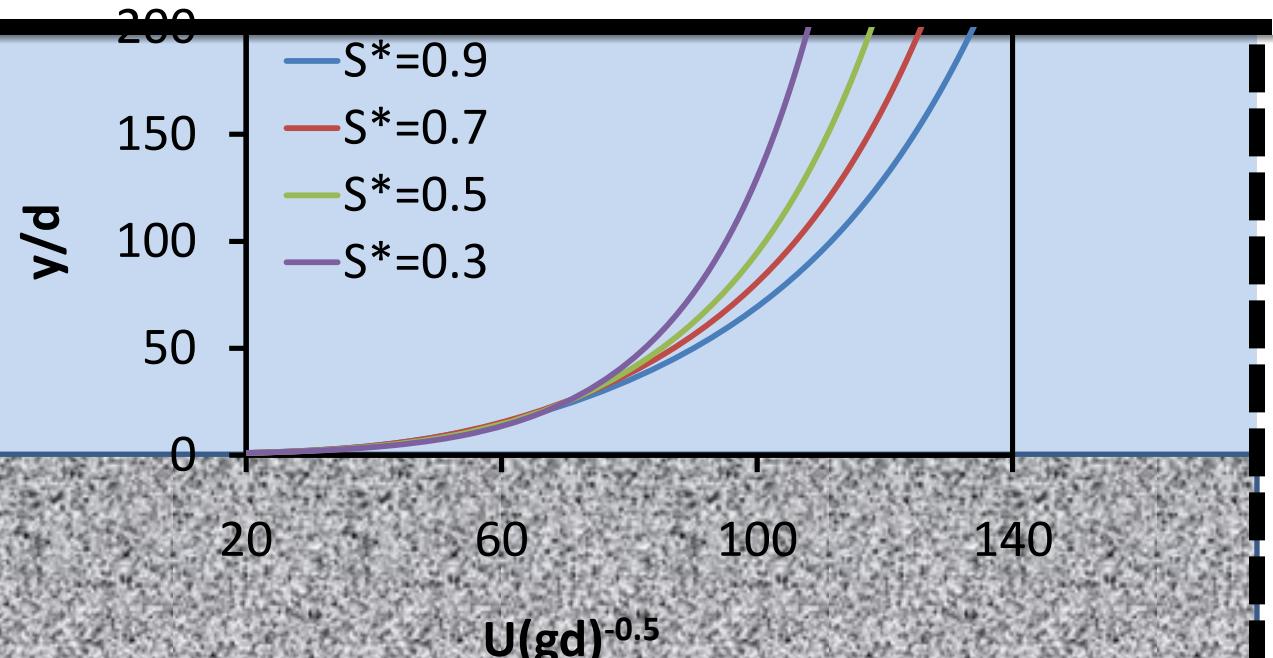
# Energy restitution efficiency



# §4: conclusions

- The analysis of the saltation process cannot be deduced from the classical results of the 3D “Splash function”
- The initial saltation process needs a large amount of energy to mobilize the upper layer of the dune
- The conservation of the moving saltation region needs less energy than the initiation regime

# §5: with wind interaction



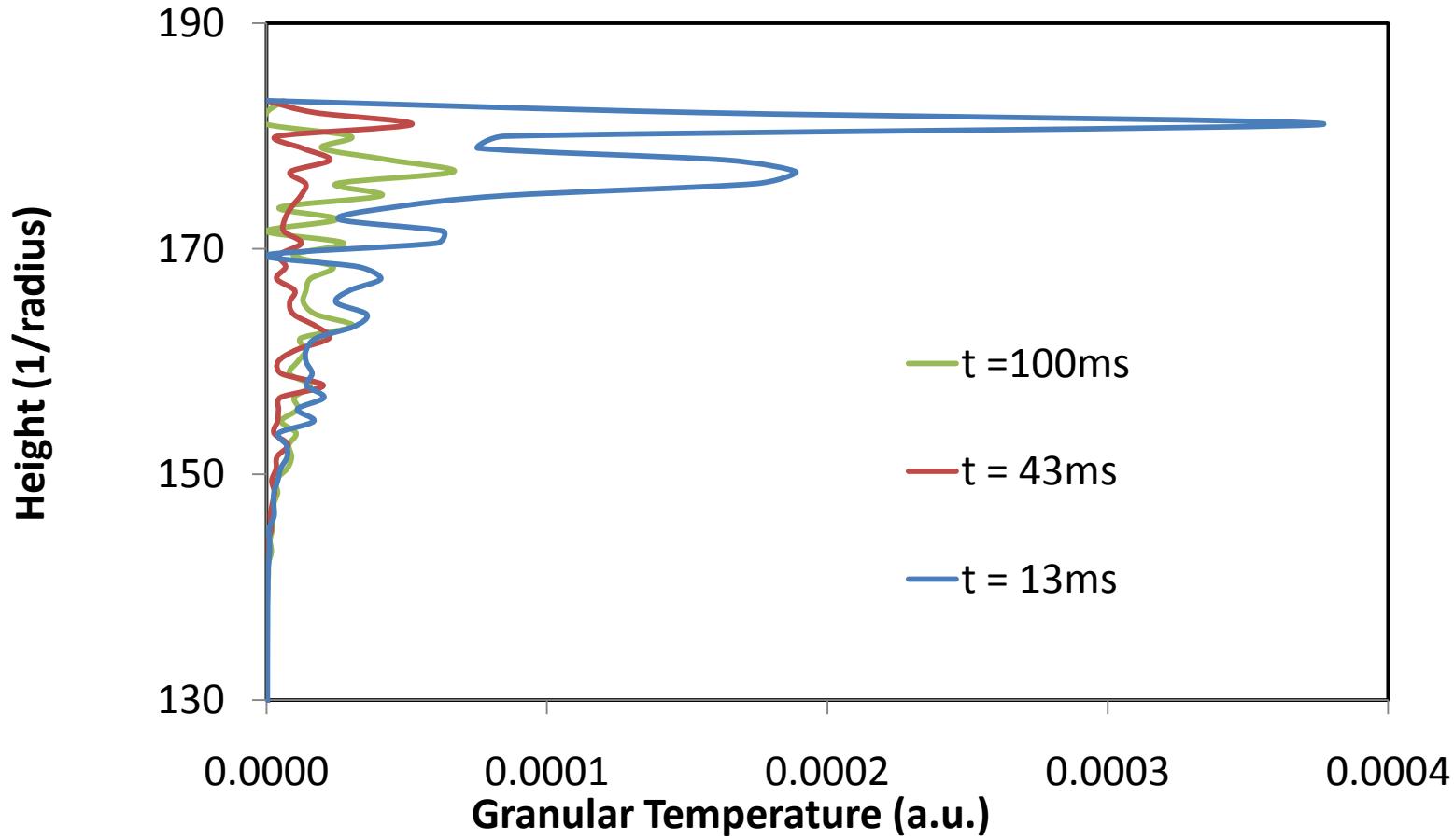
# Practical conditions

- Initial shot of N given disks at a given initial velocities and angles and variables time intervals.
- Given initial wind velocity profiles according to Creyssels et al (JFM 2010)

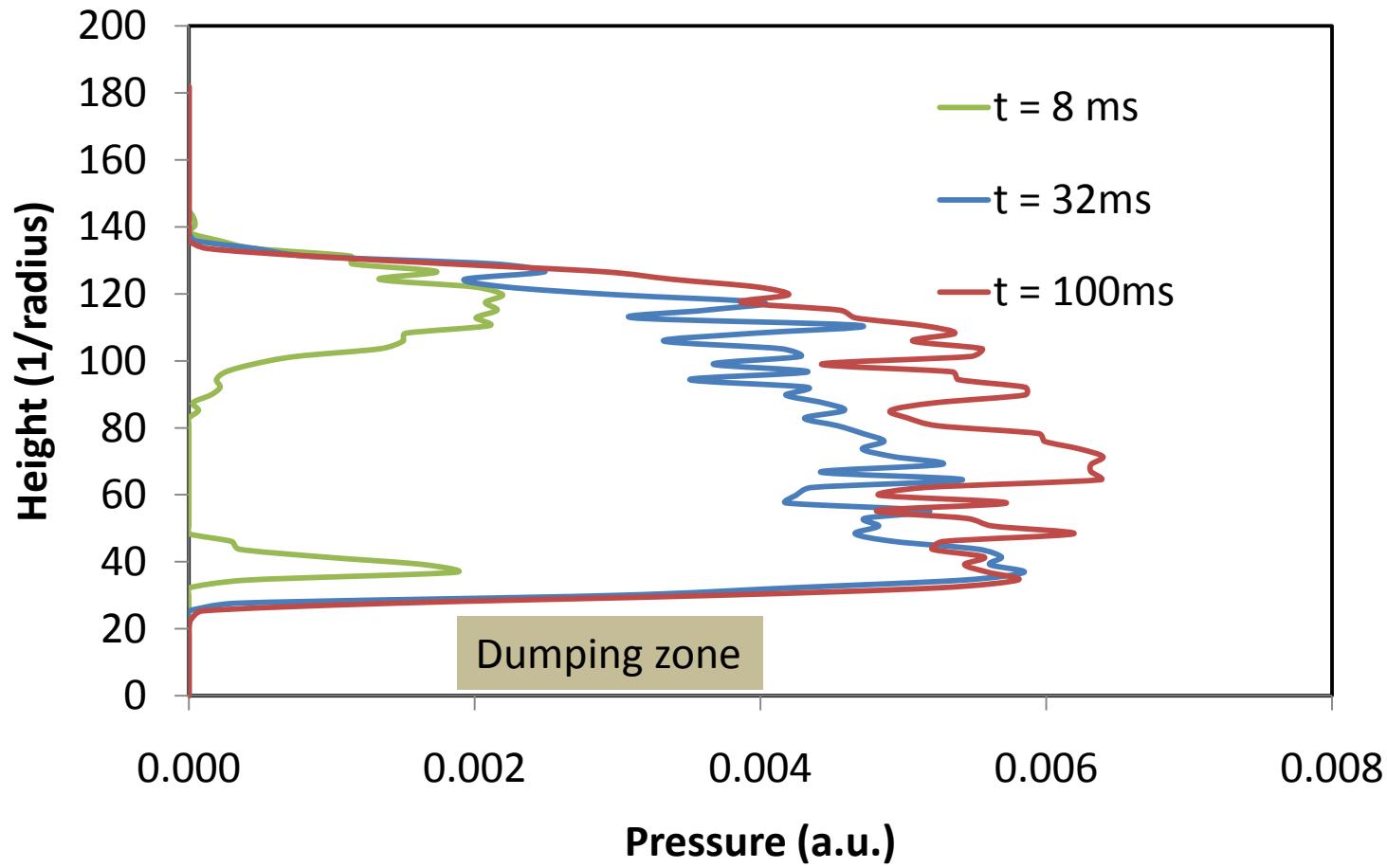
After a given number of time steps : equilibrium time

- calculus of the real grain pressure profile
- Wind velocities profiles according to the grain pressure

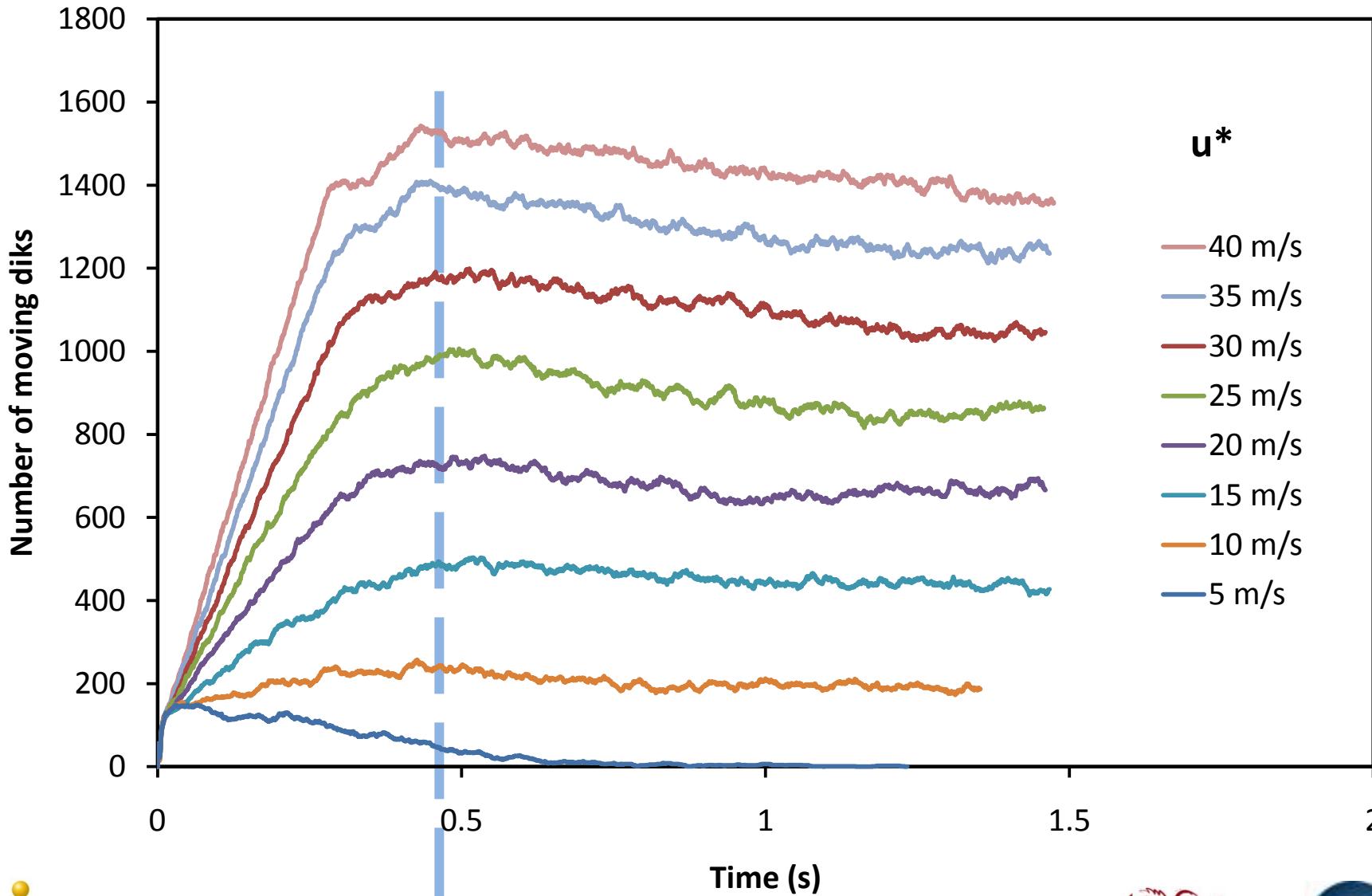
# Granular temperature



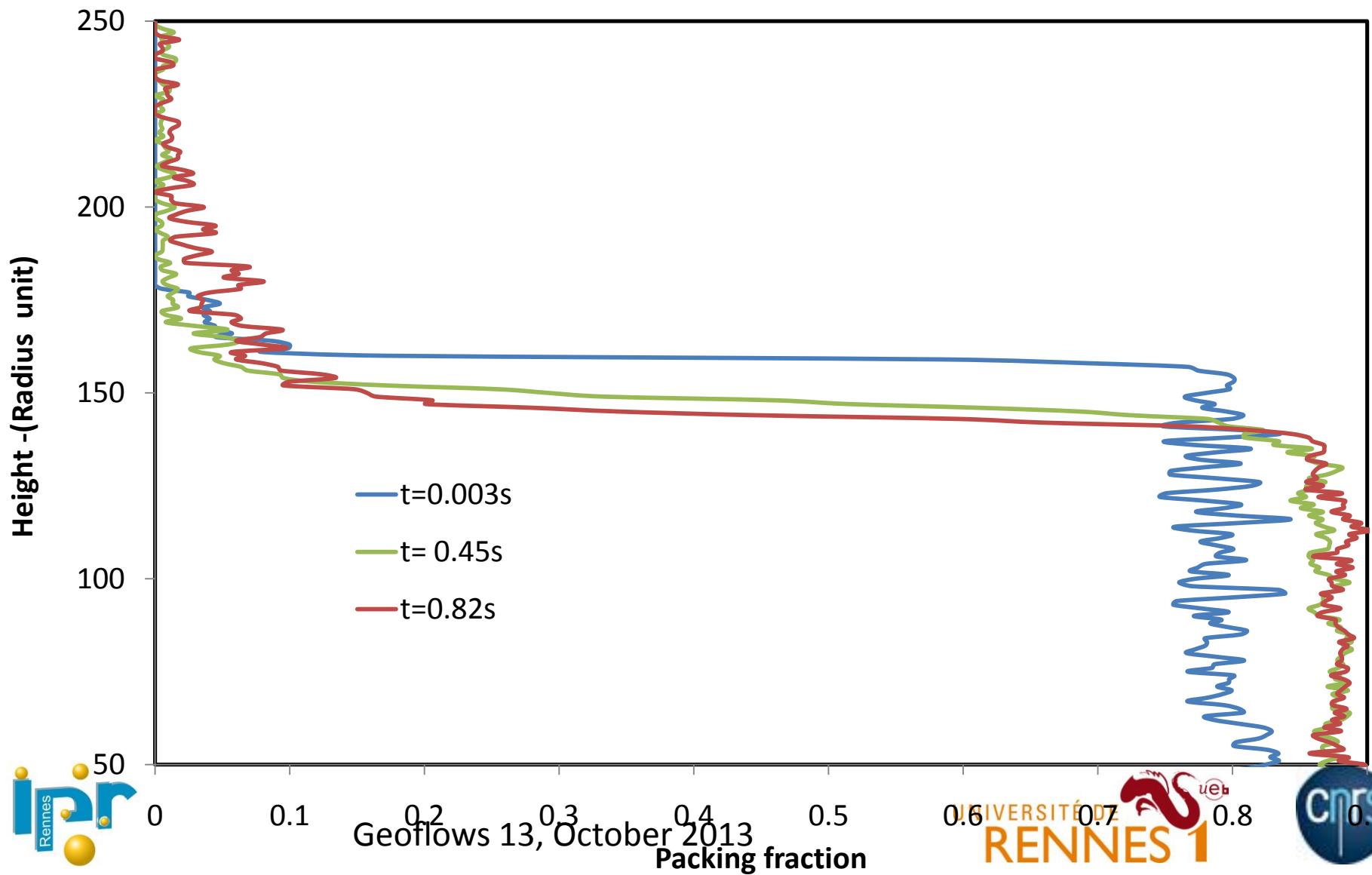
# Pressure vs height



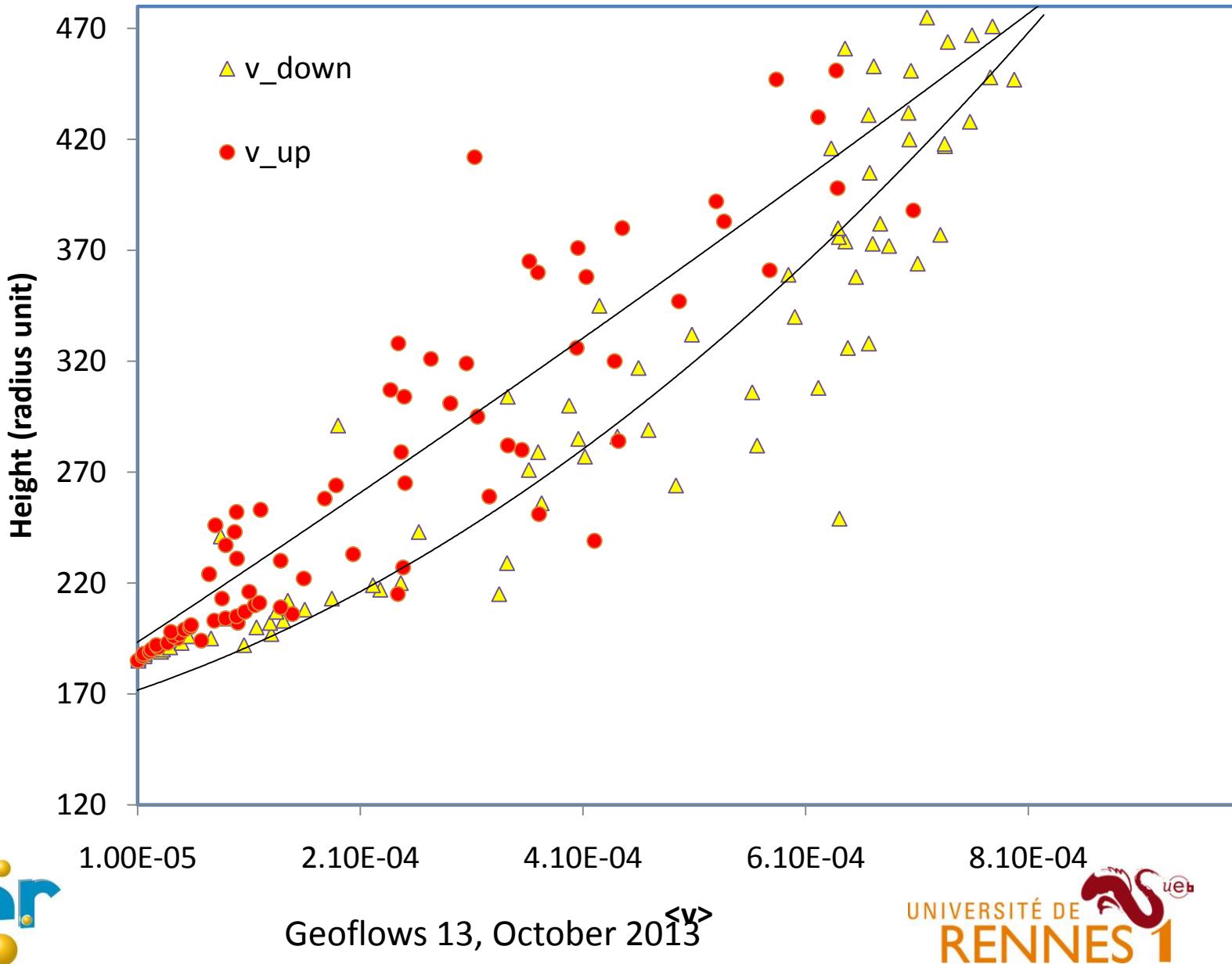
# Constant wind velocity profile



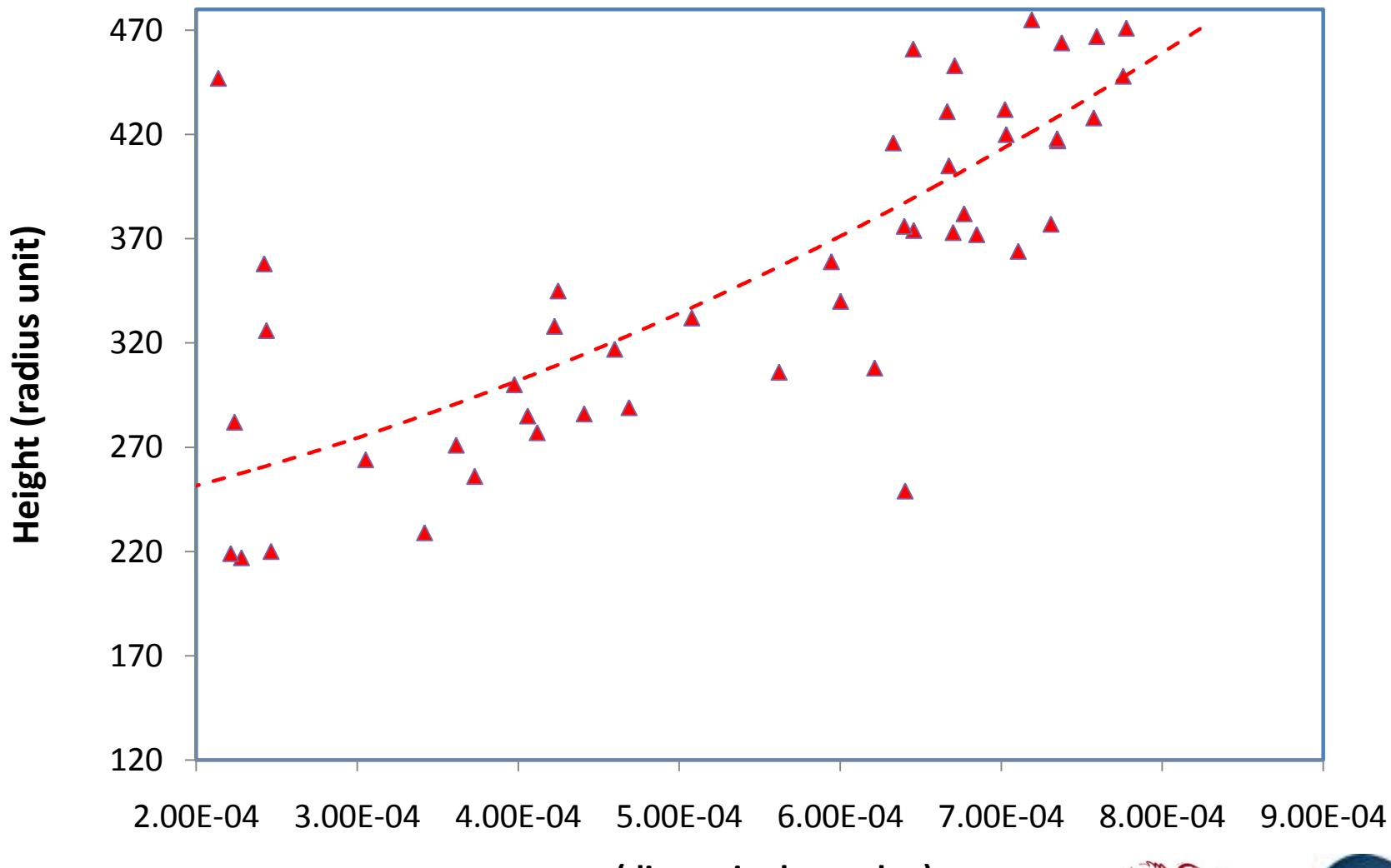
# Profile at different times



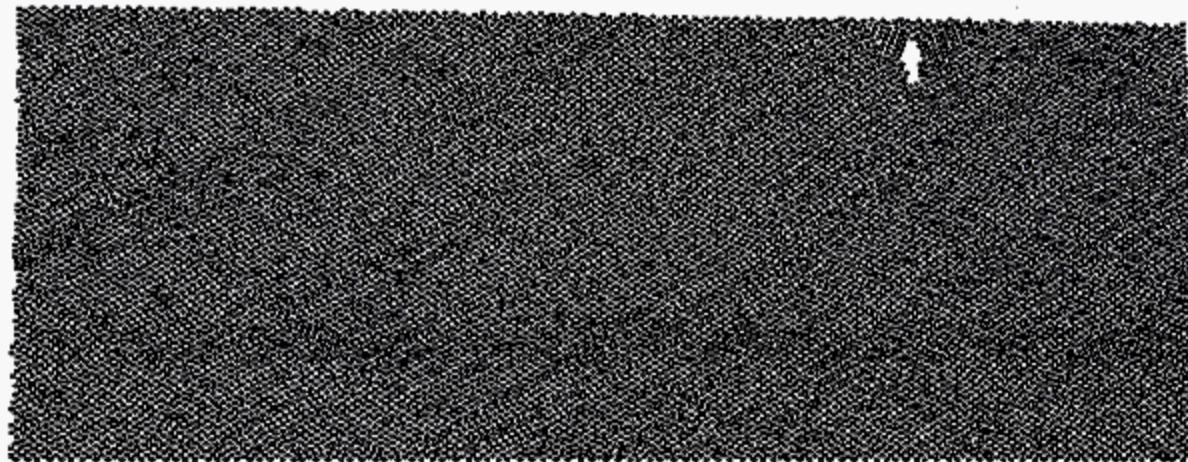
# $V_{\text{up}}$ & $V_{\text{down}}$ when stabilized



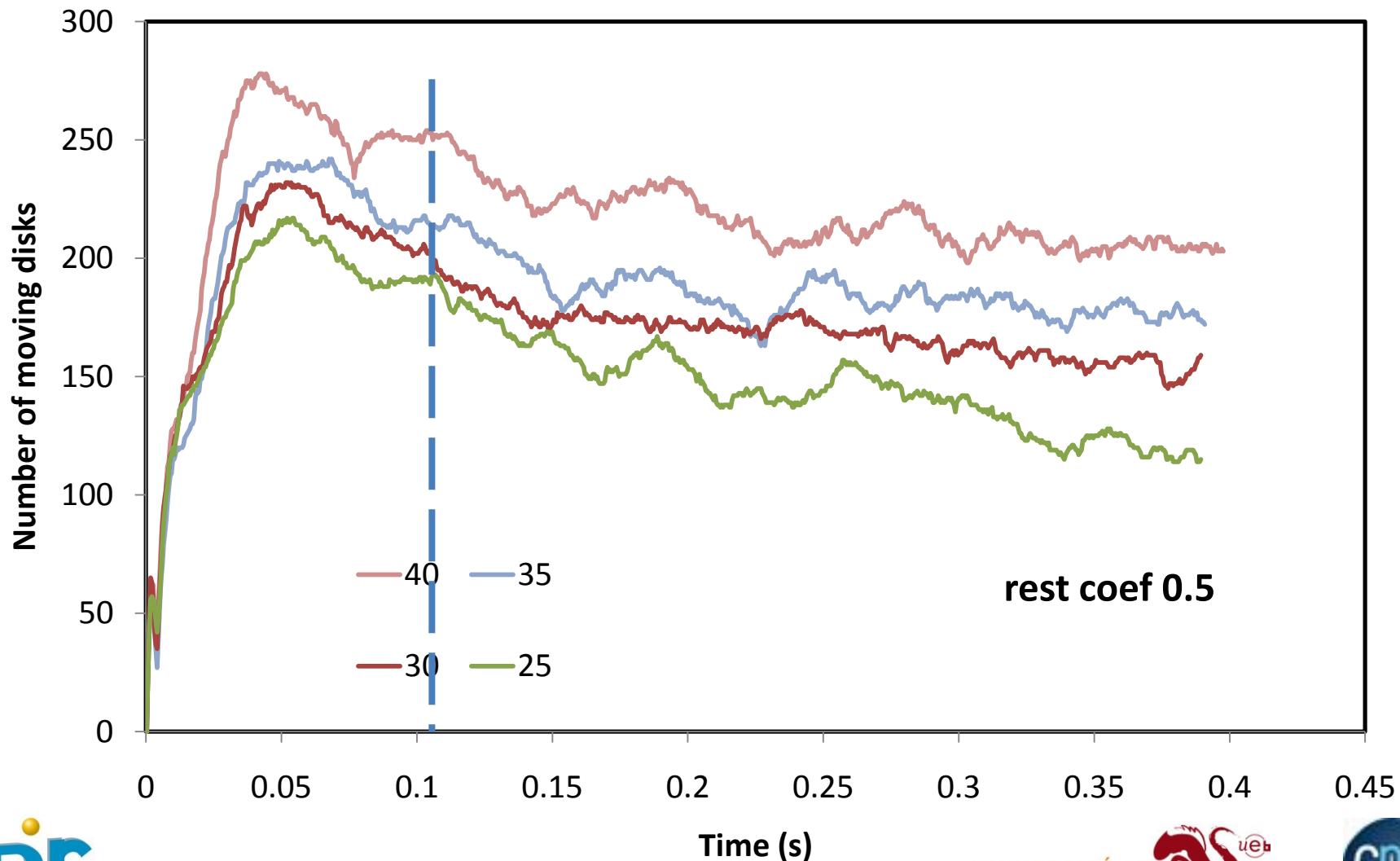
# Calculus of the pressure



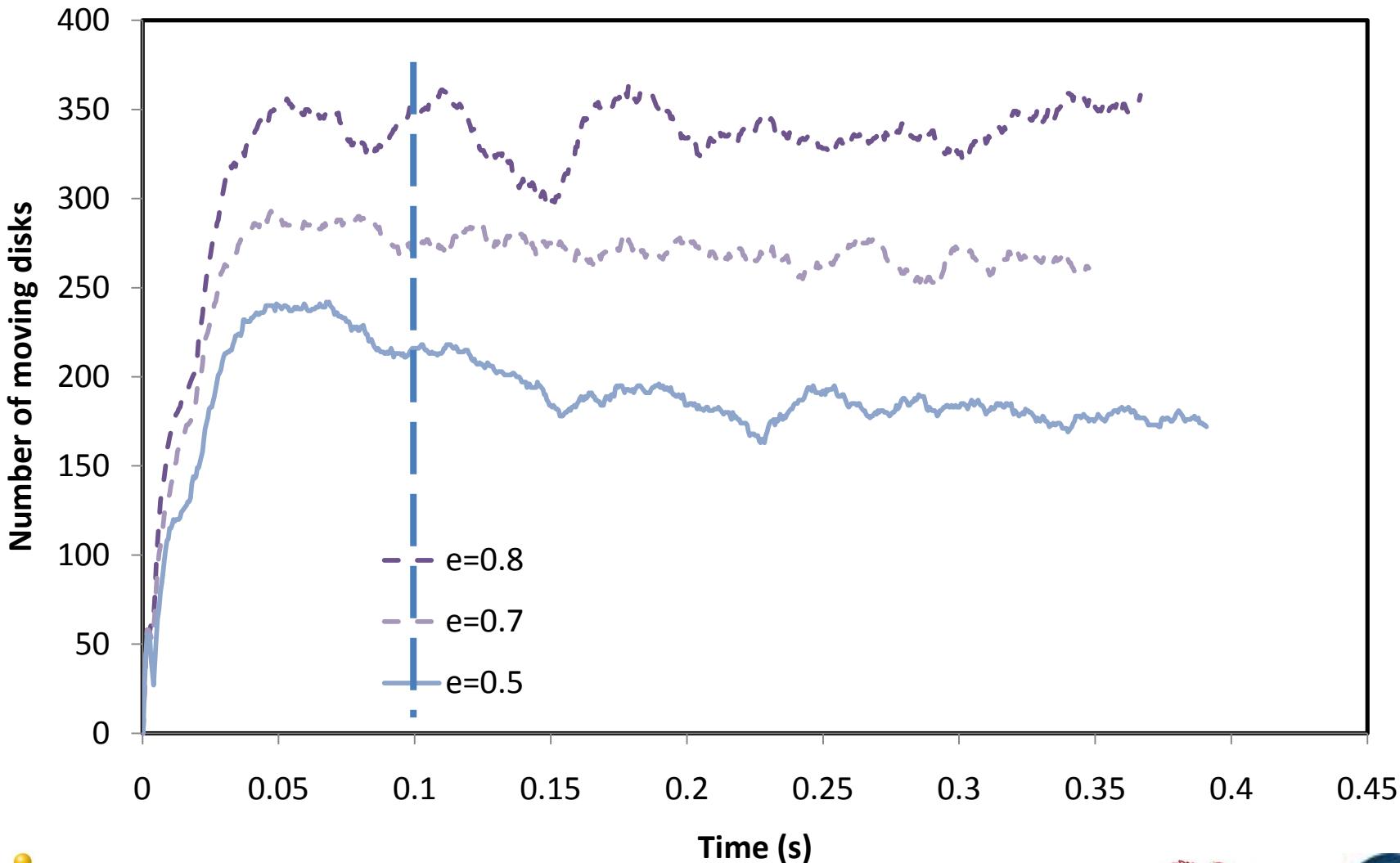
One full run for 16000 disks, restitution coefficient=0.4



# Variable wind velocities



# Variable restitution coefficient



# Conclusions

- The saltation process can be modeled from the classical DEM code with a simple wind grain interaction and no artificial parameters.
- The initial saltation process needs 'some' energy to mobilize the upper layer of the dune but the conservation of the moving saltation region can be controlled classically by the grain characteristics and the wind velocities.
- Improvements : local calculi of the wind profile

# Conclusions for §3-5

- Good correspondence between experimental and numerical results are possible
- We can and we do use the real mechanical and physical parameters of our granular problems to make a correct numerical and experimental comparisons
- some improvements can be made by adding extra effects such as :
  - Humidity
  - Electrostatic forces
  - roundness of the grains (rolling resistance)
  - and so on...