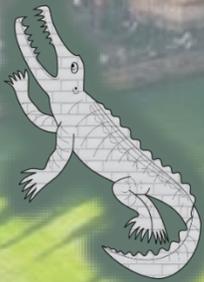


Dynamics of a New Topology – the Euler Class

Nur Ünal

UNIVERSITY OF
CAMBRIDGE
Cavendish Laboratory



TCM

KITP, 7 June 2021

Interacting Topological Matter: Atomic, Molecular And Optical Systems



Adrien Bouhon
Nordita



Robert-Jan Slager
Cambridge

FNÜ, Bouhon, Slager, PRL 125, 053601 (2020)

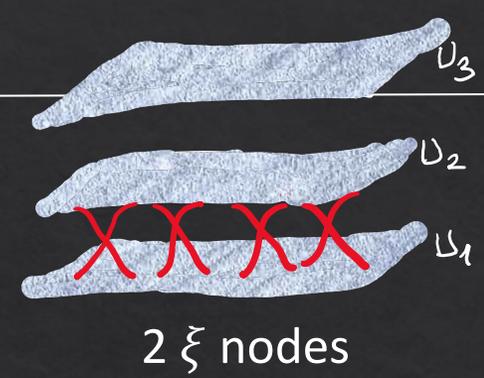


Newton International Fellowship



Engineering and Physical Sciences
Research Council

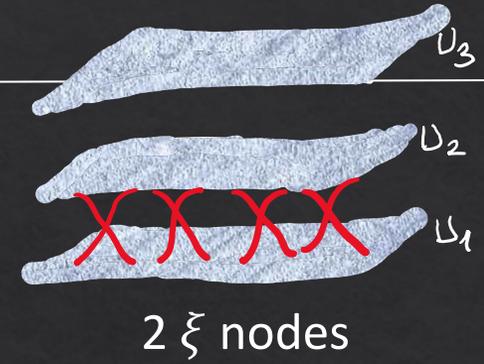
Why Euler Class?



- Remarkable progress in characterising topological phases; crystalline insulators, higher order topology, fragile invariants...
- Exotic new invariant that falls outside symmetry eigenvalue indicated phases: Euler Class
 - Analogue of Chern number in systems with C_2T or \mathcal{PT}
 - Requires minimum 3 bands
 - Band nodes host non-Abelian braiding properties!
 - Fragile topology

$$\xi = \frac{1}{2\pi} \oint d^2k \left(\langle \partial_{k_x} u_1 | \partial_{k_y} u_2 \rangle - \langle \partial_{k_y} u_1 | \partial_{k_x} u_2 \rangle \right)$$

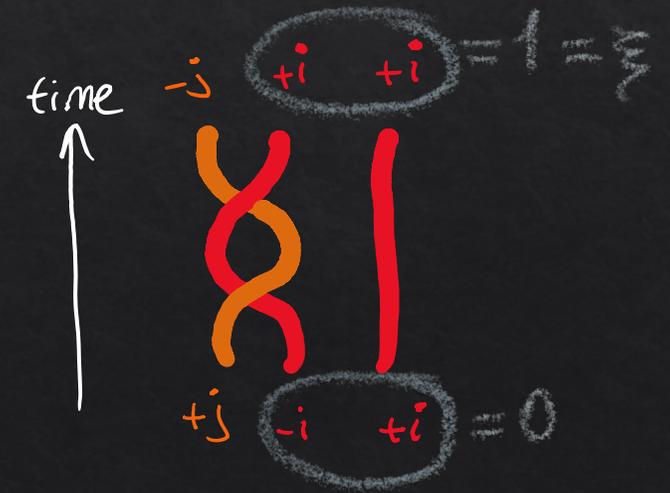
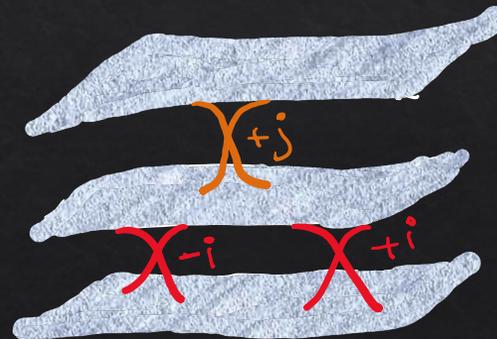
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- Analogue of Chern number in systems with C_2T or \mathcal{PT}
- Requires minimum 3 bands
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- Fragile topology



Concrete experimental signatures for Euler class?

Euler Class

Chern Number

2 bands: $H_c(\mathbf{k}) = \mathbf{d}(\mathbf{k}) \cdot \boldsymbol{\sigma}$



$$\pi_2(S^2) = \mathbf{Z}$$

$$\mathcal{C} = \frac{1}{4\pi} \oint d^2k \hat{\mathbf{d}} \cdot (\partial_{k_x} \hat{\mathbf{d}} \times \partial_{k_y} \hat{\mathbf{d}})$$

solid angle

Euler Invariant

3 bands: $\mathcal{H}(\mathbf{k}) = \mathbf{h}(\mathbf{k}) \cdot \boldsymbol{\lambda}$

Real!

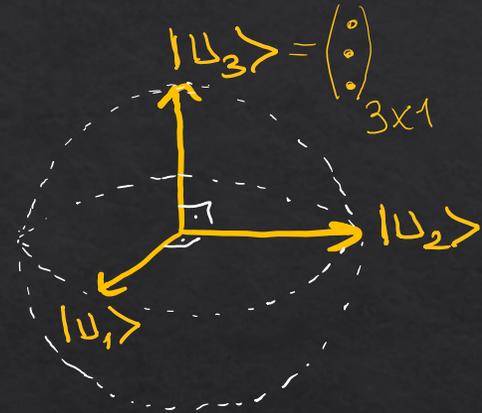
Eigenstates $\{|u_j(\mathbf{k})\rangle\}$ form a *dreibein*:

$$\mathbf{n}(\mathbf{k}) \equiv \mathbf{u}_3(\mathbf{k}) = \mathbf{u}_1(\mathbf{k}) \times \mathbf{u}_2(\mathbf{k})$$

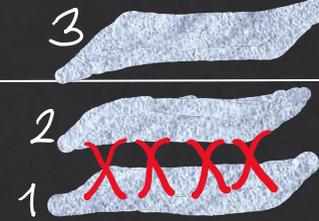
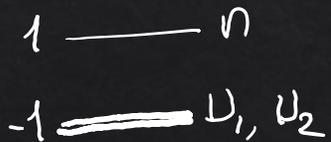
$$\mathcal{H}(\mathbf{k}) = 2 \mathbf{n}(\mathbf{k}) \cdot \mathbf{n}(\mathbf{k})^T - \mathbb{I}_3$$

$$\xi = \frac{1}{2\pi} \oint d^2k \mathbf{n} \cdot (\partial_{k_x} \mathbf{n} \times \partial_{k_y} \mathbf{n})$$

Gell-Mann



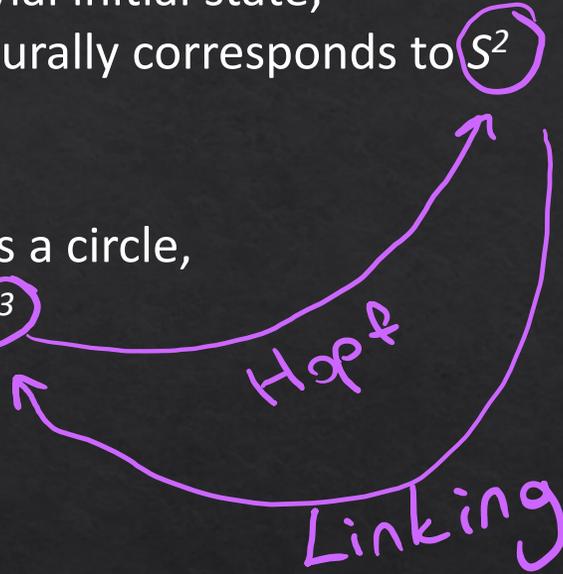
Spectrally flattened



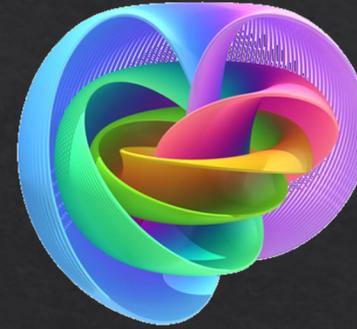
Euler Class – dynamics on S^2

1) $\psi_0(\mathbf{k}) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$: Trivial initial state, naturally corresponds to S^2

2) Time-evolution traces a circle, $(k_x, k_y, t) \equiv T^3 \rightarrow S^3$



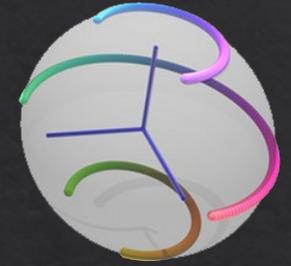
2D momentum+time



$T^3 \rightarrow S^3$

Hopf Map
 $\pi_3(S^2) = \mathbf{Z}$

Bloch Sphere



S^2

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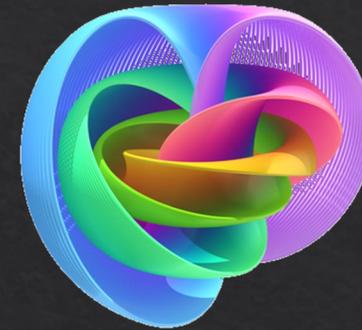
$$\psi(\mathbf{k}, t) = e^{-itH(\mathbf{k})} \psi_0(\mathbf{k})$$

$$\downarrow H^2 = \mathbb{I}_3$$

$$= [\cos(t) - \mathbf{i} \sin(t)H(\mathbf{k})] \psi_0(\mathbf{k})$$

*$\psi(\mathbf{k}, t)$
! complex X*

$$\hat{\mathbf{p}}(\mathbf{k}, t) = \psi^\dagger(\mathbf{k}, t) \boldsymbol{\mu} \psi(\mathbf{k}, t)$$

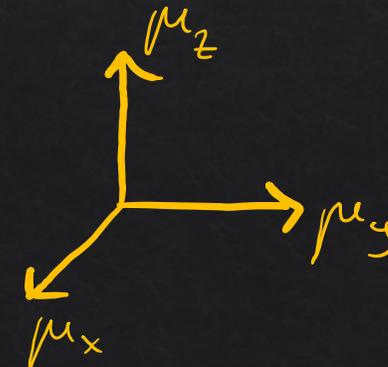


Hopf Map
 $\pi_3(S^2) = \mathbf{Z}$



(Image: Wikipedia)

“ Bloch sphere S^2 ”



$$\mu_x = \begin{pmatrix} 0 & i & 1 \\ -i & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\mu_y = \begin{pmatrix} 0 & 1 & -i \\ 1 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}$$

$$\mu_z = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

Hopf Map

Q: How to analytically establish $S^3 \rightarrow S^2$?

A: **Quaternions***

*Extends Complex numbers; \mathbf{R}^4 with \mathbf{C}^2
(\mathbf{C} relates to \mathbf{R}^2)

$$q = x_0 + x_1i + x_2j + x_3k, \quad q \in \mathbf{R}^4$$

3D vector



$$ij = k, jk = i, ki = j$$

$$i^2 = j^2 = k^2 = -1$$

Generates rotations in 3D! $R_{\nu} \mathbf{t} = \mathbf{t}'$

The matrix of a proper rotation R by angle θ around the axis $\mathbf{u} = (u_x, u_y, u_z)$, a unit vector with $u_x^2 + u_y^2 + u_z^2 = 1$, is given by:

$$R = \begin{bmatrix} \cos \theta + u_x^2 (1 - \cos \theta) & u_x u_y (1 - \cos \theta) - u_z \sin \theta & u_x u_z (1 - \cos \theta) + u_y \sin \theta \\ u_y u_x (1 - \cos \theta) + u_z \sin \theta & \cos \theta + u_y^2 (1 - \cos \theta) & u_y u_z (1 - \cos \theta) - u_x \sin \theta \\ u_z u_x (1 - \cos \theta) - u_y \sin \theta & u_z u_y (1 - \cos \theta) + u_x \sin \theta & \cos \theta + u_z^2 (1 - \cos \theta) \end{bmatrix}.$$

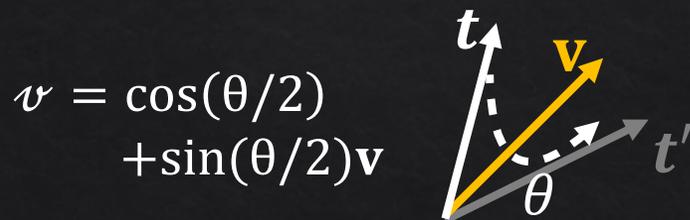
Hopf Map

- Quaternion, $q = x_0 + x_1i + x_2j + x_3k$, $q \in \mathbb{R}^4$
- Versor, $|v| = \sqrt{\sum_n x_n^2} = 1$, spans $S^3 \subset \mathbb{R}^4$
- Pure quaternion: a vector $t \in \mathbb{R}^3$

➤ Multiplying a pure quaternion with an arbitrary versor results in another pure quaternion

$$R_v: \mathbf{t} \mapsto \mathbf{t}' = v\mathbf{t}v^{-1} \quad v^{-1} = \frac{v^*}{\|v\|^2}$$

So this norm preserving action generates Rotations in 3D!



$$R_v \mathbf{t} = \mathbf{t}'$$

$$R_v = \begin{pmatrix} x_0^2 + x_1^2 - x_2^2 - x_3^2 & 2x_1x_2 - 2x_0x_3 & 2x_0x_2 + 2x_1x_3 \\ 2x_1x_2 + 2x_0x_3 & x_0^2 - x_1^2 + x_2^2 - x_3^2 & -2x_0x_1 + 2x_2x_3 \\ -2x_0x_2 + 2x_1x_3 & 2x_0x_1 + 2x_2x_3 & x_0^2 - x_1^2 - x_2^2 + x_3^2 \end{pmatrix}$$

Hopf Map

How does this define the Hopf Map?

- Versor, $|\boldsymbol{v}| = \sqrt{\sum_n x_n^2} = 1$, spans $S^3 \subset \mathbb{R}^4$
- Pure quaternion: a vector $\boldsymbol{t} \in \mathbb{R}^3$ unit $\Rightarrow t \in S^2$

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$$R_v: \boldsymbol{t} \mapsto \boldsymbol{t}' = \boldsymbol{v} \boldsymbol{t} \boldsymbol{v}^{-1}$$



$$R_v \boldsymbol{t} = \boldsymbol{t}'$$

$$\boldsymbol{v} = \cos(\theta/2) + \sin(\theta/2) \boldsymbol{v}$$



Hopf Invariant

$$H = \frac{1}{V} \oint d^3 p \epsilon^{ijkl} x_i \partial_{p_x} x_j \partial_{p_y} x_k \partial_{p_z} x_l$$

$$R_v = \begin{pmatrix} x_0^2 + x_1^2 - x_2^2 - x_3^2 & 2x_1x_2 - 2x_0x_3 & 2x_0x_2 + 2x_1x_3 \\ 2x_1x_2 + 2x_0x_3 & x_0^2 - x_1^2 + x_2^2 - x_3^2 & -2x_0x_1 + 2x_2x_3 \\ -2x_0x_2 + 2x_1x_3 & 2x_0x_1 + 2x_2x_3 & x_0^2 - x_1^2 - x_2^2 + x_3^2 \end{pmatrix}$$

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$$R_v \boldsymbol{t} = \boldsymbol{t}'$$

$$\boldsymbol{v} = \cos(\theta/2) + \sin(\theta/2) \boldsymbol{v}$$



Key Insight:

$$\psi(\boldsymbol{k}, t) = [\cos(t) - \mathbf{i} \sin(t) H(\boldsymbol{k})] \psi_0(\boldsymbol{k})$$

$$\{x_0, \boldsymbol{x}\} = \{\cos t, -\sin(t) H \psi_0\}$$

Hopf Invariant

$$H = \frac{1}{V} \oint d^3 p \epsilon^{ijkl} x_i \partial_{p_x} x_j \partial_{p_y} x_k \partial_{p_z} x_l$$

$$R_v = \begin{pmatrix} x_0^2 + x_1^2 - x_2^2 - x_3^2 & 2x_1x_2 - 2x_0x_3 & 2x_0x_2 + 2x_1x_3 \\ 2x_1x_2 + 2x_0x_3 & x_0^2 - x_1^2 + x_2^2 - x_3^2 & -2x_0x_1 + 2x_2x_3 \\ -2x_0x_2 + 2x_1x_3 & 2x_0x_1 + 2x_2x_3 & x_0^2 - x_1^2 - x_2^2 + x_3^2 \end{pmatrix}$$

Monopole – anti-monopole pairs

- Physical consequences of the Hopf construction
- Quench w/ non-trivial Euler Hamiltonian:

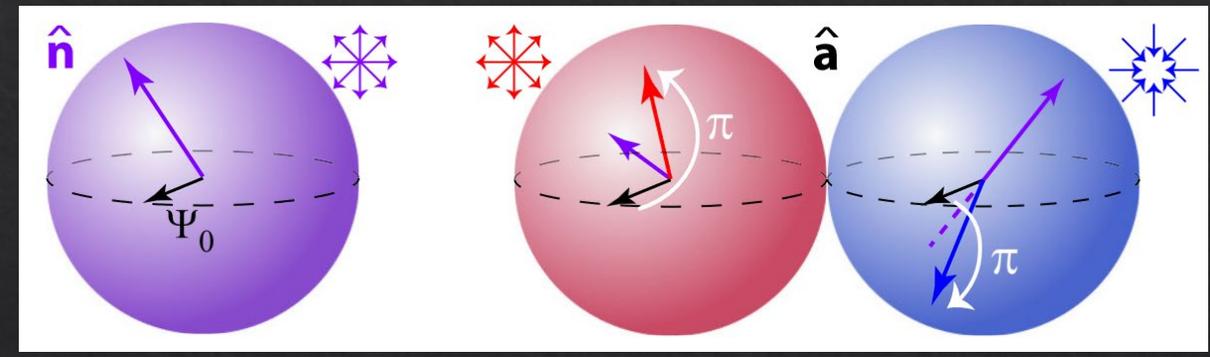
$$\mathcal{H}(\mathbf{k}) = 2 \mathbf{n}(\mathbf{k}) \cdot \mathbf{n}(\mathbf{k})^T - \mathbb{I}_3$$

$$\psi(\mathbf{k}, t) = [\cos t - i \sin t \mathcal{H}(\mathbf{k})] \psi_0$$

$\mathbf{a}(\mathbf{k}) = \mathcal{H}(\mathbf{k})\psi_0$

$$\psi_0(\mathbf{k}, 0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Monopole – anti-monopole pair topologically stable



Hamiltonian corresponds to a π -rotation around $\mathbf{n}(\mathbf{k})$.

$$\mathbf{n}(\mathbf{k}) = \begin{pmatrix} \cos \alpha \\ \sin \alpha \cos \beta \\ \sin \alpha \sin \beta \end{pmatrix} \implies \mathbf{a}(\mathbf{k}) = \begin{pmatrix} \cos 2\alpha \\ \sin 2\alpha \cos \beta \\ \sin 2\alpha \sin \beta \end{pmatrix}$$

$\alpha \in [0, \pi)$ from $+\hat{x}$

Monopole – anti-monopole pairs

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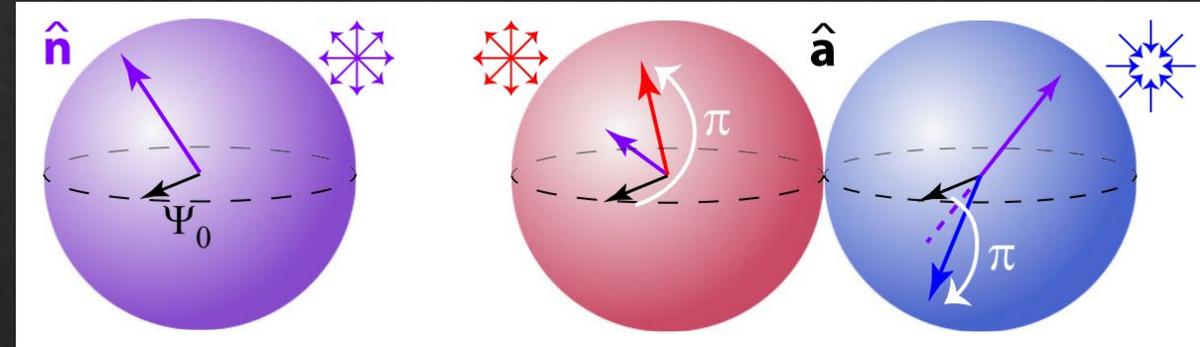
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Monopole – anti-monopole pair topologically stable



Hamiltonian corresponds to a π -rotation around $\mathbf{n}(\mathbf{k})$.

- Analytically $\text{Hopf} = \frac{1}{4\pi} \oint d^2k \mathbf{a} \cdot (\partial_{k_x} \mathbf{a} \times \partial_{k_y} \mathbf{a})$

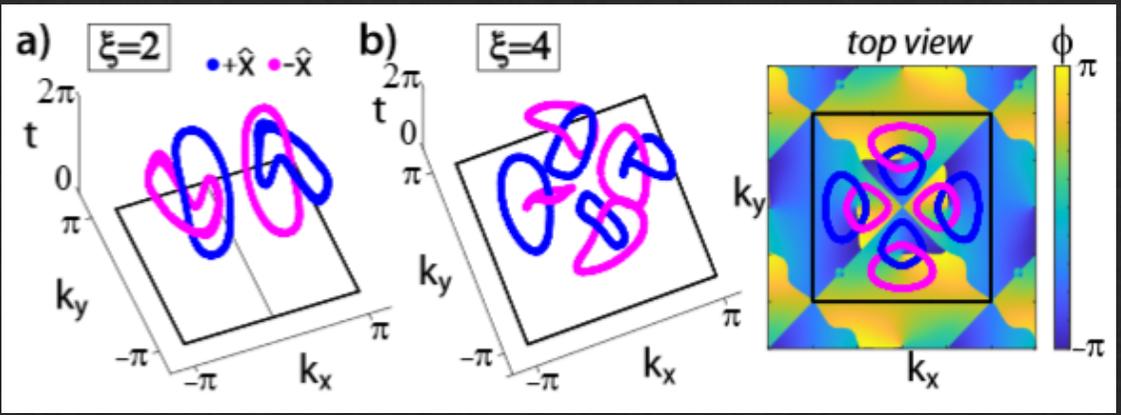
Hopf \longleftrightarrow Euler
 \downarrow
 Linking

Euler Class – observables

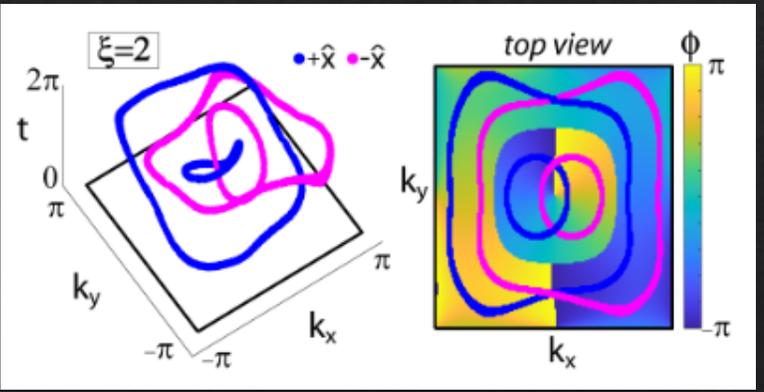


■ Linkings

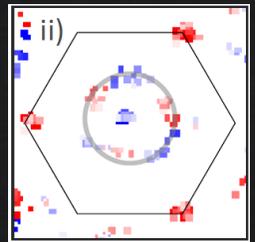
$$\psi_0(\mathbf{k}, 0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$



$$= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

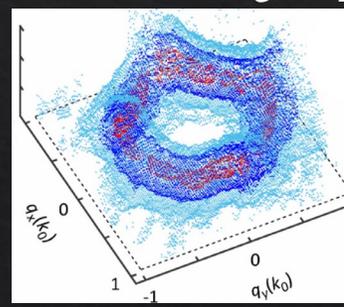
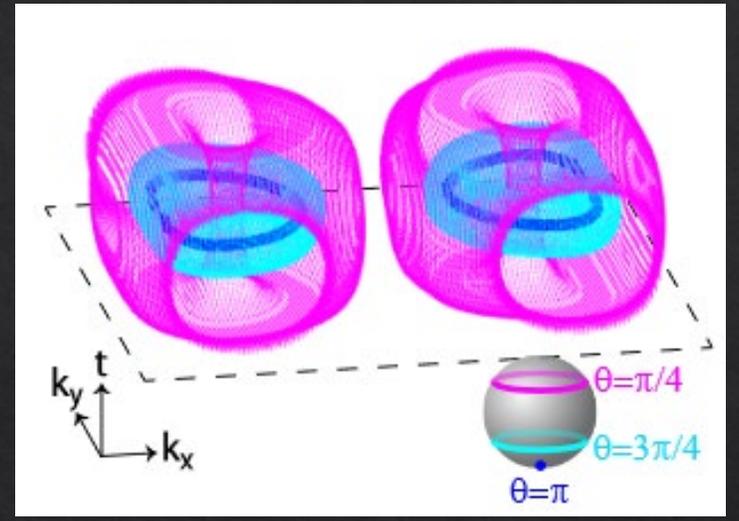


Linking measured in experiment for Chern# !
Tarnowski, FNÜ et al. Nature Comm'19



$C = 1$

■ Hopf Tori $\xi = 2$



$C = 1$

Observed in Raman lattices for Chern# !
Yi et al. arXiv:1904.11656
Sun, Yi et al. PRL'18

Euler Class – experimental protocols

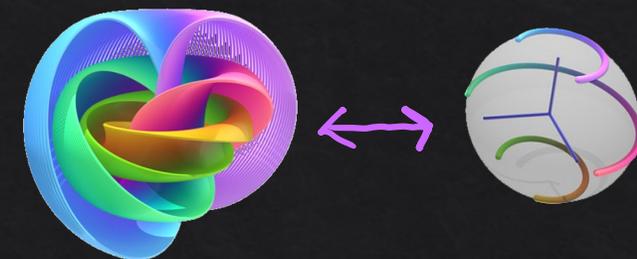
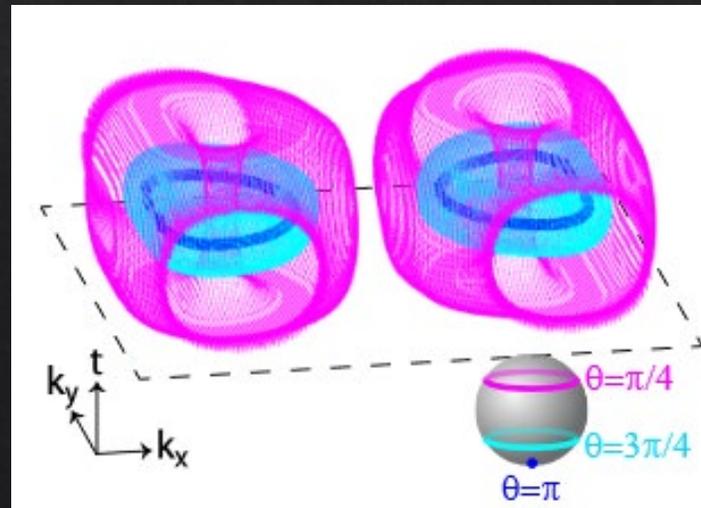
1) Pseudospin \equiv hyperfine states $|A\rangle, |B\rangle, |C\rangle$

- Quenching $|\psi_0\rangle = |A\rangle$ initiates Raman-induced oscillations
- Spin polarization: $P_z(\mathbf{k}, t) = \frac{N_A - N_B - N_C}{N_A + N_B + N_C}$
- Inverse image of $P_z(\mathbf{k}, t) = \cos \theta$ traces a closed surface in T^3

\hat{z} - direction

$$\mu_z = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

Nested Hopf tori



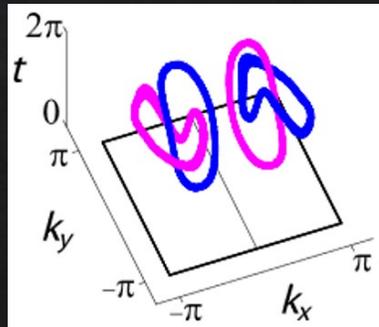
Euler Class – experimental protocols

1) Pseudospin \equiv hyperfine states \Rightarrow *Polarization*

2) Pseudospin \equiv sublattice

- TOF: $m(k, t) \propto |(\langle A| + \langle B| + \langle C|) |\psi(k, t)\rangle|^2$

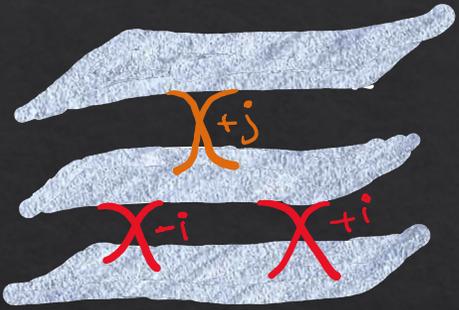
$$\psi(k, t) = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix} \xrightarrow[H_{pulse} \propto \text{diag}(1, -1, 1)]{\pi/2 \text{ pulse}} \begin{pmatrix} \psi_1 \\ i\psi_2 \\ \psi_3 \end{pmatrix} \xrightarrow[H_{tom} = \omega\mu_z/2]{\text{time } t} m(k, t) \propto [1 + \sin \theta_k \cos(\phi_k + \omega t)]$$



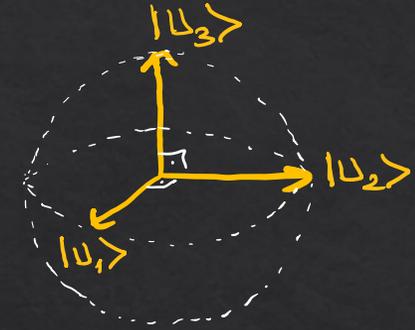
Linking as vortices in ϕ

$$\psi(k, t) = \begin{pmatrix} x_0 + ix_1 \\ x_2 \\ x_3 \end{pmatrix} \Rightarrow \zeta = \begin{pmatrix} x_0 + ix_1 \\ x_2 + ix_3 \end{pmatrix}$$

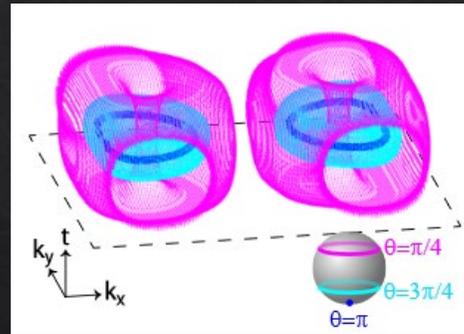
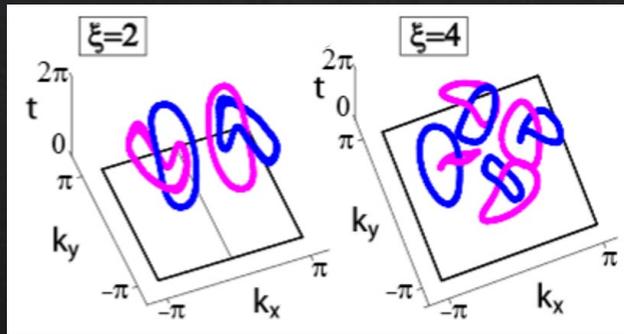




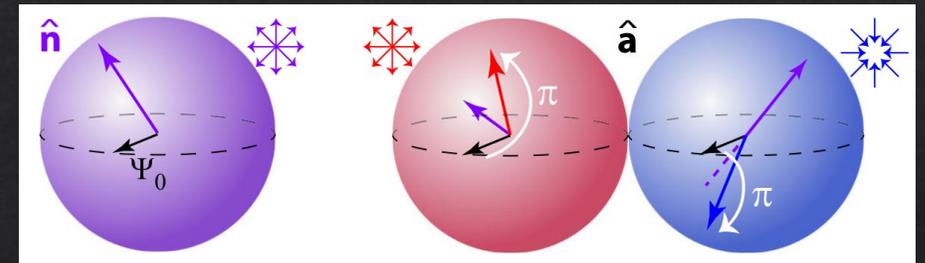
- Euler Class features many intriguing topological properties
multi-gap topology, non-Abelian braiding ...
- New phenomena in its quench dynamics!



- Naturally embodies a Hopf construction



- Monopole – anti-monopole pairs



➤ *New crystalline and exotic fragile topologies to explore in ultracold atoms...*

- Concrete signals/protocols for experiments to observe Euler Class!

Thank you!