

## Motivation

- Large excitement for machine learning in particle physics:
- Particle tagging / signal selection
- Low level reconstruction / calibration
- Simulation
... and many more

GK, Plehn (eds), et al, The Machine Learning Landscape ofTop Taggers,


## Two* types of problem:

## Supervised Learning

Attempt to infer some target (truth label): classification (jet flavour tagging) or regression (energy calibration)

Use training data with known labels (often from Monte Carlo simulation)


## Unsupervised

No target, learn the probability distribution (directly from data)


## Maximize likelihood $\mathbf{p}(\mathbf{X})$ (minimize -log $\mathbf{p ( x ) )}$

> *There also exists a number of other less-than-supervised approaches (weakly supervised learning, semi-supervised learning, ...) Not so important for now.

## Supervised

Most early works fall under this category.
Crucially important for large number of tasks.

Need:

- Higger accuracy (easy to measure, many results)
- Better stability (domain adaptation issue)
- More control over uncertainties
- Resource efficient implementations
- Experimental integration



## Unsupervised

Exciting space for developing new ideas (also including all other forms of less-than-supervised learning).


Anomaly Searches

## Physics Motivation

- Theoretical and experimental reasons to expect new physics beyond the Standard Model
- However, only negative results in searches
- Make sure that we do not miss potential discoveries at the LHC:
Supplement traditional searches with model-independent* anomaly searches
*Tricky term, will discuss meaning of model-independence later

Why are neutrinos massive?

What is the nature of dark matter \& dark energy?


Why is there more matter than anti-matter?

Why is there more matter than antimatter?

How can the Higgs boson be light when the

What are the details of cosmic inflation? mass receives large quantum corrections?

# Dissecting the problem 

- Zero: What are anomalies
- First: Build an anomaly scoring function $\mathbf{a}(X)$
- Second: Design analysis strategy
- Third: Interpret result


## What is an anomaly?



## Point anomaly

- Outliers: Datapoints far away from regular distribution
- Examples:
- Background free searches (e.g. long lived particles)
- Detector malfunctions


And now?


## Group anomaly



## Group anomaly

$\stackrel{1}{5}$
0
0

- Individual examples not anomalous, but interesting collective behaviour
- Examples:
- New physics searches, e.g. resonances



## How to build anomaly score?

- Anomaly score a should be high for anomalous (signal-like)
and low for background-like events
- Some options:
- $a(x)=$ (Semi-) Supervised


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and low for background-like events
- Some options:
- $\mathbf{a}(x)=$ (Semi-) Supervised
- Train binary classifier network (using simulation) to discriminate:
- Standard Model background vs
- Cocktail of new physics models
- Pros:
- Close to known methods, simple training
- Clear trade-off: width vs sensitivity
- Cons:
- Ambiguity on mixture choice
- Needs to account for residual difference between data/simulation


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- Some options:
- $a(x)=$ (Semi-) Supervised
- $a(x)=I / p(x \mid$ Background $)$ (from simulation)
- Systematically look for differences between background simulation and data
- MUSIC / General search



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- Systematically look for differences between background simulation and data
- MUSIC / General search
- Use histograms of many variables in many dimensions to estimate
- Potentially also improve via ML
- Pros:
- Very signal model independent
- Already delivering results
- Cons:
- Strongly depends on background simulation
- Large penalty from many histogram bins


## How to build anomaly score?

- Anomaly score a should be high for anomalous (signal-like)
and low for background-like events
- Some options:
- Search differences between different phase space regions in data
- Show example using autoencoders
- $a(x)=$ (Semi-) Supervised
- $\mathbf{a}(\mathbf{x})=\mathbf{I} / \mathbf{p}(\mathbf{x} \mid$ Background $)$
(from simulation)
(from data)


## Example:Autoencoder



Input data e.g. images, high level observables, four vectors

$$
\begin{array}{r}
\mathcal{L}(x)=\left\|x-g_{\theta}\left(f_{\phi}(x)\right)\right\|_{2} \\
a(x)=\mathcal{L}(x)
\end{array}
$$

- Core idea:
- Train lossy compression algorithm on anomaly-free data (minimise L)
- Apply to data containing potential anomalies
- Expect quality to decrease for atypical examples:
anomaly score


## Apply to jet images



- Represent data as images
- Boosted top vs QCD jets ( $\sim 600 \mathrm{GeV}$ ) I jet = I image (40x40 pixels, color=energy)
- Train QCD only sample
- Evaluate on mixed top/QCD jet sample - Tops detected as anomaly

Heimel, GK, Plehn, Thompson, QCD or What?, I808.08979
Farina, Nakai, Shih, Searching for New Physics with Deep Autoencoders, I808.08992


## Limitations

## Complexity

- If anomalies are much simpler (therefore easier to reconstruct):
$a(x)$ will still be lower, despite never encountered in training
- Observed with naive AE in QCD vs top
- Train on tops only; top still considered anomaly wrt/ QCD




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- Train on tops only; top still considered anomaly wrt/ QCD

Hope that this can be overcome with alternative AE trainings: Stay tuned for update by Heidelberg group using mixture model latent space!

## Mostly QCD for training



Mostly top for training
s by Barry
Dillon et al

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## Complexity

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- Train on tops only; top still considered anomaly wrt/ QCD

Hope that this can be overcome with alternative AE trainings: Stay tuned for update by Heidelberg group using mixture model latent space!

## Topology

- Additional potential difficulty if data space has a non-trivial global topology. See 2102.08380 for more


## Mostly QCD for training



## Brief aside on generative models: Variational autoencoder



- The decoder maps a latent space distribution X' to realistic examples
- Control over latent space:
- Decode X' to generate new examples
- Achieve by:
- Make X' Gaussian, encoder learns paramaters $\mu, \sigma$
- Add term to loss so that $(\mu, \sigma)$ approach standard normal $(0,1)$


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- $\mathbf{a}(\mathbf{x})=\mathrm{I} / \mathrm{p}(\mathbf{x} \mid$ Background $)$
(from simulation)
(from data)
- Search differences between different phase space regions in data
- Show example using autoencoders
- Pros:
- Relatively signal model independent
- Intuitive to construct and train
- Cons:
- Little control over sensitivity
- Some model assumptions needed for construction


## How to build anomaly score?

- Anomaly score a should be high for anomalous (signal-like)
and low for background-like events
- Some options:
- $a(x)=$ (Semi-) Supervised
- $a(x)=I / p(x \mid$ Background $)$
(from simulation)
(from data)
$\bullet a(x)=p(x \mid$ Signal $) / p(x \mid$ Background $)$
- Systematically look for differences between different phase space regions in data
- Show two examples:
- Mixed sample training


## Sideband approach

## Key assumptions:

- There exists one feature so that:
- Background distribution is smooth
- Signal distribution is localised (and very small wrt/ background)


- Use sidebands to train anomaly score.
- Test signal region for new physics.
- Scan over different signal regions (trial factor)
- (Other ways to define anomaly-free regions in data possible as well. Not thoroughly explored yet)


## Example: Mixed Sample training (aka CWola hunting)



$$
L_{M_{1} / M_{2}}=\frac{p_{M_{1}}}{p_{M_{2}}}=\frac{f_{1} p_{S}+\left(1-f_{1}\right) p_{B}}{f_{2} p_{S}+\left(1-f_{2}\right) p_{B}}=\frac{f_{1} L_{S / B}+\left(1-f_{1}\right)}{f_{2} L_{S / B}+\left(1-f_{2}\right)}
$$

- Distinguishing mixed samples is equivalent to signal/ background classification assuming
- Signal/background in both mixed samples are from same source
- Sufficiently different mixed samples
- Translated to anomaly detection:
- Train to distinguish signal region and sideband

Metodiev, Nachman, Thaler, Classification without labels: Learning from mixed samples in high energy physics, 1708.02949
Collins, Howe, Nachman, Anomaly Detection for Resonant New
Physics with Machine Learning, I 805.02664

- Only use inputs independent of variable used to define these regions


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(from simulation)
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- $\mathbf{a}(\mathbf{x})=\mathbf{p}(\mathbf{x} \mid$ Signal $) / \mathbf{p}(\mathbf{x} \mid$ Background $)$
- Systematically look for differences between different phase space regions in data
- Show two examples:
- Mixed sample training
- density estimation
- Pros:
- Relatively signal model independent
- Cheap to train
- Cons:
- Sensitive to correlations
- Some model assumptions needed for construction


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- Show two examples:
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- density estimation


## Example: Density Estimation

Per Neyman-Pearson: Likelihood-ratio is optimal test statistic
Unfortunatly, $p(x \mid a n o m a l y)$ is not available

$$
L_{S / B}=\frac{p(x \mid \text { anomaly })}{p(x \mid \text { normal })}
$$

## Example: Density Estimation

Per Neyman-Pearson: Likelihood-ratio is optimal test statistic
Unfortunatly, $p(x \mid a n o m a l y)$ is not available

Build data/background ratio:

$$
\begin{aligned}
L_{S / B} & =\frac{p(x \mid \text { anomaly })}{p(x \mid \text { normal })} \\
L_{D / B} & =\frac{p(x)}{p(x \mid \text { normal })}
\end{aligned}
$$

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$$

$$
L_{D / B}=\frac{p(x)}{p(x \mid \text { normal })}
$$

Approximate background density using control measurement (e.g. sideband)

$$
L_{D / B} \approx \frac{p(x)}{\tilde{p}(x \mid \text { normal })}
$$

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$$

Expand $\quad p(x)=f_{\text {normal }} p(x \mid$ normal $)+f_{\text {anomaly }} p(x \mid$ anomaly $)$

## Example: Density Estimation

Per Neyman-Pearson: Likelihood-ratio is optimal test statistic
Unfortunatly, $p(x \mid a n o m a l y)$ is not available
Build data/background ratio:

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L_{S / B}=\frac{p(x \mid \text { anomaly })}{p(x \mid \text { normal })}
$$

$$
L_{D / B}=\frac{p(x)}{p(x \mid \text { normal })}
$$

Approximate background density using control measurement (e.g. sideband)

$$
L_{D / B} \approx \frac{p(x)}{\tilde{p}(x \mid \text { normal })}
$$

Expand $\quad p(x)=f_{\text {normal }} p(x \mid$ normal $)+f_{\text {anomaly }} p(x \mid$ anomaly $)$
And insert: $\quad L_{D / B} \approx f_{\text {normal }}+f_{\text {anomaly }} \frac{p(x \mid \text { anomaly })}{\tilde{p}(x \mid \text { normal })}$

## Example: Density Estimation

Per Neyman-Pearson: Likelihood-ratio is
optimal test statistic
Unfortunatly, p(x|anomaly) is not available

$$
L_{S / B}=\frac{p(x \mid \text { anomaly })}{p(x \mid \text { normal })}
$$

- Data-Background likelihood is monotonous to Signal-Background likelihood if we can approximate background.
- We can use this to construct an anomaly score

And instert:

$$
L_{D / B} \approx f_{\text {normal }}+f_{\text {anomaly }} \frac{p(x \mid \text { anomaly })}{\tilde{p}(x \mid \text { normal })}
$$

## Normalising Flows

- Goal: assign probability density to each datapoint
- Learn bijective transformation between data and a latent space with tractable probability
- Build from simple invertible transformations, tractable Jacobian

$$
\begin{array}{r}
p(\boldsymbol{x})=p\left(\boldsymbol{f}^{-1}(\boldsymbol{x})\right) \prod_{i}\left|\operatorname{det}\left(\frac{\partial \boldsymbol{f}_{i}^{-1}}{\partial \boldsymbol{x}}\right)\right|= \\
p(\boldsymbol{u}) \prod_{i}\left|\operatorname{det}\left(\frac{\partial \boldsymbol{f}_{i}}{\partial \boldsymbol{u}}\right)\right|^{-1}
\end{array}
$$

Generate new samples


Evaluate probability/likelihood, train flow

## ANODE

- Use Masked Autoregressive Flow (I705.07057) to learn p (easy to invert NN with simple Jacobian)
- Compare extrapolated and in-region probability densities
- $a(x)=R(x \mid m)=$ ratio of densities $=L_{D / B}$


Nachman, Shih, Anomaly Detection with
Density Estimation, 2001.04990 $\mathrm{m}_{\mathrm{ij}}$ [TeV]
Thanks to T. Loesche


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- Systematically look for differences between different phase space regions in data
- Show two examples:
- Mixed sample training
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- Pros:
- Relatively signal model independent
- Powerful
- Cons:
- Expensive to train
- Some model assumptions needed for construction


## Moving on

- Many strategies exist to construct anomaly scores
- $\mathrm{a}(\mathrm{x})=$ " $\mathrm{p}(\mathrm{x} \mid$ Signal $)$ " $\rightarrow$ Semi-Supervised Cocktails
- $\mathrm{a}(\mathrm{x})=\mathrm{I} / \mathrm{p}(\mathrm{x} \mid$ Background $) \rightarrow$ General Search, Autoencoders
- $a(x)=p(x \mid$ Signal $) / p(x \mid$ Background $) \rightarrow$ CWoLA, Density Estimation
- How can we use them in a search?


## Application:ATLAS Di-Jet Search

- ATLAS carried out a search following CWoLa approach
- $A \rightarrow B C$ resonance search no assumption on masses of $\mathrm{A}, \mathrm{B}, \mathrm{C}$
- Resonance search in di-jet invariant mass using $R=1.0$ jets for $B, C$
- Split spectrum into discrete signal regions
- Use CWola method, cut on $10 \%$ and I\% most anomalous events
- Fit spectrum from sidebands
- Interpret results in W' model



## General

## Simulation Driven

- Similar to classical analyses
- high signal model independence
- downside of data/simulation difference


## Data Driven

- Straightforward idea to combine with bump hunt (see ATLAS example)
- Other data-driven techniques (ABCD?) should be possible as well, currently less explored
- Big advantage of data-only search:

No systematic uncertainties
(except background estimation from data)


## How to interpret results?

## Positive Result (some anomaly found)

## Negative Result (no anomaly found)

- Characterise what we found.
- Of course, can compare with different models and see which one fits.
(Also test for detector effects, of course)
- Ideas to systematise this needed
- Publish events?
- Need to interpret resulting exlusion
- Of course, can run different models and test (systematic uncertainties enter here!)
- Again, strategy for interpretation needed. Publish anomaly score for recasting?


21 high level observables as input

## Aside:Trigger

- Consider anomaly detection for CMS/ATLAS triggers
- Strategy: (Variational) autoencoder trained on SM cockatail


Cerri, Nguyen, Pierini, Spiropulu, Vlimant, Variational Autoencoders for New Physics Mining at the Large Hadron Collider,

## Advertisment

## The LHC Olympics 2020

A Community Challenge for Anomaly
Detection in High Energy Physics


Gregor Kasieczka (ed), ${ }^{1}$ Benjamin Nachman (ed), ${ }^{2,3}$ David Shih (ed), ${ }^{4}$ Oz Amram, ${ }^{5}$ Anders Andreassen, ${ }^{6}$ Kees Benkendorfer, ${ }^{2,7}$ Blaz Bortolato, ${ }^{8}$ Gustaaf Brooijmans, ${ }^{9}$ Florencia Canelli, ${ }^{10}$ Jack H. Collins, ${ }^{11}$ Biwei Dai, ${ }^{12}$ Felipe F. De Freitas, ${ }^{13}$ Barry M. Dillon, ${ }^{8,14}$ loan-Mihail Dinu, ${ }^{5}$ Zhongtian Dong, ${ }^{15}$ Julien Donini, ${ }^{16}$ Javier Duarte, ${ }^{17}$ D. A. Faroughy ${ }^{10}$ Julia Gonski, ${ }^{9}$ Philip Harris, ${ }^{18}$ Alan Kahn, ${ }^{9}$ Jernej F. Kamenik, ${ }^{8,19}$ Charanjit K. Khosa, ${ }^{20,30}$ Patrick Komiske, ${ }^{21}$ Luc Le Pottier, ${ }^{2,22}$ Pablo Martín-Ramiro, ${ }^{2,23}$ Andrej Matevc, ${ }^{8,19}$ Eric Metodiev, ${ }^{21}$ Vinicius Mikuni, ${ }^{10}$ Inês Ochoa, ${ }^{24}$ Sang Eon Park, ${ }^{18}$ Maurizio Pierini, ${ }^{25}$ Dylan Rankin, ${ }^{18}$ Veronica Sanz, ${ }^{20,26}$ Nilai Sarda, ${ }^{27}$ Uros̆ Seljak, ${ }^{2,3,12}$ Aleks Smolkovic, ${ }^{8}$ George Stein, ${ }^{2,12}$ Cristina Mantilla Suarez, ${ }^{5}$ Manuel Szewc, ${ }^{28}$ Jesse Thaler, ${ }^{21}$ Steven Tsan, ${ }^{17}$ Silviu-Marian Udrescu, ${ }^{18}$ Louis Vaslin, ${ }^{16}$ Jean-Roch Vlimant, ${ }^{29}$ Daniel Williams, ${ }^{9}$ Mikaeel Yunus ${ }^{18}$

Kasieczka, Nachman, Shih (eds), et al, The LHC
Olympics 2020:A Community Challenge for Anomaly
Detection in High Energy Physics, 2101.08320

- For more on anomaly detection see: https://indico.desy.de/e/anomaly2020
- Public datasets available: https://lhco2020.github.io/homepage/
- Community paper with $\sim 20$ methods



## Advertisment



## Closing

- Focused on new physics searches.

Anomaly detection also considered for data quality monitoring, detector control, computing monitoring

- Improve power of anomaly detectors
- Extends to higher number of features
- Beyond images / high-level observables
- How to properly encode normal physics / anomalous physics?
- Systematically understand sensitivity of different approaches
- Develop interpretation strategies
- Widely apply to experimental data


Thank you!

Backup

## MADE/MAF

- Masked Autoregressive flow (I502.03509/I705.07057)
- Start with fully connected network, but drop connections so output a_ / mu_j are only connected to input $x \_I, .,, x \_-1$
- Autoregressive: no dependence of early features on late features
- -> Jacobian is upper triangular matrix and easily invertible
- Combine multiple such blocks

$$
\begin{aligned}
& p(x)=\prod_{i} p\left(x_{i} \mid x_{1: i-1}\right) \\
& p\left(x_{i} \mid x_{1: i-1}\right)=\mathcal{N}\left(x_{i} \mid \mu_{i},\left(\exp \alpha_{i}\right)^{2}\right) \\
& \mu_{i}=f_{\mu_{i}}\left(x_{1: i-1}\right) \\
& \alpha_{i}=f_{\alpha_{i}}\left(x_{1: i-1}\right)
\end{aligned}
$$



# Unsupervised Learning for Fun and Precision <br> KITP - Precision21 <br> Anja Butter \& Gregor Kasieczka 

ITP, Universität Heidelberg

## Precision simulations with limited resources



[1807.11501] Cieri, Chen, Gehrmann, Glover, Huss

## Precision simulations with limited resources



ATLAS Preliminary
2020 Computing Model -CPU: 2030: Aggressive R\&D


## Speed $=$ Precision

## How can we boost MC simulations

- ML 2.0 Generative models
$\rightarrow$ Can we simulate new data?


| modular <br> speed up |
| :--- |


new concepts

## Boosting standard event generation...

1. Generate phase space points
2. Calculate event weight

$$
w_{\text {event }}=f\left(x_{1}, Q^{2}\right) f\left(x_{2}, Q^{2}\right) \times \mathcal{M}\left(x_{1}, x_{2}, p_{1}, \ldots p_{n}\right) \times J\left(p_{i}(r)\right)^{-1}
$$

3. Unweighting via importance sampling
$\rightarrow$ optimal for $w \approx 1$

## Boosting standard event generation...



## Boosting standard event generation...



## Boosting standard event generation...



## Boosting standard event generation...



## ... or training directly on event samples

## Event generation

- Generating 4-momenta
- $Z>I I, p p>j j, p p>t \bar{t}+$ decay
[1901.00875] Otten et al. VAE \& GAN
[1901.05282] Hashemi et al. GAN
[1903.02433] Di Sipio et al. GAN
[1903.02556] Lin et al. GAN
[1907.03764, 1912.08824] Butter et al. GAN
[1912.02748] Martinez et al. GAN
[2001.11103] Alanazi et al. GAN
[2011.13445] Stienen et al. NF
[2012.07873] Backes et al. GAN
[2101.08944] Howard et al. VAE


## Detector simulation

- Jet images
- Fast calorimeter simulation
[1701.05927] de Oliveira et al. GAN
[1705.02355, 1712.10321] Paganini et al. GAN
[1802.03325, 1807.01954] Erdmann et al. GAN
[1805.00850] Musella et al. GAN
[ATL-SOFT-PUB-2018-001, ATLAS-SIM-2019-004, ATL-SOFT-PROC-2019-007] ATLAS VAE \& GAN
[1909.01359] Carazza and Dreyer GAN
[1912.06794] Belayneh et al. GAN
[2005.05334, 2102.12491] Buhmann et al. VAE
[2009.03796] Diefenbacher et al. GAN
[2009.14017] Lu et al.

NO claim to completeness!

## Generative Adversarial Networks



Discriminator $\left[D\left(x_{r}\right) \rightarrow 1, D\left(x_{0}\right) \rightarrow 0\right]$

$$
L_{D}=\langle-\log D(x)\rangle_{x \sim P_{\text {Tuth }}}+\langle-\log (1-D(x))\rangle_{x \sim P_{\text {Gen }}} \rightarrow-2 \log 0.5
$$

Generator $\left[D\left(x_{0}\right) \rightarrow 1\right]$

$$
\begin{aligned}
L_{G}= & \langle-\log D(x)\rangle_{x \sim P_{G e n}} \\
& \Rightarrow \text { Nash Equilibrium } \\
& \Rightarrow \text { New statistically independent samples }
\end{aligned}
$$

## What is the statistical value of GANned events? [poososss)

- Camel function
- Sample vs. GAN vs. 5 param.-fit

Evaluation on quantiles:

$$
\mathrm{MSE}^{*}=\sum_{j=1}^{N_{\text {quant }}}\left(p_{j}-\frac{1}{N_{\text {quant }}}\right)^{2}
$$



## What is the statistical value of GANned events? [poososss)

- Camel function
- Sample vs. GAN vs. 5 param.-fit

Evaluation on quantiles:

$$
\mathrm{MSE}^{*}=\sum_{j=1}^{N_{\text {quant }}}\left(p_{j}-\frac{1}{N_{\text {quant }}}\right)^{2}
$$


$\rightarrow$ Amplification factor 2.5

$$
\text { Sparser data } \rightarrow \text { bigger amplification }
$$

## How to GAN LHC events ${ }_{[1907.0364]}$

- $t \bar{t} \rightarrow 6$ quarks
- 18 dim output
- external masses fixed
- no momentum conservation

+ Flat observables $\checkmark$
- Systematic undershoot in tails [10-20\% deviation]



## Special features



## Solution: MMD kernel

$$
\mathrm{MMD}^{2}\left(\mathrm{P}_{T,} \mathrm{P}_{G}\right)=\left\langle k\left(x, x^{\prime}\right)\right\rangle_{x, x^{\prime} \sim P_{T}}+\left\langle k\left(y, y^{\prime}\right)\right\rangle_{y, y^{\prime} \sim P_{G}}-2\langle k(x, y)\rangle_{x \sim P_{T, y} \sim P_{G}}
$$

## Correlations



## Correlations




## Reaching precision (preliminary)

1. Representation $p_{T}, \eta, \phi$

$$
\text { W + } 2 \text { jets }
$$

2. Momentum conservation
3. Resolve $\log p_{T}$
4. Regularization: spectral norm
5. Batch information
$\rightarrow 1 \%$ precision $\checkmark$

Next step automization


## Information in distributions



## The unweighting bottleneck

- High-multiplicity / higher-order $\rightarrow$ unweighting efficiencies $<1 \%$
$\rightarrow$ Simulate conditions with naive Monte Carlo generator ME by Sherpa, parton densities from LHAPDF, Rambo-on-diet

$$
p p \rightarrow \mu^{+} \mu^{-} \text {with } m_{\mu \mu}>50 \mathrm{GeV}
$$


$\rightarrow$ unweighting efficieny $0.2 \%$

## Training on weighted events

Information contained in distribution or event weights


Train on weighted events


## Training on weighted events

Information contained in distribution or event weights

Train on weighted events


Generate unweighted events


$$
L_{D}=\langle-w \log D(x)\rangle_{x \sim P_{\text {Truth }}}+\langle-\log (1-D(x))\rangle_{x \sim P_{G e n}}
$$

## Training on weighted events

Information contained in distribution or event weights

Train on weighted events


Generate unweighted events


$$
L_{D}=\langle-w \log D(x)\rangle_{x \sim P_{\text {Truth }}}+\langle-\log (1-D(x))\rangle_{x \sim P_{G e n}}
$$

normalizing flow: B. Stienen, R. Verheyen [2011.13445]

## uwGAN results



Populates high energy tails
Large amplification wrt. unweighted data!

## Fast detector simulations

- Important R\&D potential NN evaluation $\times 100-1000$ faster than GEANT4

- Same underlying techniques [GAN, VAE, (NF)]
- Challenge: High-dimensional output

$$
\leftarrow 30 \times 30 \times 30
$$

## BIB-AE PP

Bounded-Information-Bottleneck autoencoder with post processing


## BIB-AE PP

Bounded-Information-Bottleneck autoencoder with post processing


GEANT4


Simulation


## BIB-AE PP

Bounded-Information-Bottleneck autoencoder with post processing


Post Processor Network adjusts energy to recover spectrum $\rightarrow$ MIP bump


## Can we invert the simulation chain?


wish list:
multi-dimensionalbin independentstatistically well defined

## Invertible networks


[1808.04730] L. Ardizzone, J. Kruse, S. Wirkert, D. Rahner,
E. W. Pellegrini, R. S. Klessen, L. Maier-Hein, C. Rother, U. Köthe

+ Bijective mapping
+ Tractable Jacobian
+ Fast evaluation in both directions
+ Arbitrary networks $s$ and $t$


## Inverting detector effects

- $p p \rightarrow Z W \rightarrow(I I)(j j)$
- Train: parton $\rightarrow$ detector
- Evaluate: parton $\leftarrow$ detector



multi-dimensional $\checkmark$ bin independent $\checkmark$ statistically well defined ?


## Including stochastical effects

$$
\binom{x_{p}}{r_{p}} \stackrel{\text { PYTHIA,DELPHES: } g \rightarrow}{\leftarrow \text { unfolding }: \bar{g}}\binom{x_{d}}{r_{d}}
$$

Sample $r_{d}$ for fixed detector event How often is Truth included in distribution quantile?



- Problem: arbitrary balance of many loss functions


## Taking a different angle

Given an event $x_{d}$, what is the probability distribution at parton level? $\rightarrow$ sample over $r$, condition on $x_{d}$

$$
x_{p} \underset{\leftarrow \text { unfolding: } \bar{g}\left(r, f\left(x_{d}\right)\right)}{g\left(x_{p}, f\left(x_{d}\right)\right) \rightarrow} r
$$



## Taking a different angle

Given an event $x_{d}$, what is the probability distribution at parton level?
$\rightarrow$ sample over $r$, condition on $x_{d}$

$$
x_{p} \underset{\leftarrow \text { unfolding: } \bar{g}\left(r, f\left(x_{d}\right)\right)}{g\left(x_{p}, f\left(x_{d}\right)\right) \rightarrow} r
$$

$\rightarrow$ Training: Maximize posterior over model parameters

$$
\begin{aligned}
L & =-\left\langle\log p\left(\theta \mid x_{p}, x_{d}\right)\right\rangle_{x_{p} \sim P_{p}, x_{d} \sim P_{d}} \\
& =-\left\langle\log p\left(x_{p} \mid \theta, x_{d}\right)\right\rangle_{x_{p} \sim P_{p}, x_{d} \sim P_{d}}-\log p(\theta)+\text { const. } \leftarrow \text { Bayes } \\
& =-\left\langle\log p\left(\bar{g}\left(x_{p}, x_{d}\right)\right)+\log \right| \frac{\partial \bar{g}\left(x_{p}, x_{d}\right)}{\partial x_{p}}| \rangle-\log p(\theta) \leftarrow \text { change of var } \\
& =\langle 0.5|\left|\bar{g}\left(x_{p}, f\left(x_{d}\right)\right) \|_{2}^{2}-\log \right| J| \rangle_{x_{p} \sim P_{p}, x_{d} \sim P_{d}}-\log p(\theta)
\end{aligned}
$$

$\rightarrow$ Jacobian of bijective mapping

## Cross check distributions





## Condition INN on detector data raoos orses



Minimizing $\left.\left.L=\langle 0.5| \mid \bar{g}\left(x_{p}, f\left(x_{d}\right)\right)\right) \|_{2}^{2}-\log |J|\right\rangle_{x_{p} \sim P_{p}, x_{d} \sim P_{d}}-\log p(\theta)$


multi-dimensional $\checkmark$ bin independent $\checkmark$ statistically well defined $\checkmark$

## Inverting the full event I

- $p p>W Z>q \bar{q} I^{+} I^{-}+\mathrm{ISR}$
$\rightarrow$ ISR leads to large fraction of $2 / 3 / 4$ jet events
- Train and test on exclusive channels



## Inverting the full event II

$$
p p>W Z>q \bar{q} I^{+} I^{-}+\mathrm{ISR}
$$

Train on inclusive dataset


Evaluate
exclusive $2 / 3 / 4$ jet channels


## We can use ML ...

... to enable precision simulations in forward direction
... to turn weighted into unweighted events
... to invert the simulation chain statistically

$$
\ldots \text { for fun and precision :) }
$$

